

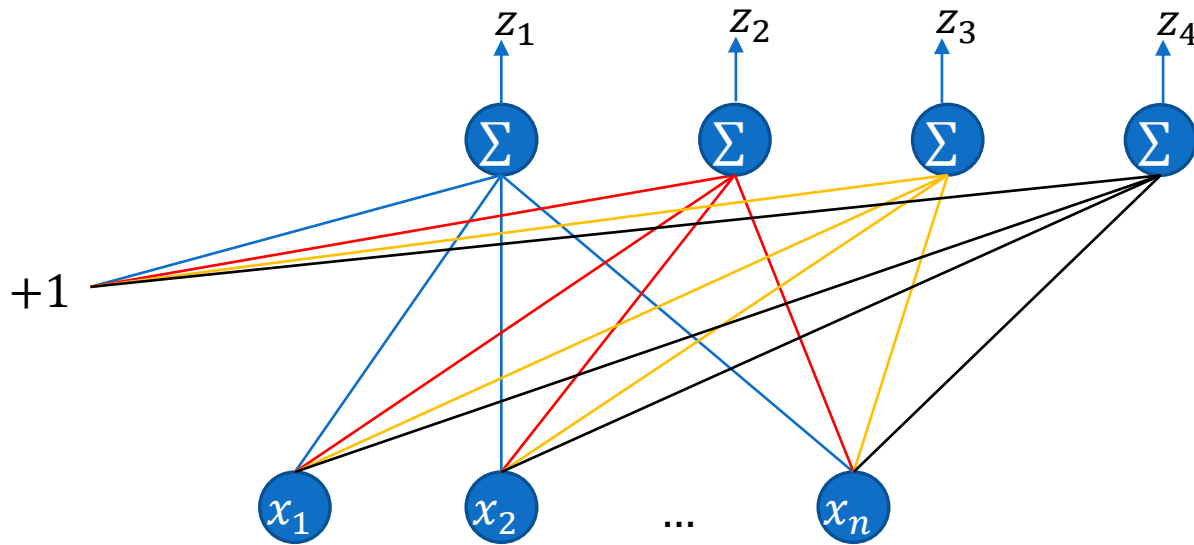
Review

SOFTMAX

Softmax: A Visual Perspective

Compute Error

$$S(z)_i = \frac{e^{z_i}}{\sum_{j=1}^C e^{z_j}}$$



Loss Function

Actual labels are one-hot-encoded.

$$\rightarrow y = \begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \hat{y} = \begin{bmatrix} 0.3 \\ 0.2 \\ 0.1 \\ 0.4 \end{bmatrix}$$

$$Loss(y, \hat{y}) = - \sum_{j=1}^c y_j \log \hat{y}_j$$

$$Loss(y, \hat{y}) = -(0. \log \hat{y}_1 + 1. \log \hat{y}_2 + 0. \log \hat{y}_3 + 0. \log \hat{y}_4)$$

$$Loss(y, \hat{y}) = -(1. \log \hat{y}_2) = -\log \hat{y}_2$$

$$J(y, \hat{y}) = \frac{1}{m} \sum_{i=1}^m Loss(y, \hat{y})$$

Use gradient descent to adjust weights once you have cost.

One Hot Encoding (aka categorical encoding)

x_1	x_2	y	<i>y One Hot Encoded</i>	<i>\hat{y} After Softmax</i>
5	9	0	[1, 0, 0]	[0.9, 0.1, 0]
6	8	0	[1, 0, 0]	[0.8, 0.2, 0]
1	2	1	[0, 1, 0]	[0.1, 0.75, 0.15]
11	12	2	[0, 0, 1]	[0, 0.05, 0.95]

$$Loss(y, \hat{y}) = - \sum_{j=1}^c y_j \log \hat{y}_j$$

$$J(y, \hat{y}) = \frac{1}{m} \sum_{i=1}^m Loss(y, \hat{y})$$

Project

- ☐ Idea Discussion!
- ☐ Dataset Creation
- ☐ Model Training
- ☐ Model Evaluation
 - Kaggle

