

Binary probit regression with I-priors

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PhD Presentation Event

<http://phd3.haziqj.ml>

Outline

① Introduction

- I-priors

- PhD Roadmap

② Probit models with I-priors

- The latent variable motivation

- Using I-priors

- Estimation (and challenges)

③ Variational inference

- Introduction

- A simple example

④ R/iprobit

- Toy example

⑤ Applications

⑥ Summary

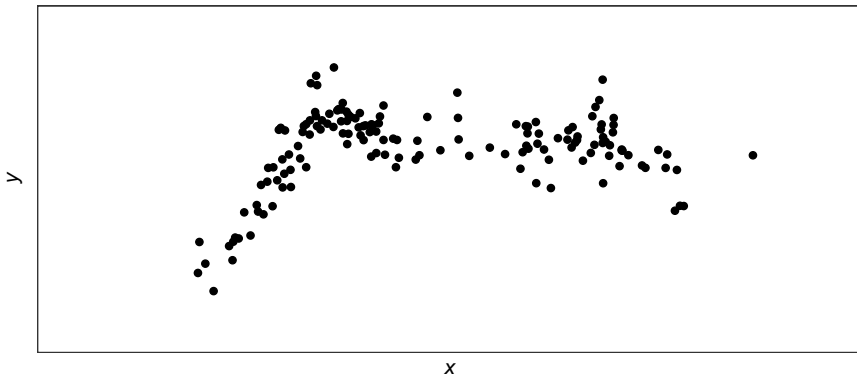
The regression model

- For $i = 1, \dots, n$, consider the regression model

$$y_i = f(x_i) + \epsilon_i$$

$$(\epsilon_1, \dots, \epsilon_n) \sim \mathbf{N}(\mathbf{0}, \Psi^{-1})$$

where $f \in \mathcal{F}$, $y_i \in \mathbb{R}$, and $x_i = (x_{i1}, \dots, x_{ip}) \in \mathcal{X}$.



l-priors

- Let \mathcal{F} be a reproducing kernel Hilbert space (RKHS) with reproducing kernel $h_\lambda : \mathcal{X} \times \mathcal{X} \rightarrow \mathbb{R}$. An l-prior on f is

$$(f(x_1), \dots, f(x_n))^T \sim N(f_0, \mathcal{I}(f))$$

with f_0 a prior mean, and \mathcal{I} the Fisher information for f , given by

$$\mathcal{I}(f(x), f(x')) = \sum_{k=1}^n \sum_{l=1}^n \psi_{kl} h_\lambda(x, x_k) h_\lambda(x', x_l).$$

- The l-prior regression model for $i = 1, \dots, n$ becomes

$$y_i = f_0(x_i) + \sum_{k=1}^n h_\lambda(x_i, x_k) w_k + \epsilon_i$$

$$(w_1, \dots, w_n) \sim N(\mathbf{0}, \Psi)$$

$$(\epsilon_1, \dots, \epsilon_n) \sim N(\mathbf{0}, \Psi^{-1})$$

W. Bergsma (2017). "Regression with l-priors". *Manuscript in preparation*

I-priors (cont.)

- Of interest is the posterior of the function

$$p(\mathbf{f}|\mathbf{y}) = \frac{p(\mathbf{y}|\mathbf{f})p(\mathbf{f})}{\int p(\mathbf{y}|\mathbf{f})p(\mathbf{f}) d\mathbf{f}},$$

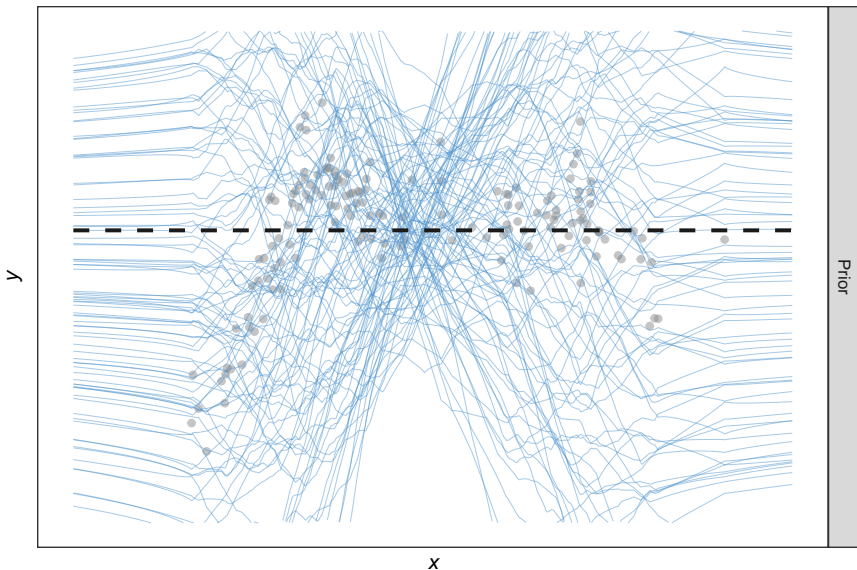
and also the posterior predictive distribution

$$p(\mathbf{y}^*|\mathbf{y}) = \int p(\mathbf{y}^*|\mathbf{y}, \mathbf{f})p(\mathbf{f}|\mathbf{y}) d\mathbf{f}.$$

