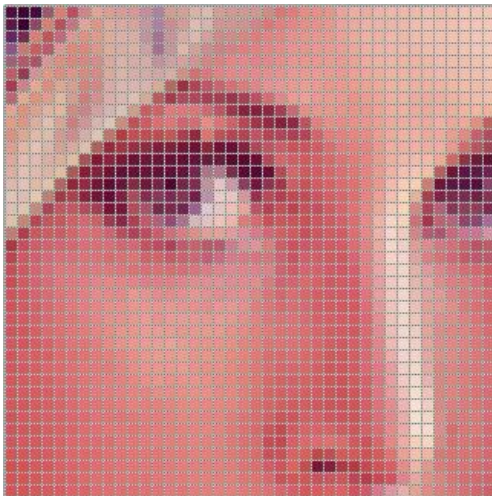


# TDS3651

## Visual Information Processing



### LECTURE 2

## Manipulating Pixels

Faculty of Computing and Informatics

Multimedia University

prepared by Lai-Kuan, Wong

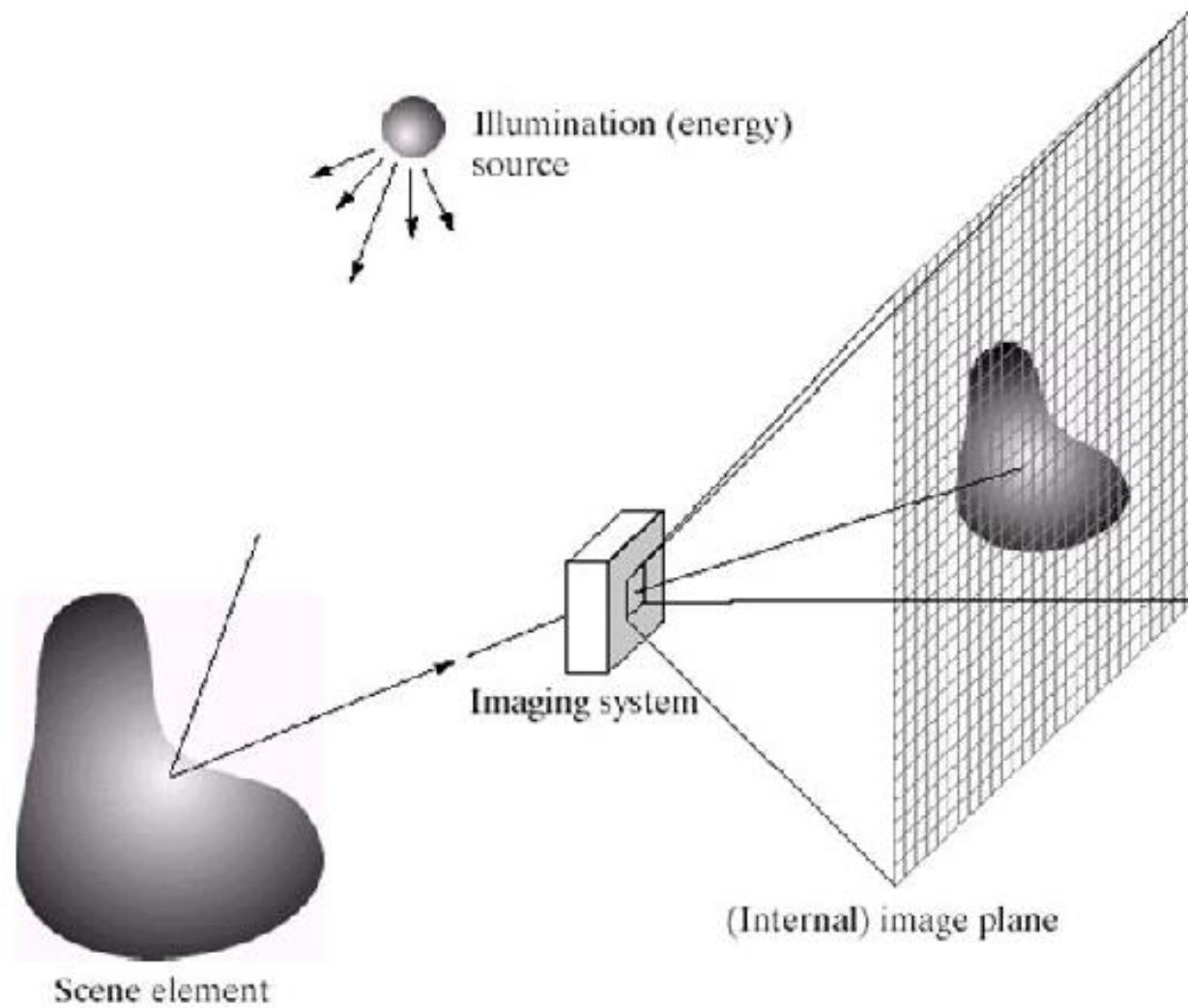
modified by Yuen Peng, Loh

# Lecture Outline

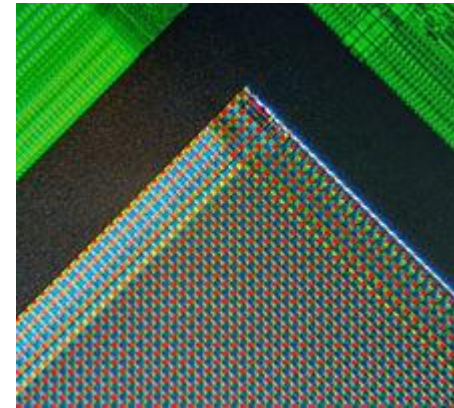
- Image Formation
- Point (Pixel)-based Processing
- Image Histograms
- Neighborhood Processing

Images and how they are  
represented

# Image formation



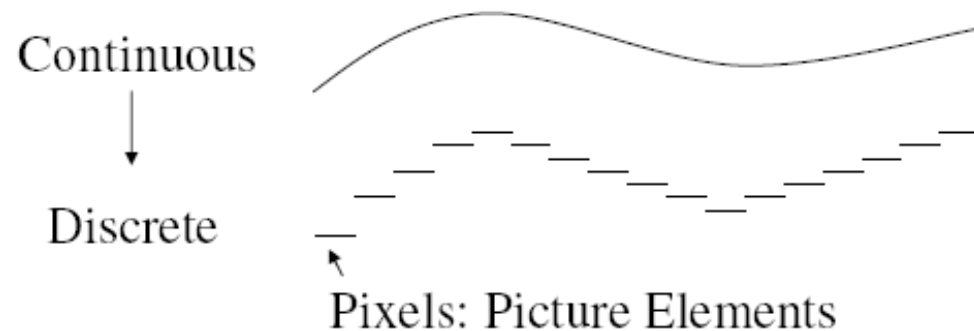
# The digital camera



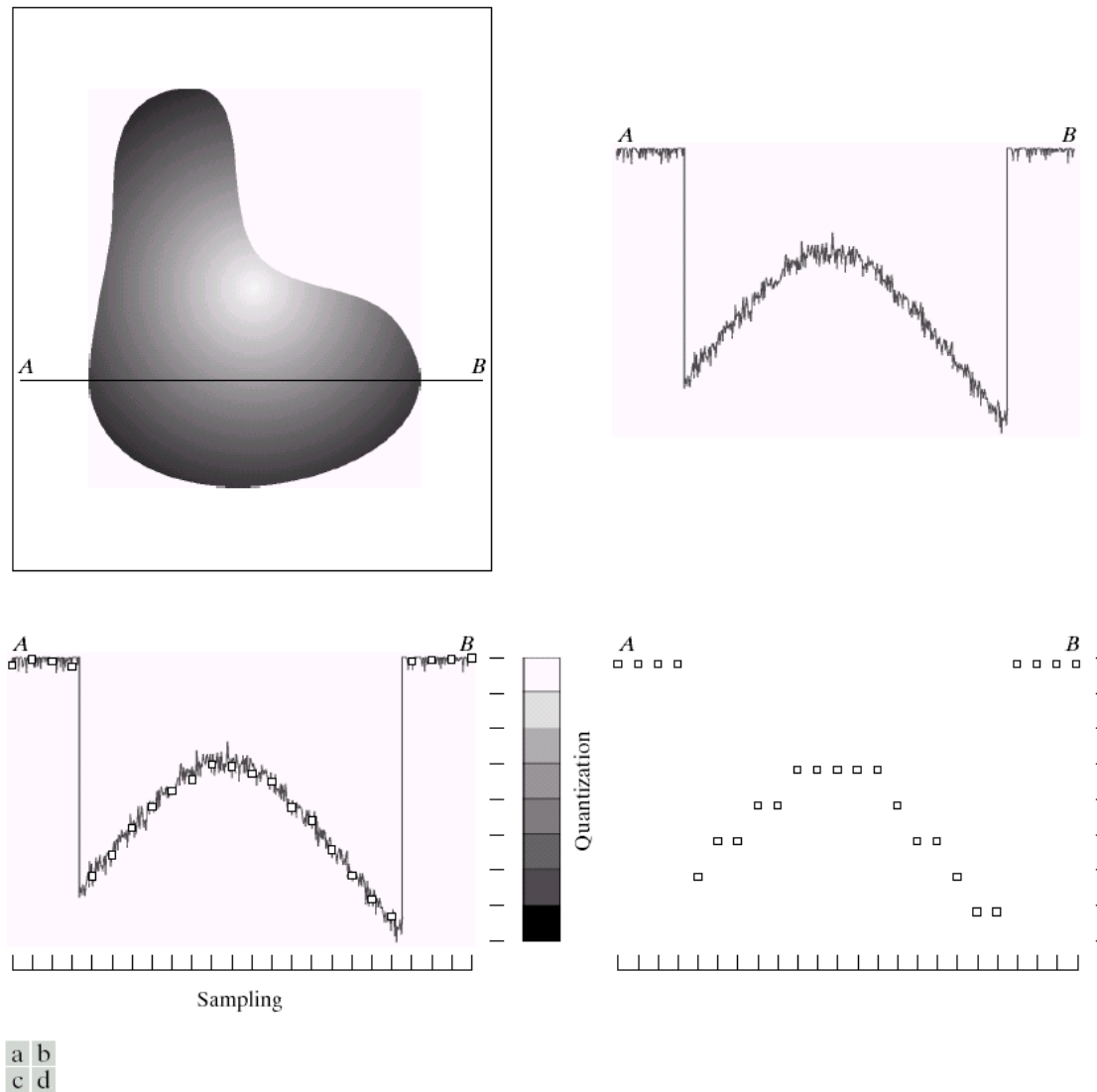
- A digital camera replaces film with a sensor array
  - Each cell in the array is a light-sensitive diode that converts photons to electrons

# Digital images

- Computers work with discrete pieces of information
- How do we digitize a continuous-value image?