Perceptron

References

□ Akshay L Chandra – medium.com

- McCulloch-Pitts Neuron — Mankind's First Mathematical Model Of A Biological Neuron: <https://towardsdatascience.com/mcculloch-pitts-model-5fdf65ac5dd1>
- Perceptron: The Artificial Neuron (An Essential Upgrade To The McCulloch-Pitts Neuron): <https://towardsdatascience.com/perceptron-the-artificial-neuron-4d8c70d5cc8d>
- Perceptron Learning Algorithm: A Graphical Explanation Of Why It Works: <https://towardsdatascience.com/perceptron-learning-algorithm-d5db0deab975>

□ Prof. Mitesh M. Khapra (<https://www.cse.iitm.ac.in/~miteshk/>) on NPTEL's (<http://nptel.ac.in/>) Deep Learning course (https://onlinecourses.nptel.ac.in/noc18_cs41/preview)

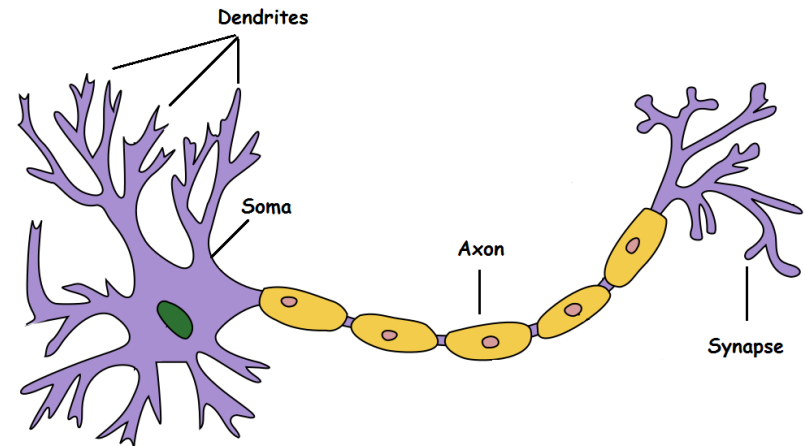
□ Machine Learning for Intelligent Systems, Kilian Weinberger, Cornell, Lectures 3-6, <https://www.cs.cornell.edu/courses/cs4780/2018fa/lectures/lecturenote03.html>

□ Perceptrons. An Introduction to Computational Geometry. Marvin Minsky and Seymour Papert. M.I.T. Press, Cambridge, Mass., 1969. <https://science.sciencemag.org/content/165/3895/780>

McCulloch-Pitts Neuron

- ❑ The fundamental unit of ANNs – An Artificial Neuron
- ❑ 1943 by McCulloch and Pitts: Mimicking the functionality of a biological neuron

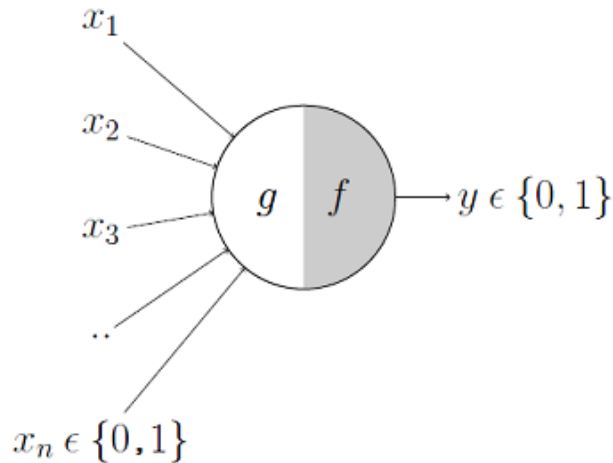
Dendrites receive signals from other neurons
Soma processes the information
Axons transmit the output
Synapses are the connections to other neurons



- ❑ About 86 billion of these in our brains on average!
- ❑ Each neuron gets activated/fired when its firing criteria is met
 - Based on the aggregation of signals from the inputs

McCulloch-Pitts Neuron

- The first computational model of a neuron was proposed by Warren McCulloch (neuroscientist) and Walter Pitts (logician) in 1943.



