

Optimizing the Relevance-Redundancy Tradeoff for Efficient Semantic Segmentation

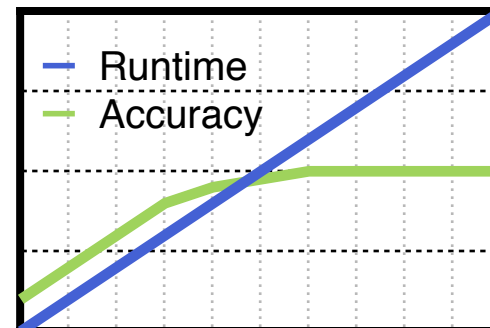
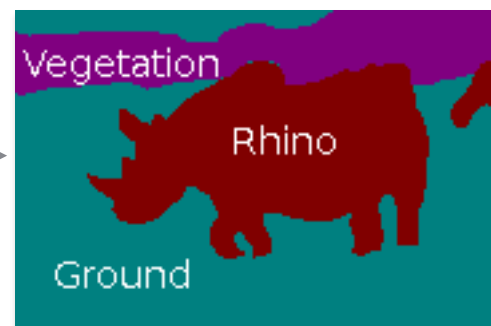
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Joint work with Julia Diebold and Daniel Cremers



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$$\min E = \min \{ \lambda \cdot \boxed{D} + R \}$$

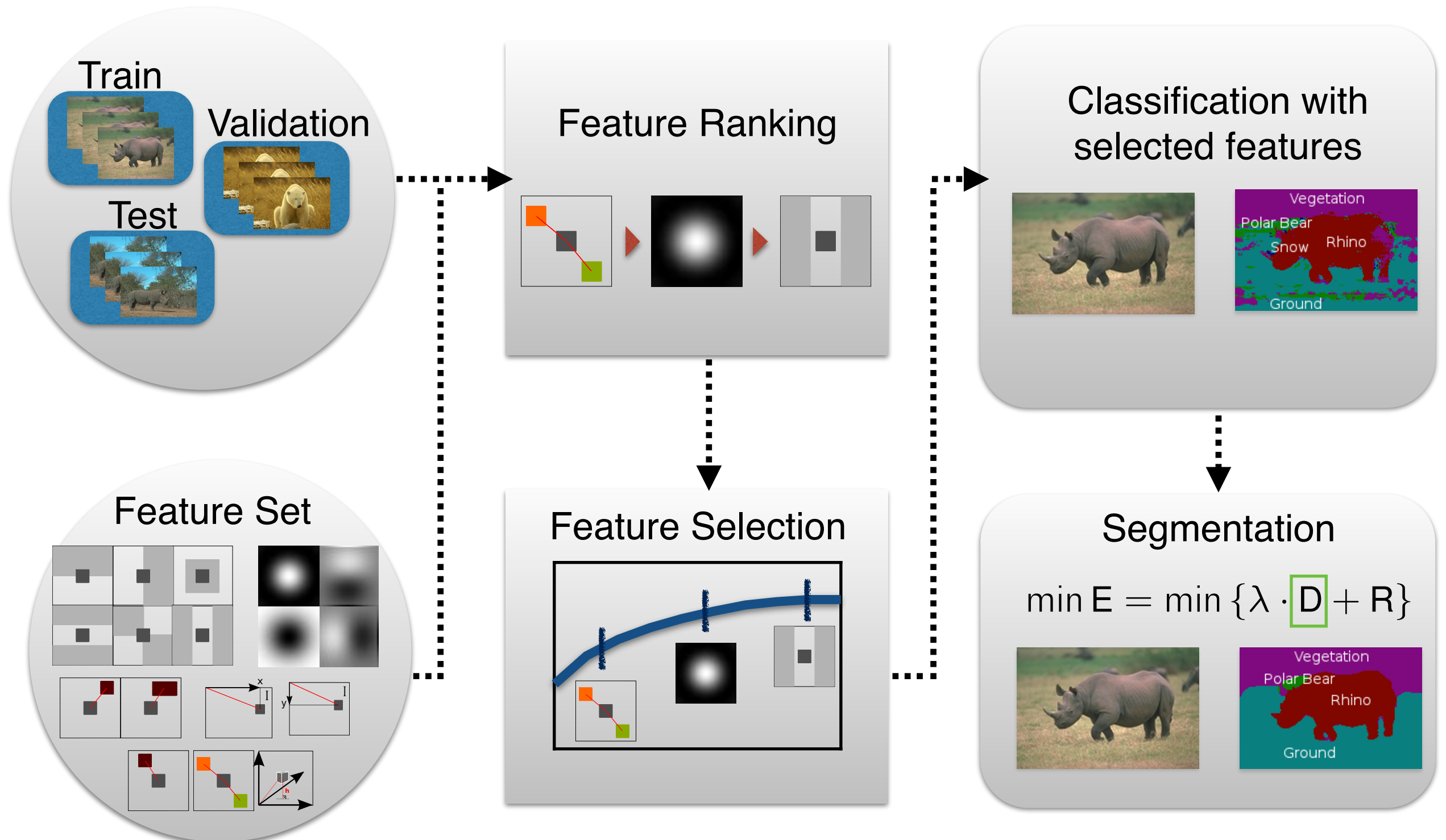


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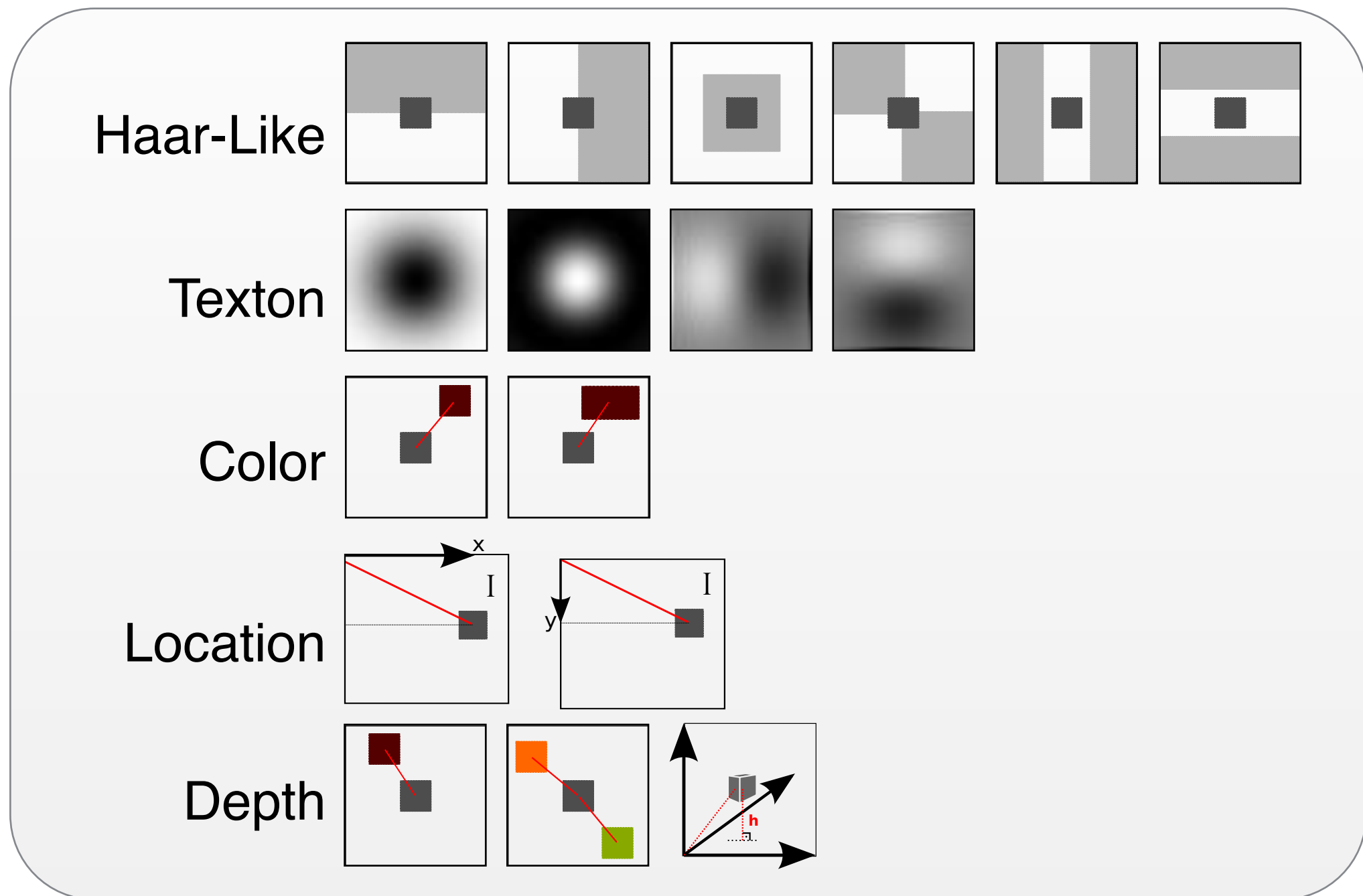
Joint work with Julia Diebold and Daniel Cremers



