

TODO: verify that this is all that needs to be done. Read the code to ensure all ports that are used are on here.

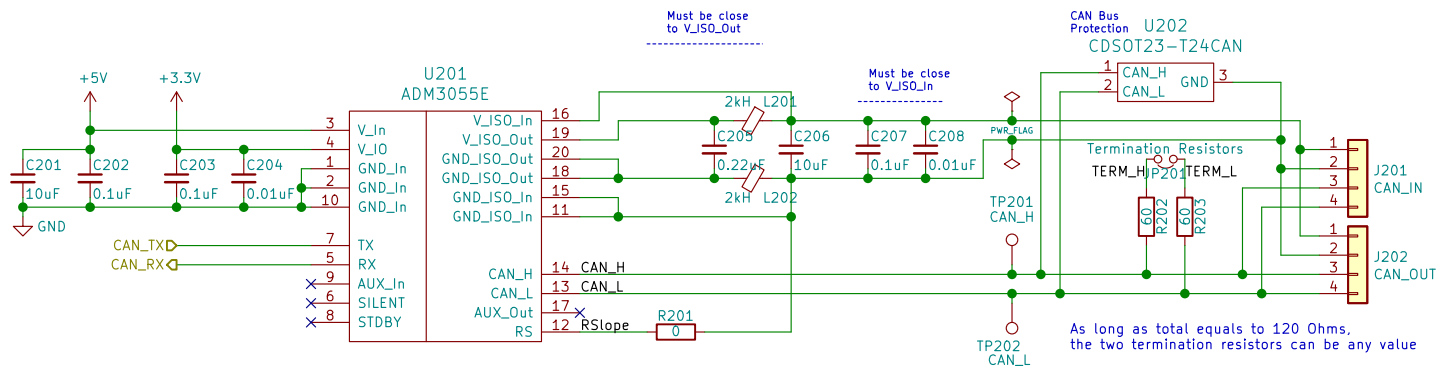
Look at all the other comments.

Also check over all the footprints again.

Also look at all the bodge wires running around the twins' board.

Also, if we're including another CAN line, we should probably include another pot.

| For the board itself | For the gecko |
|----------------------|--------------------|
| H101 Mounting Hole | H104 Mounting Hole |
| H102 Mounting Hole | H105 Mounting Hole |
| H103 Mounting Hole | H106 Mounting Hole |
| | H107 Mounting Hole |



Sheet: /CarCAN/
File: CAN.sch

Title:

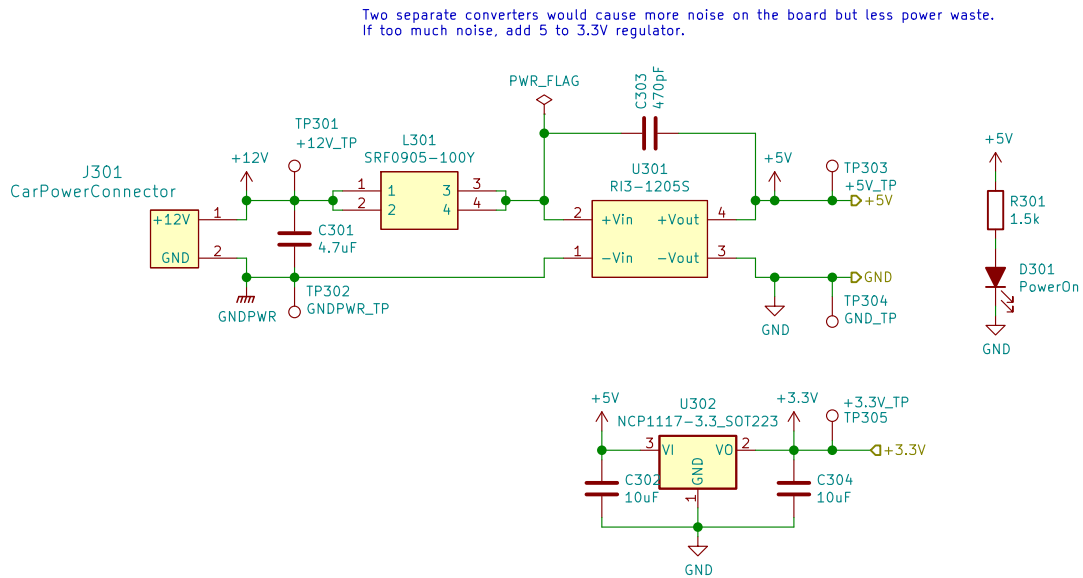
Size: A4

Date:

KiCad E.D.A. kicad 5.1.6-c6e7f7d86ubuntu20.04.1

Rev:

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Sheet: /PowerDist/
File: PowerDist.sch

Title:

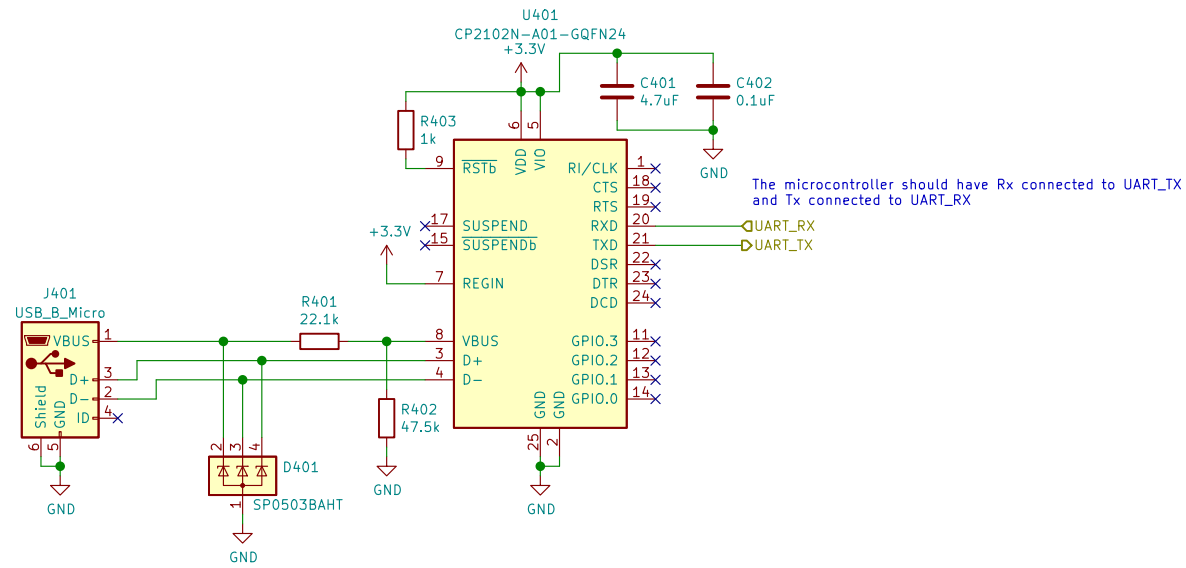
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KiCad E.D.A. kicad 5.1.6-c6e7f7d86ubuntu20.04.1

Rev:

Id: 3/6



Sheet: /USB/
File: USB.sch

Title:

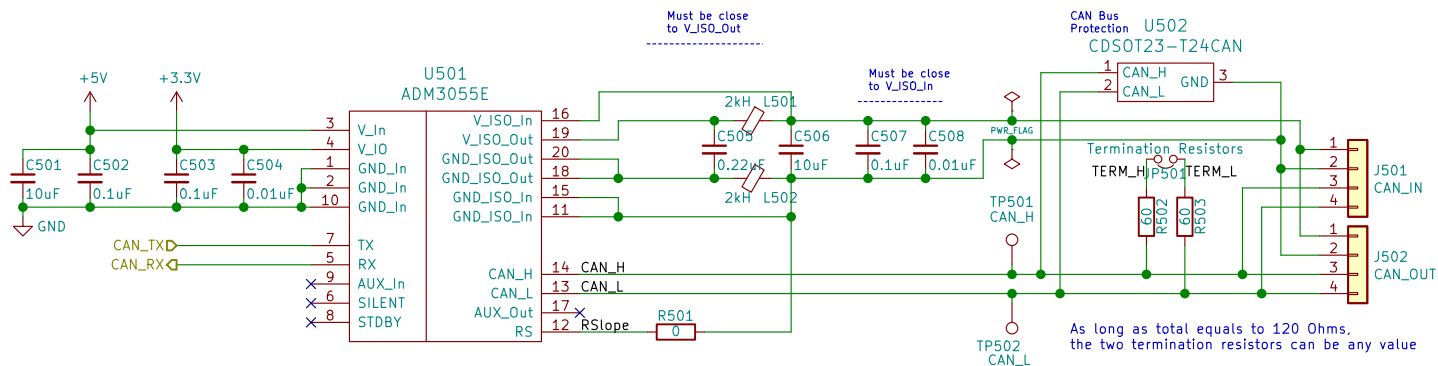
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Rev:

Id: 4/6



Sheet: /MotorCAN/
File: CAN.sch

Title:

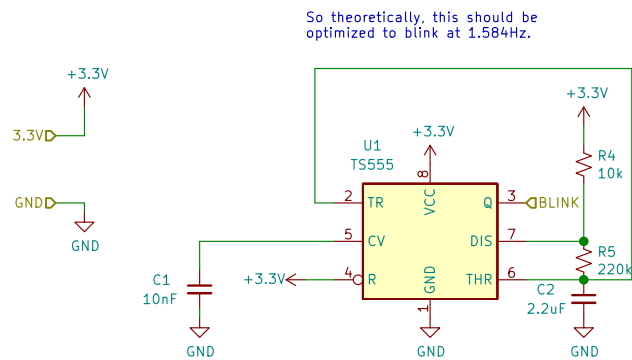
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Date:

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Rev:

Id: 5/6



Sheet: /lights-timer/
File: lights-timer.sch

Title:

Size: A4

Date:

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Rev:

Id: 6/6