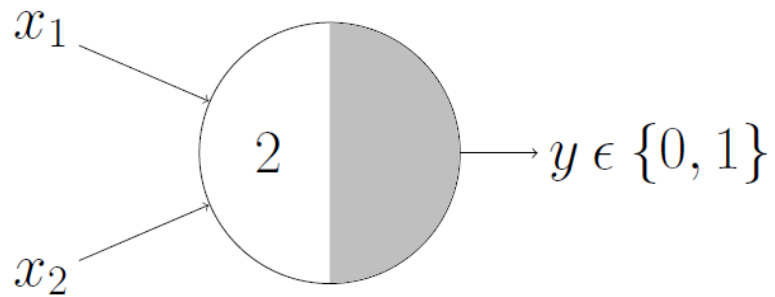
$$g(x_1, x_2, \dots, x_n) = g(X) = \sum_{i=1}^n x_i$$

$$y = f(g(X)) = \begin{cases} 1 & \text{if } g(X) \geq \theta \\ 0 & \text{if } g(X) < \theta \end{cases}$$

- g aggregates inputs, f makes decisions based on θ
- θ is a hand-coded threshold
- All x_i are binary inputs and y_i is a binary output

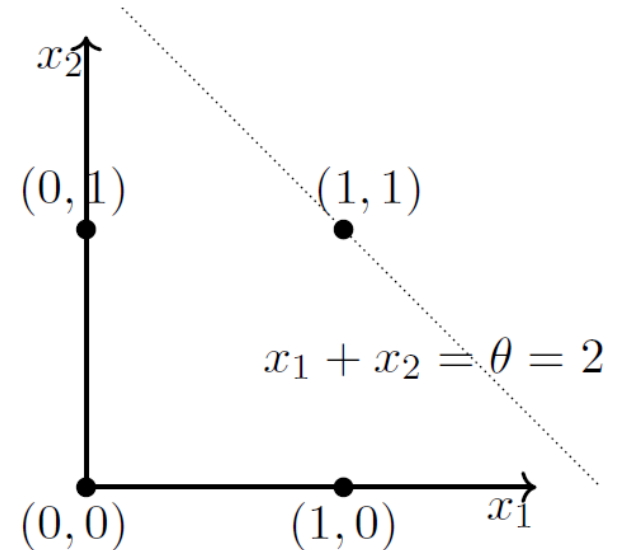
Boolean Functions

