

# Regression modelling using I-priors

NUS Department of Statistics & Data Science Seminar

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For i = 1, ..., n, consider the regression model

$$y_i = f(x_i) + \epsilon_i$$

$$(\epsilon_1, \dots, \epsilon_n)^{\top} \sim \mathsf{N}_n(0, \Psi^{-1})$$
(1)

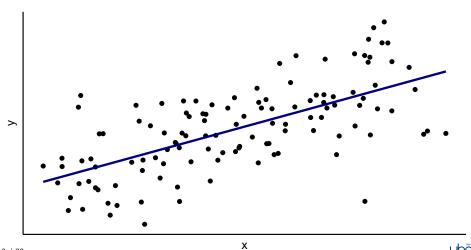
where each  $y_i \in \mathbb{R}$ ,  $x_i \in \mathcal{X}$  (some set of covariates), and f is a regression function. This forms the basis for a multitude of statistical models:

- 1. Ordinary linear regression when f is parameterised linearly.
- 2. Varying intercepts/slopes model when  $\mathcal X$  is grouped.
- 3. Smoothing models when f is a smooth function.
- 4. Functional regression when  $\mathcal{X}$  is functional.

#### Goal

To estimate the regression function f given the observations  $\{(y_i, x_i)\}_{i=1}^n$ .

Suppose  $f(x_i) = x_i^{\top} \beta$  for i = 1, ..., n, where  $x_i, \beta \in \mathbb{R}^p$ .



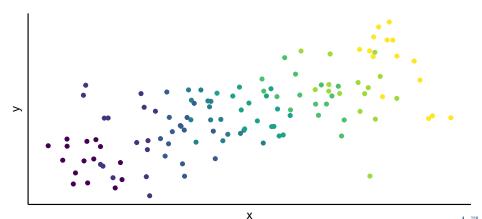
Introduction

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# Varying intercepts/slopes model

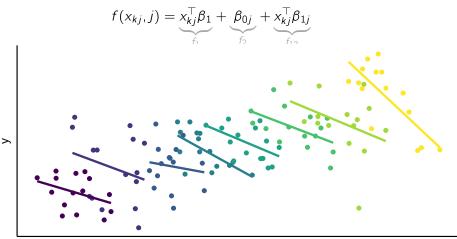
Suppose each unit  $i=1,\ldots,n$  relates to the kth observation in group  $j\in\{1,\ldots,m\}$ . Model the function f additively:

$$f(x_{kj},j) = f_1(x_{kj}) + f_2(j) + f_{12}(x_{kj},j).$$



# Varying intercepts/slopes model

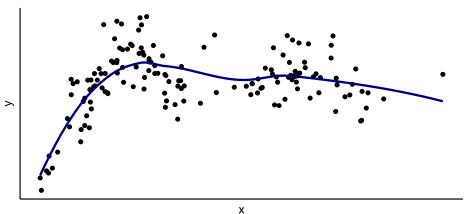
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# **Smoothing models**

Introduction

Suppose  $f \in \mathcal{F}$  where  $\mathcal{F}$  is a space of "smoothing functions" (models like LOESS, kernel regression, smoothing splines, etc.).



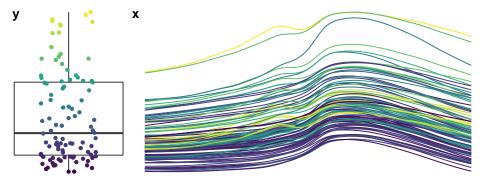
# **Functional regression**

Introduction

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Suppose the input set  $\mathcal{X}$  is functional. The (linear) regression aims to estimate a coefficient function  $\beta:\mathcal{T}\to\mathbb{R}$ 

$$y_i = \underbrace{\int_{\mathcal{T}} x_i(t)\beta(t) dt}_{f(x_i)} + \epsilon_i$$



# For the regression model stated in (1), we assume that f lies in some RKHS of functions $\mathcal{F}$ , with reproducing kernel h over $\mathcal{X}$ .

### Definition 1 (I-prior)

The entropy maximising prior distribution for f, subject to constraints, is

$$f(x) = \sum_{i=1}^{n} h(x, x_i) w_i$$

$$(w_1, \dots, w_n)^{\top} \sim N_n(0, \Psi)$$
(2)

Therefore, the covariance kernel of  $\mathbf{f} = (f(x_1), \dots, f(x_n))^{\top}$  is determined by the function

$$k(x, x') = \sum_{i=1}^{n} \sum_{j=1}^{n} \Psi_{i,j} h(x, x_i) h(x', x_j),$$

which happens to be **Fisher information** between two linear forms of f.