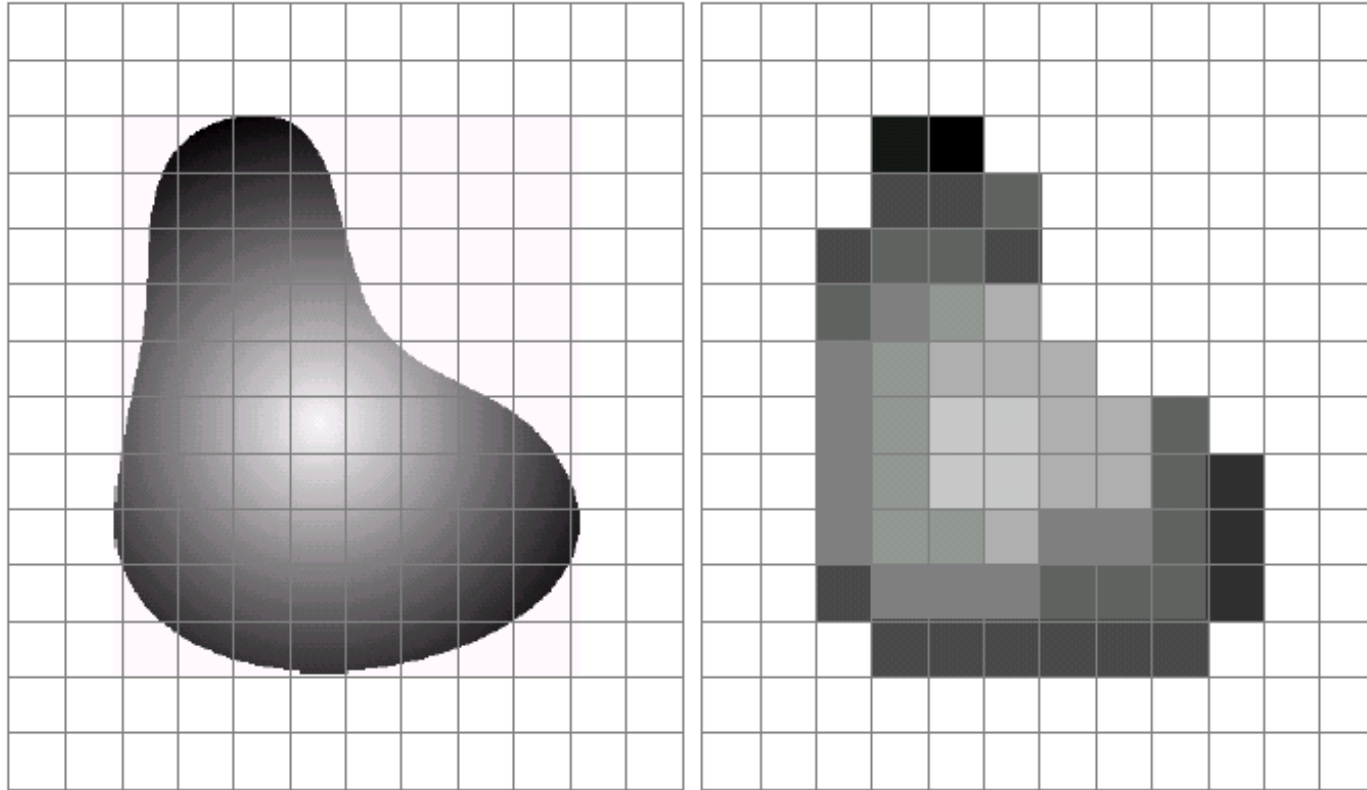


# Generating a Digital Image



**FIGURE 2.16** Generating a digital image. (a) Continuous image. (b) A scan line from *A* to *B* in the continuous image, used to illustrate the concepts of sampling and quantization. (c) Sampling and quantization. (d) Digital scan line.

# Image Sampling & Quantization



a b

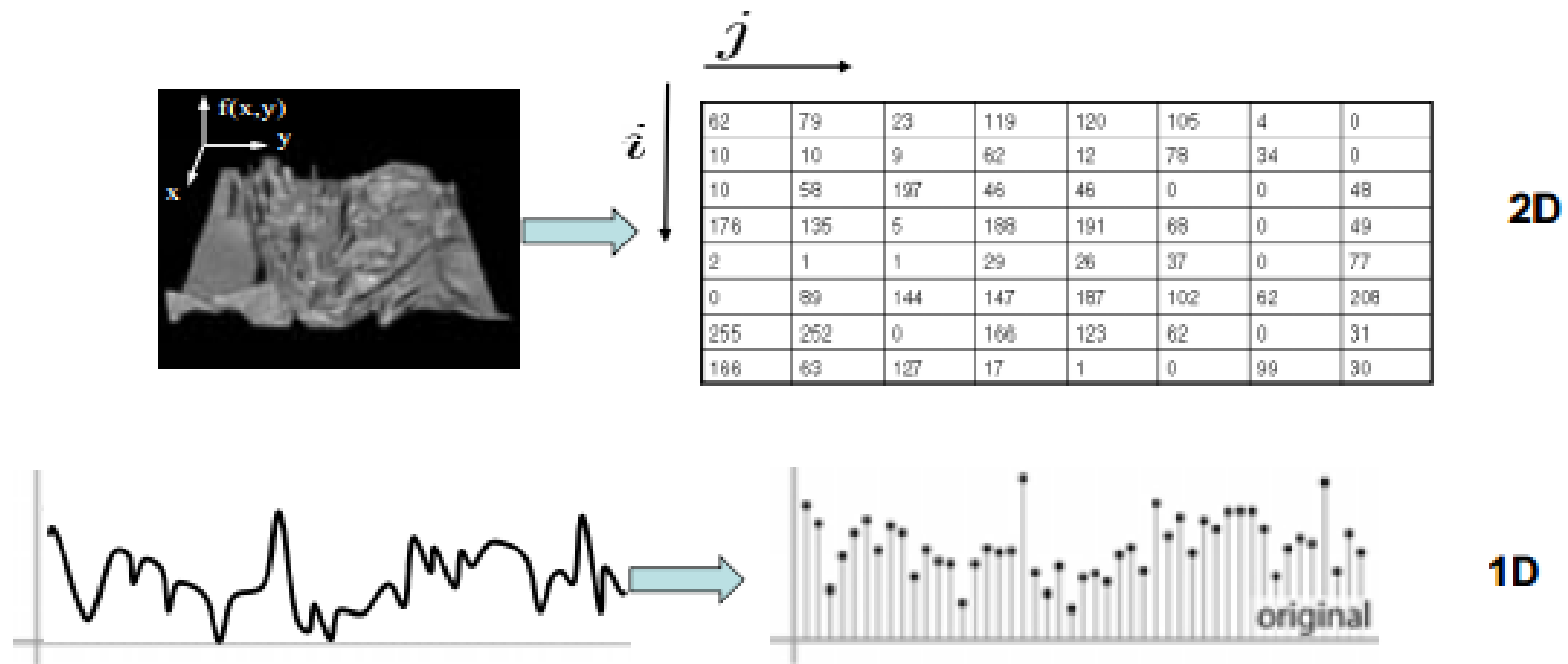
**FIGURE 2.17** (a) Continuous image projected onto a sensor array. (b) Result of image sampling and quantization.

---



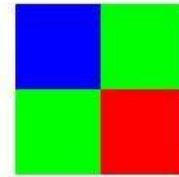
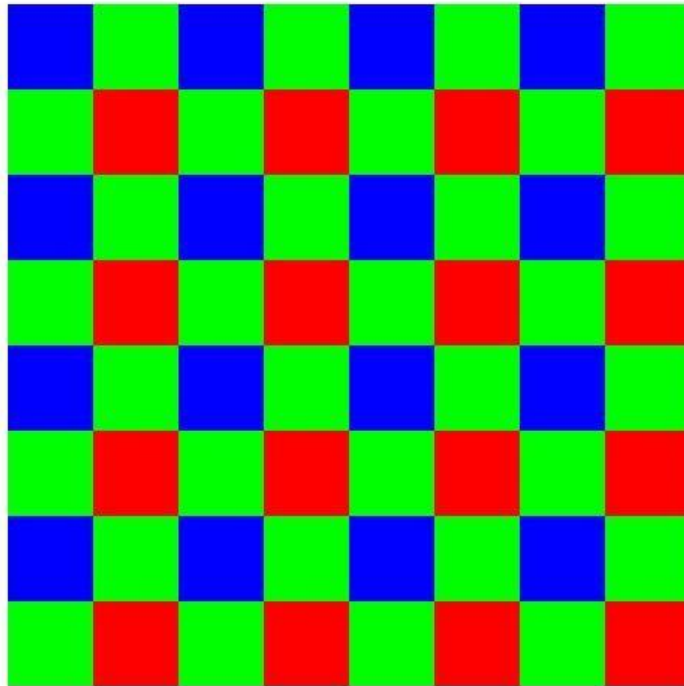
# Image Sampling & Quantization

- **Sample** the 2D space on a regular grid
- **Quantize** each sample (round to nearest integer)
- Image thus represented as a matrix of integer values



# How does the image sensor capture colours?

Bayer filter



Basic element of the filter

Bayer filter

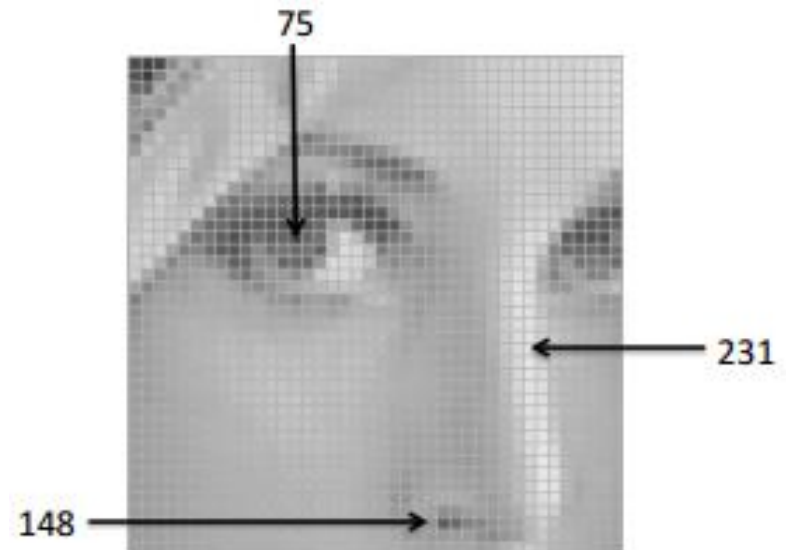
[https://en.wikipedia.org/wiki/Bayer\\_filter](https://en.wikipedia.org/wiki/Bayer_filter)

Capturing Digital Images (The Bayer Filter) – Computerphile

<https://www.youtube.com/watch?v=LWxu4rkZBLw>

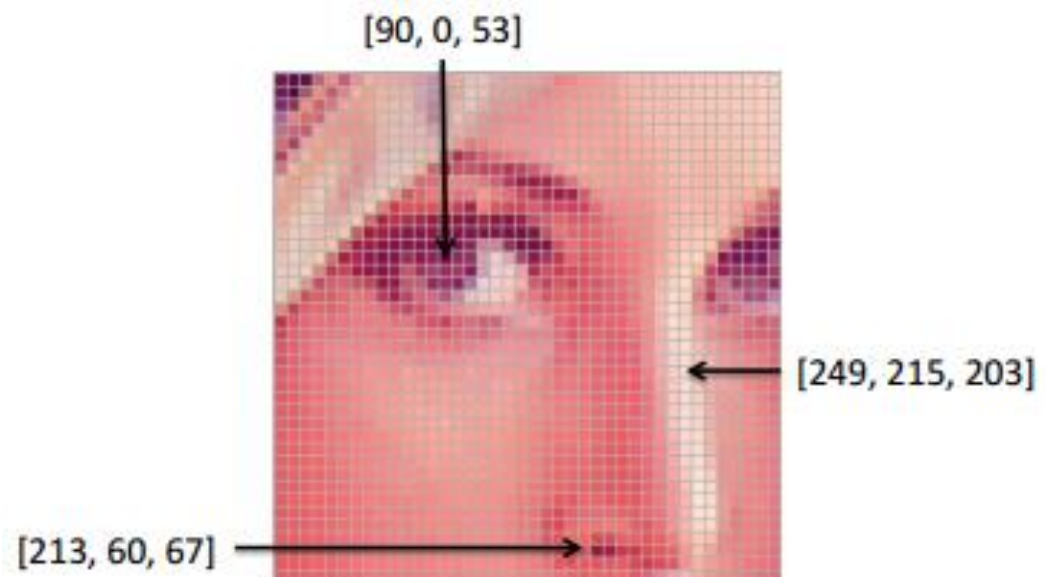
# Image as functions

- An image contains discrete number of pixels
  - A simple example
  - Pixel value:
    - “grayscale” (or “intensity”) :  $[0, 255]$