□ AND Function



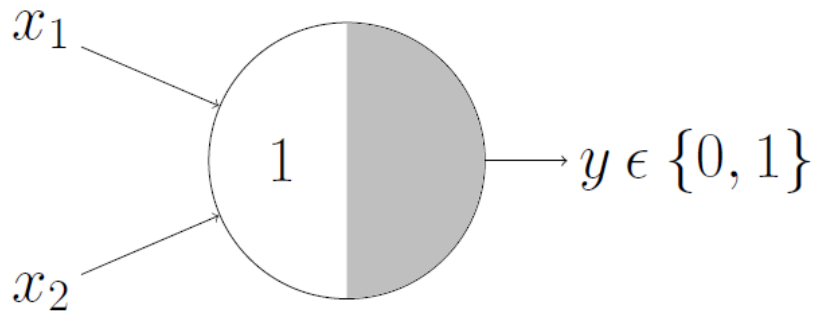
AND function

$$x_1 + x_2 = \sum_{i=1}^2 x_i \geq 2$$



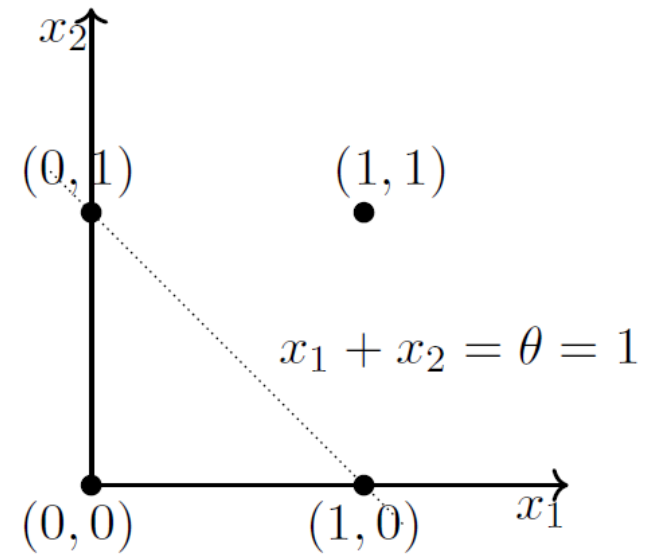
Boolean Functions

□ OR Function



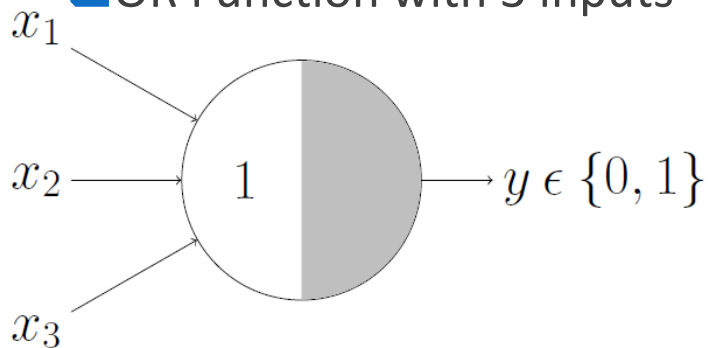
OR function

$$x_1 + x_2 = \sum_{i=1}^2 x_i \geq 1$$



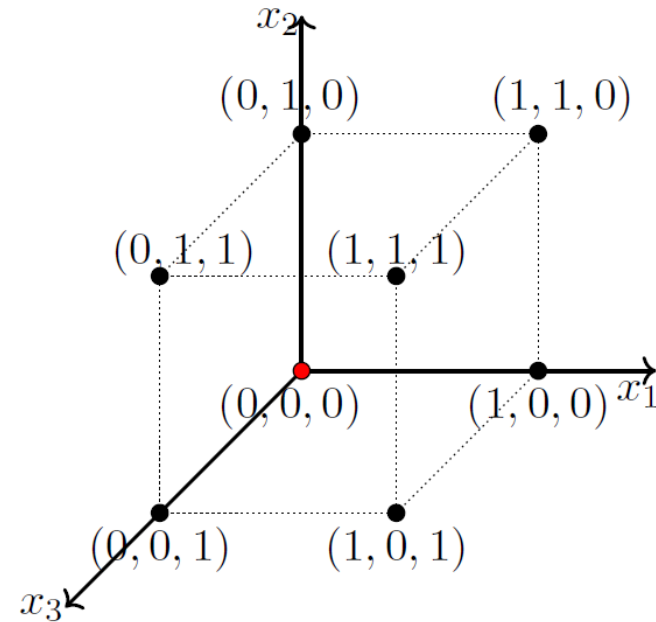
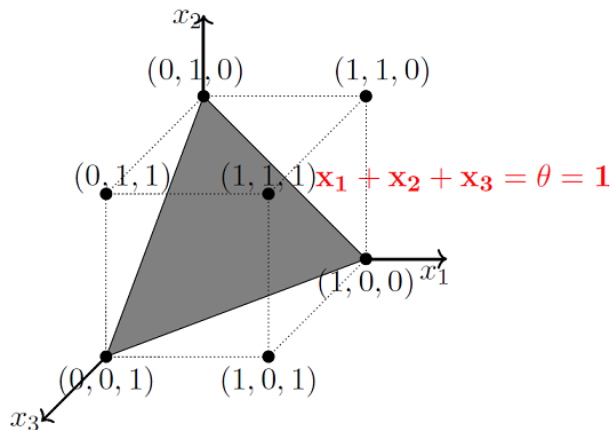
Boolean Functions