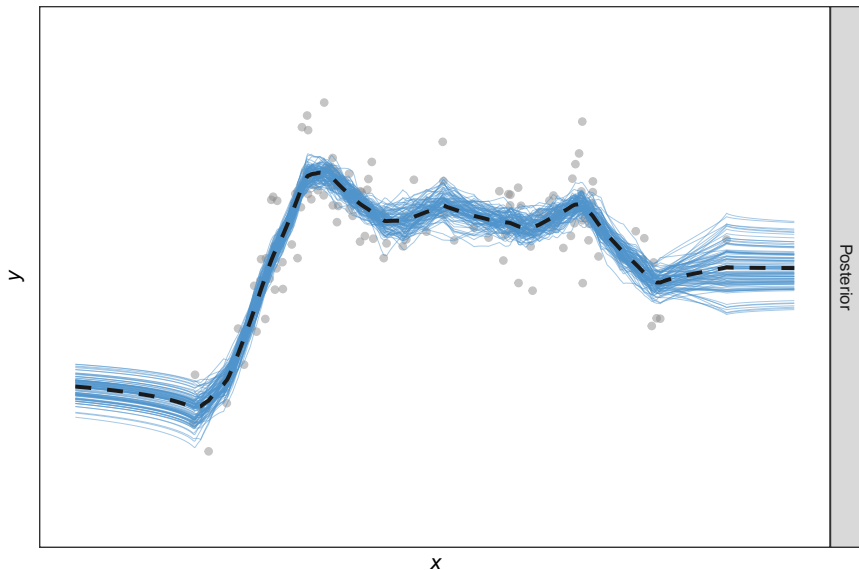
- Estimation using EM algorithm or direct maximisation of the marginal likelihood $\log p(\mathbf{y})$.
- Fully Bayesian estimation also possible.

HJ (2017). *iprior: Linear Regression using I-Priors*. R Package version 0.6.4:
CRAN/GitHub

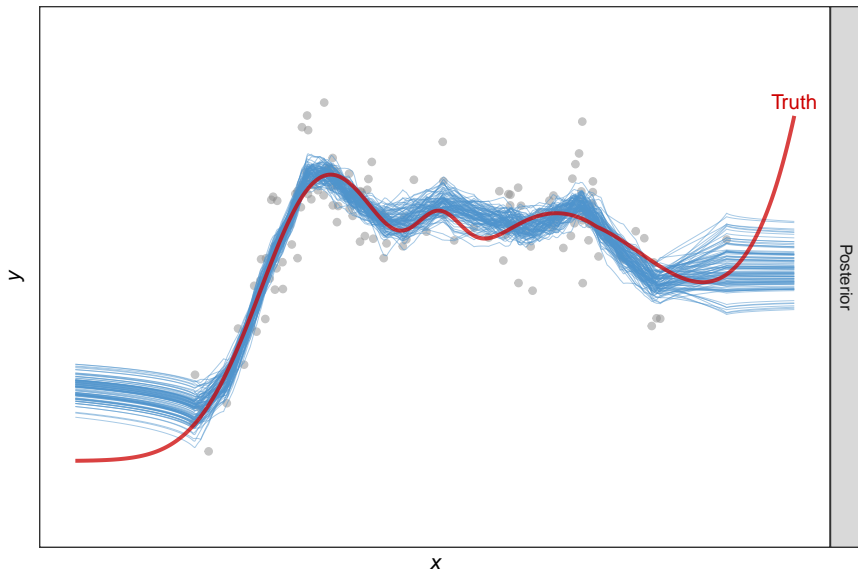
Fractional Brownian motion (FBM) RKHS



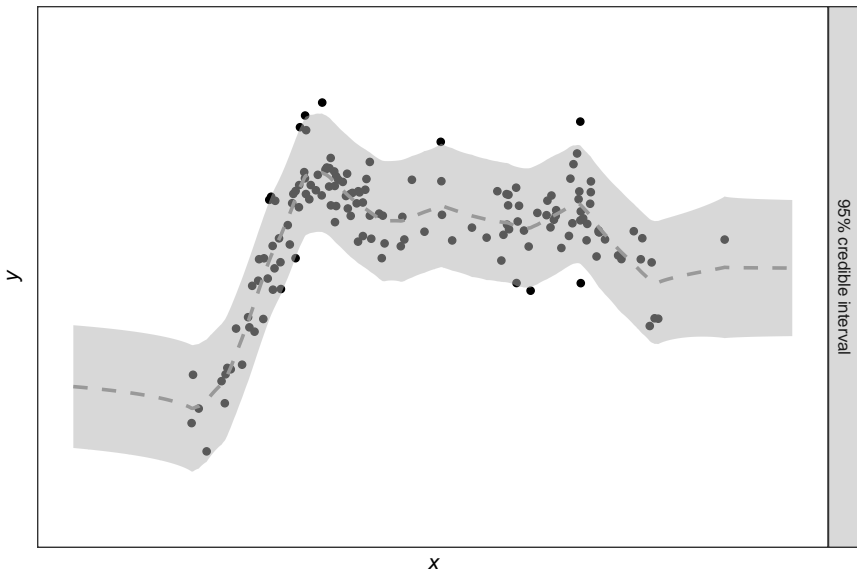
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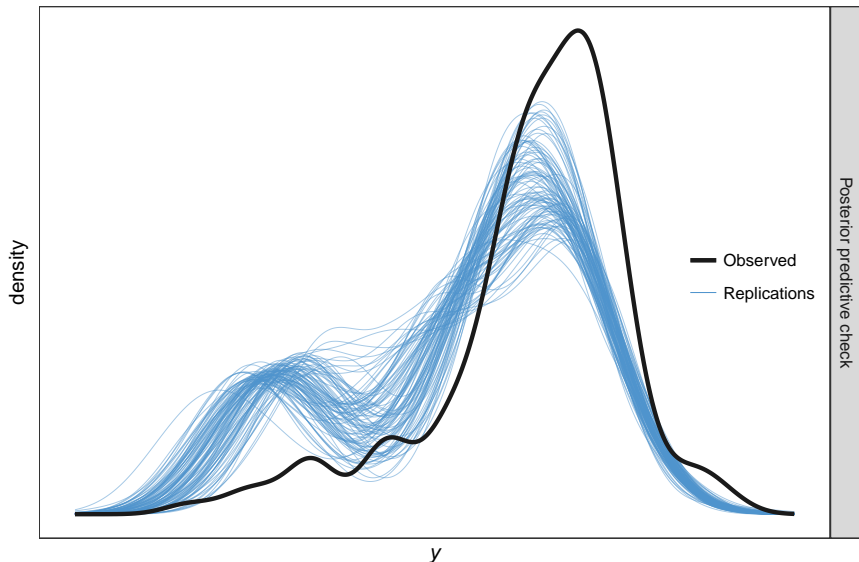
Fractional Brownian motion (FBM) RKHS



