

A Brief Guide to Variational Inference

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UBD Interview Seminar

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Outline

① Introduction

- Idea

- Mean-field distributions

- Coordinate ascent algorithm

② Example

- Gaussian mixtures

③ Discussion

- Zero-forcing vs Zero-avoiding

- Quality of approximation

Introduction

- Consider a statistical model parameterised by $\boldsymbol{\theta} = (\theta_1, \dots, \theta_p)^\top$ for which we have observations $\mathbf{y} = \{y_1, \dots, y_n\}$ and also some latent variables $\mathbf{z} = \{z_1, \dots, z_m\}$.

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$$I := \int p(\mathbf{y}|\mathbf{z})p(\mathbf{z}) \, d\mathbf{z} = p(\mathbf{y})$$

- ▶ Frequentist likelihood maximisation $\arg \max_{\boldsymbol{\theta}} \log p(\mathbf{y}|\boldsymbol{\theta})$
- ▶ Bayesian posterior analysis $p(\mathbf{z}|\mathbf{y}) = p(\mathbf{y}, \mathbf{z})/p(\mathbf{y})$

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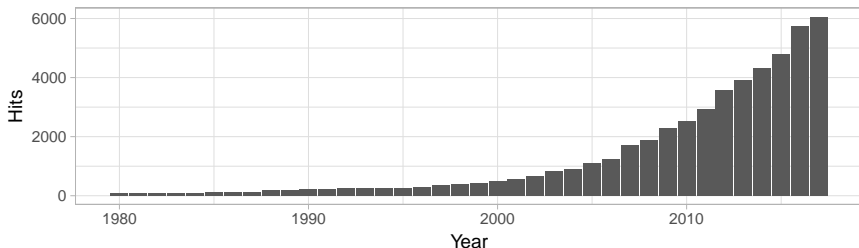
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 - ▶ Bayesian posterior analysis $p(\mathbf{z}|\mathbf{y}) = p(\mathbf{y}, \mathbf{z})/p(\mathbf{y})$
- Variational inference approximates the “posterior” $p(\mathbf{z}|\mathbf{y})$ by a tractably close distribution in the Kullback-Leibler sense.
- Advantages:
 - ▶ Computationally fast
 - ▶ Convergence easily assessed
 - ▶ Works well in practice

In the literature

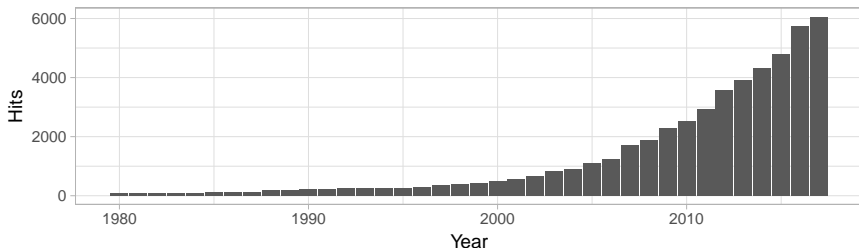
Google Scholar results for 'variational inference'



- Well known in machine learning, slowly encroaching other fields.

In the literature

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- Well known in machine learning, slowly encroaching other fields.
- Applications (Blei et al., 2017):
 - ▶ Computer vision and robotics (image denoising, tracking, recognition)
 - ▶ Natural language processing and speech recognition (topic modelling)
 - ▶ Social statistics (probit models, latent class models, variable selection)
 - ▶ Computational biology (phylogenetic hidden Markov models, population genetics, gene expression analysis)
 - ▶ Computational neuroscience (autoregressive processes, hierarchical models, spatial models, artificial neural networks)

Introductory texts

- D. M. Blei et al. (2017). “Variational Inference: A Review for Statisticians”. *J. Am. Stat. Assoc*, 112.518, pp. 859–877
- C. M. Bishop (2006). *Pattern Recognition and Machine Learning*. Springer
- K. P. Murphy (2012). *Machine Learning: A Probabilistic Perspective*. The MIT Press
- M. J. Beal (2003). “Variational algorithms for approximate Bayesian inference”. PhD thesis. Gatsby Computational Neuroscience Unit, University College London
- HJ (Oct. 2018). “Regression modelling using priors depending on Fisher information covariance kernels (I-priors)”. PhD thesis. London School of Economics and Political Science

Idea

$$p(\mathbf{z}|\mathbf{y})$$

$$q(\mathbf{z})$$

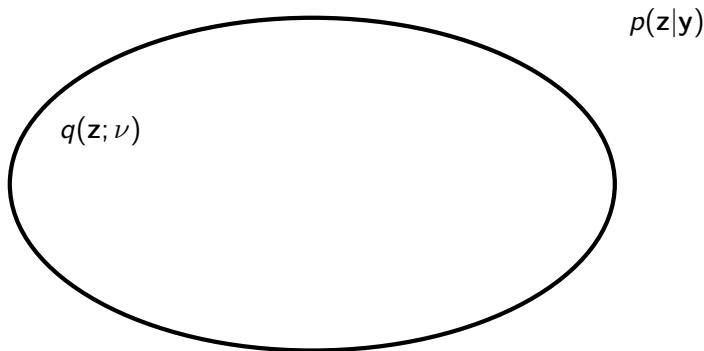
- Minimise Kullback-Leibler divergence (using calculus of variations)

$$\text{KL}(q\|p) = - \int \log \frac{p(\mathbf{z}|\mathbf{y})}{q(\mathbf{z})} q(\mathbf{z}) d\mathbf{z}.$$

- Use $\tilde{q}(\mathbf{z}; \nu^*) := \arg \min_q \text{KL}(q\|p)$ as an approximation to $p(\mathbf{z}|\mathbf{y})$.