OR Function with 3 inputs



OR function

$$x_1 + x_2 + x_3 = \sum_{i=1}^3 x_i \geq 1$$

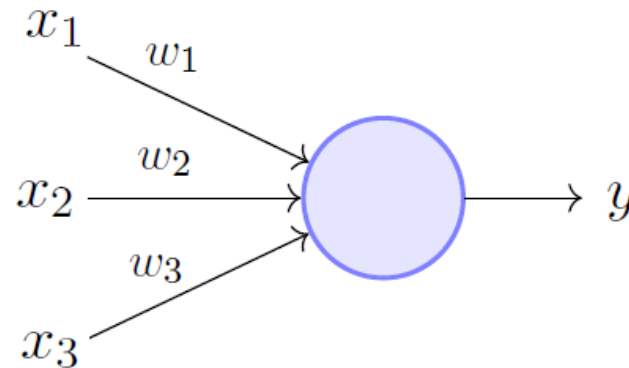


The decision boundary would be a plane!

Limitations of M-P Neuron

- ❑ Limited to Boolean inputs
- ❑ Hand-coded thresholds
- ❑ All inputs are equally important
 - Are all inputs born equal?
 - Is number of legs as important for a **human vs cat** classifier as number of ears?
- ❑ What about functions that are not linearly separable? E.g., the XOR function?
- ❑ In 1958, Fran Rosenblatt, an American Psychologist, proposed the perceptron model
 - Added **weights and thresholds that could be learned.**
 - Allowed **real-numbered inputs.**

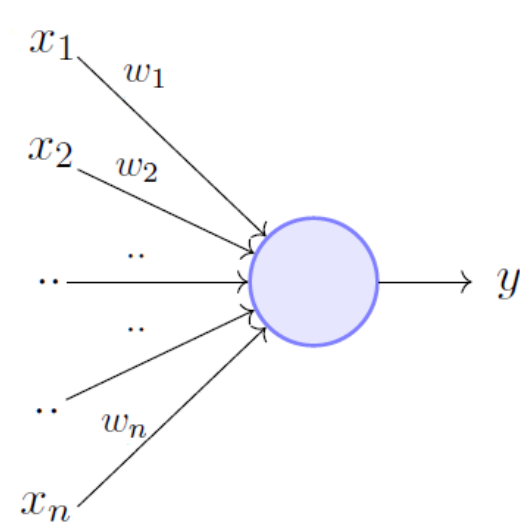
The Perceptron



Perceptron Model (Minsky-Papert in 1969)

- ❑ Numerical weights associated with inputs
- ❑ No longer limited to Boolean inputs
- ❑ A learning mechanism to train the weights and threshold.

The Perceptron



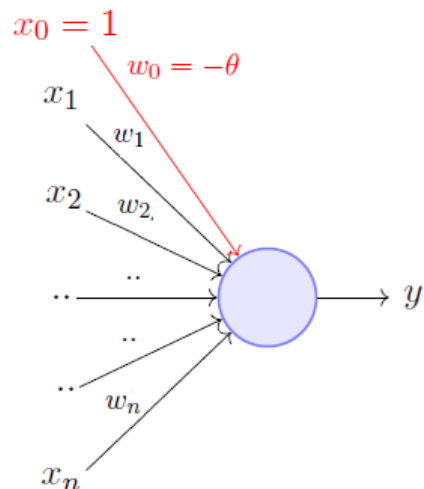
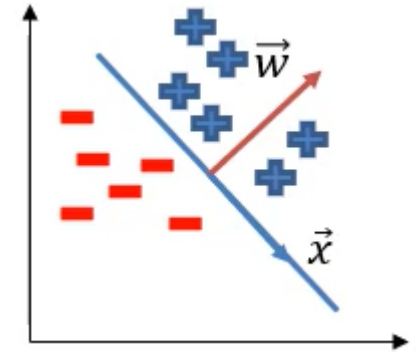
$$y = 1 \quad \text{if } \sum_{i=1}^n w_i * x_i \geq \theta$$