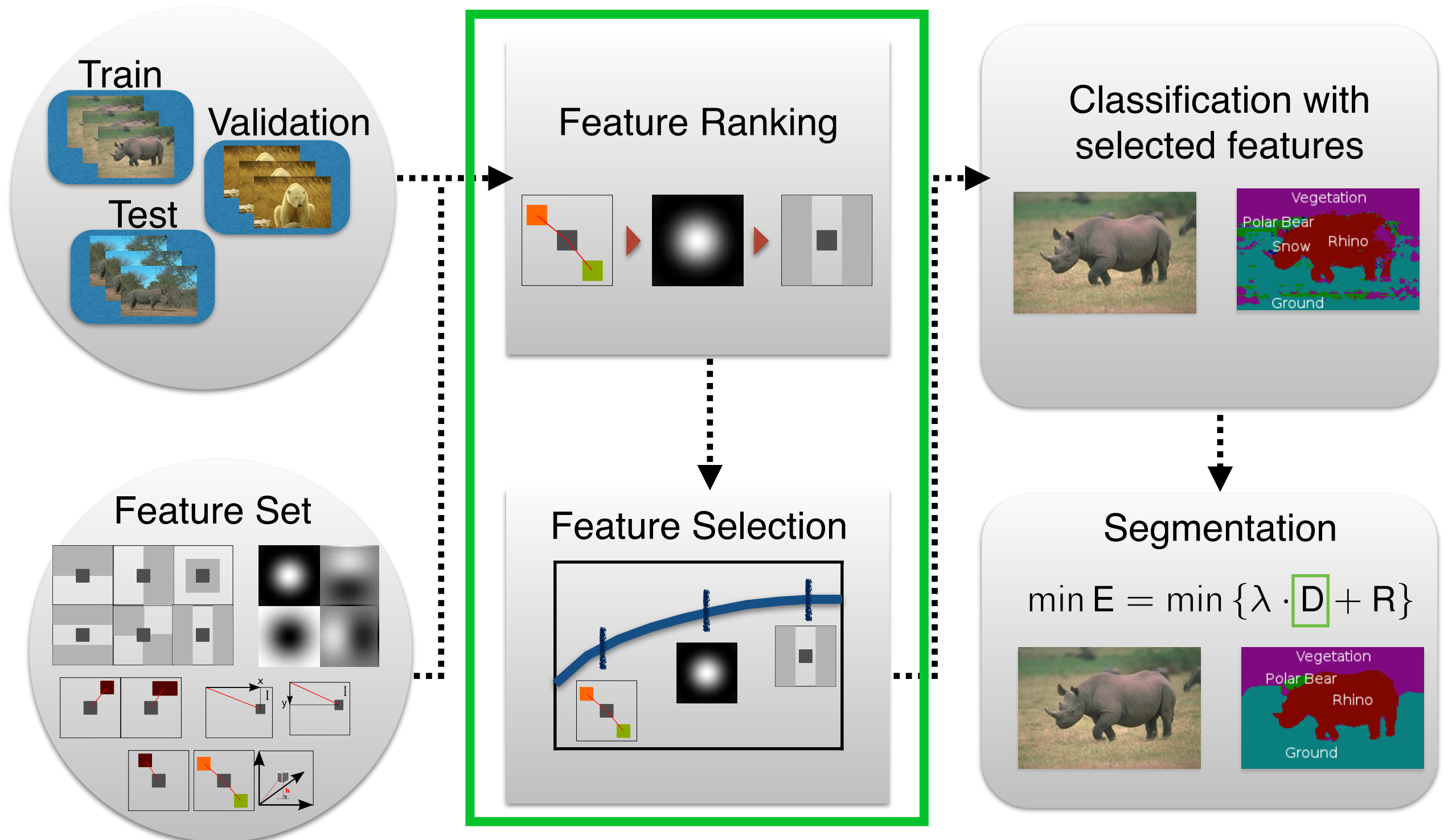
Optimizing the Relevance-Redundancy Tradeoff



Feature Set



Feature Analysis



Feature Ranking

Objective:

- maximize the relevance between the feature and its class
- minimize the redundancy between the feature pairs

$\max \Phi (\text{Rel}, \text{Red}) ,$

$\Phi = \text{Relevance} - \text{Redundancy}$

$$= \text{MI} (f_i; \text{class}) - \frac{1}{m-1} \sum_{i \neq j} \text{MI} (f_i; f_j)$$

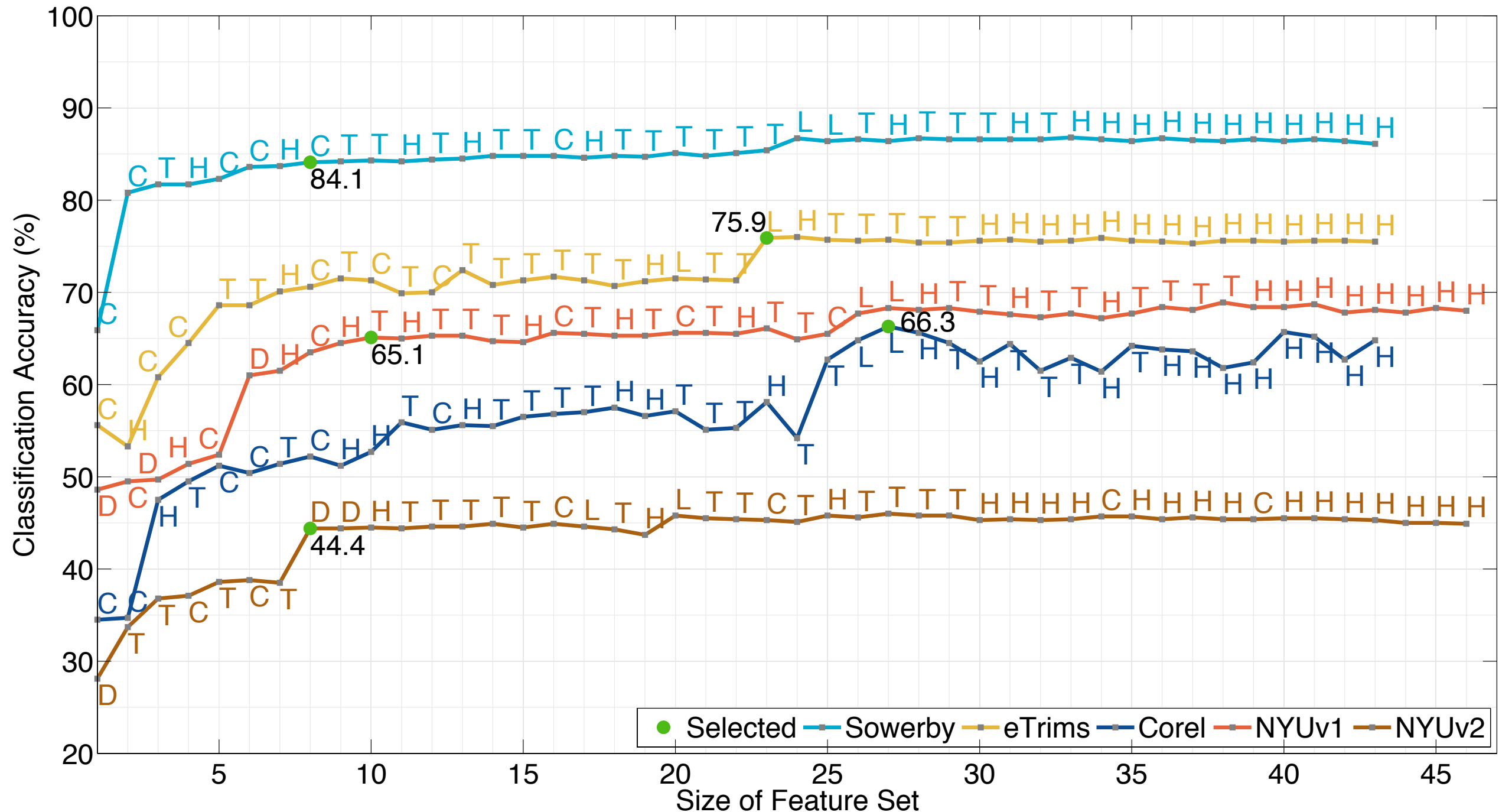
$$\text{MI} (X; Y) = \int_Y \int_X \log \frac{p(x, y)}{p(x) p(y)} dx dy$$