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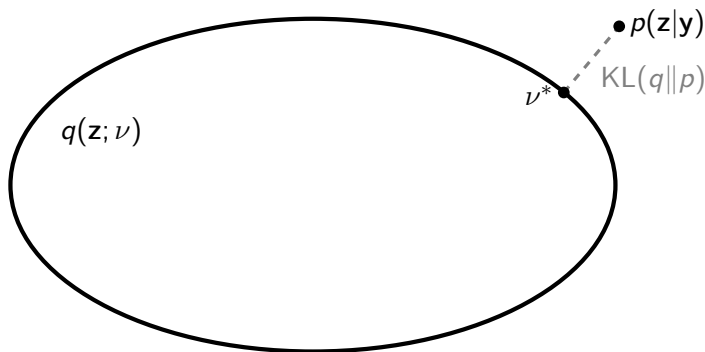
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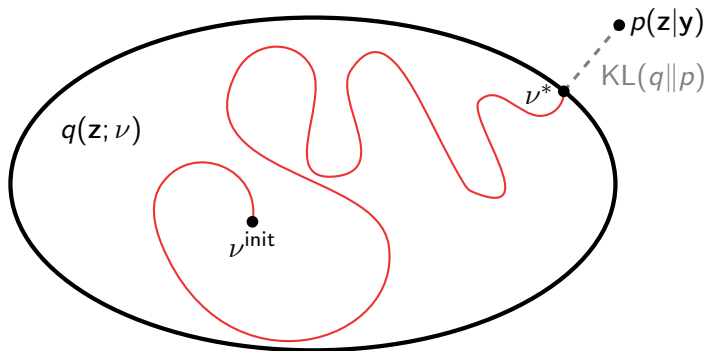
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- N.b. Equality in the bound when $q(\mathbf{z}) \equiv p(\mathbf{z}|\mathbf{y})$, and $\text{KL}(q\|p)$ vanishes (c.f. EM algorithm).

Factorised distributions (Mean-field theory)

- Maximising \mathcal{L} over all possible q not feasible. Need some restrictions, but only to achieve tractability.
- Suppose we partition elements of \mathbf{z} into M disjoint groups $\mathbf{z} = (\mathbf{z}_{[1]}, \dots, \mathbf{z}_{[M]})$, and assume

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- Under this restriction, the solution to $\arg \max_q \mathcal{L}(q)$ is

$$\tilde{q}_j(\mathbf{z}_{[j]}) \propto \exp \left(\mathbb{E}_{-j} [\log p(\mathbf{y}, \mathbf{z})] \right) \quad (1)$$

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- In practice, these unnormalised densities are of recognisable form (especially if conjugacy is considered).

