## Perceptons

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16th April 2018

Adapted from slides provided by Prof. Michael Mandel.



#### Outline

Definition

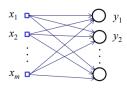
Decision boundary Linear separability

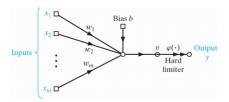
Learning rule

Convergence theorem

#### Perceptrons

- Architecture: one-layer feedforward net
  - Without loss of generality, consider a single-neuron perceptron





#### Definition

$$y=arphi(
u)$$
 
$$u=\sum_{i=1}^m w_i x_i + b$$
 
$$\varphi(
u)=\left\{ egin{array}{ll} 1 & ext{if } 
u\geq 0 \\ -1 & ext{otherwise} \end{array} 
ight.$$

Hence a McCulloch-Pitts neuron, but with real-valued inputs

#### Pattern recognition

- With a bipolar output, the perceptron performs a 2-class classification problem, *i.e.*, apples vs. oranges.
- How do we learn to perform classification?
- The perceptron is given pairs of input  $x_p$  and desired output  $d_p$
- How can we find  $y_p = \varphi(x_p^T w) = d_p, \forall p$

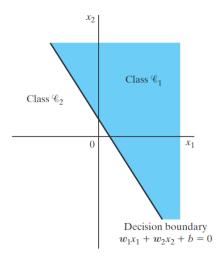
## But first: decision boundary

- Can we visualize the decision the perceptron would make in classifying every potential point?
- Yes, it is called the discriminant function

$$g(x) = x^T w = \sum_{i=0}^m w_i x_i$$

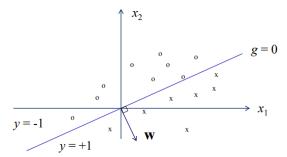
- What is the boundary between the two classes like?
- This is a linear function of x

# Decision boundary example



#### Decision boundary

- For an m-dimensional input space, the decision boundary is an (m-1)-dimensional hyperplane perpendicular to w. The hyperplane separate the input space into two halves, with one half having y=1, and the other half having y=-1
  - When b=0, the hyperplane goes through the origin.



#### Linear separability

- For a set of input patterns  $x_p$ , if there exists at least one w that separates d=1 patterns from d=-1 patterns, then the classification problem is linearly separable.
  - In other words, there exists a linear discriminant function that produces no classification error.
  - Examples: AND, OR, XOR

#### Linear separability

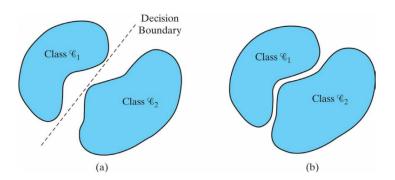


Figure: illustration: left: Linear separable, right: Not linear separable

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## Perceptron definition (recap. )

$$y = \varphi(\nu)$$
 
$$\nu = \sum_{i=1}^m w_i x_i + b$$
 
$$\varphi(\nu) = \left\{ \begin{array}{ll} 1 & \text{if } \nu \geq 0 \\ -1 & \text{otherwise} \end{array} \right.$$

Hence a McCulloch-Pitts neuron, but with real-valued inputs

## Perceptron learning rule

- Learn parameters w from examples  $(x_p, d_p)$
- In an online fashion, i.e., one point at a time
- Adjust weights as necessary, i.e., when incorrect
- Adjust weights to be more like d=1 points and more like negative d=-1 points.

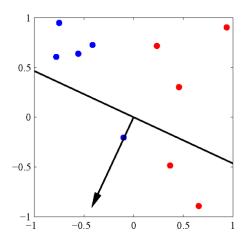
## Biological analogy

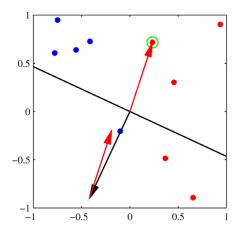
- Strengthen an active synapse if the postsynaptic neuron fails to fire when it should have fired
- Weaken an active synapse if the neuron fires when it should not have fired
- Formulated by Rosenblatt based on biological intuition

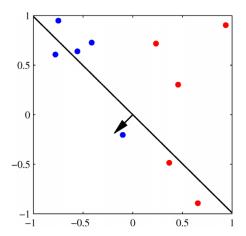
## Quantitatively

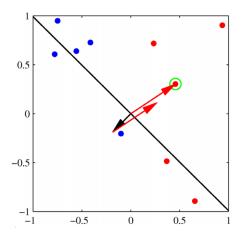
$$w(n+1) = w(n) + \Delta w(n) = w(n) + \eta [d(n) - y(n)] x(n)$$
(1)

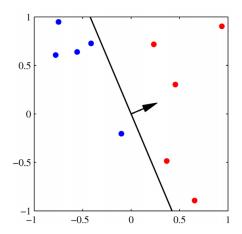
- n: iteration number, iterating over points in turn
- $\eta$ : step size or learning rate
- Only updates w when y(n) is incorrect











- Each weight update moves w closer to d=1 patterns, or away from d=-1 patterns.
- Final weight vector in example solves the classification problem
- Is that true in all cases?

