

A superconducting cyclotron accelerator based materials test facility for bulk radiation damage studies

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Abstract

A design study has been conducted for a materials test facility (MTF) utilizing superconducting cyclotron accelerators for simulating neutron damage and helium accumulation in materials for fission reactor and fusion applications. Superconducting cyclotrons are compact and can produce high energies beams allowing for inexpensive testing of thick (~ 1 mm) material samples. A 35 MeV, 1 mA proton beam is used for simulating atomic displacement damage caused by neutrons with damage rates for on the order of 50–200 displacements per atom (DPA) per year for various materials. By using a high energy beam with a range greater than the samples' thickness, relatively uniform bulk damage can be achieved in the samples. The use of thick samples preserves the materials' micro-structure enabling mechanical testing of macroscopic properties. A 100 MeV cyclotron with an energy degrader is used to produce a variable energy helium beam for helium implantation. The cyclotrons are independently controlled to match the He/dpa ratio to specific environments/neutron spectra or to independently study the effects of He implantation and displacement damage. The novel design for MTF target chamber uses helium-jet impingement cooling to remove heat from multiple samples and allowing for steady state operation and in-situ tensile testing so that samples can be irradiated under active loads. Critical issues associated with heat removal, beam material interactions, and operating limits are studied to demonstrate the feasibility of the MTF.

Keywords:

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1. Introduction

The study of materials in radiation environments is critical for improving the reliability of modern fission reactors, the development of next generation fission reactors, and the eventual development fusion reactors. In fission and fusion, neutrons typically damage materials through two mechanisms: the displacement of atoms in the material and the accumulation of helium from (n,α) reactions and α -decay of activated nuclei. These processes depend strongly on the neutron spectrum and the physical and nuclear properties of the material. Since neutrons have relatively long mean free paths, the damage occurs within the bulk of material, causing changes to the material's atomic structure leading to macroscopic changes affecting its mechanical and thermal properties.

The ability to test fission and fusion relevant ma-

terials in environments with high neutron fluxes is limited to research reactors, high energy accelerator based techniques such as spallation and D-T target fusion. These methods, however, induce radiation damage at similar or lower rates than power reactors themselves. Since most materials in reactors and fusion applications must have lifetimes of several years or greater, the development of new methods of testing materials with increased neutron or neutron-like damage rates will greatly benefit the field of nuclear material science.

Currently, simulation of neutron damage with ion irradiation is an established technique [1, 2]. The long-range coulomb interactions of the protons increase the damage rate per ion by several orders of magnitude as compared to neutrons. This allows for accelerated radiation damage rates when irradiating materials. However, these techniques are limited by the difficulty of heat removal from

samples and are constrained by low energy (< 10 MeV) beams which can only produce near surface ($< 100 \mu\text{m}$) damage in materials. To simulate neutron damage effects, high energy proton beams ($\approx 30\text{--}40$ MeV) are required. With recent developments in accelerator technology, it is now possible to achieve these high energies with compact (~ 2 m diameter) super conducting cyclotrons instead of linear accelerators (10–100 m length).

We propose a novel accelerator based materials test facility (MTF) for simulating bulk radiation damage in samples up to ~ 1 mm thick. This facility utilizes advances in superconducting cyclotron technology and two independent ion beams provide unparalleled versatility and in radiation damage simulation. Neutron damage is simulated in samples contained in temperature controlled target chamber using helium jet-impingement for sample cooling. Displacement by inducing displacements with a 36 MeV proton beam that penetrates the bulk of the sample. In addition, a 100 MeV helium beam with an energy degrader allows for a variable energy He source for uniform implantation of helium across the sample to induce materials effects associated with helium accumulation within the material. MTF will therefore, allow the testing of nuclear materials in a relatively short amount of time with independent control of the damage mechanisms in a temperature controlled, inert gas environment.