Ranking:

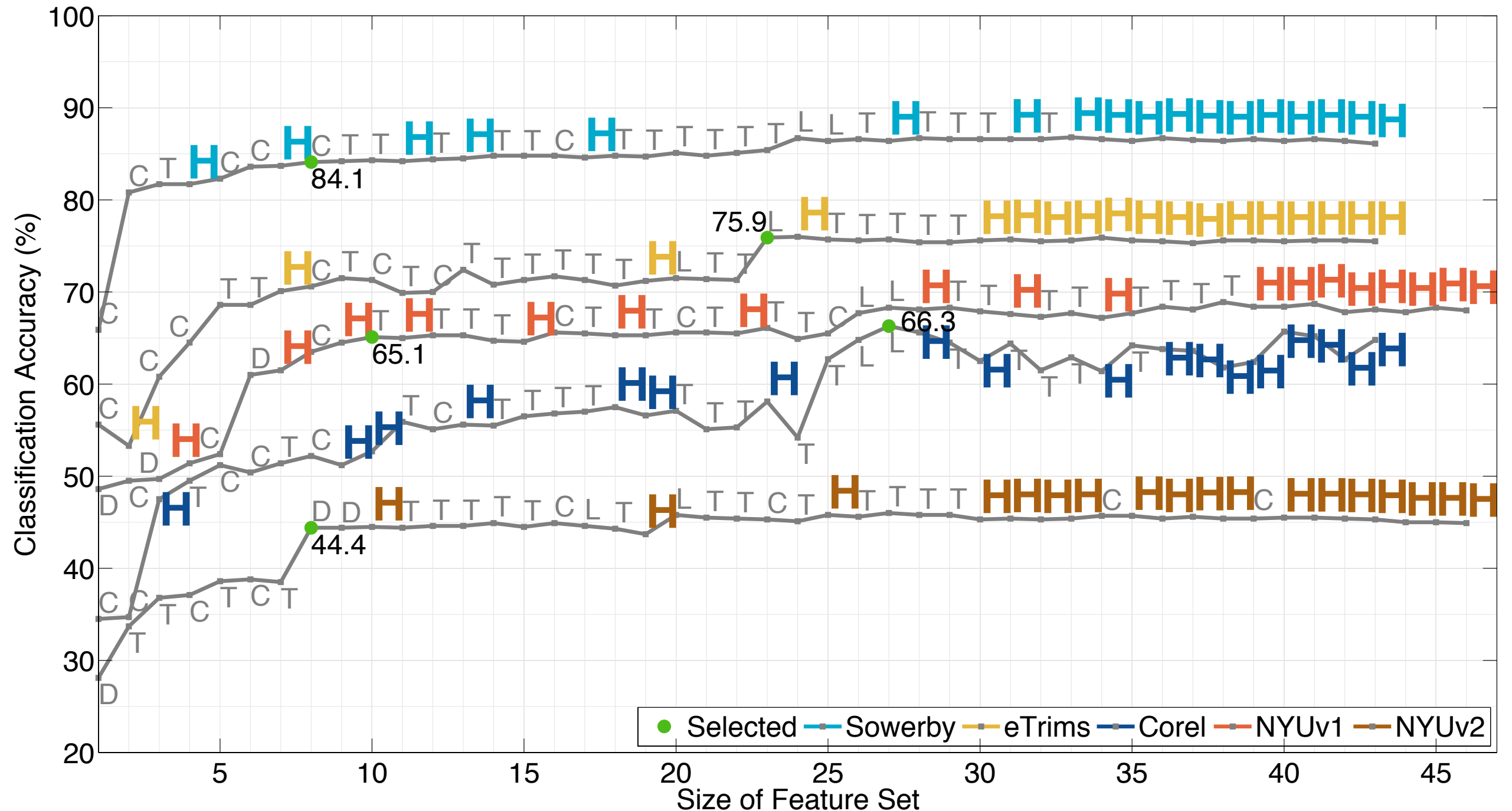
- iteratively rank the features, select one feature at a time
- maximize the objective function at each iteration:

$$f_m = \arg \max_{f_i \in \mathcal{F} \setminus \mathcal{F}_{m-1}} \left[\text{MI} (f_i; c) - \frac{1}{m-1} \sum_{f_j \in \mathcal{F}_{m-1}} \text{MI} (f_i; f_j) \right]$$