Posterior predictive distribution



Posterior predictive distribution



Roadmap

- ① Introduction
- ② Probit models with I-priors
- ③ Variational inference
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The latent variable motivation

- Consider binary responses y_1, \dots, y_n together with their corresponding covariates x_1, \dots, x_n .
- For $i = 1, \dots, n$, model the responses as

$$y_i \sim \text{Bern}(p_i).$$

- Assume that there exists continuous, underlying latent variables y_1^*, \dots, y_n^* , such that

$$y_i = \begin{cases} 1 & \text{if } y_i^* \geq 0 \\ 0 & \text{if } y_i^* < 0. \end{cases}$$

- Model these continuous latent variables according to

$$y_i^* = f(x_i) + \epsilon_i$$

where $(\epsilon_1, \dots, \epsilon_n) \sim \text{N}(\mathbf{0}, \Psi^{-1})$ and $f \in \mathcal{F}$ (some RKHS).

Using I-priors

- Assume an I-prior on f . Then,

$$f(x_i) = \alpha + \sum_{k=1}^n h_{\lambda}(x_i, x_k) w_k$$
$$(w_1, \dots, w_n) \sim N(\mathbf{0}, \Psi)$$

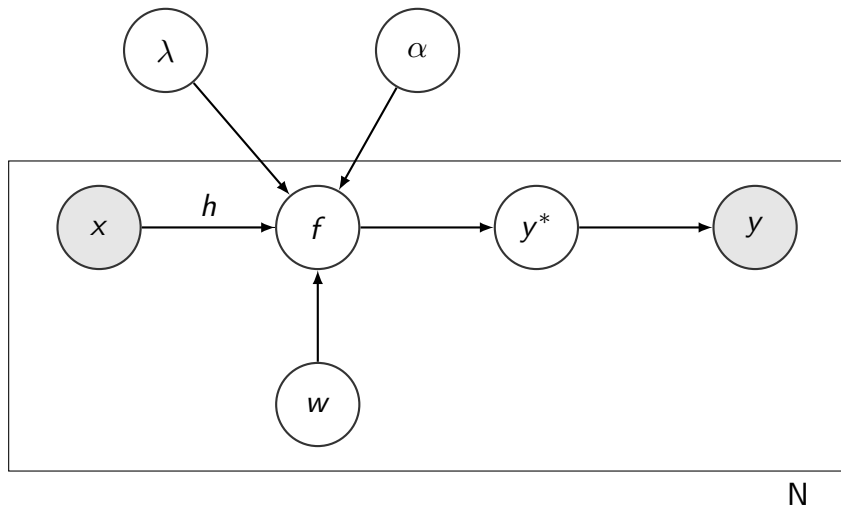
- For now, consider iid errors $\Psi = \psi \mathbf{I}_n$. In this case,

$$\begin{aligned} p_i = P[y_i = 1] &= P[y_i^* \geq 0] \\ &= P[\epsilon_i \leq f(x_i)] \\ &= \Phi\left(\psi^{1/2}(\alpha + \sum_{k=1}^n h_{\lambda}(x_i, x_k) w_k)\right) \end{aligned}$$

where Φ is the CDF of a standard normal.

- No loss of generality compared with using an arbitrary threshold τ or error precision ψ . Thus, set $\psi = 1$.

The probit I-prior model



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Estimation

- Denote $f_i = f(x_i)$ for short.
- The marginal density

$$\begin{aligned} p(\mathbf{y}) &= \int p(\mathbf{y}|\mathbf{f})p(\mathbf{f}) d\mathbf{f} \\ &= \int \prod_{i=1}^n \left[\Phi(f_i)^{y_i} (1 - \Phi(f_i))^{1-y_i} \right] \cdot \mathbf{N}(\alpha \mathbf{1}_n, \mathbf{H}_\lambda^2) d\mathbf{f} \end{aligned}$$

for which $p(\mathbf{f}|\mathbf{y})$ depends, cannot be evaluated analytically.

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- Some strategies:
 - ✗ Naive Monte-Carlo integral

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 - ✗ EM algorithm with a MCMC E-step

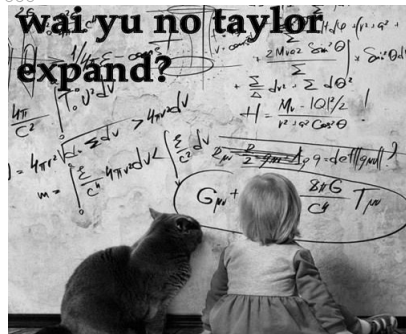
Estimation

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- The marginal density

$$\begin{aligned}
 p(y) &= \int p(y|f)p(f) df \\
 &= \int \prod_{i=1}^n [\Phi(f_i)^{y_i} (1 - \Phi(f_i))^{1-y_i}] \cdot N(\alpha \mathbf{1}_n, \mathbf{H}_\lambda^2) df
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 - ✗ Naive Monte-Carlo integral
 - ✗ EM algorithm with a MCMC E-step
 - ✓ Laplace approximation



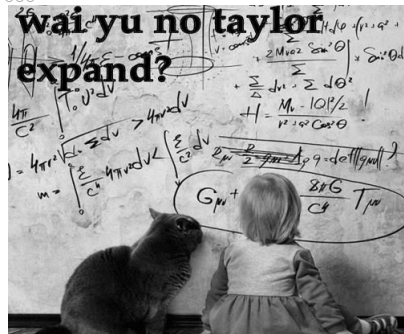
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for which $p(f|y)$ depends, cannot be evaluated analytically.