# Image as functions

- An image contains discrete number of pixels
  - A simple example
  - Pixel value:
    - “grayscale” (or “intensity”) :  $[0, 255]$
    - “color”
      - RGB:  $[R, G, B]$
      - Lab :  $[L, a, b]$
      - HSV:  $[H, S, V]$



# Digital colour images

Color images,  
RGB color  
space



R



G

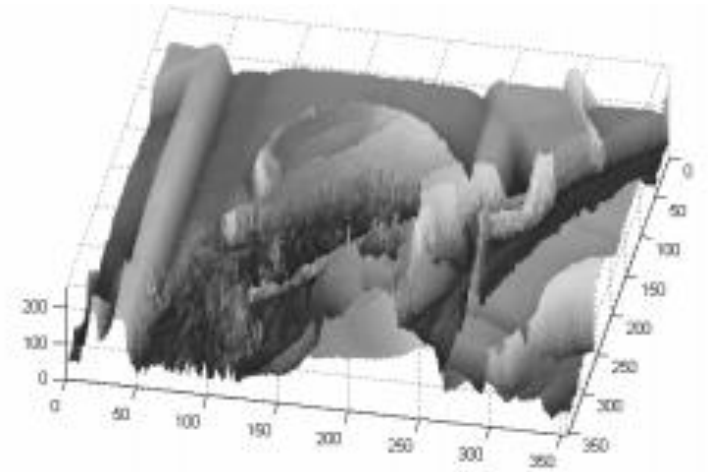


B

# Image as functions

- **An image** as a function of  $f$  from  $R^2$  to  $R^M$ 
  - $f(x, y)$  gives the **intensity** at position  $(x, y)$
  - Defined over a rectangle, with a finite range:

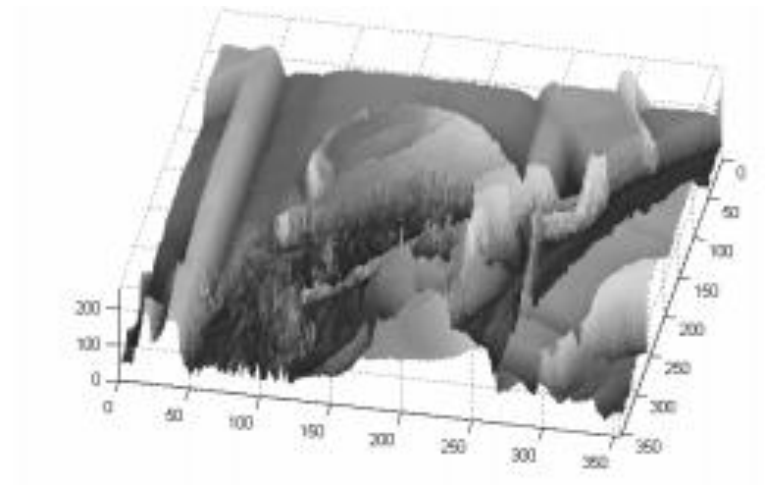
$$f: \underbrace{[a, b] \times [c, d]}_{\text{domain support}} \rightarrow \underbrace{[0, 255]}_{\text{range}}$$



# Image as functions

- **An image** as a function of  $f$  from  $R^2$  to  $R^M$ 
  - Color image ( $R^3$ )

$$f(x, y) = \begin{bmatrix} r(x, y) \\ g(x, y) \\ b(x, y) \end{bmatrix}$$



- RGB-D image?

# Image as functions

Q: RGB-D image?

A. Duration

B. Depth

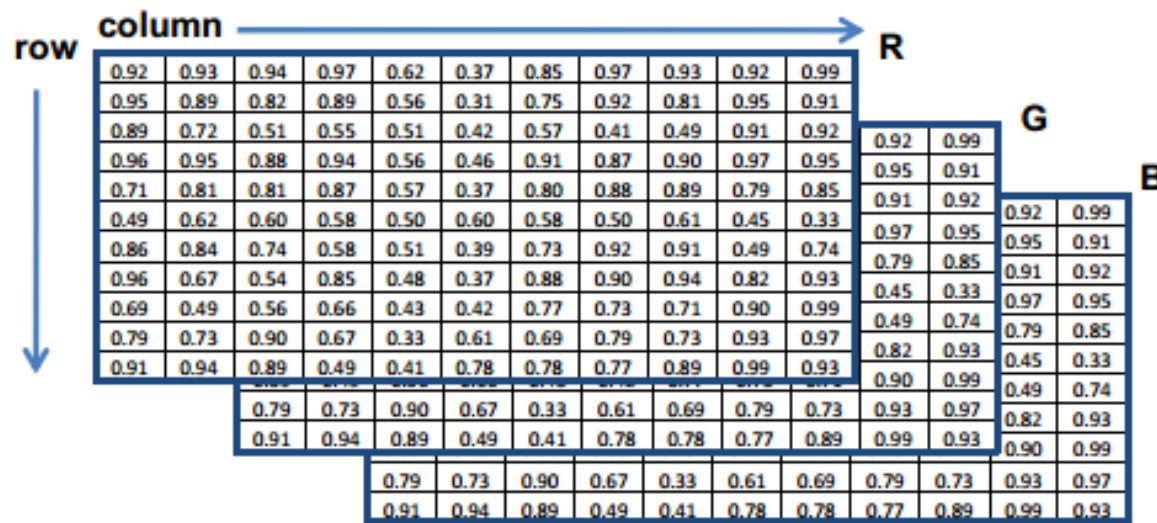
C. Direction  
know

D. Don't

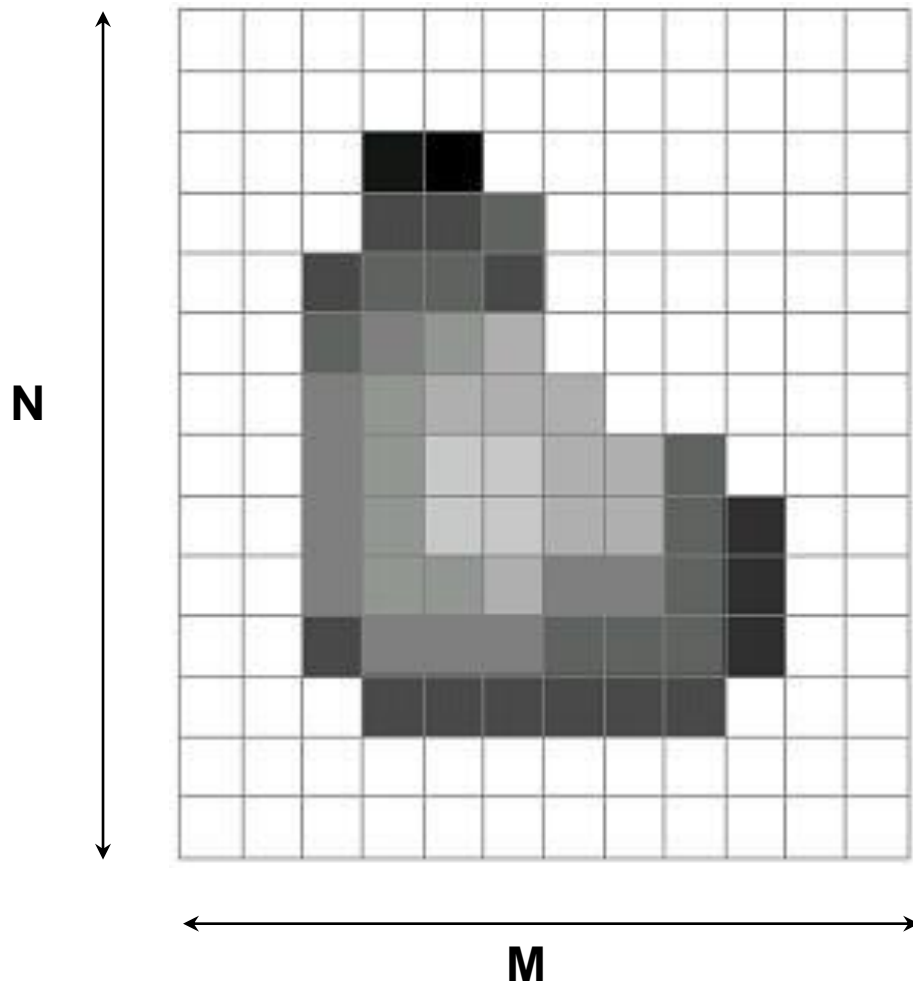


# How are images represented?

- Images represented as a 3-D array (or 'matrix')
  - **Python**: 'ndarray' container in numpy. Image values are 'uint8' type
- Example: a  $N \times M$  RGB image stored in array 'im'
  - `im[0,0,0]` – top-left pixel value in R channel
  - `im[0,0]` – pixel values at location (0,0) for all 3 channels



# Number of Bits



- $k$ -bit image
- The number of gray levels typically is an integer power of 2
- Number of bits required to store a digitized image

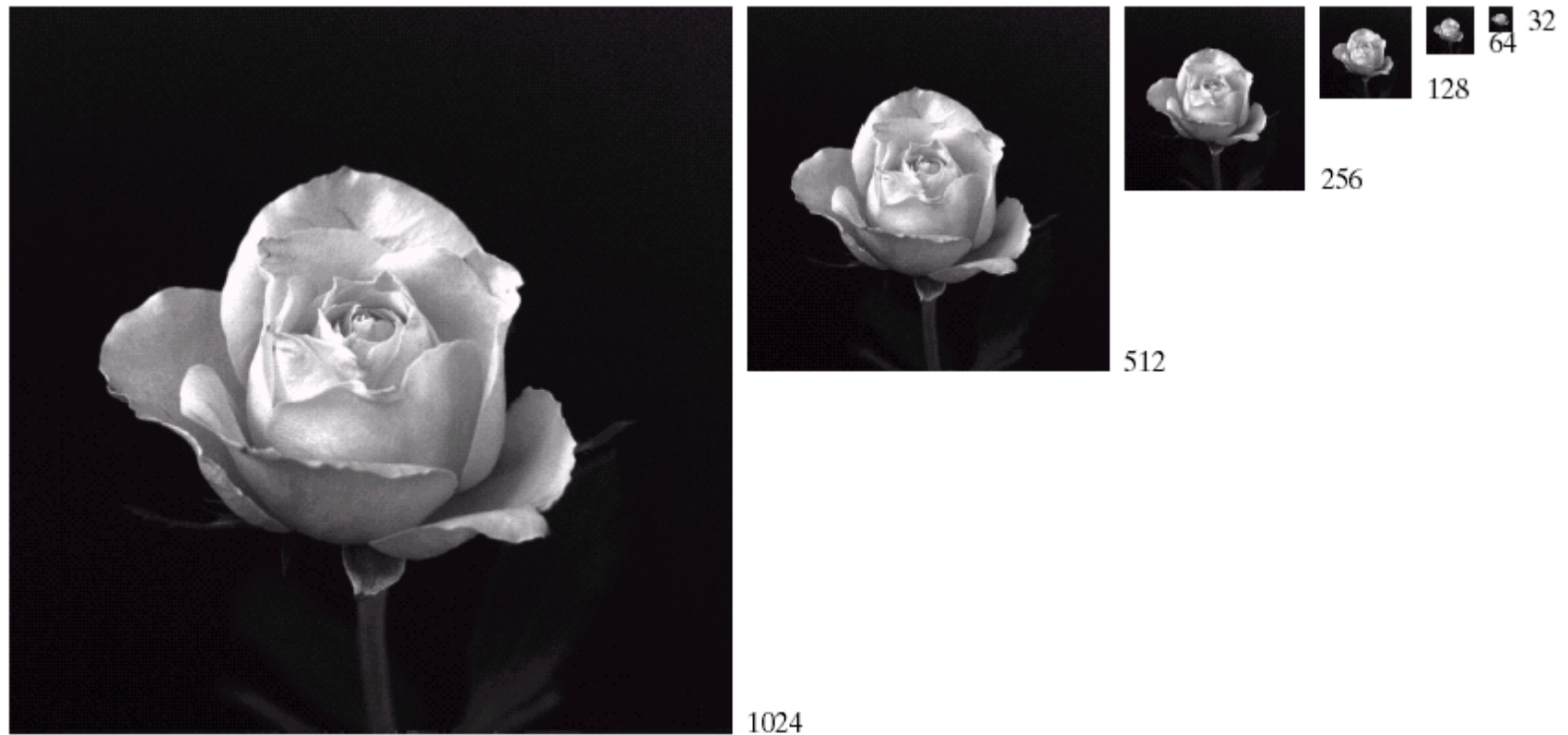
$$L = 2^k$$

$$B = M \cdot N \cdot k$$

# Resolution

- Resolution
  - How much details you can see in the image
  - Depends on **sampling** and **gray levels**
  - The **higher** the resolution of the image
    - The **better** the approximation of the digitized image from the original
    - The **larger** the size of the image