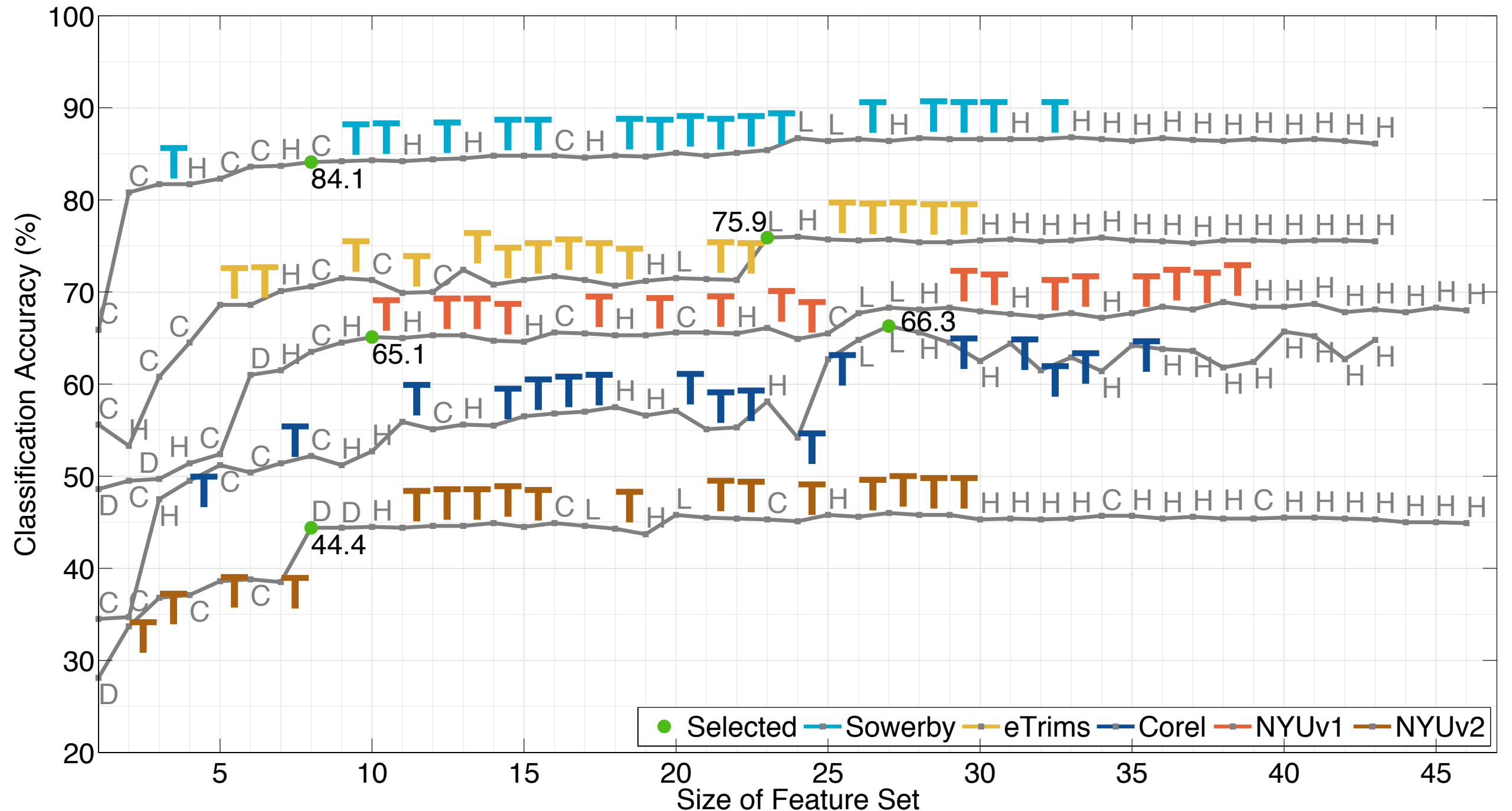
Incremental Feature Analysis



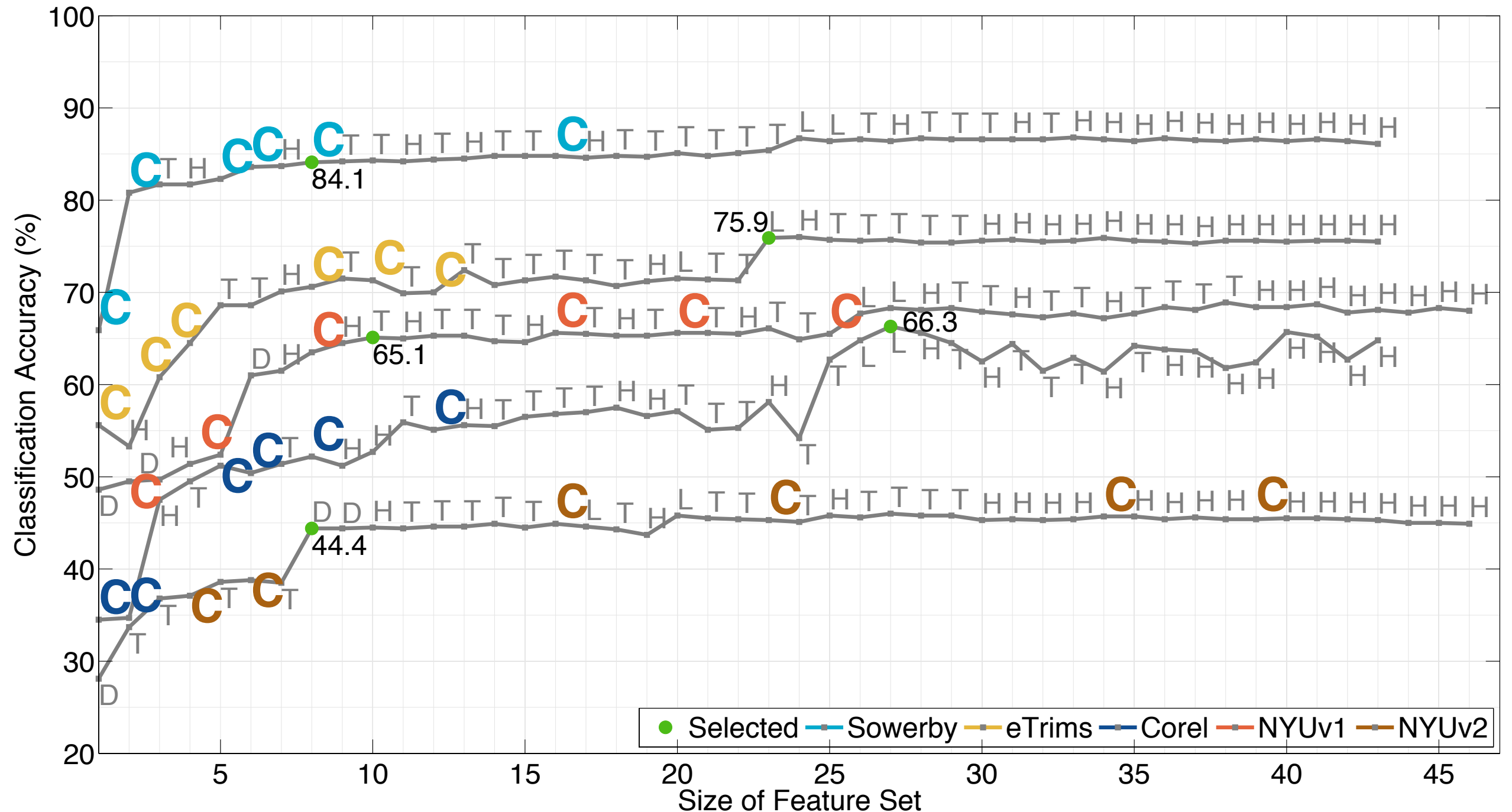
Relevance of Haar-Like Features



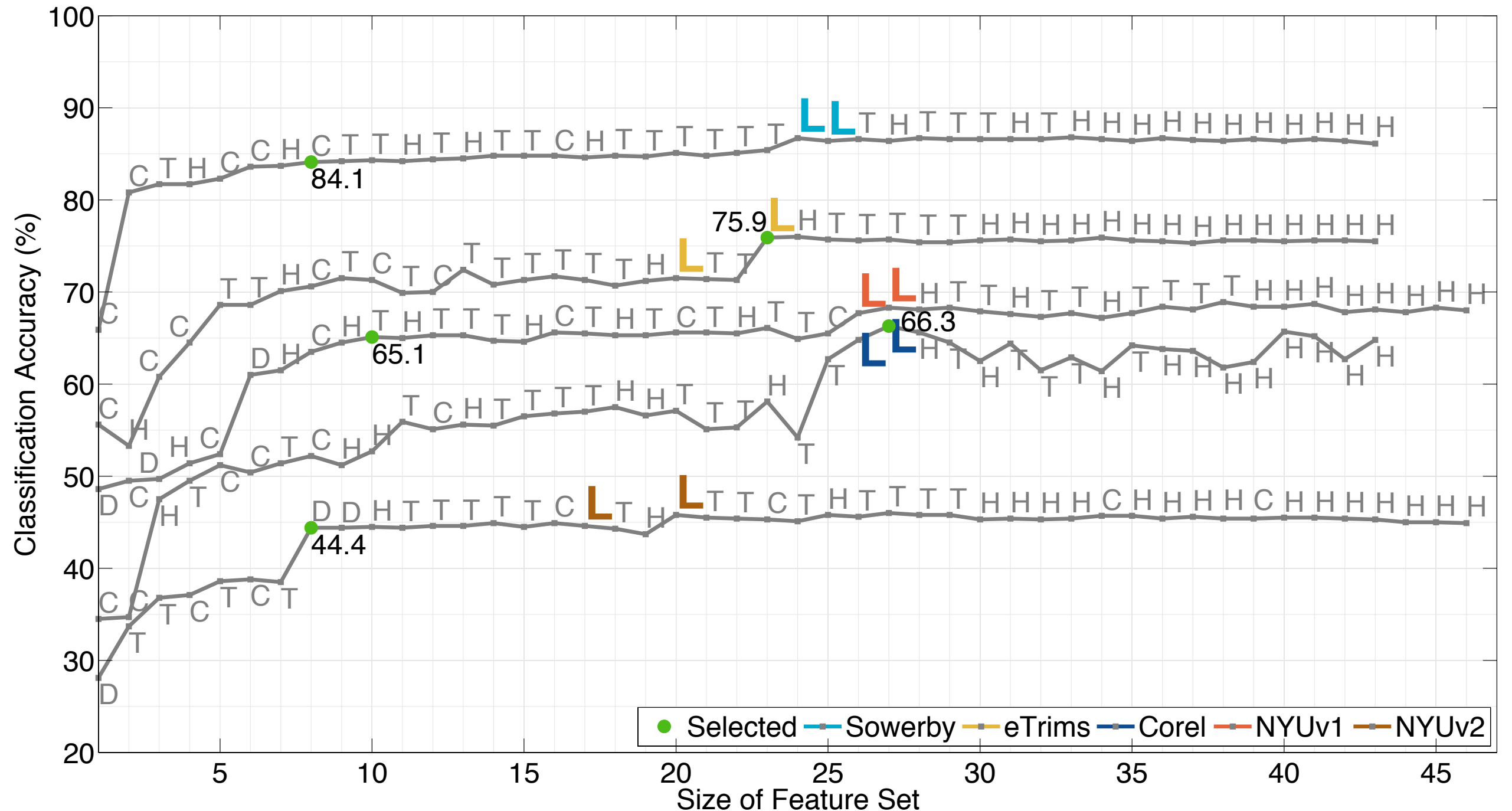
Relevance of Texton Features



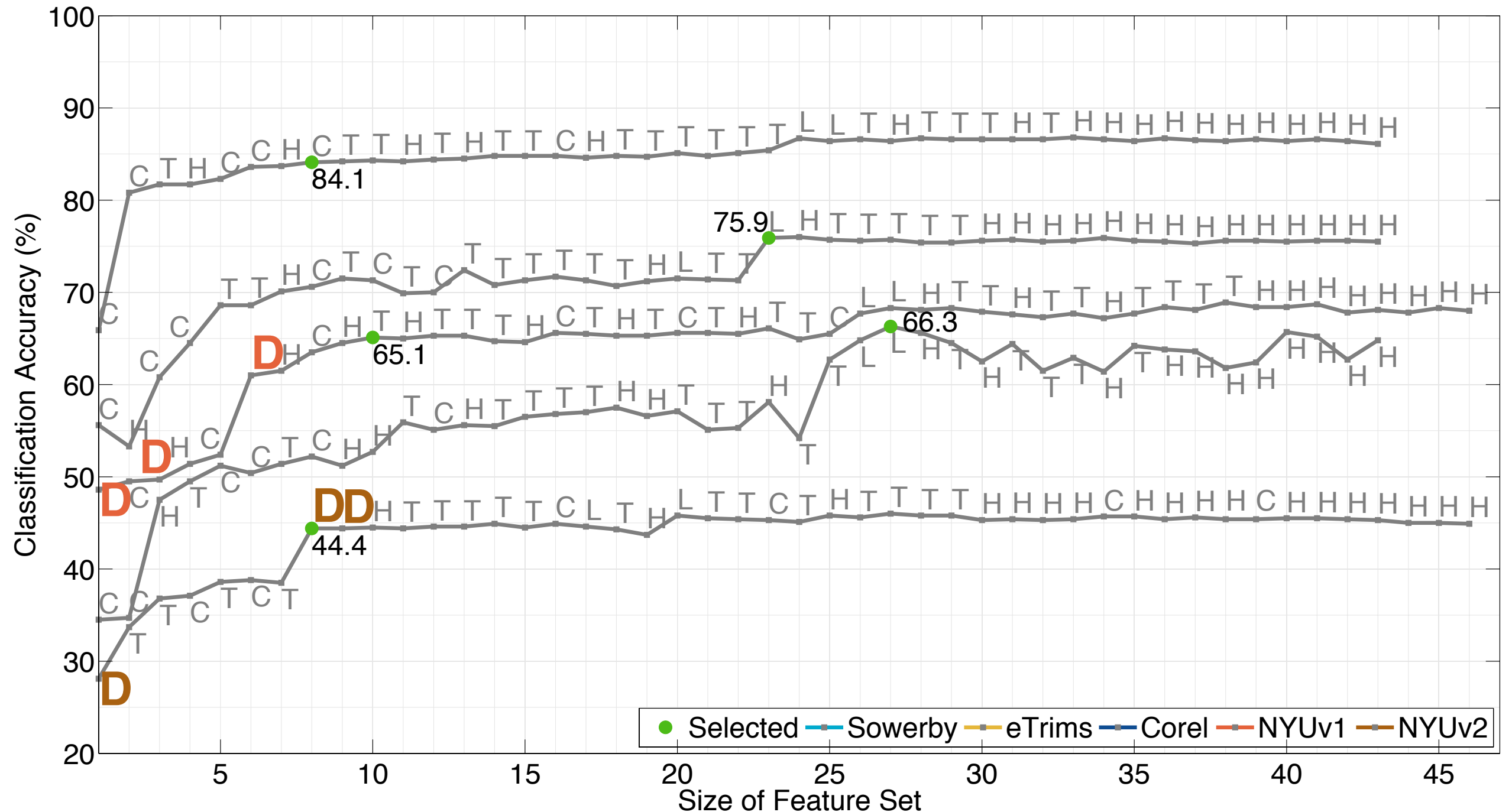
Relevance of Color Features



