



Information Technology University
Advanced Digital System Design Fall 2018
Assignment 5

Date of Launch: 6-December-2018

Maximum Marks: 80

Due Date: Saturday, 15-December-2018

Due Time: 23:59hours

Instructor: Dr. Rehan Hafiz

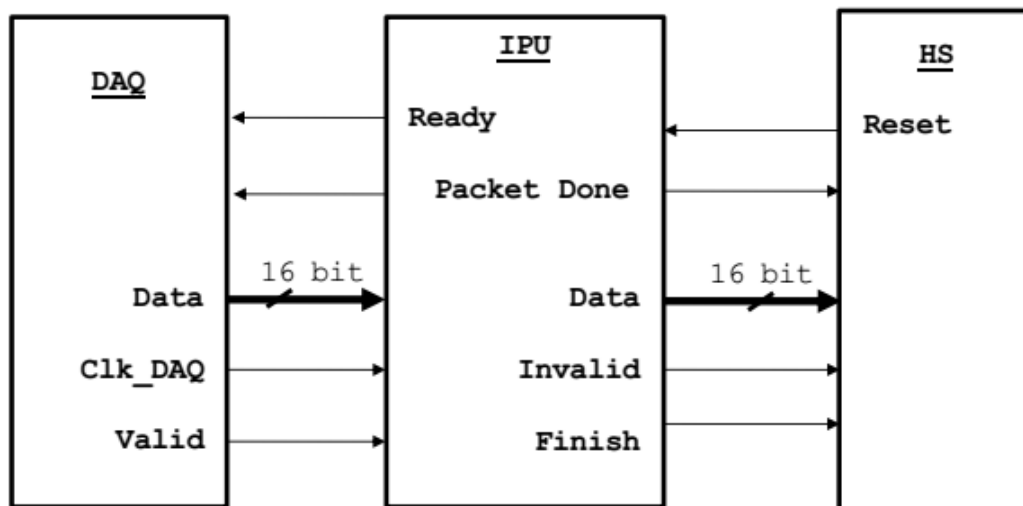
TAs: Hazoor Ahmad, Zeeshan Haider

Important Instructions:

- This is an individual assignment. Each student must work alone, without help from any other person. Plagiarism is NOT allowed. Copying material from the web or from documents and submitting it for this assignment without giving credit/reference is plagiarism. **Copied assignment will be marked ZERO.**
- The Verilog Code should be synthesizable. The Verilog code should be properly commented. An optimized implementation will result in more credits.
- 10 marks/day will be deducted in case of late submission after due date.

Question Requirements:

- Please perform this assignment in Group of **TWO**.
- Provide the Micro-Architecture (Good to use PowerPoint/Visio to make your diagrams)
- Then code it in Verilog & provide your simulation results in a PDF document
- You also need to perform the simulation in MATLAB using the Fixed-Point Toolbox. The coefficients and $x[n]$ shall be all in Q8.8 format (Shall be discussed in Class).
- The code for DAQ & HS is also required to be provided. DAQ shall use a ROM to initialize it with the same $x[n]$ as for Matlab.
- Your output should match that of a corresponding simulation performed by yourselves in MATLAB. Make your own evaluation framework that allows you to test your code.
- Your MATLAB simulation should generate a $x[n]$ data file for your DAQ. DAQ should import it using \$readmemh. After your simulation your HS should store the results in a memory and you should dump the memory in a file. Then import it back in MATLAB to show that both the MATLAB and Xilinx results match.



To be submitted:

- Zipped Xilinx Project Folder with source codes & simulation
- PDF report containing
 - Micro-Architecture (Data-path + Complete FSM)
 - Your MATLAB vs Xilinx Simulation Results
- MATLAB code
- Fixed Point Simulation of the functionality using the MATLAB's Fixed-Point Toolbox

Design Specifications:

You have to design an IPU (Interfacing & Processing unit) that will provide an interface between a Data Acquisition Module (DAQ) and a Host System (HS). The IPU provides the functionality of applying the following processing on the received data

$$y[n] = ax[n-2] + bx[n-4] + cx[n-6]$$

The figure below shows the interfacing blocks at a very abstract level.