$$= 0 \quad \text{if } \sum_{i=1}^n w_i * x_i < \theta$$

Rewriting the above,

$$y = 1 \quad \text{if } \sum_{i=1}^n w_i * x_i - \theta \geq 0$$

$$= 0 \quad \text{if } \sum_{i=1}^n w_i * x_i - \theta < 0$$



A more accepted convention,

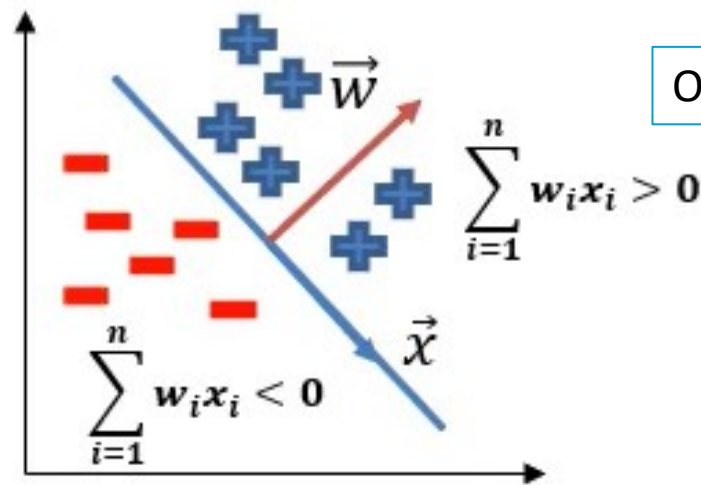
$$y = 1 \quad \text{if } \sum_{i=0}^n w_i * x_i \geq 0$$

$$= 0 \quad \text{if } \sum_{i=0}^n w_i * x_i < 0$$

where, $x_0 = 1$ and $w_0 = -\theta$

The Perceptron

- If we set $\theta = 0$, then the decision is simply: $h(x_i) = \text{sgn}(w^T x_i + \theta)$
- After absorbing θ , this becomes: $h(x_i) = \text{sgn}(w^T x_i)$