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Algorithm 4 CAVI

```

1: initialise Variational factors  $q_j(\mathbf{z}_{[j]})$ 
2: while  $\mathcal{L}(q)$  not converged do
3:   for  $j = 1, \dots, M$  do
4:      $\log q_j(\mathbf{z}_{[j]}) \leftarrow \mathbb{E}_{-j}[\log p(\mathbf{y}, \mathbf{z})] + \text{const.}$  ▷ from (1)
5:   end for
6:    $\mathcal{L}(q) \leftarrow \mathbb{E}_q[\log p(\mathbf{y}, \mathbf{z})] - \mathbb{E}_q[\log q(\mathbf{z})]$ 
7: end while
8: return  $\tilde{q}(\mathbf{z}) = \prod_{j=1}^M \tilde{q}_j(\mathbf{z}_{[j]})$ 

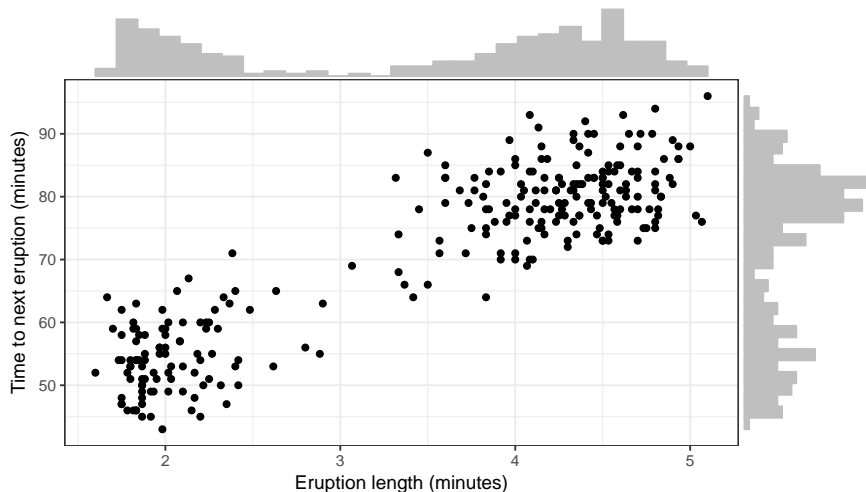
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① Introduction

② Example

③ Discussion

Gaussian mixture model (Old Faithful data set)



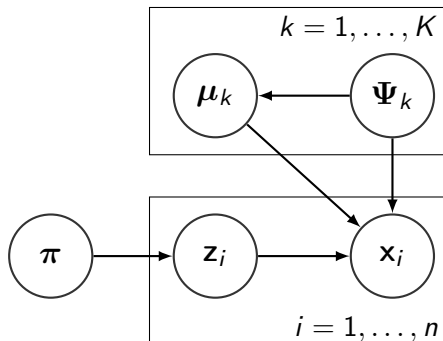
- Let $\mathbf{x}_i \in \mathbb{R}^d$ and assume $\mathbf{x}_i \stackrel{\text{iid}}{\sim} \sum_{k=1}^K \pi_k \mathcal{N}_d(\boldsymbol{\mu}_k, \boldsymbol{\Psi}_k^{-1})$ for $i = 1, \dots, n$.

Gaussian mixture model

- Introduce $\mathbf{z}_i = (z_{i1}, \dots, z_{iK})$, a 1-of- K binary vector, where each $z_{ik} \sim \text{Bern}(\pi_k)$.
- Assuming $\mathbf{z} = \{\mathbf{z}_1, \dots, \mathbf{z}_n\}$, the conditional likelihood is

$$p(\mathbf{x}|\mathbf{z}, \boldsymbol{\mu}, \boldsymbol{\Psi}) = \prod_{i=1}^n \prod_{k=1}^K \text{N}_d(\mathbf{x}_i | \boldsymbol{\mu}_k, \boldsymbol{\Psi}_k^{-1})^{z_{ik}}.$$

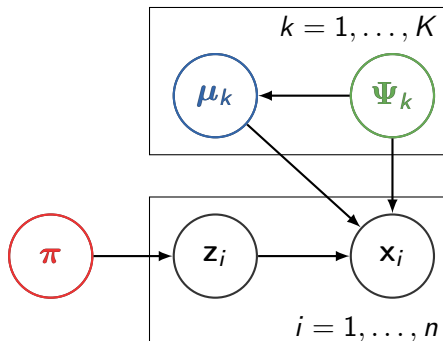
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Gaussian mixture model



$$\begin{aligned}
 p(\mathbf{x}, \mathbf{z}, \boldsymbol{\pi}, \boldsymbol{\mu}, \boldsymbol{\Psi}) &= p(\mathbf{x}|\mathbf{z}, \boldsymbol{\mu}, \boldsymbol{\Psi})p(\mathbf{z}|\boldsymbol{\pi}) \\
 &\quad \times p(\boldsymbol{\pi})p(\boldsymbol{\mu}|\boldsymbol{\Psi})p(\boldsymbol{\Psi}) \\
 &= p(\mathbf{x}|\mathbf{z}, \boldsymbol{\mu}, \boldsymbol{\Psi})p(\mathbf{z}|\boldsymbol{\pi}) \\
 &\quad \times \text{Dir}_K(\boldsymbol{\pi}|\alpha_{01}, \dots, \alpha_{0K}) \\
 &\quad \times \prod_{k=1}^K \text{N}_d(\boldsymbol{\mu}_k|\mathbf{m}_0, (\kappa_0 \boldsymbol{\Psi}_k)^{-1}) \\
 &\quad \times \prod_{k=1}^K \text{Wis}_d(\boldsymbol{\Psi}_k|\mathbf{W}_0, \nu_0)