# Subsampling

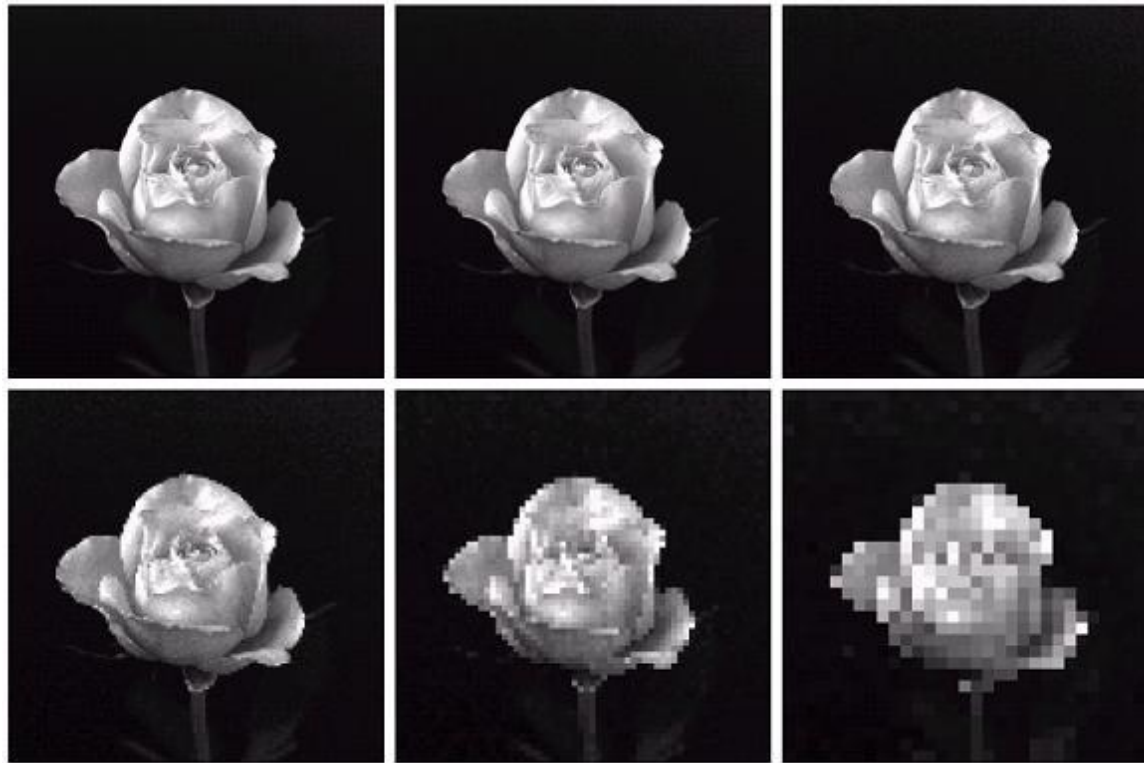


**FIGURE 2.19** A  $1024 \times 1024$ , 8-bit image subsampled down to size  $32 \times 32$  pixels. The number of allowable gray levels was kept at 256.

# Subsampling Problem?

- Q: What are some problems that may occur if your images are sampled (or subsampled) to a lower resolution?
  - A. Blurred
  - B. Pixelated
  - C. Lose color
  - D. Distorted

# Checkerboard Effect



a	b	c
d	e	f

(a) 1024x1024

(b) 512x512

(c) 256x256

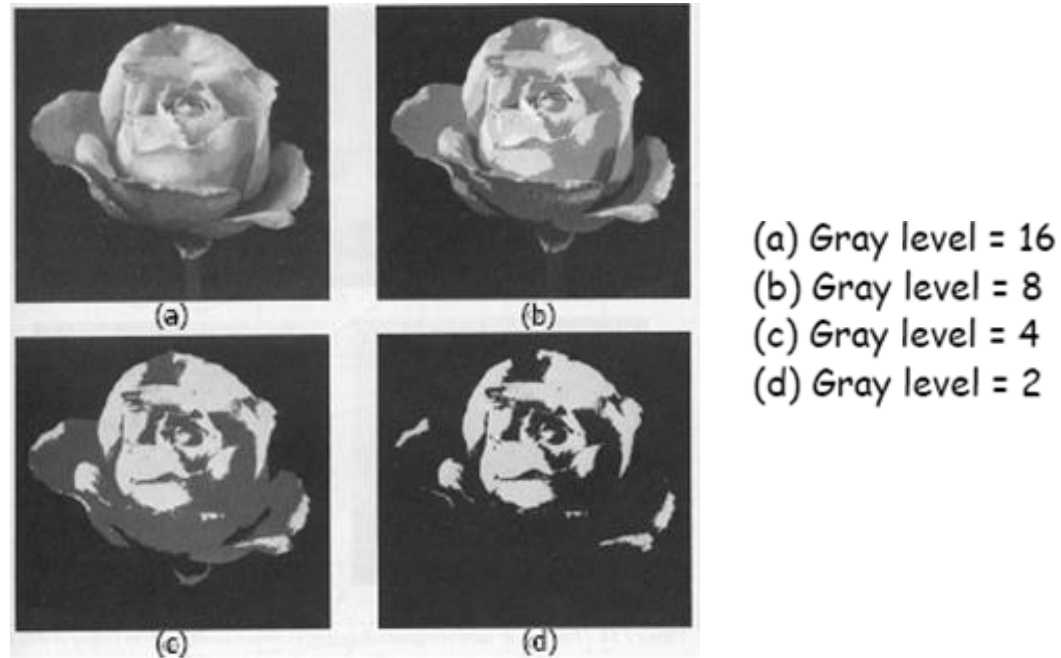
(d) 128x128

(e) 64x64

(f) 32x32

- If the resolution is decreased too much, the checkerboard effect can occur.

# False Contouring



- If gray levels are insufficient, smooth areas will be affected
- False contouring occurs at smooth areas which has fine grayscale values

# Question

- You have a 8-bit RGB image of resolution 1024x768 pixels. What is the size of the image file? (Give your answer in Mb)

Answer: ?

- A.  $(1024 \times 768) / (1024 \times 1024)$   
= 0.75 MB
- B.  $(1024 \times 768 \times 3) / (1024 \times 1024)$   
= 2.25 MB
- C.  $(1024 \times 768 \times 8) / (1024 \times 1024)$   
= 6.00 Mb
- D.  $(1024 \times 768 \times 3 \times 8) / (1024 \times 1024)$   
= 18.00 Mb