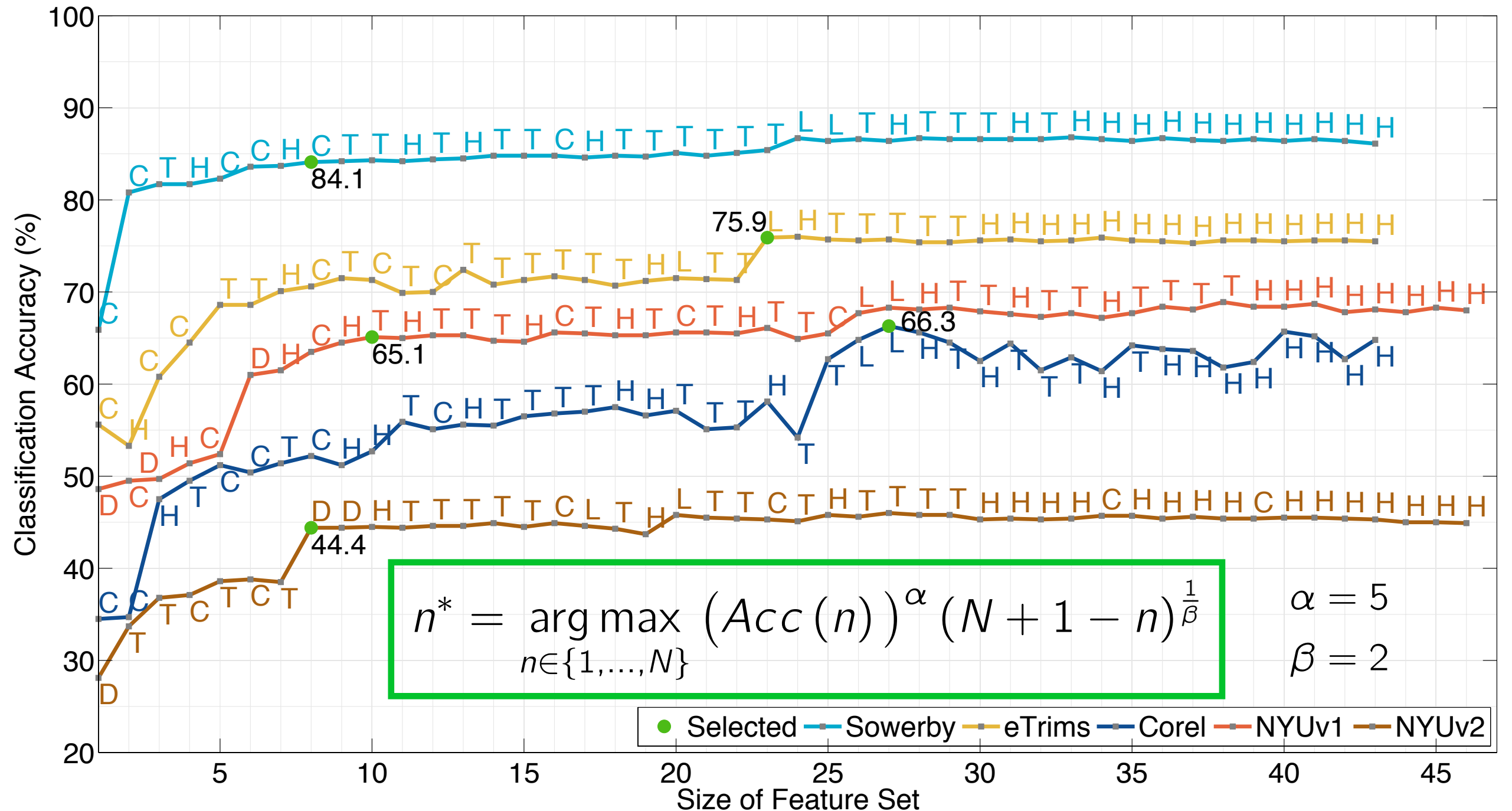
Relevance of Location Features



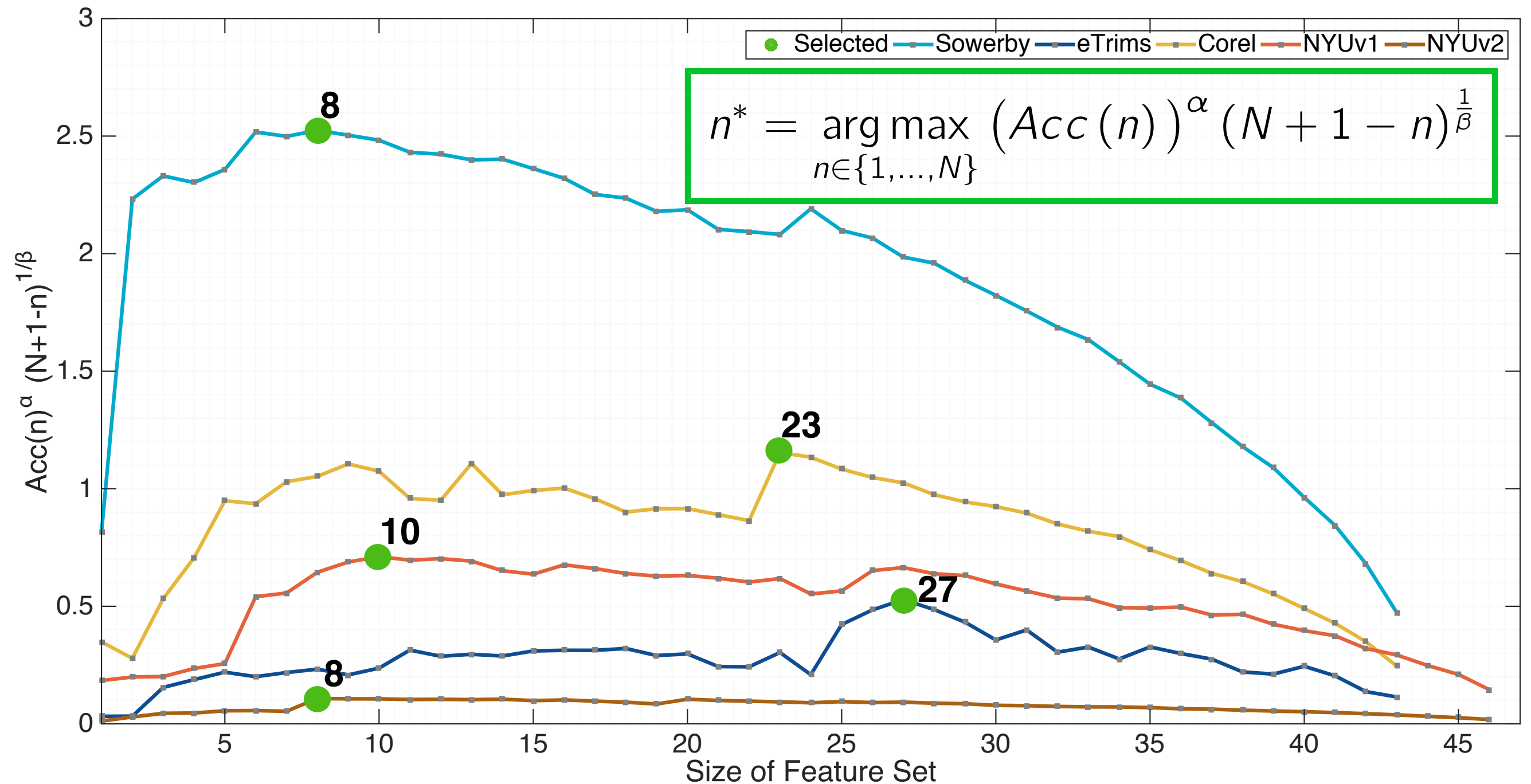
Relevance of Depth Features



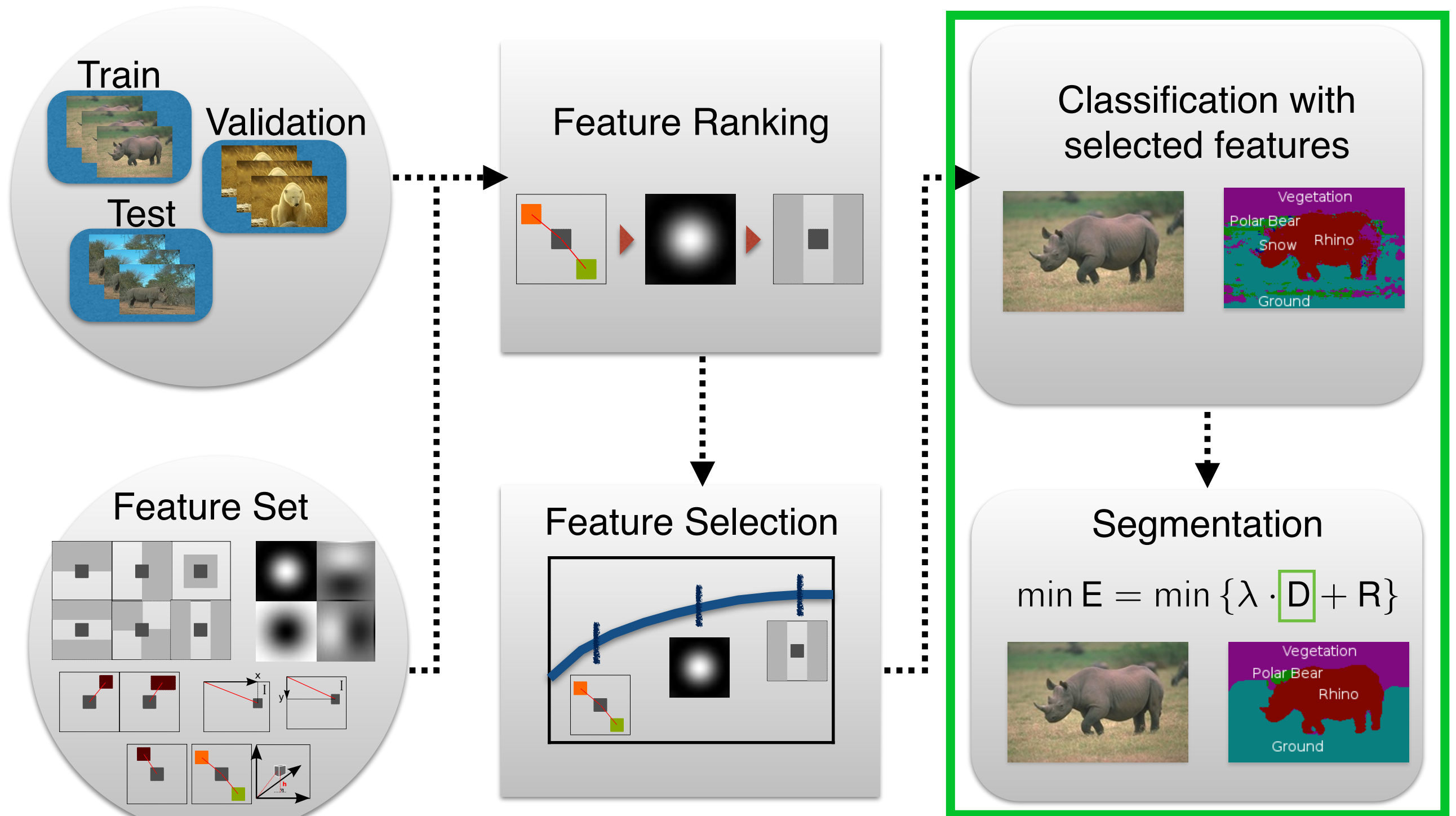
Feature Selection



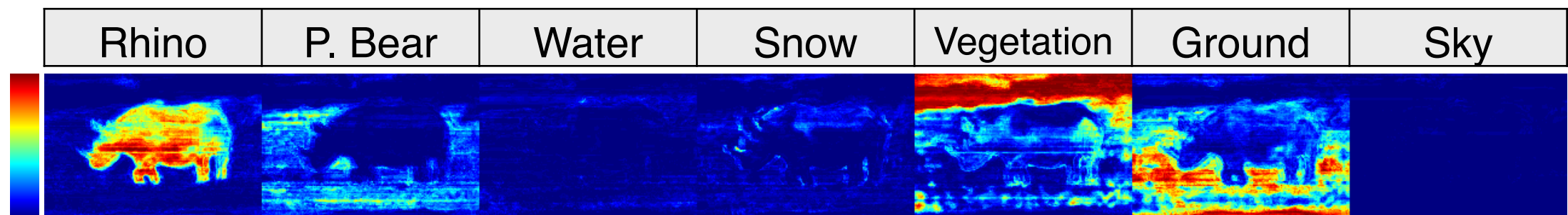
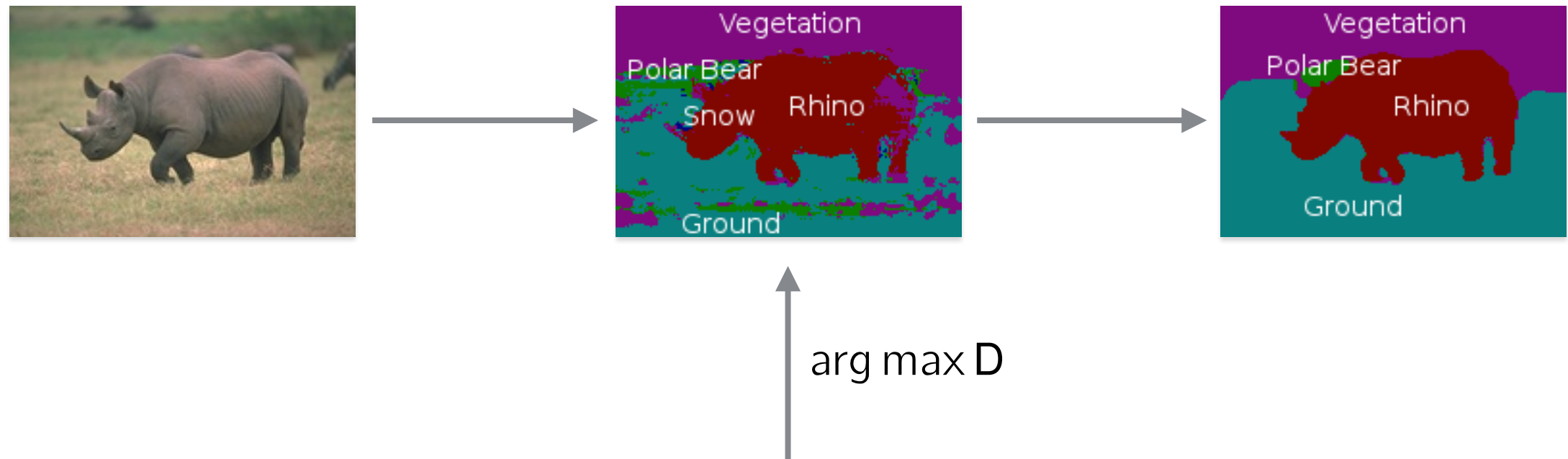