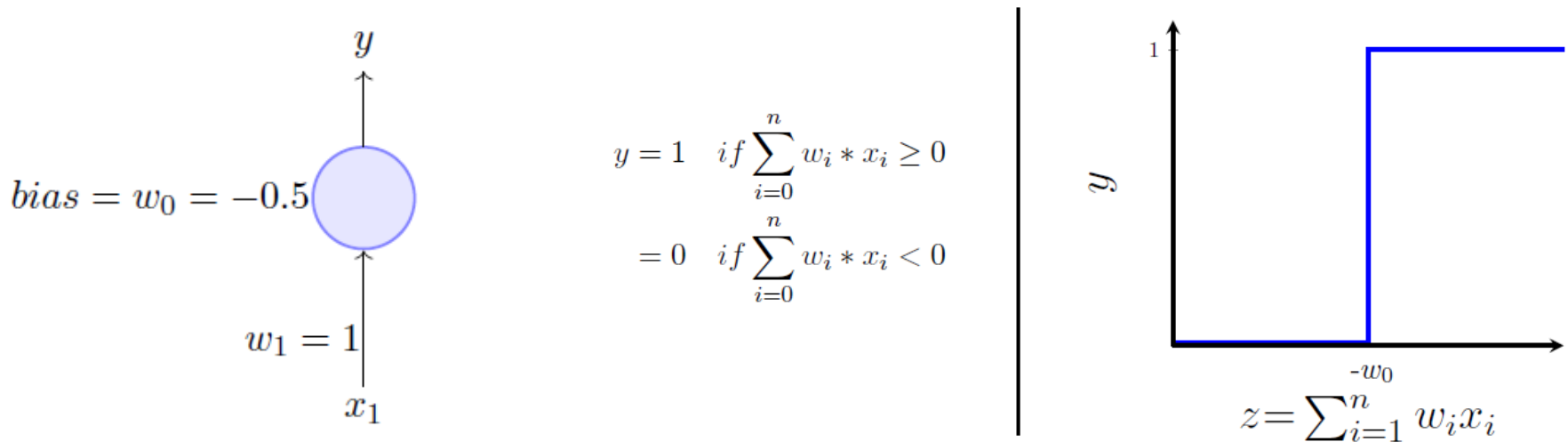
Output is either +ve or -ve

- This also simplifies defining correct/incorrect classification:

$$y_i(w^T x_i) > 0 \Leftrightarrow x_i \text{ is classified correctly}$$
$$y_i > 0 \text{ and } (w^T x_i) > 0 \text{ OR } y_i < 0 \text{ and } (w^T x_i) < 0$$

Connecting the dots

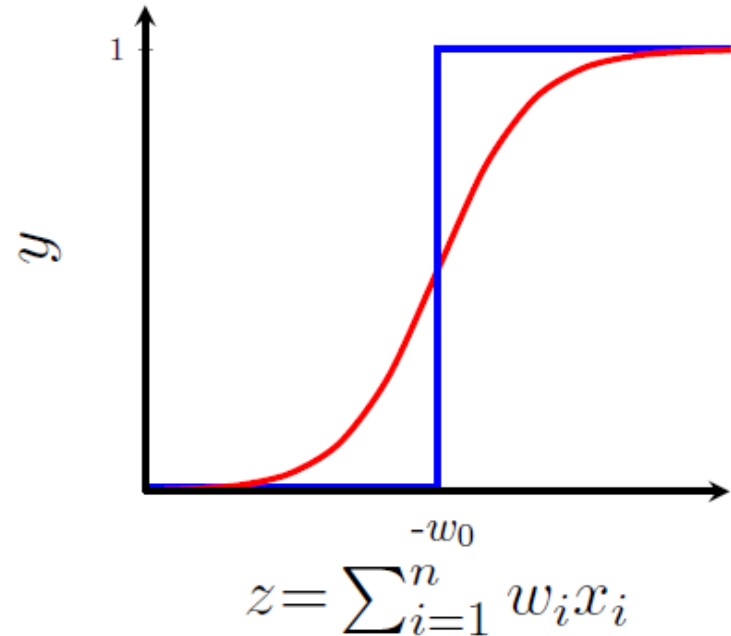
- ❑ The perceptron employs very harsh thresholds!
- ❑ E.g., if the threshold is 0.5, input = 0.49 to the thresholding function would yield a negative and input=0.51 would yield a positive output



Connecting the dots – Using other activation functions

- We can use a smoother function like sigmoid!