2. Background

There is a need for a materials testing facility that can accurately, and quickly access material properties. This would be a facility that could achieve at least 40-50+ dpa per year. Currently, there are no fast spectrum and fusion material test facilities. There are two thermal spectrum test facilities (ATR [?] and HFIR [3]). The The International Fusion Materials Irradiation Facility (IFMIF) has been proposed for construction within the the next decade. IFMIF uses a high energy deuteron beam and a tritiated (tritium-containing) target to produce fusion neutrons designed to test hundreds to thousands of samples at once. However, the projected costs of IFMIF approach 1 billion dollars and are limited to damage rates on the order of 10-20 dpa per year of operation [?].

Another option is fission test reactors. Test reactors have been an valuable reasource for testing in neutron environments, however, due to the time

scales involved, high DPA experiments are impractical. For example, a typical neutron irradiation experiment in a test reactor often requires as much as a year of sample preparation, cooling analysis and capsule design before testing, followed by several years of neutron exposure in the reactor [4]. Additional time is needed because of the safety and legal issues of the handling of radioactive materials in the vicinity of a nuclear reactor and because of the high activation level of the irradiated sample and its container. This time period, sometimes up to 5 years, as well as the high overall cost of the test run does not allow for iterations or rapid turn around on experiments.

Accelerator based techniques ion irradiation techniques are also in use because of their many practical advantages over neutron irradiation. Proton irradiation (or other light ions, decreases induced activation of the test equipment and instrumentation, increases the reliability of the experiment allowing it to be interrupted without disturbing the sample, and in many cases the energy of the ion beam can be variable to adjust the recoil spectrum of the atoms. Most importantly, proton irradiation time, logisticss, and operational costs are substantially less compared to neutron irradiation [1].

Ion irradiation can achieve extremely high localized damage rates (often as high as > 10 DPA/day), especially with low energy (< 10 MeV) beams. However, heat removal from samples can be challenging at these high damage rates. Th low energy ion beams have a limited range, typically $< 100\mu\text{m}$, over which the damage profile is highly non-uniform and peaks close to the ions' maximum penetration depth. Though these surface damage studies produce a wealth of useful results, they cannot capture the bulk damage effects that occur on the length scale of a material's grain structure which often dominate the behavior of structural materials. [NEEDS MORE BACKGROUND FROM A MAT-SCI PERSPECTIVE].

Extending the ion-irradiation capabilities to macroscopic scale of ~ 1 mm, critical importance because it would not only enable testing of samples with damage over multiple grain widths but would also allow for samples that are large enough for test mechanical. Developing these capabilities while simultaneously incorporating independent helium accumulation and temperature and the ability of in-situ mechanical testing is therefore, the goal the MTF design study.

3. MTF conceptual design

MTF uses two compact superconducting cyclotron accelerators to simulate neutron damage. A model of the facility concept is shown in Figure 1. A 36 MeV proton cyclotron is used for simulating displacement damage. This beam energy was chosen to allow for nearly uniform displacement damage in the bulk of samples up to 1 mm thick.

To simulate the accumulation of helium, which occurs in reactors as a result of α -decay and (n,α) reactions, a 100 MeV helium cyclotron is used for implantation. The helium implantation depth is controlled by reducing the beam energy with an 'energy degrader' such as metallic, actively cooled wedge-plate that is inserted into the beam.

A versatile target chamber holds the samples and allows for independent mechanical testing of multiple samples during irradiation over a wide temperature range. Two beam lines with quadrupole focusing and magnetic steering are used for the beam transport system, which is used to converge the beams on the target samples. Helium jet impingement cooling is used on both sides of the samples to remove heat from the irradiated region. After the proton beam passes through the samples it slows down and stops within the volume of a helium filled chamber, which minimizes activation and facilitates cooling.

3.1. Target Chamber

In the target chamber, samples are mounted in a row and are connected to a test stand that can apply mechanical loads to measure stress-strain properties in-situ or apply loads during irradiation to study radiation-induced creep. High pressure helium jets are used for cooling the samples that can have volumetric heating from the beam approaching $\sim 20 \text{ GW/m}^3$ (20 W/mm^3). Helium is used because it is an established cooling method and because of its favorable qualities as an inert gas that is relatively transparent to ion beams. Helium has excellent thermal properties, high sound speed, and does not become activated by the beam. Helium is also a noble gas and does not chemically react with the surfaces of the samples, even at high temperatures. In addition, the beam dump is filled with helium and is integrated into the cooling system to allow beam to slow down and stop after passing through the sample, causing minimal activation outside of the sample.