- Some strategies:
 - ✗ Naive Monte-Carlo integral
 - ✗ EM algorithm with a MCMC E-step
 - ✓ Laplace approximation
 - ✓ MCMC sampling



Laplace's method

- Interested in $p(\mathbf{f}|\mathbf{y}) \propto p(\mathbf{y}|\mathbf{f})p(\mathbf{f}) =: e^{Q(\mathbf{f})}$, with normalising constant $p(\mathbf{y}) = \int e^{Q(\mathbf{f})} d\mathbf{f}$. The Taylor expansion of Q about its mode $\tilde{\mathbf{f}}$

$$Q(\mathbf{f}) \approx Q(\tilde{\mathbf{f}}) - \frac{1}{2}(\mathbf{f} - \tilde{\mathbf{f}})^\top \mathbf{A}(\mathbf{f} - \tilde{\mathbf{f}})$$

is recognised as the logarithm of an unnormalised Gaussian density, with $\mathbf{A} = -D^2Q(\mathbf{f})$ being the negative Hessian of Q evaluated at $\tilde{\mathbf{f}}$.

- The posterior $p(\mathbf{f}|\mathbf{y})$ is approximated by $N(\tilde{\mathbf{f}}, \mathbf{A}^{-1})$, and the marginal by

$$p(\mathbf{y}) \approx (2\pi)^{n/2} |\mathbf{A}|^{-1/2} p(\mathbf{y}|\tilde{\mathbf{f}}) p(\tilde{\mathbf{f}})$$

- Won't scale with large n ; difficult to find modes in high dimensions.

R. Kass and A. Raftery (1995). "Bayes Factors". *Journal of the American Statistical Association* 90.430, §4.1, pp. 777-778.

Full Bayesian analysis using MCMC

- Assign hyperpriors on parameters of the I-prior, e.g.

- ▶ $\lambda^2 \sim \Gamma^{-1}(a, b)$

- ▶ $\alpha \sim N(c, d^2)$

for a hierarchical model to be estimated fully Bayes.

- No closed-form posteriors - need to resort to MCMC sampling.
- Computationally slow, and sampling difficulty results in unreliable posterior samples.

DENSITY PLOTS OF LAMBDA HERE

- ① Introduction
- ② Probit models with l-priors
- ③ Variational inference**
- ④ R/iprobit
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Variational inference

- Name derived from calculus of variations which deals with maximising or minimising functionals.

Functions $p : \theta \mapsto \mathbb{R}$ (standard calculus)

Functionals $\mathcal{H} : p \mapsto \mathbb{R}$ (variational calculus)

- Using standard calculus, we can solve

$$\arg \max_{\theta} p(\theta) =: \hat{\theta}$$

e.g. p is a likelihood function, and $\hat{\theta}$ is the ML estimate.

- Using variational calculus, we can solve

$$\arg \max_p \mathcal{H}(p) =: \tilde{p}$$

e.g. \mathcal{H} is the entropy $\mathcal{H} = - \int p(x) \log p(x) dx$, and \tilde{p} is the entropy maximising distribution.

Variational inference (cont.)

- Consider a statistical model where we have observations (y_1, \dots, y_n) and also some latent variables (z_1, \dots, z_n) .
- The z_i could be random effects or some auxiliary latent variables.
- In a Bayesian setting, this could also include the parameters to be estimated.
- **GOAL:** Find approximations for
 - ▶ The posterior distribution $p(\mathbf{z}|\mathbf{y})$; and
 - ▶ The marginal likelihood (or model evidence) $p(\mathbf{y})$.
- Variational inference is a deterministic approach, unlike MCMC.

C. M. Bishop (2006). *Pattern Recognition and Machine Learning*. Springer, Ch. 10

K. P. Murphy (1991). *Machine Learning: A Probabilistic Perspective*. The MIT Press. DOI: 10.1007/SpringerReference_35834, Ch. 21

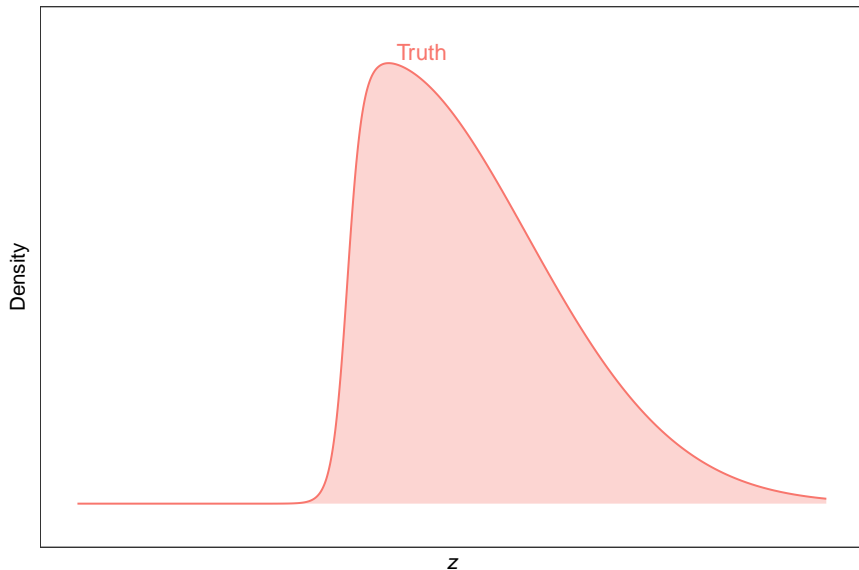
Decomposition of the log marginal

- Let $q(\mathbf{z})$ be some density function to approximate $p(\mathbf{z}|\mathbf{y})$. Then the log-marginal density can be decomposed into