Number of Selected Features



Semantic Image Segmentation



Classification & Segmentation



$$\min E = \min \{ \lambda \cdot \boxed{D} + R \}$$

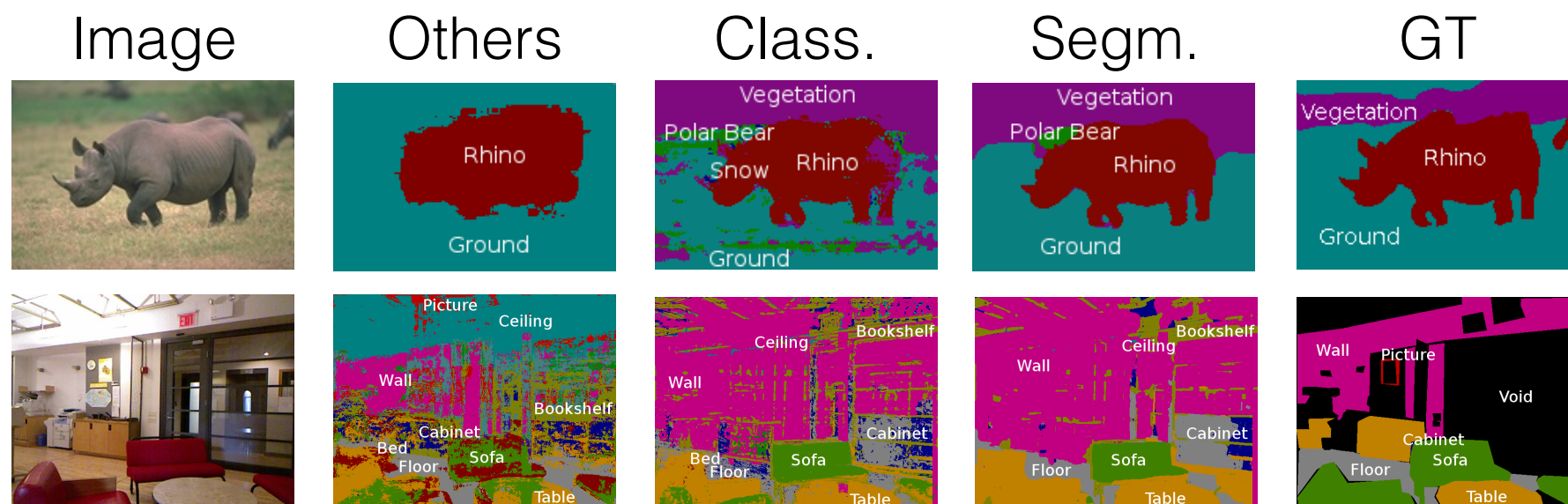
Improved Runtime

	Training Time (in seconds)					Testing Time (in seconds)				
	eTrims	Corel	Sowerby	NYUv1	NYUv2	eTrims	Corel	Sowerby	NYUv1	NYUv2
Shotton et al.	—	1800	1200	—	—	—	1.10	2.50	—	—
Fröhlich et al.	—	—	—	—	—	17.0	—	—	—	—
Couprie et al.	—	—	—	—	172800	—	—	—	—	0.70
Hermans et al.	—	—	—	—	—	—	—	—	0.38	0.38
Proposed	143	20	2	133	183	6.6	0.27	0.07	0.32	0.26