$$y = \frac{1}{1 + e^{-(w_0 + \sum_{i=1}^n w_i x_i)}}$$



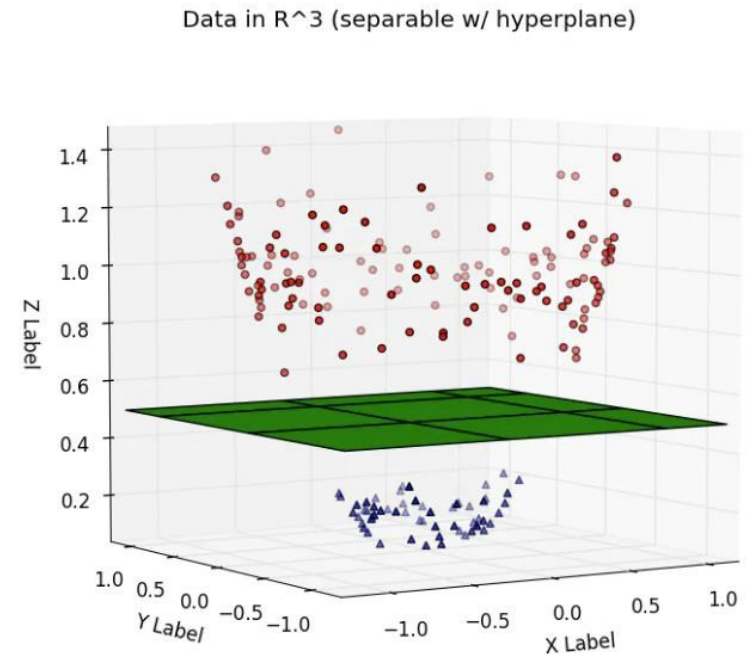
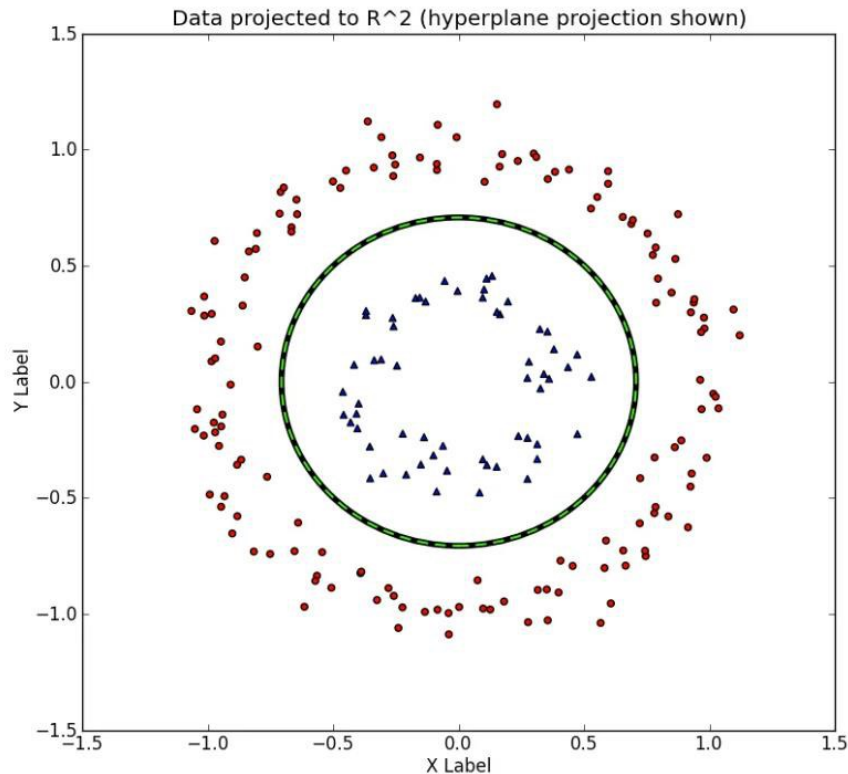
- The output is no longer binary but a real value between 0 and 1, which can be interpreted as a probability
- So instead of yes/no decision, we get the probability of yes.
- The output is **smooth, continuous, and differentiable**.

The Perceptron

- ❑ A perceptron separates the input space into two halves, positive and negative.
- ❑ All the inputs that produce **true** lie on one side (positive half) and all the inputs that produce **false** lie on the other side (negative half space)
- ❑ **A single Perceptron can only be used to implement linearly separable functions**
 - Just like M-P Neuron
- ❑ **How Perceptron is different than M-P Neuron?**
 - The inputs can be assigned different importance
 - The weights and the thresholds can be learned.
 - The inputs can be real values

How to make linearly separable decision boundary? What should be changed in Perceptron?

One way: Adding Dimensions to Achieve Linear Separability



Second Way: Use Hidden Layers

Book Reading

- ☐ Jurafsky – Chapter 7
- ☐ Tom Mitchel – Chapter 4