 \end{aligned}$$

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Variational inference for GMM

- Assume the mean-field posterior density

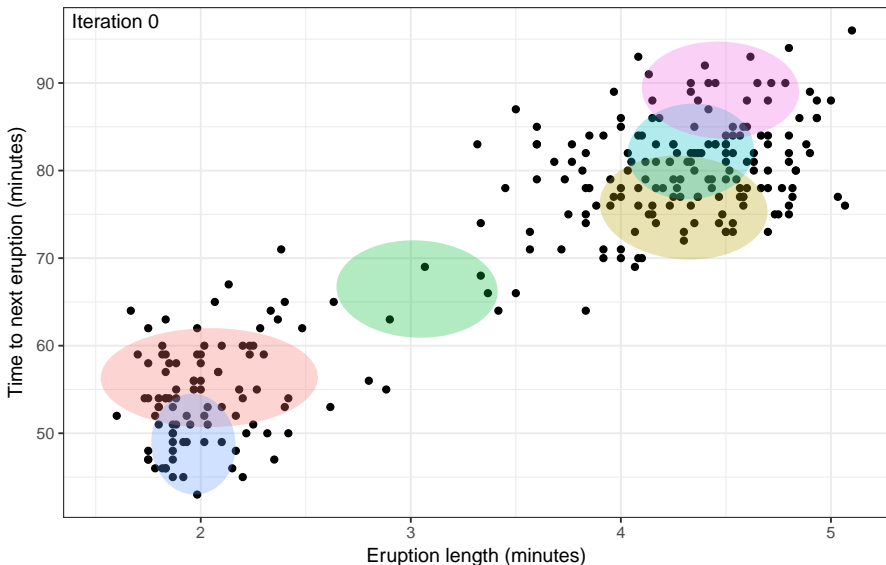
$$\begin{aligned}q(\mathbf{z}, \boldsymbol{\pi}, \boldsymbol{\mu}, \boldsymbol{\Psi}) &= q(\mathbf{z})q(\boldsymbol{\pi}, \boldsymbol{\mu}, \boldsymbol{\Psi}) \\ &= q(\mathbf{z})q(\boldsymbol{\pi})q(\boldsymbol{\mu}|\boldsymbol{\Psi})q(\boldsymbol{\Psi}).\end{aligned}$$

Algorithm 5 CAVI for GMM

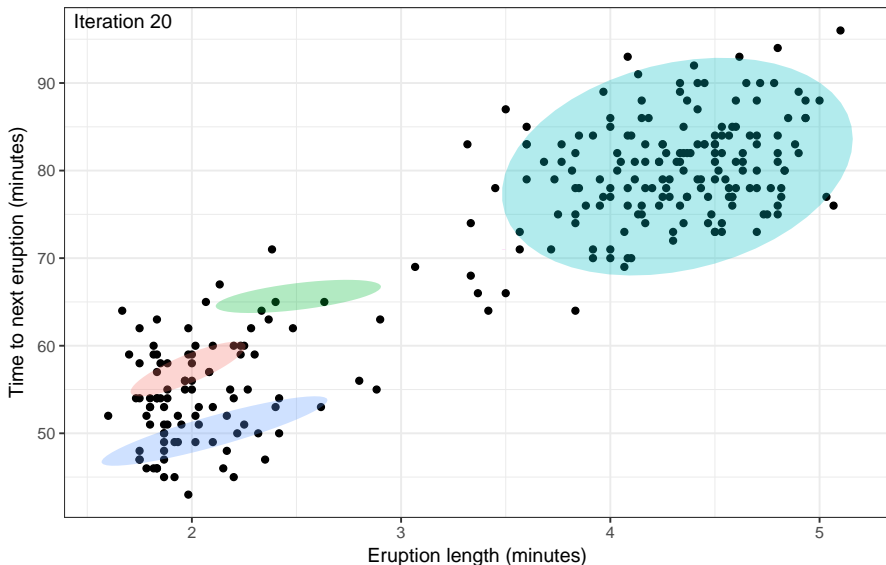
[details](#)

- initialise** Variational factors $q(\mathbf{z})$, $q(\boldsymbol{\pi})$ and $q(\boldsymbol{\mu}, \boldsymbol{\Psi})$
 - while** $\mathcal{L}(q)$ not converged **do**
 - $q(z_{ik}) \leftarrow \text{Bern}(\cdot)$
 - $q(\boldsymbol{\pi}) \leftarrow \text{Dir}_K(\cdot)$
 - $q(\boldsymbol{\mu}|\boldsymbol{\Psi}) \leftarrow \text{N}_d(\cdot, \cdot)$
 - $q(\boldsymbol{\Psi}) \leftarrow \text{Wis}_d(\cdot, \cdot)$
 - $\mathcal{L}(q) \leftarrow \mathbb{E}_q[\log p(\mathbf{x}, \mathbf{z}, \boldsymbol{\pi}, \boldsymbol{\mu}, \boldsymbol{\Psi})] - \mathbb{E}_q[\log q(\mathbf{z}, \boldsymbol{\pi}, \boldsymbol{\mu}, \boldsymbol{\Psi})]$
 - end while**
 - return** $\tilde{q}(\mathbf{z}, \boldsymbol{\pi}, \boldsymbol{\mu}, \boldsymbol{\Psi}) = \tilde{q}(\mathbf{z})\tilde{q}(\boldsymbol{\pi})\tilde{q}(\boldsymbol{\mu}|\boldsymbol{\Psi})\tilde{q}(\boldsymbol{\Psi})$
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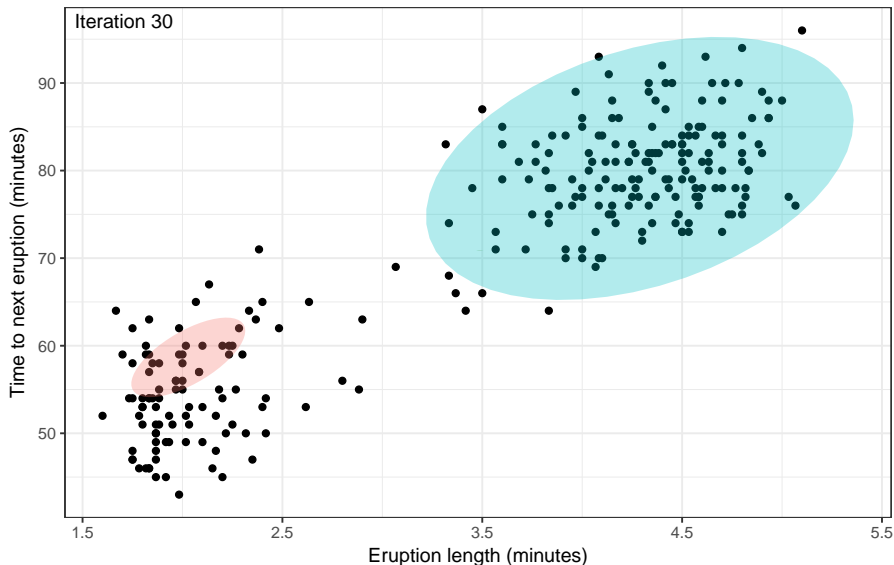
Variational inference for GMM (cont.)



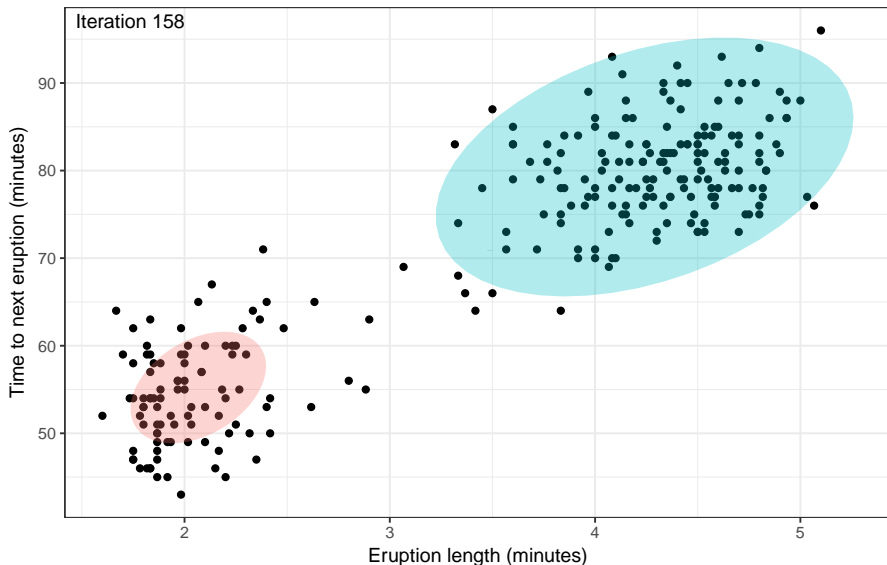
Variational inference for GMM (cont.)



Variational inference for GMM (cont.)



Variational inference for GMM (cont.)



Final thoughts on variational GMM

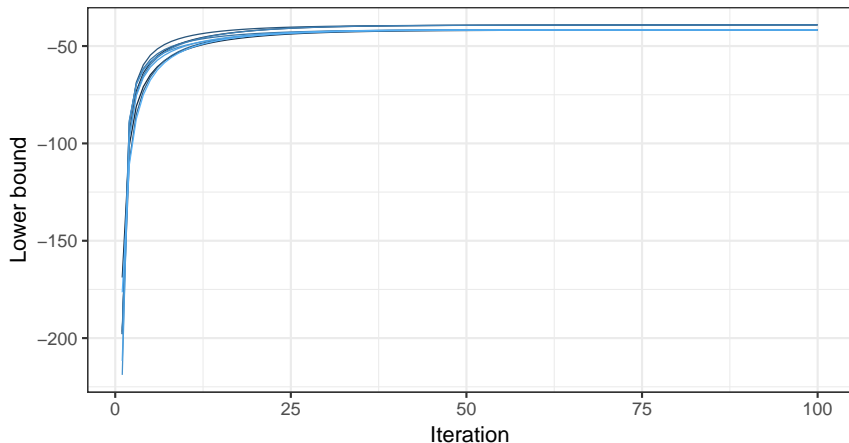
- Similar algorithm to the EM, and therefore similar computational time.
- Can extend to mixture of bernoullis a.k.a. latent class analysis.
- **PROS:**
 - ▶ Automatic selection of number of mixture components.
 - ▶ Less pathological special cases compared to EM solutions because regularised by prior information.
 - ▶ Less sensitive to number of parameters/components.
- **CONS:**
 - ▶ Hyperparameter tuning.

① Introduction