To separate the pressurized target chamber from the beamlines and the accelerator – which require a high vacuum environment – a titanium ($\sim 50 \mu\text{m}$) beam window is used as a vacuum/helium interface. Titanium is used because of it is a favorable balance of high strength and low beam stopping. A conceptual model of the target chamber is shown in figure 2 and a cut away schematic of beam and cooling geometry is shown in figure 3. Modeling and analysis of the each of these components are described in the following sections.

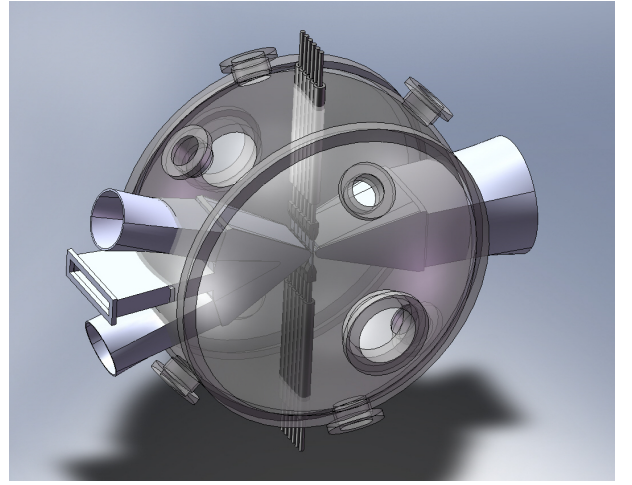


Figure 2: A proposed model of the target chamber is shown. A series of sample holders are held in the center by independent tensile testing actuators. Manifolds for the helium cooling inlets and beam inlet are shown on the left, and a helium inlet/beam exit is shown on the right.

4. Accelerators and beam parameters

Isochronous cyclotrons are continuous wave machines allowing for maximum time averaged beam current. Unlike the classical Lawrence cyclotron, isochronous cyclotron can produce much higher energy beams, into the hundreds of MeV, by increasing the magnetic field radius to account for the relativistic mass increase $B = \gamma B_0$. There is also flexibility in the design to allow for variable energy and ion species by altering the RF frequency and isochronous field. Isochronous cyclotrons require an additionally complex magnetic structure for maintain the orbits' phase stability though the design process for these fields is well understood [16]. Today isochronous cyclotrons are most commonly built cyclotron and are well suited for MTF

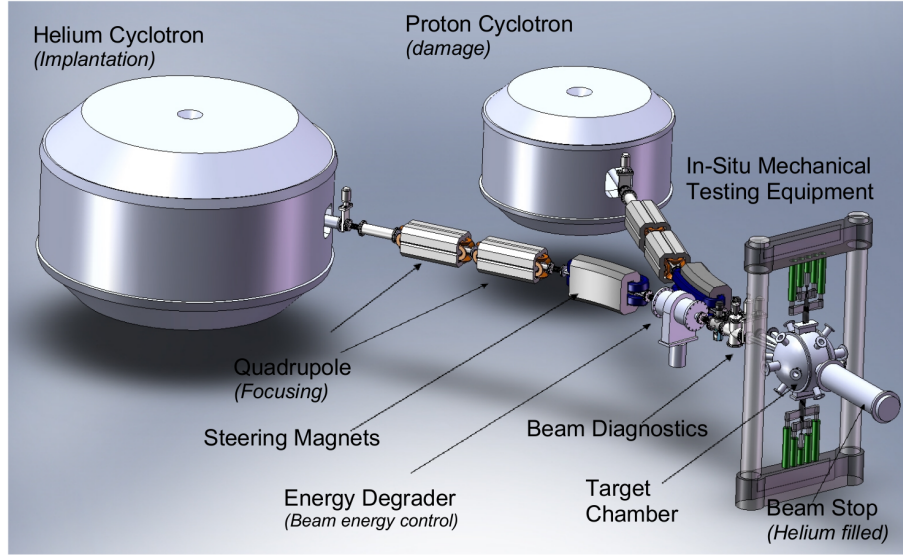


Figure 1: The two cyclotrons, for helium implantation and 36 MeV protons, are shown on the left. The beams pass through beam optics and diagnostics. The target chamber is shown on the right, with a beam dump on the far side. Thermal insulation and coolant piping not shown.