On average we improve the runtime by a factor of 7.7

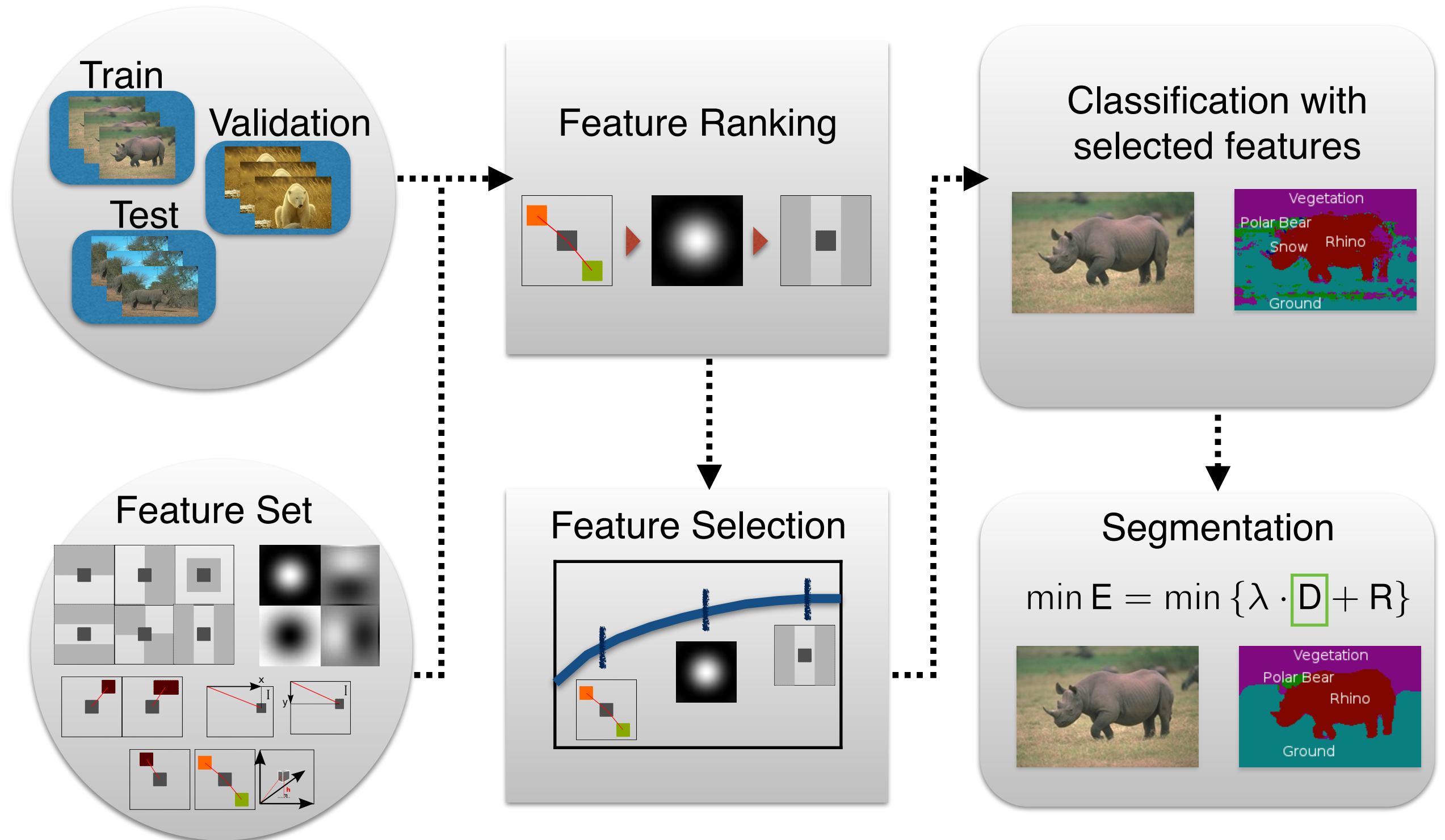
Competitive Results

	Classification					Segmentation				
	eTrims	Corel	Sowerby	NYUv1	NYUv2	eTrims	Corel	Sowerby	NYUv1	NYUv2
Shotton et al.	—	68.4	85.6	—	—	—	74.6	88.6	—	—
Fröhlich et al.	—	—	—	—	—	77.2	—	—	—	—
Couprie et al.	—	—	—	—	—	—	—	—	—	52.4
Hermans et al.	—	—	—	65.0	—	—	—	—	71.5	54.2
Proposed	77.1	74.4	87.1	65.0	44.0	77.9	78.2	88.8	66.5	45.0



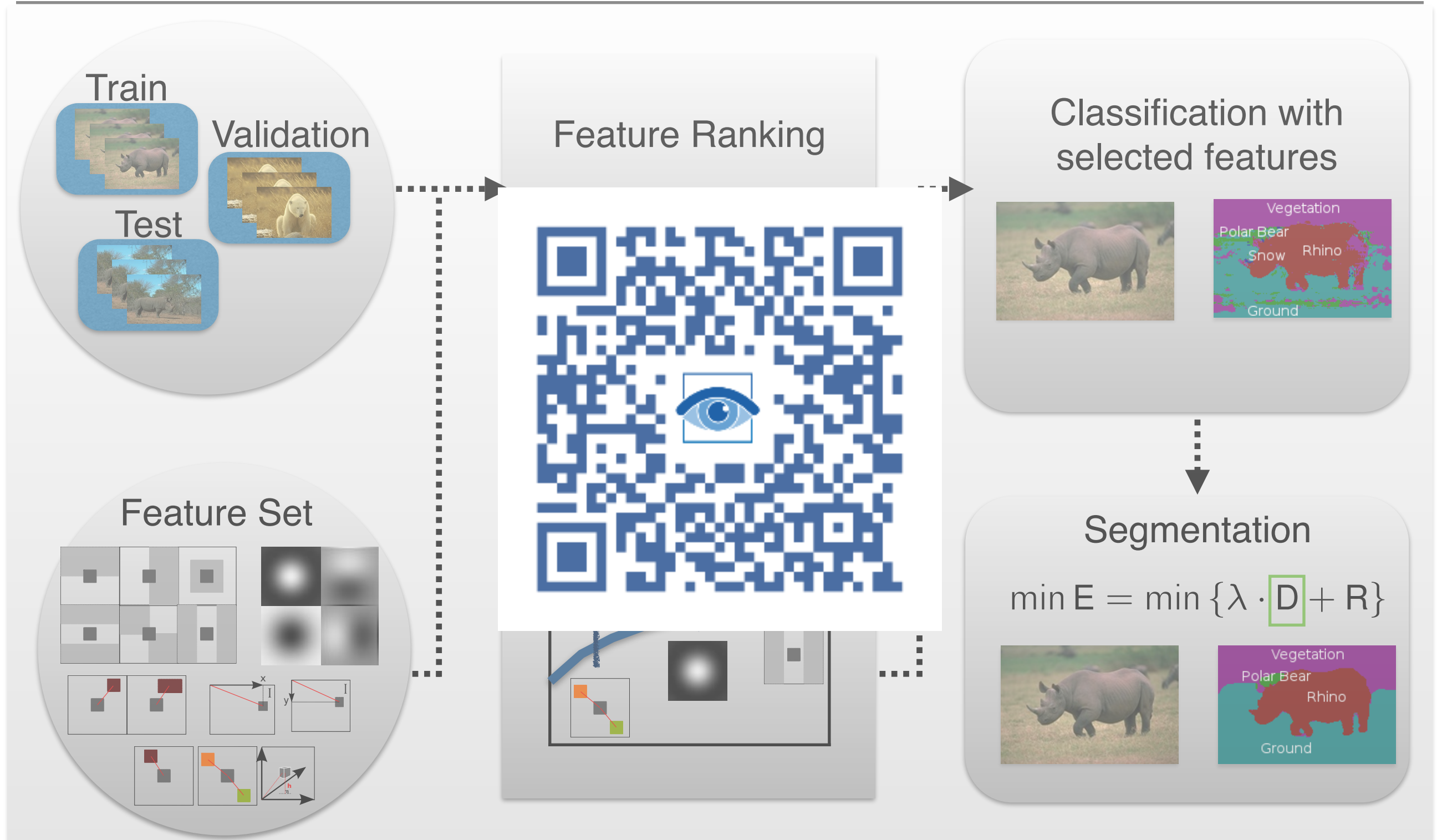
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References

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- Indoor Semantic Segmentation using depth information
Camille Couprie, Clément Farabet, Laurent Najman, and Yann LeCun ICLR'13
- Dense 3D Semantic Mapping of Indoor Scenes from RGB-D Images
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