② Example

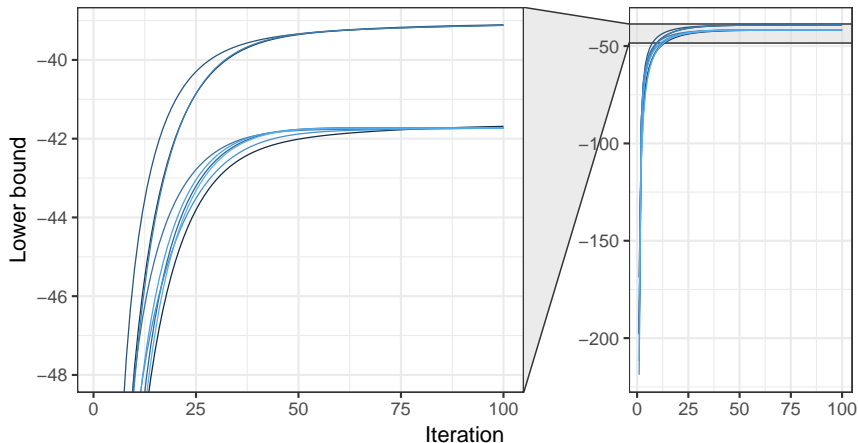
③ Discussion

Non-convexity of ELBO



- CAVI only guarantees converges to a local optimum.
- Multiple local optima may exist.

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Zero-forcing vs Zero-avoiding

- Back to the KL divergence:

$$\text{KL}(q\|p) = \int \log \frac{q(\mathbf{z})}{p(\mathbf{z}|\mathbf{y})} q(\mathbf{z}) \, d\mathbf{z}$$

- $\text{KL}(q\|p)$ is large when $p(\mathbf{z}|\mathbf{y})$ is close to zero, unless $q(\mathbf{z})$ is also close to zero (*zero-forcing*).
- What about other measures of closeness?

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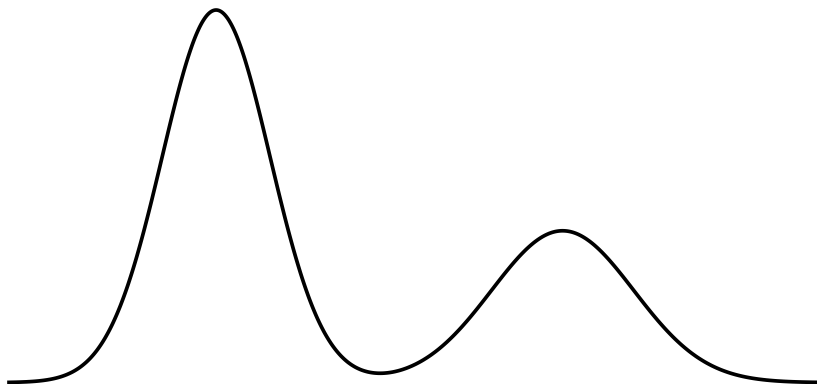
- $\text{KL}(q\|p)$ is large when $p(\mathbf{z}|\mathbf{y})$ is close to zero, unless $q(\mathbf{z})$ is also close to zero (*zero-forcing*).
- What about other measures of closeness? For instance,

$$\text{KL}(p\|q) = \int \log \frac{p(\mathbf{z}|\mathbf{y})}{q(\mathbf{z}|\mathbf{y})} p(\mathbf{z}|\mathbf{y}) d\mathbf{z}.$$

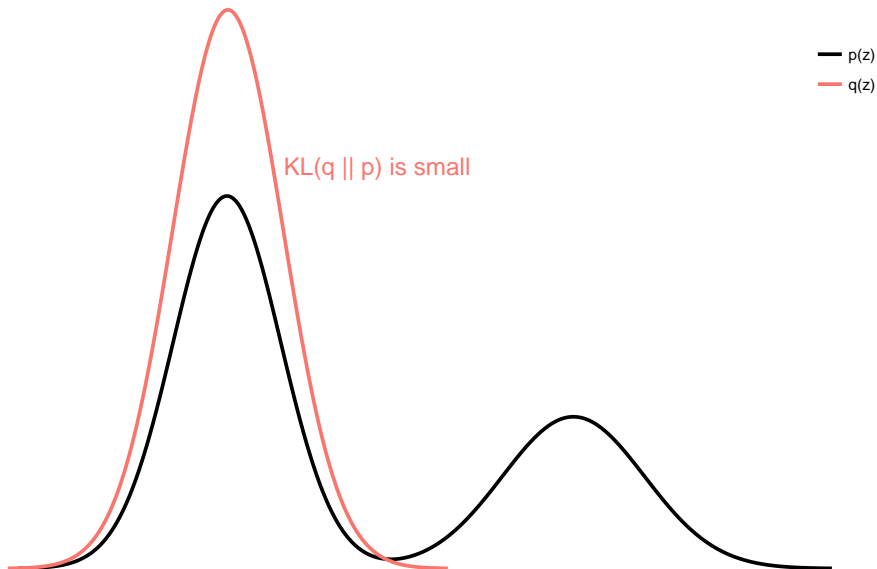
- This gives the Expectation Propagation (EP) algorithm.
- It is *zero-avoiding*, because $\text{KL}(p\|q)$ is small when both $p(\mathbf{z}|\mathbf{y})$ and $q(\mathbf{z})$ are non-zero.

Zero-forcing vs Zero-avoiding (cont.)

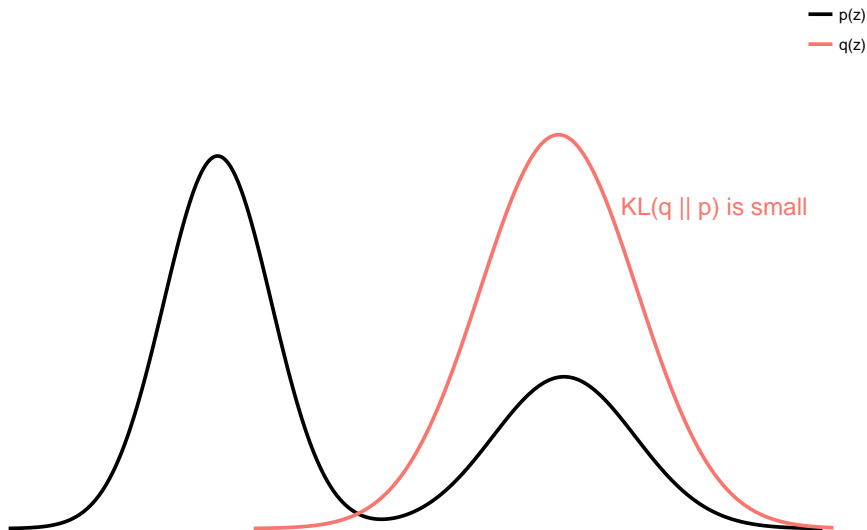
— $p(z)$



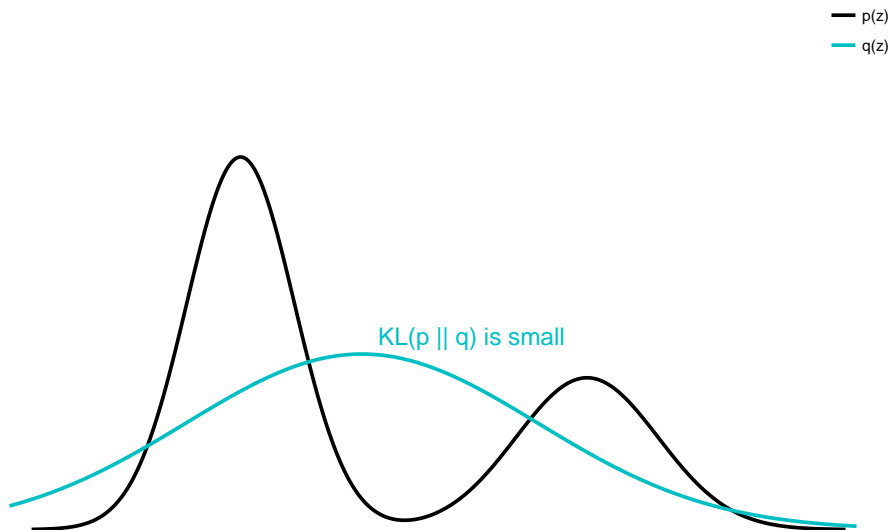
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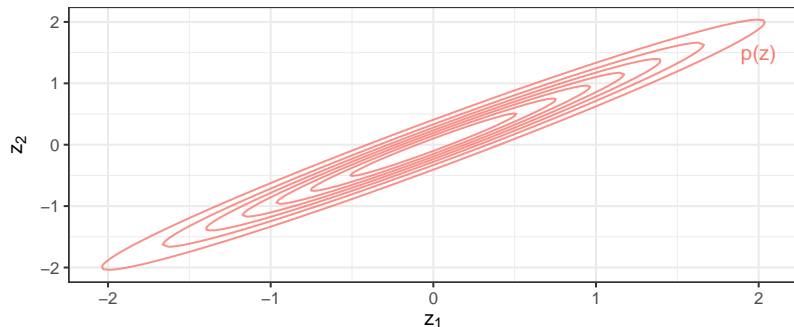
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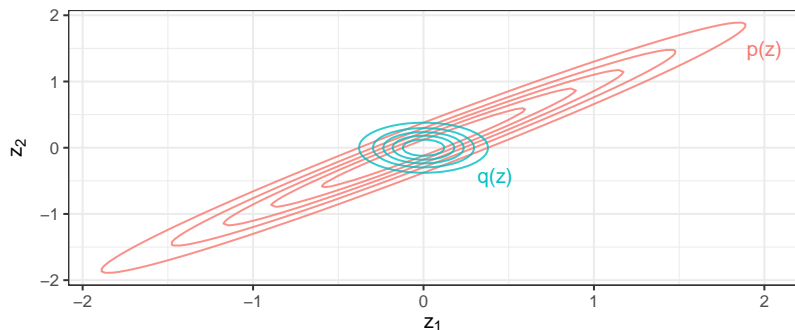


Distortion of higher order moments



- Consider $\mathbf{z} = (z_1, z_2)^\top \sim N_2(\boldsymbol{\mu}, \boldsymbol{\Psi}^{-1})$, $\text{Cov}(z_1, z_2) \neq 0$.

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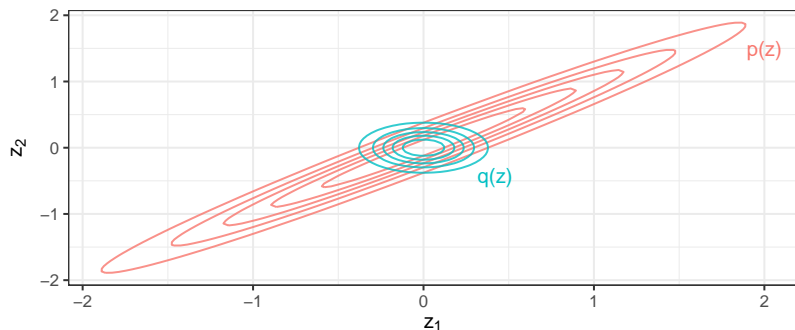


- Consider $\mathbf{z} = (z_1, z_2)^\top \sim N_2(\boldsymbol{\mu}, \boldsymbol{\Psi}^{-1})$, $\text{Cov}(z_1, z_2) \neq 0$.
- Approximating $p(\mathbf{z})$ by $q(\mathbf{z}) = q_1(z_1)q_2(z_2)$ yields

$$\tilde{q}_1(z_1) = N(z_1 | \mu_1, \psi_{11}^{-1}) \quad \text{and} \quad \tilde{q}_2(z_2) = N(z_2 | \mu_2, \psi_{22}^{-1})$$

and by definition, $\text{Cov}(z_1, z_2) = 0$ under \tilde{q} .