# The I-prior (cont.)

#### Interpretation:

Introduction

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The more information about f, the larger its prior variance, and hence the smaller the influence of the prior mean (and vice versa).



# The I-prior (cont.)

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#### Of interest then are

1. Posterior distribution for the regression function,

$$p(\mathbf{f} | \mathbf{y}) = \frac{p(\mathbf{y} | \mathbf{f})p(\mathbf{f})}{\int p(\mathbf{y} | \mathbf{f})p(\mathbf{f}) d\mathbf{f}}.$$

2. Posterior predictive distribution (given a new data point  $x_{new}$ )

$$p(y_{new} \mid \mathbf{y}) = \int p(y_{new} \mid f_{new}) p(f_{new} \mid \mathbf{y}) \, \mathrm{d}f_{new},$$

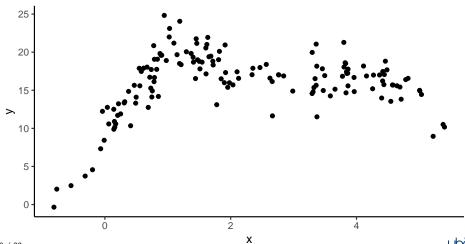
where  $f_{new} = f(x_{new})$ .

# Introduction (cont.)

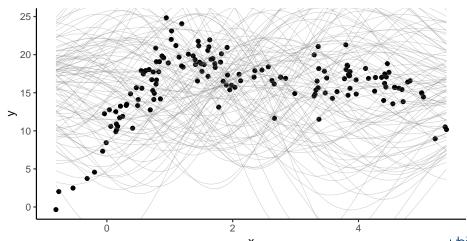
Introduction

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Observations  $\{(y_i, x_i) \mid y_i, x_i \in \mathbb{R} \ \forall i = 1, \dots, n\}.$ 



# Choose $h(x, x') = e^{-\frac{\|x - x'\|^2}{2l^2}}$ (Gaussian kernel). Sample paths from I-prior:



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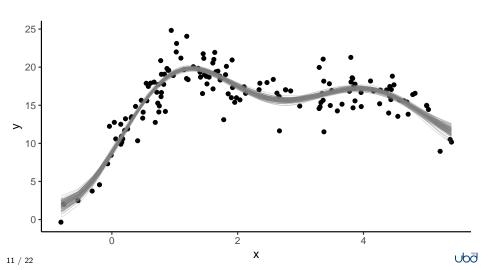
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# Introduction (cont.)

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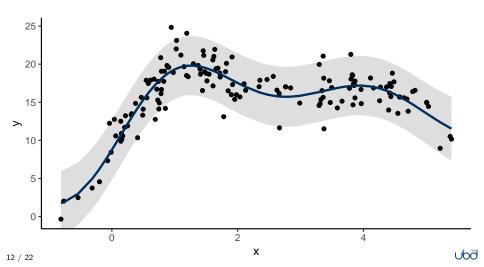
Sample paths from the posterior of f:



# Introduction (cont.)

Introduction

Posterior mean estimate for y = f(x) and its 95% credibility interval.



Estimation

#### Advantages

Introduction

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- Provides a unifying methodology for regression.
- Simple and parsimonious model specification and estimation.
- Often yield comparable (or better) predictions than competing ML algorithms.

# machine-learning method inference independent multicollinearity exponential-family entropy exponential-family entropy distributions covariates. Supdate advantage approximation covariates. Supdate advantage approximation covariates. Supdate multiplication machine machin

#### Competitors:

Tikhonov regulariser (e.g. cubic spline smoother)

$$\hat{f} = \arg\min_{f} \sum_{i=1}^{n} (y_i - f(x_i))^2 + \lambda \int f''(x)^2 dx$$

Gaussian process regression

Regression using I-priors
Reproducing kernel Hilbert spaces
The Fisher information

Estimation

Examples

# Reproducing kernel Hilbert spaces

Assumption: Let  $f \in \mathcal{F}$  be an RKHS with kernel h over a set  $\mathcal{X}$ .

## Definition 2 (Hilbert spaces)

A *Hilbert space*  $\mathcal{F}$  is a vector space equipped with a positive semidefinite inner product  $\langle \cdot, \cdot \rangle_{\mathcal{F}} : \mathcal{F} \times \mathcal{F} \to \mathbb{R}$ .