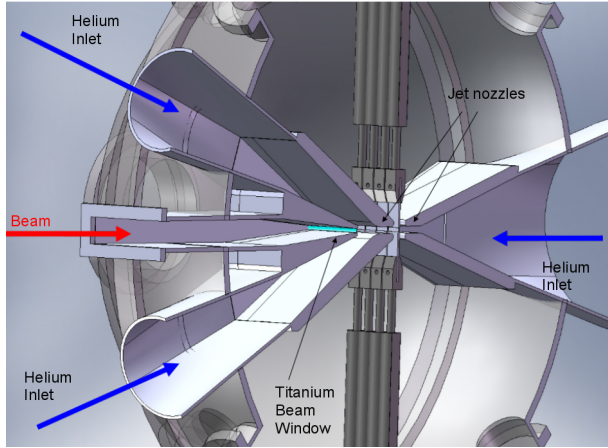


Figure 3: A cutaway model of the target chamber is shown to illustrate the geometry of the helium gas jets nozzles, samples, and the beam window.

because of their steady state operation, compact size, and industry experience.

A 36 MeV isochronous proton cyclotron and a 100 MeV isochronous helium cyclotron with 4–5 T B-fields were chosen for the MTF conceptual design. These design parameters were chosen considering proton beam penetration depth, displacement damage distribution, He implantation depth, and feasibility based on technical experience in cyclotron field.

4.1. Proton beam parameters

Since proton range increases with beam energy while displacement damage rate decreases with energy, the optimal beam energy is achieved at the lowest energy that produces uniform damage in a sample of a given thickness. Damage rates are also constrained by the desired sample thickness because cooling requirements that are limited by heat transfer at the surface and heat conduction within the sample. A proton energy of 36 MeV was chosen to assure adequate penetration of 1 mm samples with a nearly-uniform damage profile while maintaining the a high displacement rate. This energy was chosen based on calculations of damage profiles and proton ranges, performed using SRIM2008 [5]. The damage profile caused by 36MeV protons in 304 stainless steel is shown in

figure 4.

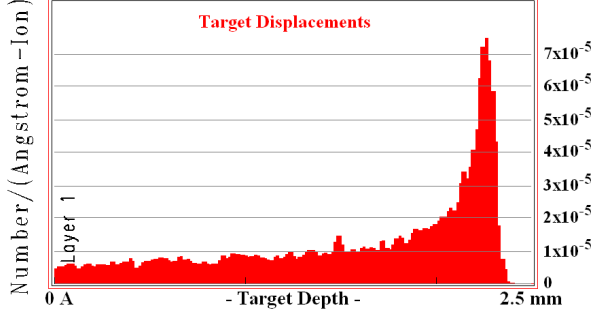


Figure 4: Displacement profile for protons in 304 Stainless Steel generated with SRIM2008. Nearly uniform bulk damage is observed in the first 1 mm of the proton range.

The achievable beam current sets a fundamental limit on the sample volume that can be studied. As beam current increases, the achievable beam current densities on the sample quickly exceed the heat removal limits. For example, even with relatively low average beam current (<0.1 mA), a 1 mm thick, 1 cm wide sample, heat removal is primary constraint on induced the DPA rate, as shown in section 8. The total current however is very important because, by sweeping the beam across many samples, the average beam current density can be adjusted to maximize the damage rate over a maximum number of samples.

Compact high current cyclotron pose several technical challenges that limit the maximum beam current. As the magnetic field is increased to make the cyclotron smaller, the field gradients in the radial direction must increase to maintain the proper fields for isochronous acceleration. This causes the orbits to be in close proximity, requiring the beam to have very small transverse dimensions. High current and small beam size makes beams stability more problematic and close orbits makes beam extraction more substantially more difficult.