# Summary of perceptron learning algorithm

- Definition:
  - w(n): (m+1)-by-1 weight vector (including bias) at step n
- Inputs:
  - x(n):  $n^{th}$  (m+1)-by-1 input vector with first element = 1
  - d(n):  $n^{th}$  desired response
- Initialization: set w(0) = 0
- Repeat until no points are mis-classified
  - Compute response:  $y(n) = \operatorname{sgn} \left[ w(n)^T x(n) \right]$
  - Update: w(n+1) = w(n) + [d(n) y(n)] x(n)

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## Perceptron convergence theorem

- Assume that there exists some unit vector  $w_0$  and some  $\alpha$  such that  $d(n)w_0^Tx(n) \geq \alpha$ , *i.e.* the data are linearly separable.
- Assume also that there exists some R such that  $||x(n)|| = \sqrt{x(n)^T x(n)} \le R \quad \forall n$
- Then the perceptron algorithm makes at most  $R^2/\alpha^2$  errors

#### Perceptron convergence proof outline

- Define  $w_k$  as the parameter vector when the algorithm makes its  $k^{th}$  error (note  $w_1=0$ )
- First show  $k\alpha \leq ||w_{k+1}||$  by induction
- Second show  $||w_{k+1}||^2 \le kR^2$  by induction
- Then it follows that  $k \le R^2/\alpha^2$ , *i.e.* the perceptron makes a finite number of errors.

- Assume that the k<sup>th</sup> error is made on example n.
- Because of the perceptron update rule,

$$w_{k+1}^{T} w_{0} = (w_{k} + d(n)x(n)^{T})w_{0}$$

$$= w_{k}^{T} w_{0} + d(n)x(n)^{T} w_{0}$$

$$\geq w_{k}^{T} w_{0} + \alpha$$
(2)

- Because, by assumption,  $d(n)x(n)^Tw_0 \ge \alpha$
- Then, by induction on k,  $w_{k+1}^T w_0 \ge k\alpha$
- In addition,  $\|w_{k+1}\|\|w_0\| \geq w_{k+1}^T w_0$  by Cauchy-Schwartz, with  $\|w_0\| = 1$
- Thus,  $||w_{k+1}|| \ge w_{k+1}^T w_0 \ge k\alpha$

# Second show $||w_{k+1}||^2 \le kR^2$ by induction

Because of the perceptron update rule

$$||w_{k+1}||^2 = ||w_k + d(n)x(n)||^2$$
  
=  $||w_k||^2 + d^2(n)||x(n)||^2 + 2d(n)x(n)^T w_k$  (3)

- By definition,  $d^2(n) = 1$
- By assumption,  $||x(n)||^2 \le R^2$
- Because the n-th points was misclassified  $2d(n)x(n)^Tw_k \leq 0$
- Thus,  $||w_{k+1}||^2 \le ||w_k||^2 + R^2$
- And , by induction on k,  $||w_{k+1}||^2 \leq kR^2$

# Then it follows that $k \leq R^2/\alpha^2$

- We have shown  $k\alpha \leq ||w_{k+1}||$  and  $||w_{k+1}||^2 \leq kR^2$
- So,  $k^2 \alpha^2 \le ||w_{k+1}||^2 \le kR^2$
- Then it follows that  $k \leq R^2/\alpha^2$
- Thus the perceptron learning algorithm makes a bounded number of mistakes, i.e., converges.

#### Perceptron learning remarks

- If data are not linearly separable
  - Algorithm will iterate forever
- Scaling w does not affect the preceptron's decision
  - = So the learning rate  $\eta$  does not affect the perceptron's decision either, and can be set to 1
- The solution weight vector w is not unique.

#### Generalization

- Performance of a learning machine on test patterns not used during training
- Perceptrons generalize by deriving a decision boundary in the input space. Selection of training pattens is thus important for generalization.

# Thank you!