#### Definition 3 (Reproducing kernels)

A symmetric, bivariate function  $h: \mathcal{X} \times \mathcal{X} \to \mathbb{R}$  is called a *kernel*, and it is a *reproducing kernel* of  $\mathcal{F}$  if h satisfies  $\forall x \in \mathcal{X}$ ,

- i.  $h(\cdot, x) \in \mathcal{F}$ ; and
- ii.  $\langle f, h(\cdot, x) \rangle_{\mathcal{F}} = f(x), \forall f \in \mathcal{F}.$

In particular,  $\forall x, x' \in \mathcal{F}$ ,  $h(x, x') = \langle h(\cdot, x), h(\cdot, x') \rangle_{\mathcal{F}}$ .

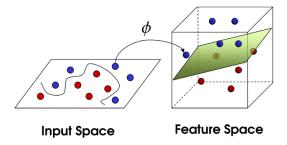
# Reproducing kernel Hilbert spaces (cont.)

• In ML literature, Mercer's Theorem states

$$h(x, x') = \langle \phi(x), \phi(x') \rangle_{\mathcal{V}} \Leftrightarrow h \text{ is semi p.d.}$$

where  $\phi: \mathcal{X} \to \mathcal{V}$  is a mapping from  $\mathcal{X}$  to the *feature space*  $\mathcal{V}$ .

• In many ML models, need not specify  $\phi$  explicitly; computation is made simpler by the use of kernels.



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# Reproducing kernel Hilbert spaces (cont.)

#### Theorem 4

There is a bijection between

- i. the set of positive semidefinite functions; and
- ii. the set of RKHSs.

## Corollary 5

Any  $f \in \mathcal{F}$  can be approximated arbitrarily well by functions of the form

$$\tilde{f}(x) = \sum_{i=1}^{n} w_i h(x, x_i)$$

for some constants  $w_1, \ldots, w_n \in \mathbb{R}$ , because  $\mathcal{F}$  is the completion of the vector space  $\tilde{\mathcal{F}} = \operatorname{span}\{h(\cdot, x) \mid x \in \mathcal{X}\}$  equipped with the squared norm  $\|\tilde{f}\|^2 = \sum_{i,j=1}^n w_i w_j h(x_i, x_j)$ .

# **Examples of RKHSs**

Introduction



#### The Fisher information

# Lemma 6 (Fisher information for regression function)

The Fisher information for f is given by

$$\mathcal{I}_f = \sum_{i=1}^n \sum_{j=1}^n \psi_{ij} h(\cdot, x_i) \otimes h(\cdot, x_j)$$

where  $\otimes$  is...

Introduction

# The Fisher information (cont.)

It's helpful to think of  $\mathcal{I}_f$  as a bilinear form  $\mathcal{I}_f: \mathcal{F} \times \mathcal{F} \to \mathbb{R}$  defined by

$$\mathcal{I}_f = -\operatorname{\mathsf{E}} 
abla^2 L(f|y),$$

so the Fisher information between two point evaluation functionals of is

$$\mathcal{I}(f(x), f(x')) = \mathcal{I}_f(h(\cdot, x), h(\cdot, x')) = \sum_{i=1}^n \sum_{i=1}^n \psi_{ij} h(x, x_i) h(x', x_j).$$

#### Example 7

Let



Suppose further that  $f \in \mathcal{F}$  where  $\mathcal{F}$  is a reproducing kernel Hilbert space (RKHS) with reproducing kernel  $h: \mathcal{X} \times \mathcal{X} \to \mathbb{R}$ . Then (1) can be expressed as

$$y_{i} = \langle f, h(\cdot, x_{i}) \rangle_{\mathcal{F}} + \epsilon_{i}$$

$$(\epsilon_{1}, \dots, \epsilon_{n})^{\top} \sim \mathsf{N}(\mathbf{0}, \mathbf{\Psi}^{-1})$$
(3)

The Fisher information for f is given by

$$\mathcal{I}_f = \sum_{i=1}^n \sum_{j=1}^n \psi_{ij} h(\cdot, x_i) \otimes h(\cdot, x_j)$$

Examples

where each  $y_i \in \mathbb{R}$ ,, and  $f \in \mathcal{F}$  a reproducing kernel Hilbert space (RKHS) with kernel  $h: \mathcal{X} \times \mathcal{X} \to \mathbb{R}$ . The I-prior (Bergsma, 2019) for the regression function f is the random function defined

$$f(x_i) = f_0(x_i) + \sum_{k=1}^n h(x_i, x_k) w_k$$

$$(w_1, \dots, w_n)^\top \sim \mathsf{N}(\mathbf{0}, \mathbf{\Psi})$$
(4)

where  $f_0$  is some prior mean for the regression function.

Regression using I-priors

Estimation

Examples

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## **Further research**

Hello