1Byte = 8bits

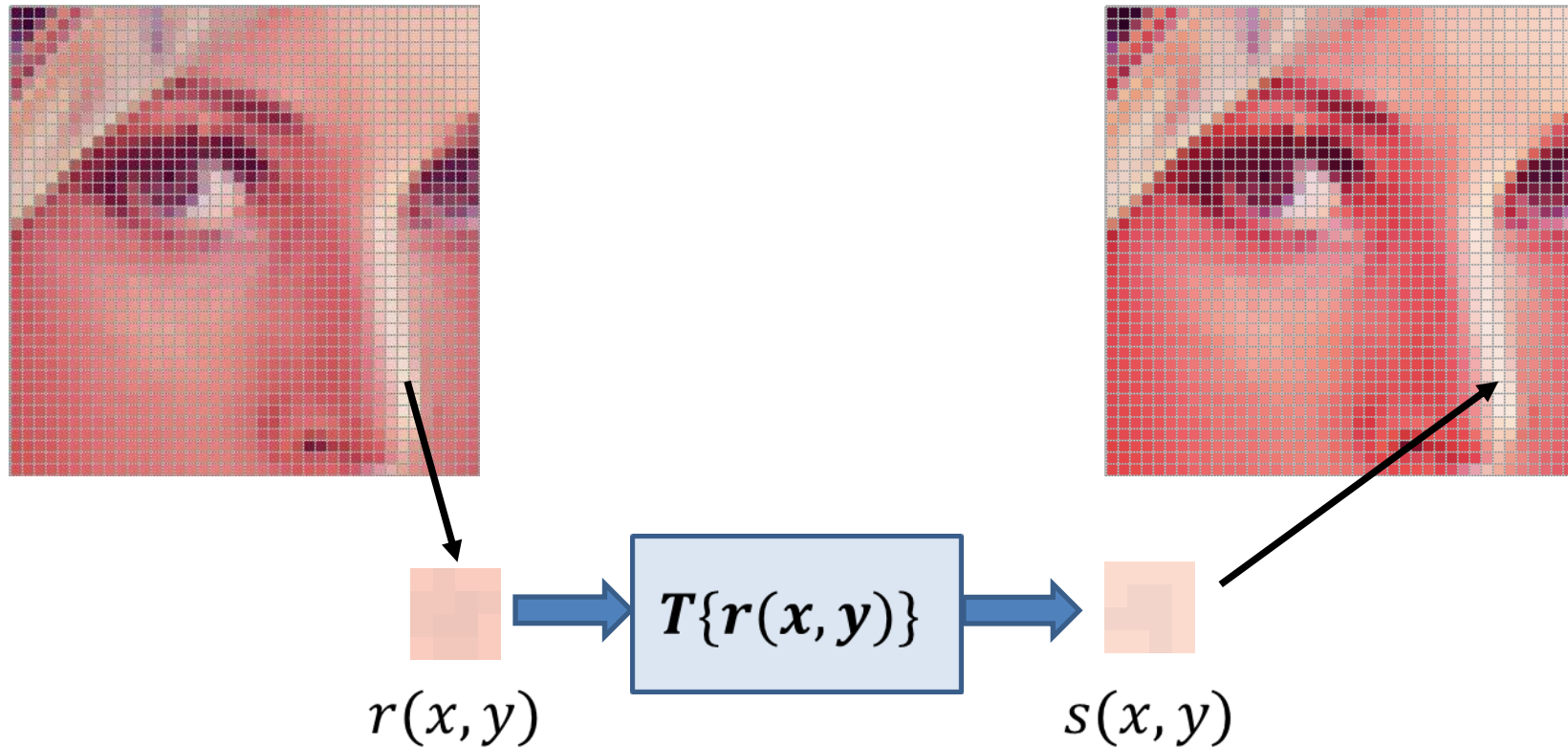
1kB = 1024B

1MB = 1024kB



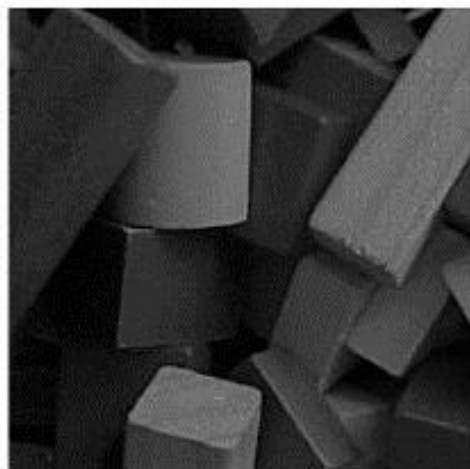
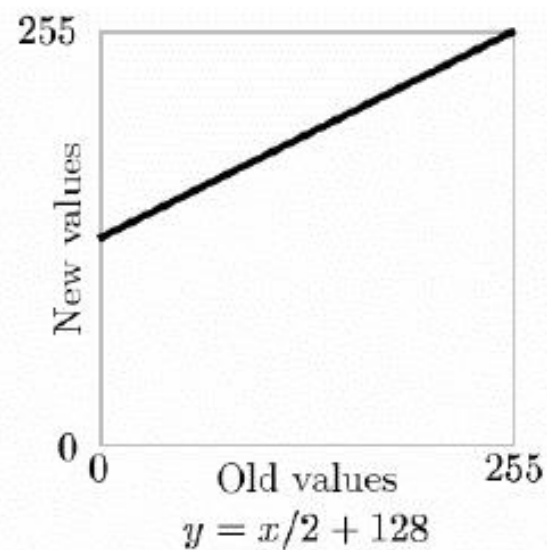
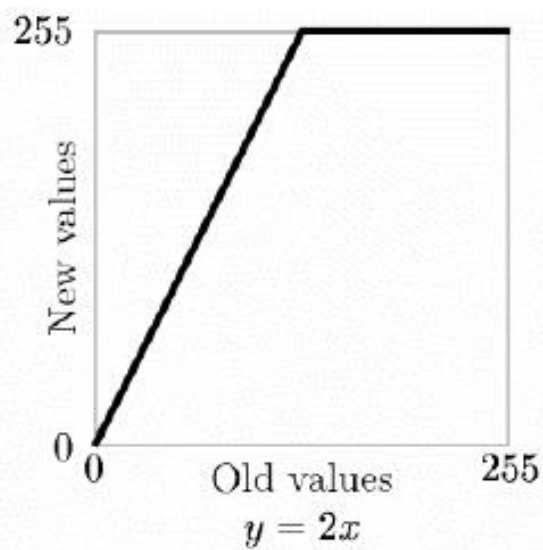
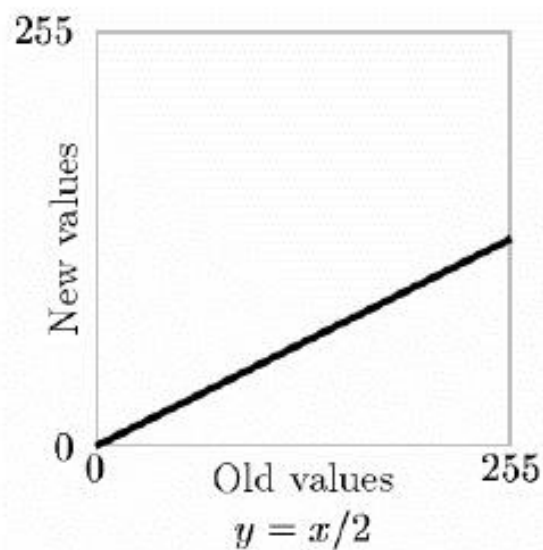
# Pixel (Point)-based Processing

# Pixel (or Point)-based Processing



With the transformation function  $T$ , do that for all pixels in the image!

# Arithmetic Operations



b3:  $y = x/2$



b4:  $y = 2x$



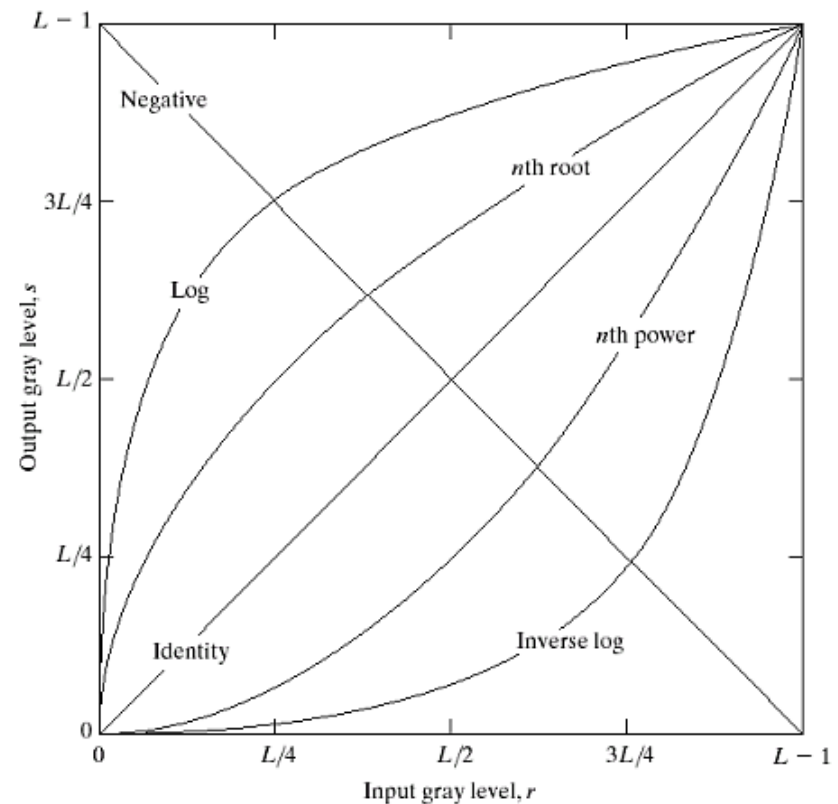
b5:  $y = x/2 + 128$

# What other operations?

- Whole family of possible functions that you can apply...

- **Question:** What can non-linear functions do?

E.g. irregular increase / decrease of pixel intensities (allows enhancement)



# Linear Stretching

- Enhance the dynamic range by linear stretching the original gray levels to a new target range
- Example
  - Original range [100, 150]
  - Target range: [0, 255]
  - What's the general transformation function?

A  $s = \frac{(r - r_2)}{(r_1 - r_2)} * (S_2 - S_1) + S_1$

.

B  $s = \frac{(r - r_1)}{(r_2 - r_1)} * (S_2 - S_1) + S_1$

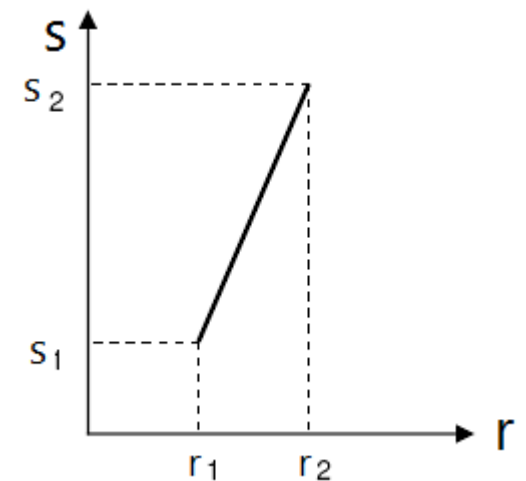
.

C  $s = \frac{(r - r_2)}{(r_1 - r_2)} * (S_1 - S_2) + S_1$

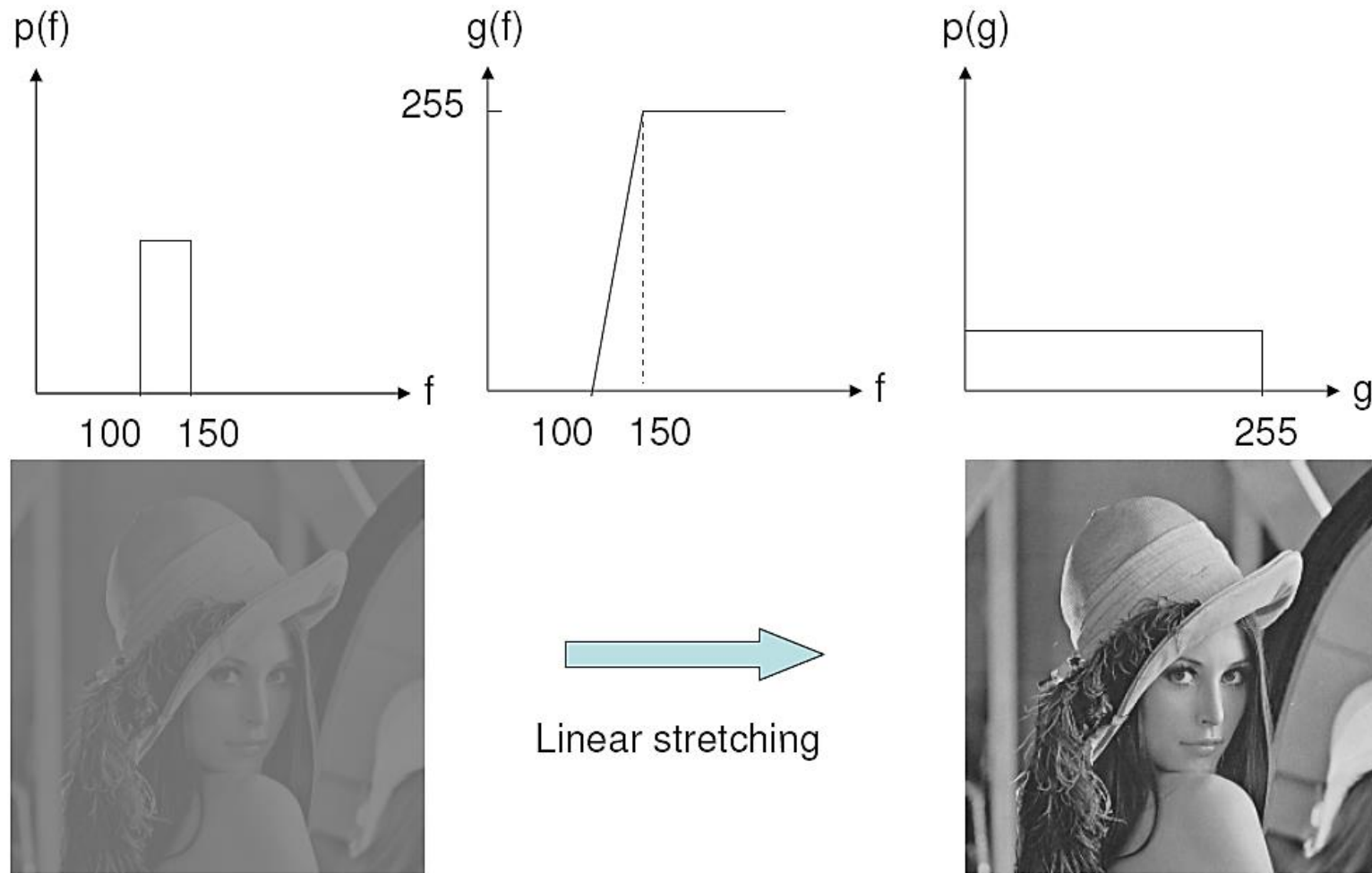
.

D  $s = \frac{(r - r_1)}{(r_2 - r_1)} * (S_1 - S_2) + S_1$

.