Distortion of higher order moments



- Consider $\mathbf{z} = (z_1, z_2)^\top \sim N_2(\boldsymbol{\mu}, \boldsymbol{\Psi}^{-1})$, $\text{Cov}(z_1, z_2) \neq 0$.
- Approximating $p(\mathbf{z})$ by $q(\mathbf{z}) = q_1(z_1)q_2(z_2)$ yields

$$\tilde{q}_1(z_1) = N(z_1 | \mu_1, \psi_{11}^{-1}) \quad \text{and} \quad \tilde{q}_2(z_2) = N(z_2 | \mu_2, \psi_{22}^{-1})$$

and by definition, $\text{Cov}(z_1, z_2) = 0$ under \tilde{q} .

- This leads to underestimation of variances (widely reported in the literature—Zhao and Marriott, 2013).

Quality of approximation

- Variational inference converges to a different optimum than ML, except for certain models (Gunawardana and Byrne, 2005).

Quality of approximation

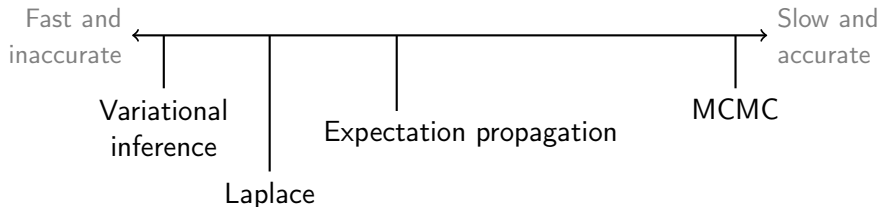
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- Speed trumps accuracy?



End

Thank you!

Slides and source code are made available at: <http://socialstats.haziqj.ml>

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④ Additional material

- The variational principle

- Comparison to EM

- The EM algorithm

- Laplace's method

- Solutions to Gaussian mixture

The variational principle

- Name derived from calculus of variations which deals with maximising or minimising functionals.

Functions $p : \theta \mapsto \mathbb{R}$ (standard calculus)

Functionals $\mathcal{H} : p \mapsto \mathbb{R}$ (variational calculus)

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- Using variational calculus, we can solve

$$\arg \max_p \mathcal{H}(p) =: \tilde{p}$$

e.g. \mathcal{H} is the entropy $\mathcal{H} = - \int p(x) \log p(x) dx$, and \tilde{p} is the entropy maximising distribution.

Comparison to the EM algorithm

- In addition to latent variables \mathbf{z} , typically there are unknown parameters θ to be estimated.
 - ▶ Frequentist estimation: θ is fixed
 - ▶ Bayesian estimation: $\theta \sim p(\theta)$ is random
- Consider θ fixed. Maximising the (marginal) log-likelihood directly

$$\arg \max_{\theta} \log \left\{ \int \overbrace{p(\mathbf{y}|\mathbf{z}, \theta)p(\mathbf{z}|\theta)}^{p(\mathbf{y}, \mathbf{z})} d\mathbf{z} \right\}$$

is difficult. However, if somehow the latent variables were known, then the problem may become easier.