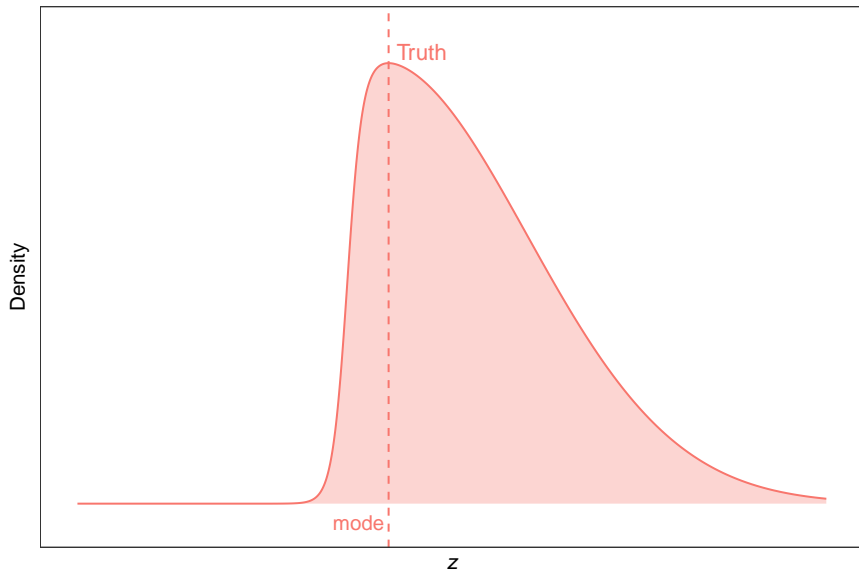
$$\begin{aligned}\log p(\mathbf{y}) &= \log p(\mathbf{y}, \mathbf{z}) - \log p(\mathbf{z}|\mathbf{y}) \\ &= \int \left\{ \log \frac{p(\mathbf{y}, \mathbf{z})}{q(\mathbf{z})} - \log \frac{p(\mathbf{z}|\mathbf{y})}{q(\mathbf{z})} \right\} q(\mathbf{z}) d\mathbf{z} \\ &= \mathcal{L}(q) + \text{KL}(q\|p) \\ &\geq \mathcal{L}(q)\end{aligned}$$

- \mathcal{L} is referred to as the “lower-bound”, and it serves as a surrogate function to the marginal.
- Maximising the $\mathcal{L}(q)$ is equivalent to minimising $\text{KL}(q\|p)$.
- Although $\text{KL}(q\|p)$ is minimised at $q(\mathbf{z}) \equiv p(\mathbf{z}|\mathbf{y})$ (c.f. EM algorithm), we are unable to work with $p(\mathbf{z}|\mathbf{y})$.

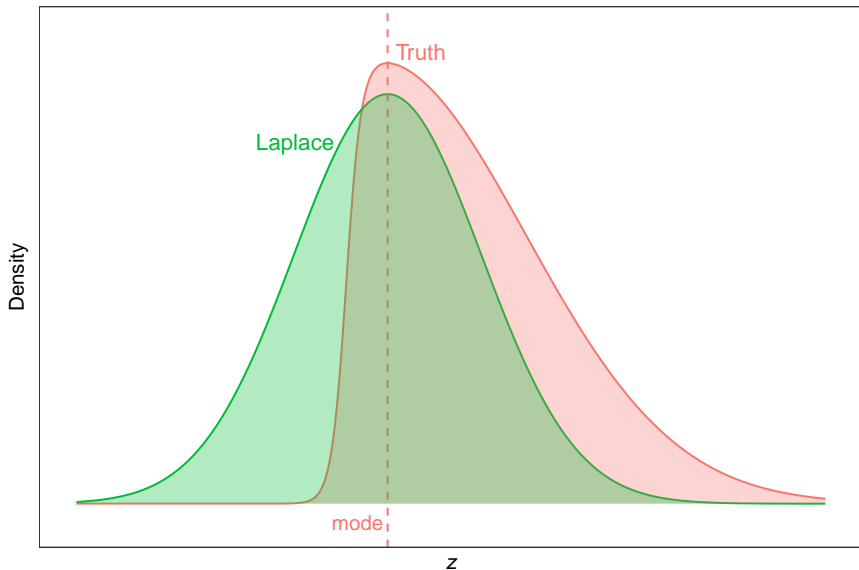
Comparison of approximations (density)