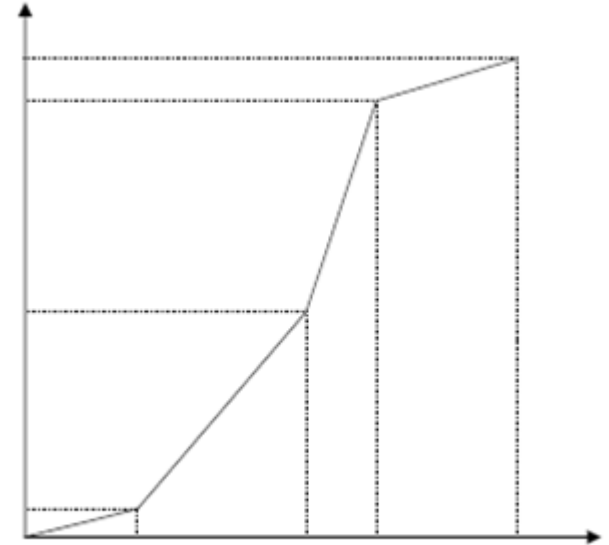


# Linear Stretching

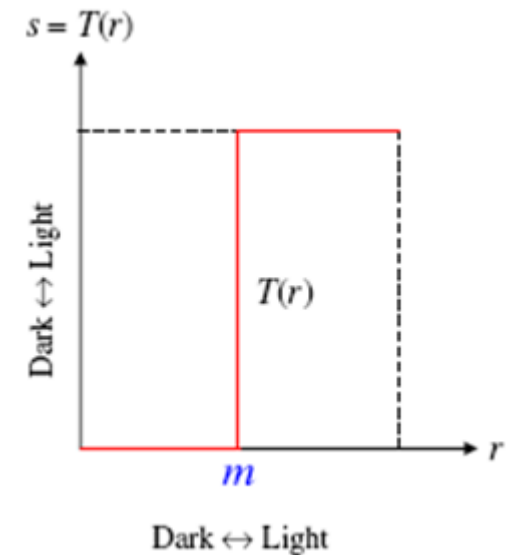


# Piecewise Linear Stretching

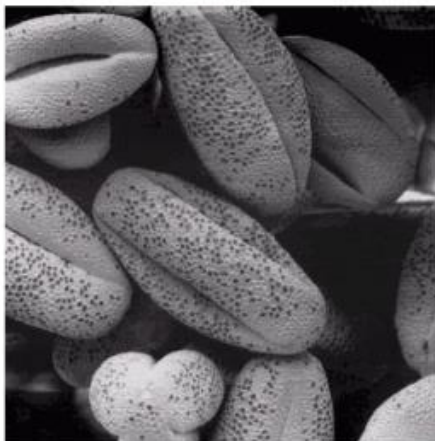
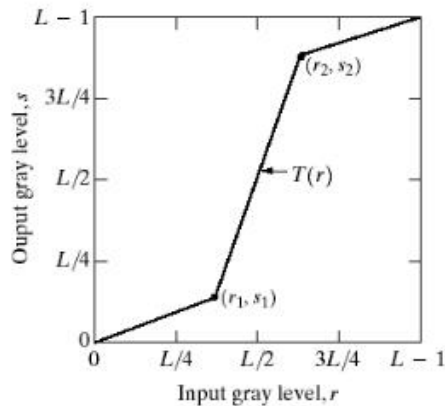
- Can have as many segments we want...



- **Thresholding**: Map to only two possible values, producing a **binary image**



# Application: Contrast Stretching



- Problem: Low contrast image, result of poor illumination, lack of dynamic range
- **Solution:** Linear contrast stretching using the given transformation function (*bottom left*)
- Result after thresholding (*bottom right*)



# We can use more than an image...

- **Image addition** – Pixel-wise addition of values from two images
  - Use to create double-exposures or composite images



$$g(x, y) = f_1(x, y) + f_2(x, y)$$

- Or do a weighted blend:

$$g(x, y) = \alpha_1 f_1(x, y) + \alpha_2 f_2(x, y)$$

# We can use more than an image...

- **Image subtraction** – Pixel-wise subtraction of one image from another image
  - Use to find changes between two images



$$g(x, y) = f_1(x, y) - f_2(x, y)$$

- Absolute difference works better (Why?)

# Histograms

# Image Histogram

- **Histogram**: Diagram that shows **distribution of data**
- Histogram of a digital image with gray levels in the range  $[0, L - 1]$  is a discrete function with  $k$  bins

$$h(r_k) = n_k$$

where

- $r_k$ : the  $k$ -th gray level
- $n_k$ : the number of pixels in the image having gray level  $r_k$
- $h(r_k)$ : histogram of a digital image with gray levels  $r_k$

# Normalized Histogram

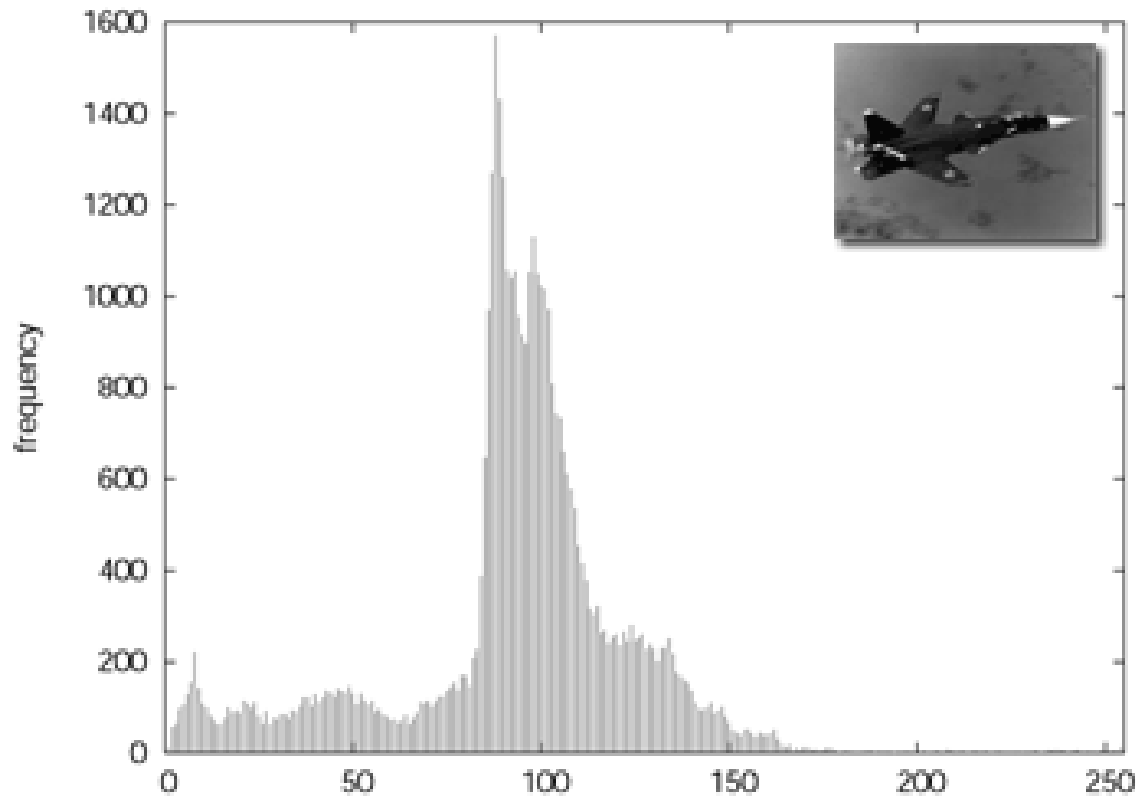
- Divide each bin count  $n_k$  of the histogram by the total number of pixels in the image,  $n$

$$p(r_k) = n_k/n$$

for  $k = 0, 1, \dots, L-1$

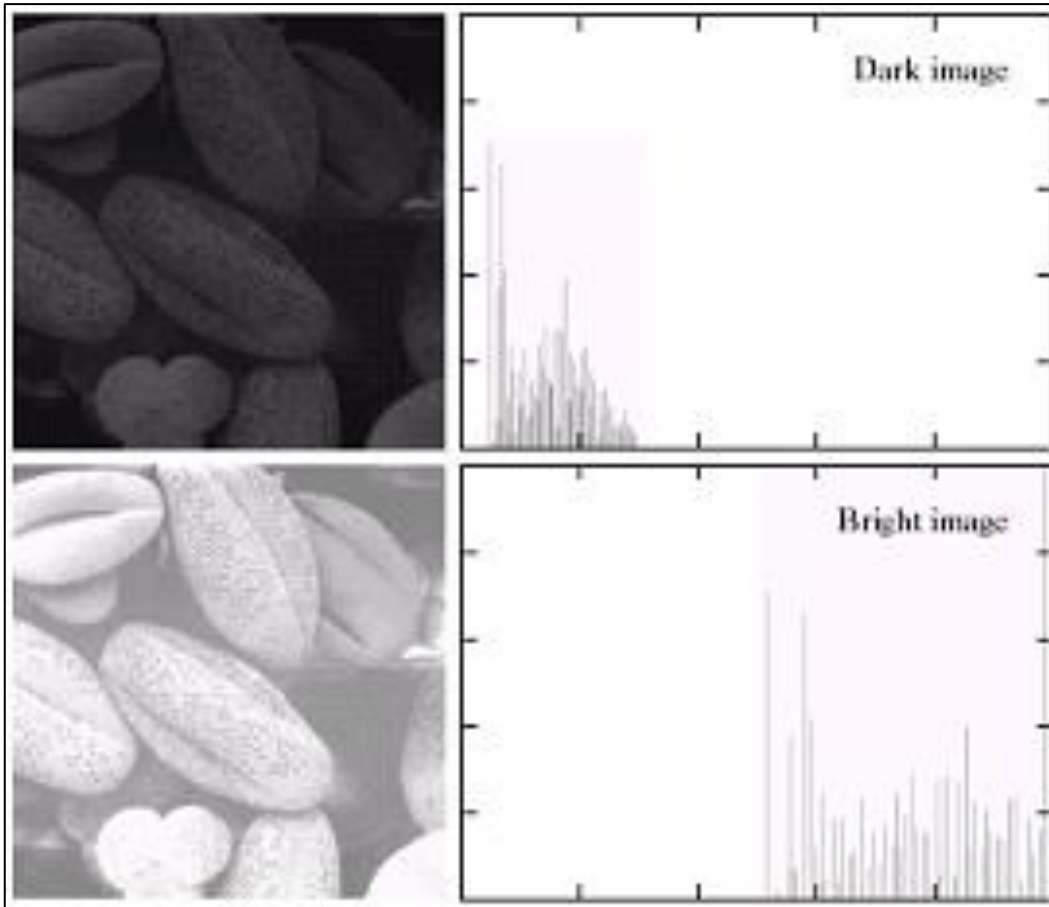
- $p(r_k)$  : probability of occurrence of gray level  $r_k$
- The **sum** of all components of a normalized histogram is **equal to 1**

# Image Histogram



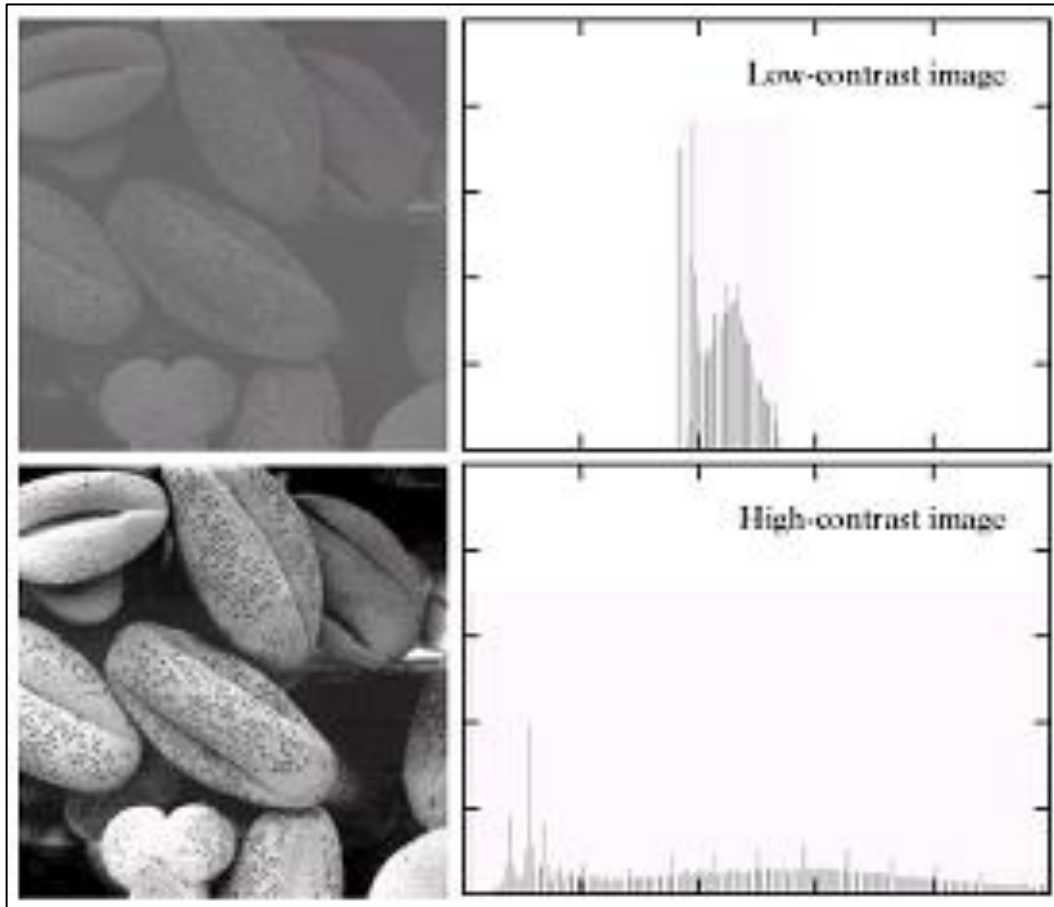
- What can the histogram of an image tell us?