- Given initial values $\theta^{(0)}$, the EM algorithm cycles through
 - ▶ **E-step**: Compute $Q(\theta|\theta^{(t)}) := \mathbb{E}_{\mathbf{z}}[\log p(\mathbf{y}, \mathbf{z}|\theta) | \mathbf{y}, \theta^{(t)}]$
 - ▶ **M-step**: $\theta^{(t+1)} \leftarrow \arg \max_{\theta} Q(\theta|\theta^{(t)})$
 for $t = 1, 2, \dots$ until convergence.

Comparison to the EM algorithm (cont.)

Variational inference/Bayes	(Variational) EM algorithm
GOAL: Posterior densities for (\mathbf{w}, θ)	GOAL: ML/MAP estimates for θ
Variational approximation for latent variables and parameters $q(\mathbf{w}, \theta) \approx p(\mathbf{w}, \theta \mathbf{y})$	Variational approximation for latent variables only $q(\mathbf{w}) \approx p(\mathbf{w} \mathbf{y})$
Priors required on θ	Priors not necessary for θ
Derivation can be tedious	Derivation less tedious
Inference on θ through (approximate) posterior density $q(\theta)$	Asymptotic distribution of θ not well studied; standard errors for θ not easily obtained

Laplace's method

- Interested in $p(\mathbf{f}|\mathbf{y}) \propto p(\mathbf{y}|\mathbf{f})p(\mathbf{f}) =: e^{Q(\mathbf{f})}$, with normalising constant $p(\mathbf{y}) = \int e^{Q(\mathbf{f})} d\mathbf{f}$. The Taylor expansion of Q about its mode $\tilde{\mathbf{f}}$

$$Q(\mathbf{f}) \approx Q(\tilde{\mathbf{f}}) - \frac{1}{2}(\mathbf{f} - \tilde{\mathbf{f}})^\top \mathbf{A}(\mathbf{f} - \tilde{\mathbf{f}})$$

is recognised as the logarithm of an unnormalised Gaussian density, with $\mathbf{A} = -D^2Q(\mathbf{f})$ being the negative Hessian of Q evaluated at $\tilde{\mathbf{f}}$.

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- The posterior $p(\mathbf{f}|\mathbf{y})$ is approximated by $N(\tilde{\mathbf{f}}, \mathbf{A}^{-1})$, and the marginal by

$$p(\mathbf{y}) \approx (2\pi)^{n/2} |\mathbf{A}|^{-1/2} p(\mathbf{y}|\tilde{\mathbf{f}}) p(\tilde{\mathbf{f}})$$

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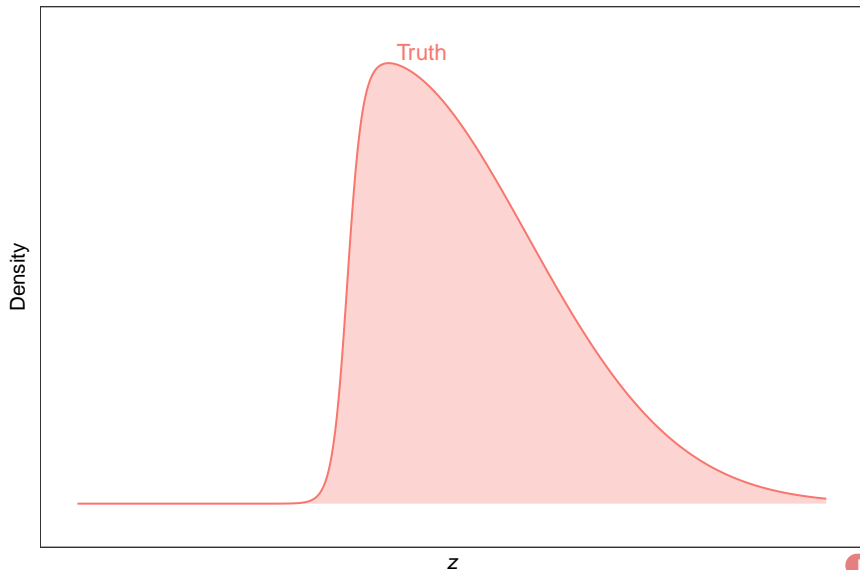
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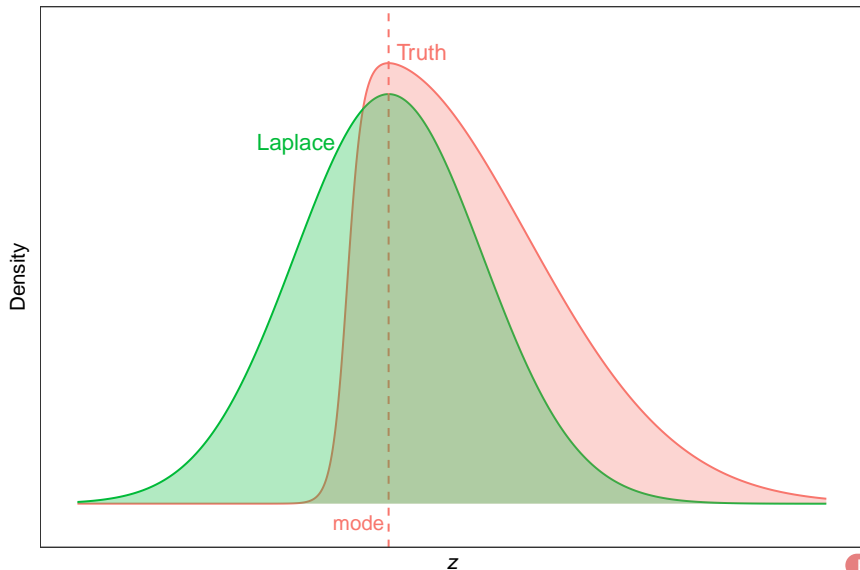
- Won't scale with large n ; difficult to find modes in high dimensions.