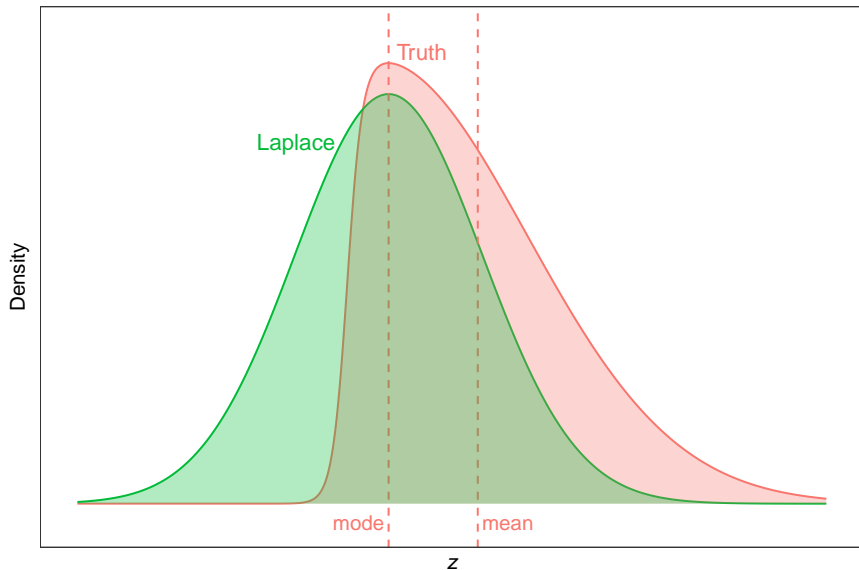
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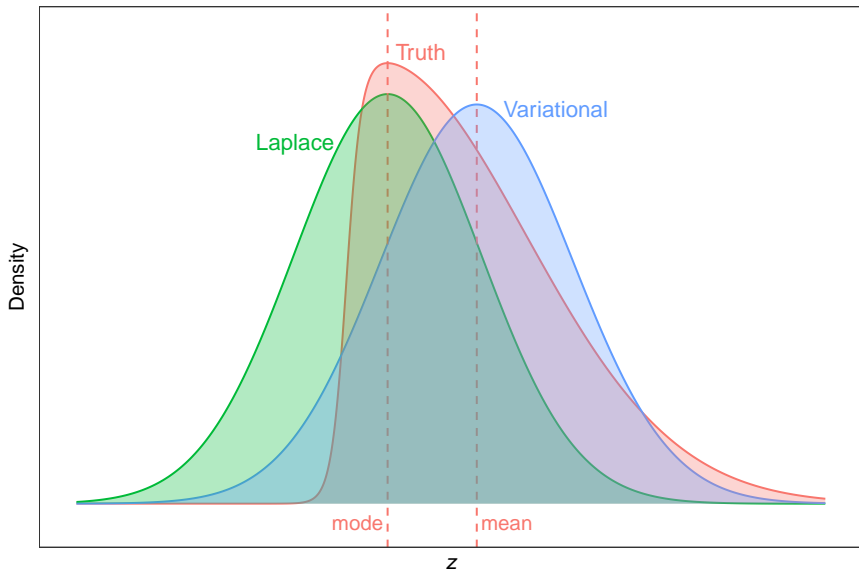
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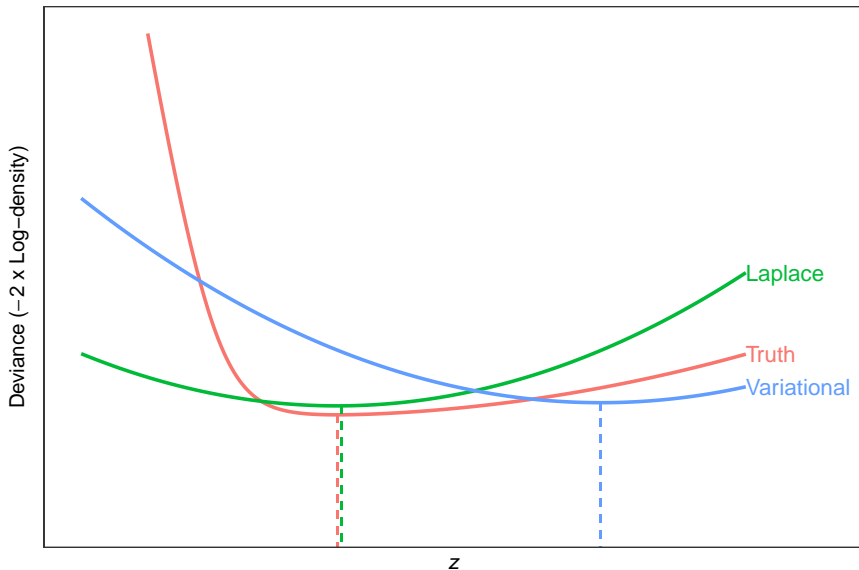
Comparison of approximations (density)



Comparison of approximations (density)



Comparison of approximations (deviance)



Factorised distributions (Mean-field theory)

- Maximising \mathcal{L} over all possible q not feasible. Need some restrictions, but only to achieve tractability.
- Suppose we partition elements of \mathbf{z} into m disjoint groups $\mathbf{z} = (\mathbf{z}^{(1)}, \dots, \mathbf{z}^{(m)})$, and assume

$$q(\mathbf{z}) = \prod_{j=1}^m q_j(\mathbf{z}^{(j)})$$

- Under this restriction, the solution to $\arg \max_q \mathcal{L}(q)$ is

$$\tilde{q}_j(\mathbf{z}^{(j)}) \propto \exp \left(\mathbb{E}_{-j} [\log p(\mathbf{y}, \mathbf{z})] \right) \quad (1)$$

for $j \in \{1, \dots, m\}$.

- In practice, these unnormalised densities are of recognisable form (especially if conjugate priors are used).

D. M. Blei, A. Kucukelbir, and J. D. McAuliffe (2016). "Variational Inference: A Review for Statisticians". [arXiv: 1601.00670](https://arxiv.org/abs/1601.00670)

Coordinate ascent mean-field variational inference (CAVI)

- The optimal distributions are coupled with another, i.e. each $\tilde{q}_j(\mathbf{z}^{(j)})$ depends on the optimal moments of $\mathbf{z}^{(k)}$, $k \in \{1, \dots, m : k \neq j\}$.
- One way around this to employ an iterative procedure.
- Assess convergence by monitoring the lower bound

$$\mathcal{L}(q) = \mathbb{E}_q[\log p(\mathbf{y}, \mathbf{z})] - \mathbb{E}_q[\log q(\mathbf{z})].$$

Algorithm 1 CAVI

- 1: **initialise** Variational factors $q_j(\mathbf{z}^{(j)})$
 - 2: **while** $\mathcal{L}(q)$ not converged **do**
 - 3: **for** $j = 1, \dots, m$ **do**
 - 4: $\log q_j(\mathbf{z}^{(j)}) \leftarrow \mathbb{E}_{-j}[\log p(\mathbf{y}, \mathbf{z})] + \text{const.}$
 - 5: **end for**
 - 6: $\mathcal{L}(q) \leftarrow \mathbb{E}_q[\log p(\mathbf{y}, \mathbf{z})] - \mathbb{E}_q[\log q(\mathbf{z})]$
 - 7: **end while**
 - 8: **return** $\tilde{q}(\mathbf{z}) = \prod_{j=1}^m \tilde{q}_j(\mathbf{z}^{(j)})$
-