# Histogram & Image Contrast



- **Dark Image**
  - Components of histogram are concentrated on the low side of the gray scale
- **Bright Image**
  - Components of histogram are concentrated on the high side of the gray scale

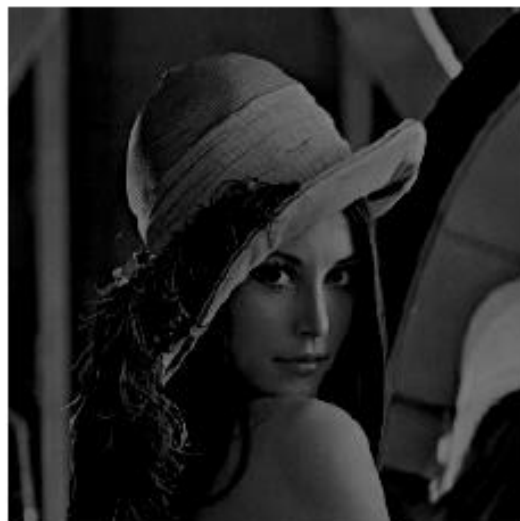
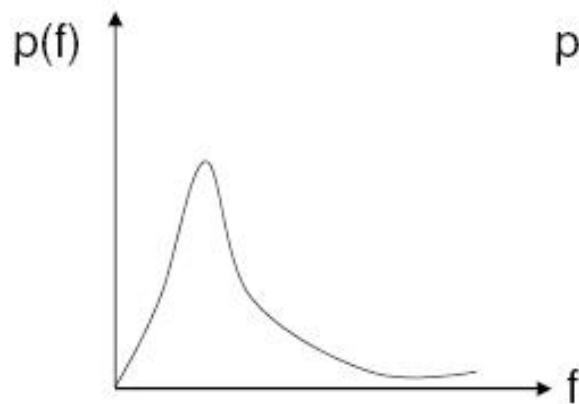
# Histogram & Image Contrast



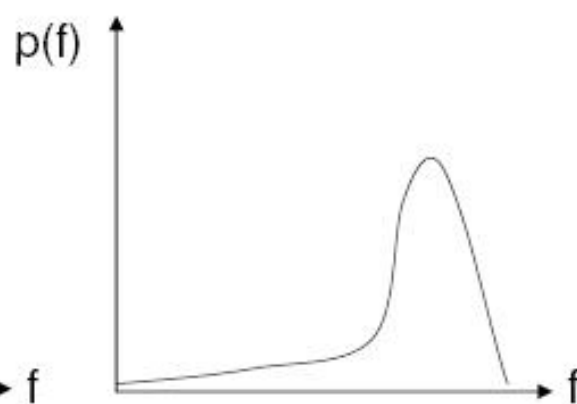
- **Low-contrast Image**
  - Histogram is narrow and centered towards the middle of the gray scale
- **High-contrast Image**
  - Histogram covers a broad range of the gray scale and the distribution of pixels is not too far from uniform, with very few vertical lines being much higher than others



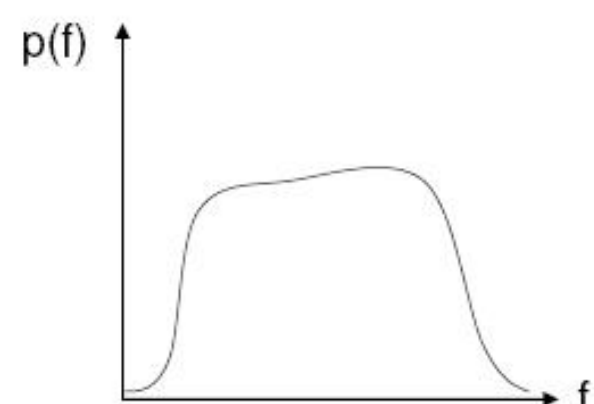
# Histogram & Image Contrast



(a) Too dark



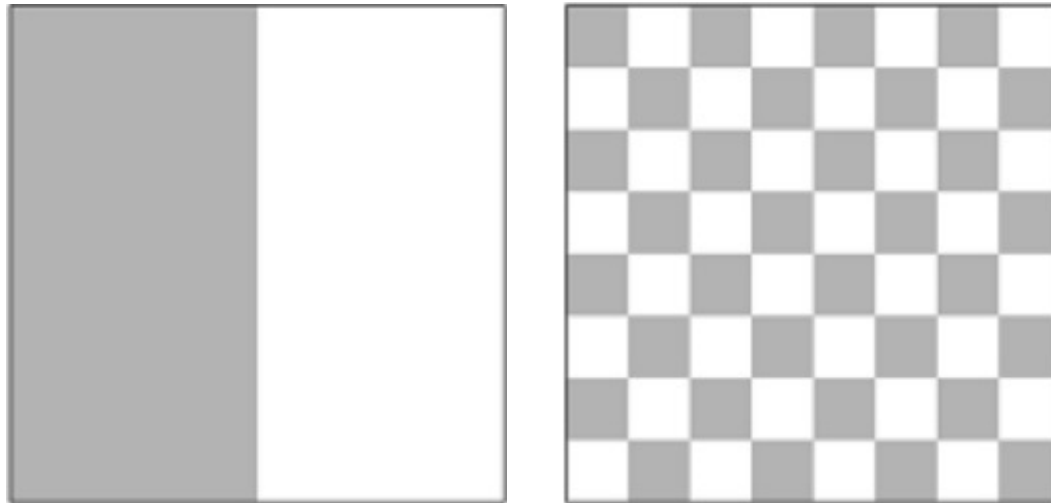
(b) Too bright



(c) Well balanced

# Different images, same histogram!

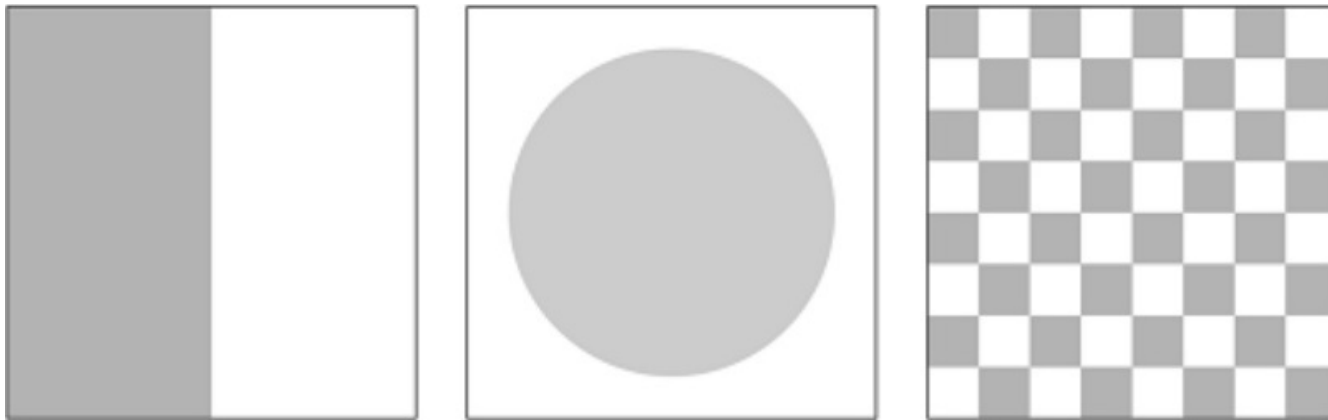
- Visualize the histogram for the following two images of size 64x64.



- Do you think they have the same histogram? Why?

# Different images, same histogram!

- The following images have the same histogram:



- Histogram reflects the **pixel intensity distribution**, not the spatial distribution!
- Can we reconstruct an image from a histogram?

# Image histogram!

- What is the pattern of the histogram for the images below?

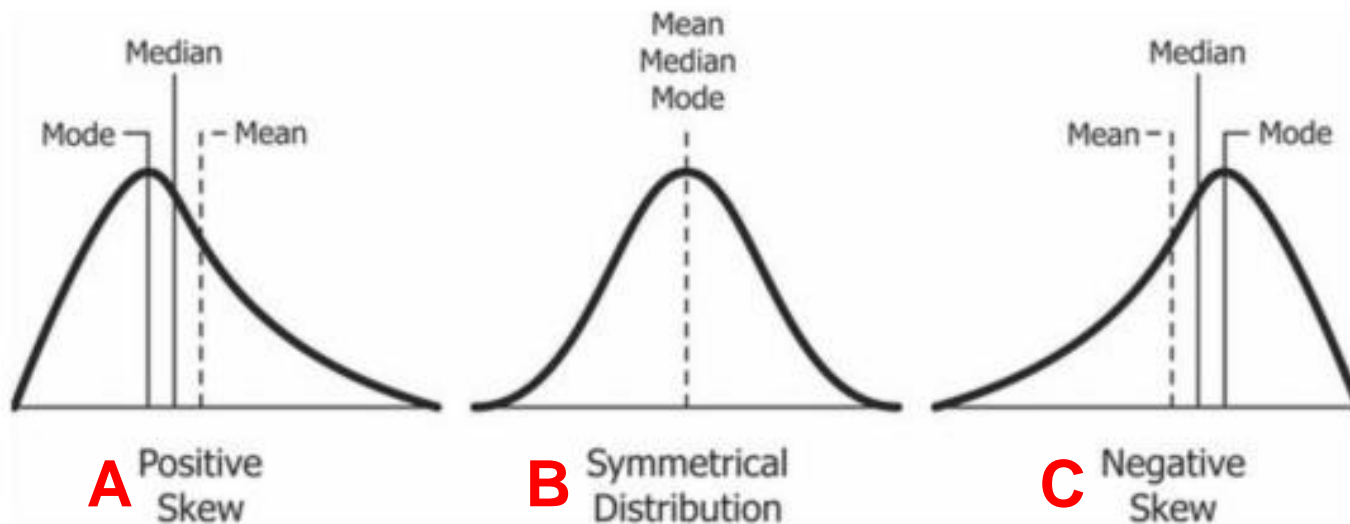
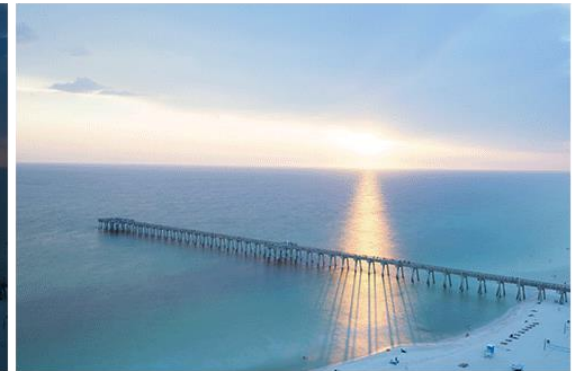
Correct Exposure