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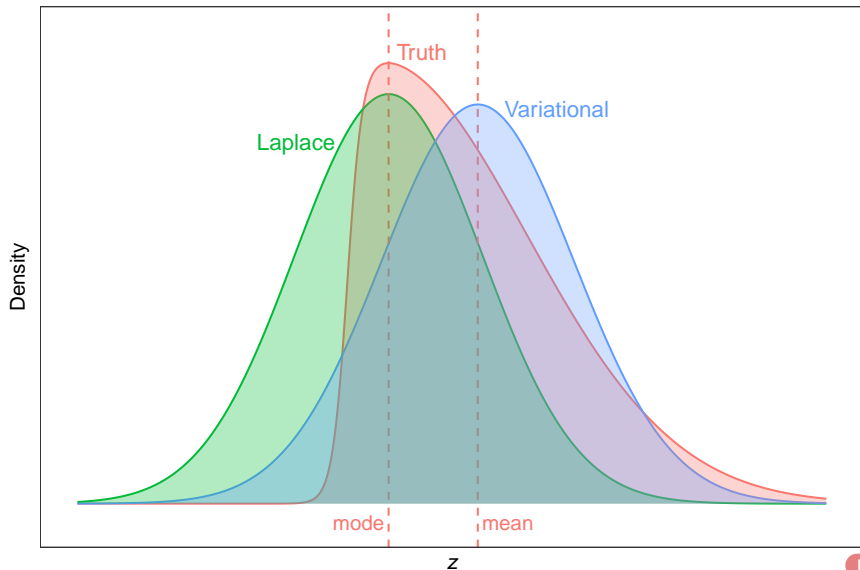
Comparison of approximations (density)



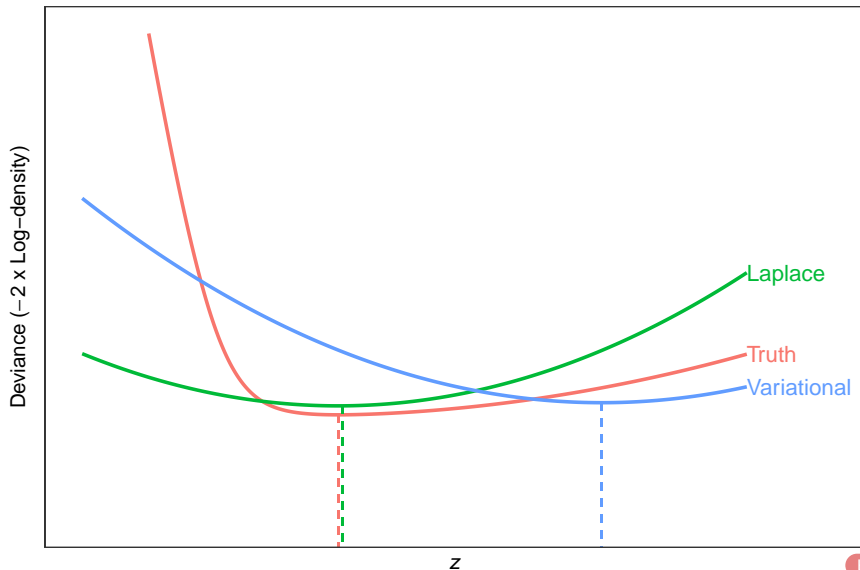
Comparison of approximations (density)



Comparison of approximations (density)



Comparison of approximations (deviance)



Variational solutions to Gaussian mixture model

Variational M-step

$$\tilde{q}(\mathbf{z}) = \prod_{i=1}^n \prod_{k=1}^K r_{ik}^{z_{ik}}, \quad r_{ik} = \rho_{ik} / \sum_{k=1}^K \rho_{ik}$$

$$\begin{aligned} \log \rho_{ik} = & \mathbb{E}[\log \pi_k] + \frac{1}{2} \mathbb{E}[\log |\Psi_k|] - \frac{d}{2} \log 2\pi \\ & - \frac{1}{2} \mathbb{E}[(\mathbf{x}_i - \boldsymbol{\mu}_k)^\top \Psi_k (\mathbf{x}_i - \boldsymbol{\mu}_k)] \end{aligned}$$

Variational E-step

$$\tilde{q}(\pi_1, \dots, \pi_K) = \text{Dir}_K(\boldsymbol{\pi} | \tilde{\boldsymbol{\alpha}}), \quad \tilde{\alpha}_k = \alpha_{0k} + \sum_{i=1}^n r_{ik}$$

$$\tilde{q}(\boldsymbol{\mu}, \Psi) = \prod_{k=1}^K \text{N}_d(\boldsymbol{\mu}_k | \tilde{\mathbf{m}}_k, (\tilde{\kappa}_k \Psi_k)^{-1}) \text{Wis}_d(\Psi_k | \tilde{\mathbf{W}}_k, \tilde{\nu}_k)$$

Variational solutions to Gaussian mixture model (cont.)

$$\begin{aligned}\tilde{\kappa}_k &= \kappa_0 + \sum_{i=1}^n r_{ik} \\ \tilde{\mathbf{m}}_k &= (\kappa_0 \mathbf{m}_0 + \sum_{i=1}^n r_{ik} \mathbf{x}_i) / \tilde{\kappa}_k \\ \mathbf{W}_k^{-1} &= \mathbf{W}_0^{-1} + \sum_{i=1}^n r_{ik} (\mathbf{x}_i - \bar{\mathbf{x}}_k)(\mathbf{x}_i - \bar{\mathbf{x}}_k)^\top \\ \bar{\mathbf{x}}_k &= \sum_{i=1}^n r_{ik} \mathbf{x}_i / \sum_{i=1}^n r_{ik} \\ \nu_k &= \nu_0 + \sum_{i=1}^n r_{ik}\end{aligned}$$

Also useful

$$\mathbb{E} \left[(\mathbf{x}_i - \boldsymbol{\mu}_k)^\top \boldsymbol{\Psi}_k (\mathbf{x}_i - \boldsymbol{\mu}_k) \right] = d / \tilde{\kappa}_k + \nu_k (\mathbf{x}_i - \tilde{\mathbf{m}}_k)^\top \tilde{\mathbf{W}}_k (\mathbf{x}_i - \tilde{\mathbf{m}}_k)$$

$$\mathbb{E}[\log \pi_k] = \sum_{i=1}^d \psi \left(\frac{\nu_k + 1 - i}{2} \right) + d \log 2 + \log |\tilde{\mathbf{W}}_k|$$

$$\mathbb{E}[\log |\boldsymbol{\Psi}_k|] = \psi(\tilde{\alpha}_k) - \psi\left(\sum_{k=1}^K \tilde{\alpha}_k\right), \quad \psi(\cdot) \text{ is the digamma function}$$