The DAQ provides a new 16-bit sample ($x[n]$) on every positive edge of its clock on its primary Data line (Data). The data is organized in the form of packets where each packet consists of TWELVE 16-bit consecutive samples of $x[n]$. The DAQ also provides a "Valid" signal that defines the window in which the packets are valid. Only valid packet needs to be processed in the IPU. Non-valid packet/data will be discarded.

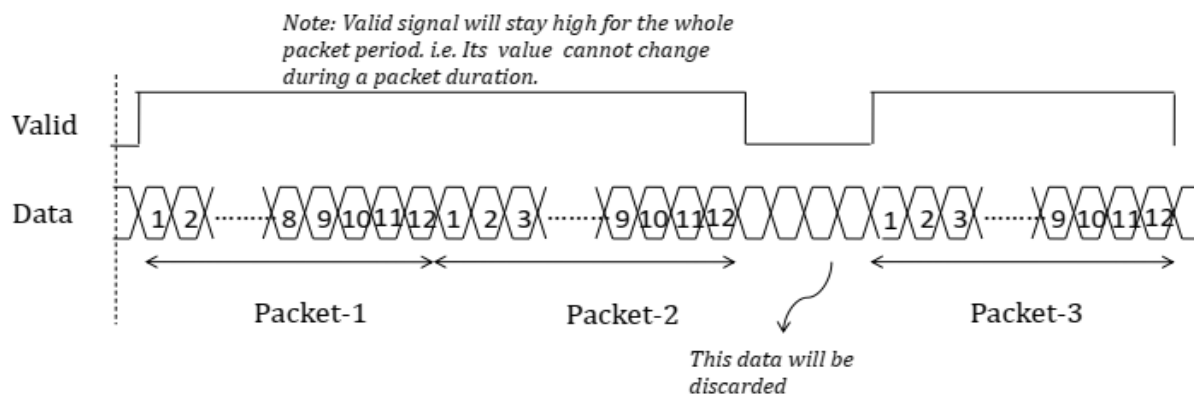
The required functionality of the IPU is explained below:

1. Whenever the HS wants to receive the data; or whenever the HS wants to reset the IPU; the HS gives a single cycle "reset" signal to IPU. This also initializes the IPU output to ZERO.
2. Starting from the next clock cycle; the IPU sends a "ready" signal to the DAQ. This informs the DAQ that the HS is ready to get the data from DAQ via IPU.
3. When the DAQ has valid data ready; it responds by sending a continuous stream of data in the form of packets.

4. A single cycle "Packet Done" signal is generated by IPU after processing of every packet.
5. A single cycle "Finish" signal is generated by IPU after a batch of 32 Packets is processed.
6. The IPC shall enter a wait state after the Finish signal & wait for 'reset' signal from HS to start the processing again.
7. In-case the input data from DAQ is in-valid; the IPU simply freezes all the computational blocks in their current state and sets the Invalid flag for the HS.

In addition to the signals shown in the figure; following functionalities are also required. There is also an internal variable Average Value that stores the average of all the $y[n]$ till yet. There is an input signal to IPU named TEST and an output to the IPU named TEST_Result. The functionality of these signals is as follows:

- If (TEST=1); value of TEST_Result is ONE if current $y[n]$ is greater than average $y[n]$
- If (TEST=1); value of TEST_Result is ZERO if current $y[n]$ is less than or equal to average $y[n]$
- If (TEST=0); value of TEST Result is ZERO.



(Design Question) You are hired as a design engineer at Silicontron. Your latest job is to develop a Micro-Architecture [Datapath & Controller] of the IPU.

- a) Labelled and complete Datapath showing all data & control signal routings & connection.
- b) Correct & Complete Controller FSM