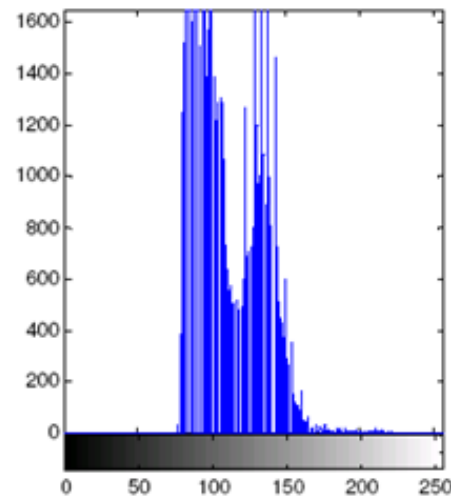
Under Exposure



Over Exposure



# Problem with Contrast

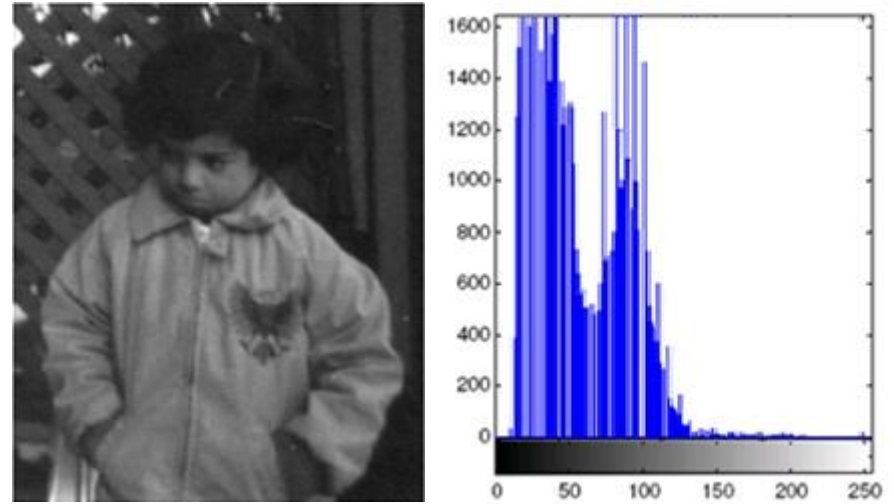
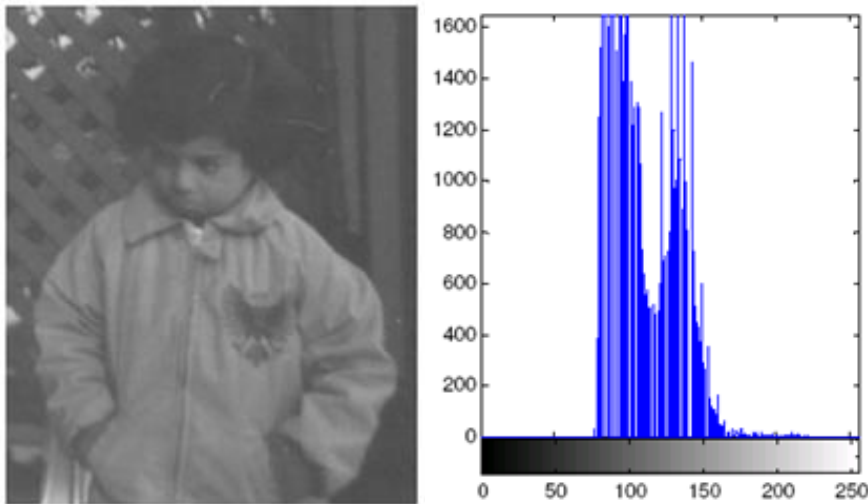


- How can we solve this problem of low/poor contrast in image?

You can attempt to find a point-based transformation function that can perform some kind of linear stretching...

# Problem with Contrast

- Linear stretching

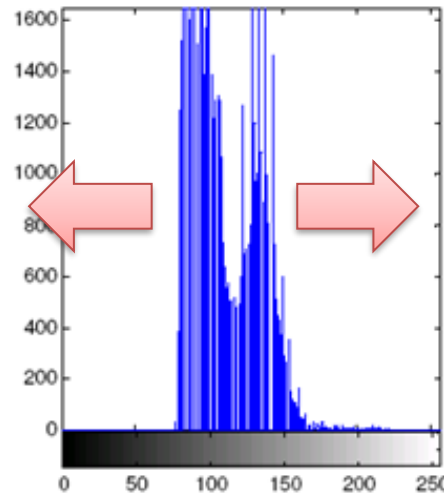


Is it good enough?

# Histogram Equalization

- **Histogram** **EQUALization**

- Aim: To “equalize” the histogram, to “flatten”,  
“**distribute as uniform as possible**” in an automatic way



- **Idea: Adjust** probability density function of the original histogram so that the probabilities spread equally

# Discrete Implementation

- Transforms an image with an arbitrary histogram to an image that has a somewhat flat histogram

1. Find the cumulative distribution (CD) of gray level  $l$ ,

$$\tilde{g}(l) = \sum_{k=0}^l p_F(k), l = 0, 1, \dots, K - 1$$

2. Convert the CD values to the max possible range of values  $[0, L-1]$  by quantization

$$g(l) = \left\lfloor \left( \sum_{k=0}^l p_F(k) \right) * (L - 1) \right\rfloor$$

3. Map the old pixel values to the new transformed values.



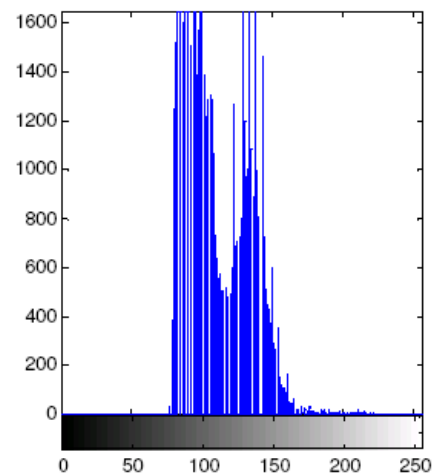
# Correcting the Pouting Child



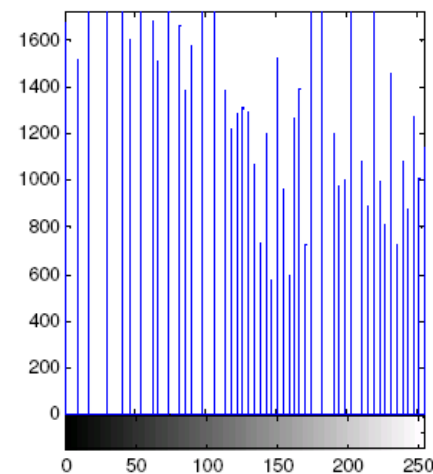
Original image with low contrast



Enhanced image



Original girl image with low contrast



Enhancement image with histogram equalization

# Example: Discrete Implementation

0	76	0.19	0.19
1	100	0.25	0.44
2	84	0.21	0.65
3	64	0.16	0.81
4	32	0.08	0.89
5	24	0.06	0.95
6	12	0.03	0.98
7	8	0.02	1.00

# Example: Discrete Implementation

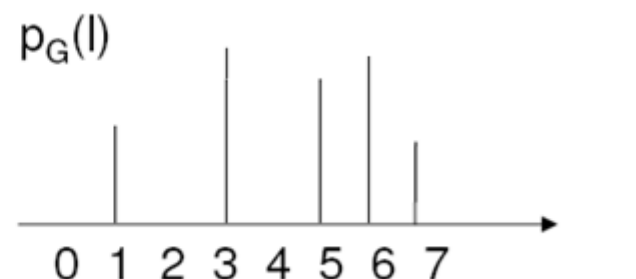
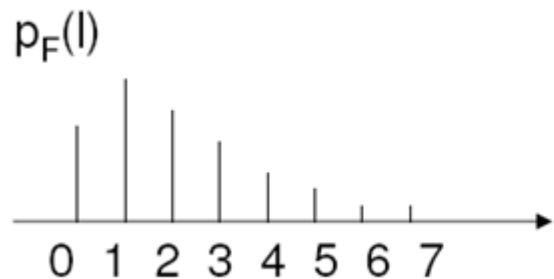
0	76	0.19	0.19	$[1.33] = 1$
1	100	0.25	0.44	$[3.08] = 3$
2	84	0.21	0.65	$[4.55] = 5$
3	64	0.16	0.81	$[5.67] = 6$
4	32	0.08	0.89	$[6.03] = 6$
5	24	0.06	0.95	$[6.65] = 7$
6	12	0.03	0.98	$[6.86] = 7$
7	8	0.02	1.00	$[7] = 7$

# Example: Discrete Implementation

0	76	0.19	0.19	$[1.33] = 1$	0	0
1	100	0.25	0.44	$[3.08] = 3$	0.19	1
2	84	0.21	0.65	$[4.55] = 5$	0	2
3	64	0.16	0.81	$[5.67] = 6$	0.25	3
4	32	0.08	0.89	$[6.03] = 6$	0	4
5	24	0.06	0.95	$[6.65] = 7$	0.21	5
6	12	0.03	0.98	$[6.86] = 7$	$0.16+0.08=0.24$	6
7	8	0.02	1.00	$[7] = 7$	$0.06+0.03+0.02=0.11$	7

# Example: Discrete Implementation

0	76	0.19	0.19	$[1.33] = 1$	0	0
1	100	0.25	0.44	$[3.08] = 3$	0.19	1
2	84	0.21	0.65	$[4.55] = 5$	0	2
3	64	0.16	0.81	$[5.67] = 6$	0.25	3
4	32	0.08	0.89	$[6.03] = 6$	0	4
5	24	0.06	0.95	$[6.65] = 7$	0.21	5
6	12	0.03	0.98	$[6.86] = 7$	$0.16+0.08=0.24$	6
7	8	0.02	1.00	$[7] = 7$	$0.06+0.03+0.02=0.11$	7



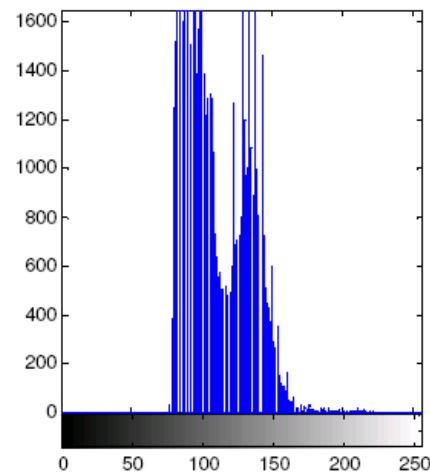
# Correcting the Pouting Child



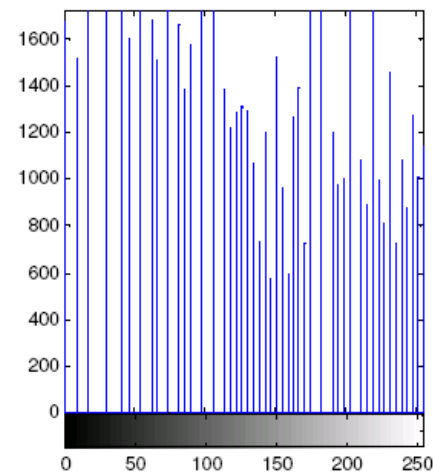
Original image with low contrast



Enhanced image



Original girl image with low contrast



Enhancement image with histogram equalization

# Summary

- **Image Formation**
  - Pixels
  - Sampling and Quantization
- **Pixel (point)-based Processing**
- **Image Histograms**
  - Histogram Equalization

# Recommended Reading

- [Gonzalez&Woods] Chapter 2 & 3