Estimation of a 1-dim Gaussian mean and variance

- GOAL: Bayesian inference of mean μ and variance ψ^{-1}

$$y_i \stackrel{\text{iid}}{\sim} \text{N}(\mu, \psi^{-1}) \quad \text{Data}$$

$$\mu | \psi \sim \text{N}(\mu_0, (\kappa_0 \psi)^{-1}) \quad \text{Priors}$$

$$\psi \sim \Gamma(a_0, b_0)$$

$$i = 1, \dots, n$$

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$$i = 1, \dots, n$$

- Substitute $p(\mu, \psi | \mathbf{y})$ with the mean-field approximation

$$q(\mu, \psi) = q_\mu(\mu) q_\psi(\psi)$$

Estimation of a 1-dim Gaussian mean and variance

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- From (1), we can work out the solutions

Estimation of a 1-dim Gaussian mean and variance

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- Under the mean-field restriction, the solution to $\arg \max_q \mathcal{L}(q)$ is

$$\tilde{q}_j(\mathbf{z}^{(j)}) \propto \exp \left(\mathbb{E}_{-j}[\log p(\mathbf{y}, \mathbf{z})] \right) \quad (1)$$

- for $j \in \{1, \dots, m\}$.

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$$q(\mu, \psi) = q_\mu(\mu) q_\psi(\psi)$$

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$$\log \tilde{q}_\mu(\mu) = \mathbb{E}_\psi[\log p(\mathbf{y}|\mu, \psi)] + \mathbb{E}_\psi[\log p(\mu|\psi)] + \text{const.}$$

$$\begin{aligned} \log \tilde{q}_\psi(\psi) &= \mathbb{E}_\mu[\log p(\mathbf{y}|\mu, \psi)] + \mathbb{E}_\mu[\log p(\mu|\psi)] + \log p(\psi) \\ &\quad + \text{const.} \end{aligned}$$

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- for $j \in \{1, \dots, m\}$.

$$q(\mu, \psi) = q_\mu(\mu) q_\psi(\psi)$$

- From (1), we can work out the solutions

$$\tilde{q}_\mu(\mu) \equiv \mathcal{N} \left(\frac{\kappa_0 \mu_0 + n \bar{y}}{\kappa_0 + n}, \frac{1}{(\kappa_0 + n) \mathbb{E}_q[\psi]} \right)$$

Estimation of a 1-dim Gaussian mean and variance

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$$q(\mu, \psi) = q_\mu(\mu) q_\psi(\psi)$$

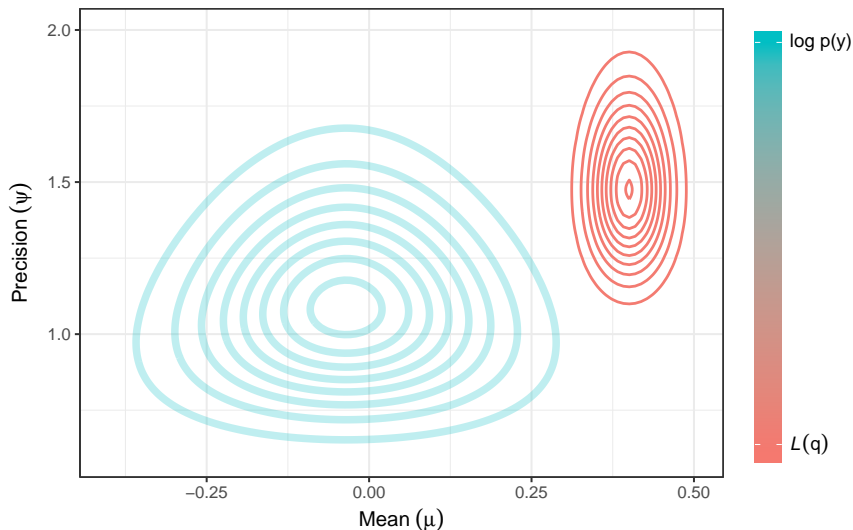
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$$\tilde{q}_\mu(\mu) \equiv \mathcal{N} \left(\frac{\kappa_0 \mu_0 + n \bar{y}}{\kappa_0 + n}, \frac{1}{(\kappa_0 + n) \mathbb{E}_q[\psi]} \right) \quad \text{and} \quad \tilde{q}_\psi(\psi) \equiv \Gamma(\tilde{a}, \tilde{b})$$

$$\tilde{a} = a_0 + \frac{n}{2} \quad \tilde{b} = b_0 + \frac{1}{2} \mathbb{E}_q \left[\sum_{i=1}^n (y_i - \mu)^2 + \kappa_0 (\mu - \mu_0)^2 \right]$$

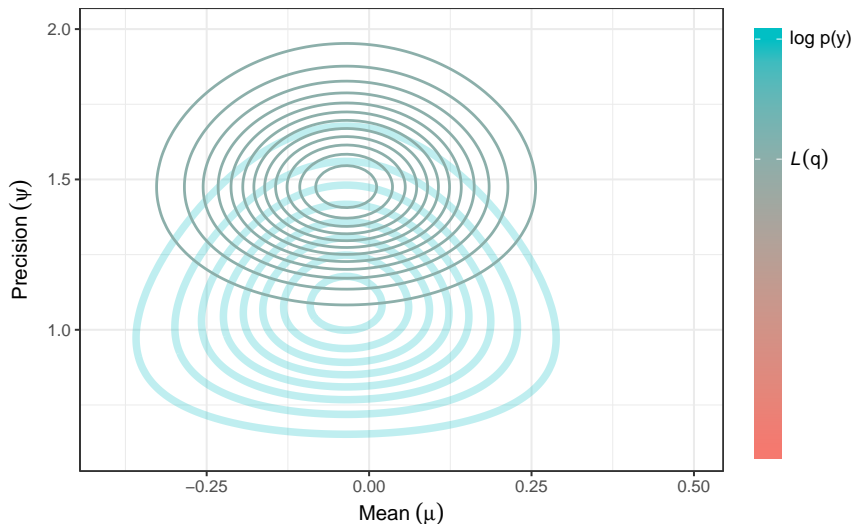
Estimation of a 1-dim Gaussian mean and variance (cont.)

Iteration 0 (initialisation)



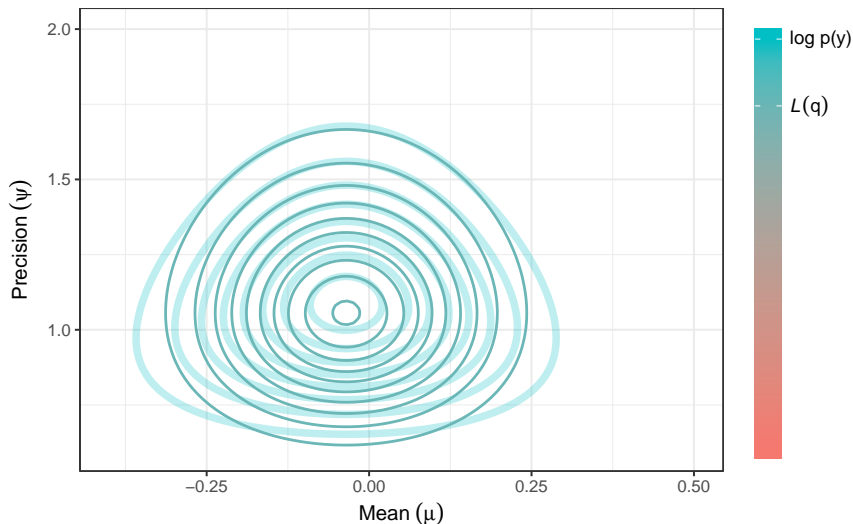
Estimation of a 1-dim Gaussian mean and variance (cont.)

Iteration 1 (μ update)



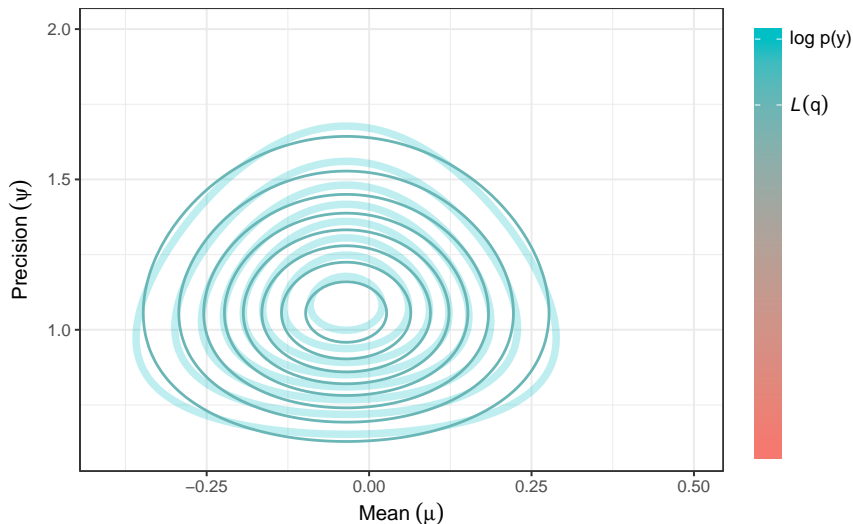
Estimation of a 1-dim Gaussian mean and variance (cont.)

Iteration 1 (ψ update)



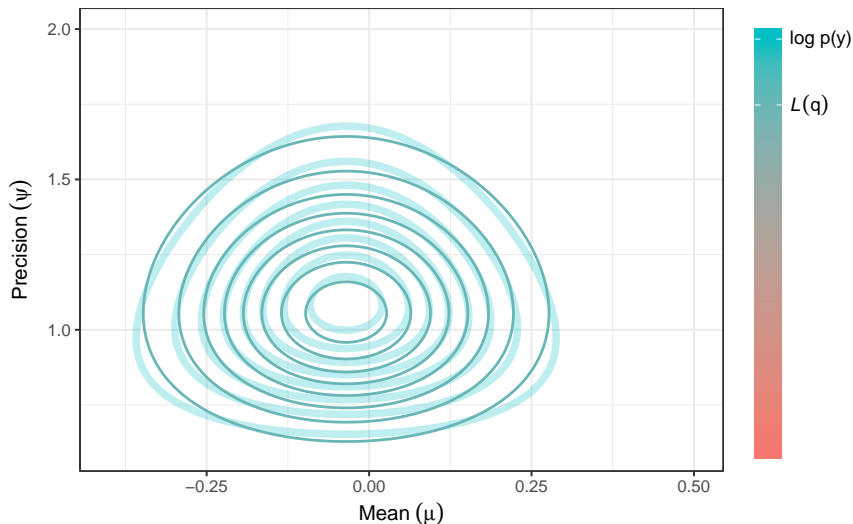
Estimation of a 1-dim Gaussian mean and variance (cont.)

Iteration 2 (μ update)



Estimation of a 1-dim Gaussian mean and variance (cont.)

Iteration 2 (ψ update)



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Simulated data

R code

Timings, parameter estimates, training error rate, test error rate

Diagnostics

Monitor the lower bound

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Cardiac arrhythmia data set

Multilevel example

Longitudinal example

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Summary

Way forward

End

Thank you!

References I

- Bergsma, W. (2017). "Regression with I-priors". *Manuscript in preparation*.
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