For this study, a range of 0.1 - 1 mA of beam current is assumed. Since optimization of the for high beam current and extraction involved a detailed design of the cyclotron, the bounds of this range were estimated from industry experience. Currents on the order of 0.1 mA have been readily achieved by superconducting cyclotrons on this scale [?]. The upper bound is more difficult to determine, however, since isotope production cyclotron have achieved reliable beam currents exceeding 2 mA [6]

Table 1: Annual Helium accumulation

Material type	He Accumulation [appm/year]
Metals (fusion)	~ 200
Graphite/SiC (fusion)	>1000
Metals (fission)	10-100

Table 2: Estimates of helium accumulation rates for materials in reactor relevant environments [?]

[?] at slightly lower fields, ~ 1 mA was chosen as a conservative upper limit than can be achieved without substantial R&D efforts.

5. Helium Implantation

The accumulation of helium in irradiated materials from α decay and (n, α) reactions contributes significantly to embrittlement and swelling of materials. Helium implantation is therefore a very important feature of MTF. Helium implantation is achieved in samples up to 1 mm thick with a 100 MeV cyclotron because helium ions with this energy have ranges of greater than 1 mm for most materials. An energy degrader is used to reduce the beam energy to vary the implantation depth, which allows for a uniform helium profile.

The helium/DPA ratio has a strong dependence on the materials nuclear properties and the neutron spectrum. Since a separate cyclotron is used for helium implantation, the helium/dpa ratio is highly flexible and can be adjusted to match the helium/dpa ratios for practically any known fission or fusion materials application. The annual He accumulation is shown for several reactor applications in table 2.

5.1. Implantation Rate

The helium implantation rate can be calculated directly from the helium beam current density with equation 1. The He implantation rate can also be calculated in atomic parts per million per hour [appm/hour] as shown in equation 2.

$$\Phi_{He} = \frac{J_{He}}{q_o} \longrightarrow R_{He}[\text{He/s}] = \frac{\Phi_{He}}{\Delta x} \quad (1)$$

$$R_{He}[\text{appm/hr}] = \frac{(3.6 \times 10^9) \cdot J_{He}[\text{A/m}^2]}{e[\text{coul}] \cdot n_t[\text{m}^{-3}] \cdot \Delta x[\text{m}]} \quad (2)$$

5.2. Accelerated He implantation

At high temperatures, defects caused by radiation damage can be annealed. Thermal annealing is seen by many materials, including steels [7], silicon carbide [8], and tungsten [9]. This means that for materials at high temperature, it is possible to simulate radiation damage at much higher rates with only helium implantation, assuming the removal displacement damage effects by annealing. For intermediate temperatures, it might also be sufficient to amorphize the material with several proton induced DPA followed by rapid He implantation. This mode of operation could be extremely advantageous because it would enable end-of-life material studies to be performed orders of magnitude faster than proton induced DPA studies.

Since all of the energy of implanted ions is the deposited in the material, the main challenge at high implantation rates is volumetric heating. The volumetric heating can be calculated from the time averaged beam energy \bar{E} from equation 3, where $E(t)$ must be calculated to create a uniform deposition profiles from inverse range data $[R(E)]^{-1} = E(R)$, where $R(E)$ can be calculated from SRIM 2008 [5]. An expression for a sinusoidally varying range sweep for implantation, $E(t)$ is given by equation 4, where ω is the range sweep frequency.

$$\bar{E} = \frac{1}{\tau} \int_0^\tau E(t) dt \quad (3)$$

$$E(t) = E(R(t)), \quad R(t) = \frac{\Delta x}{2} (1 + \sin(\omega t)) \quad (4)$$

The average volumetric heating q''' is therefore is estimated by $q''' = J \cdot \bar{E} / \Delta x$, where J is the current density and Δx is the thickness. To simplify the calculation, \bar{E} can be approximated as the energy required to implant at the maximum depth, divided by 2. Using this simplification, the maximum hourly rate for helium implantation in atomic parts per million normalized to surface heat flux is shown in Figure 5. Since 1 MW/m² is only a modest heat removal rate for He jet impingement cooling, annual He accumulations (table 2), or even end-of-life accumulation, can be simulated in a matter of hours or days.

6. Cyclotron Design

Beams with high time-averaged current are desirable for damage simulation. Isochronous cyclotron

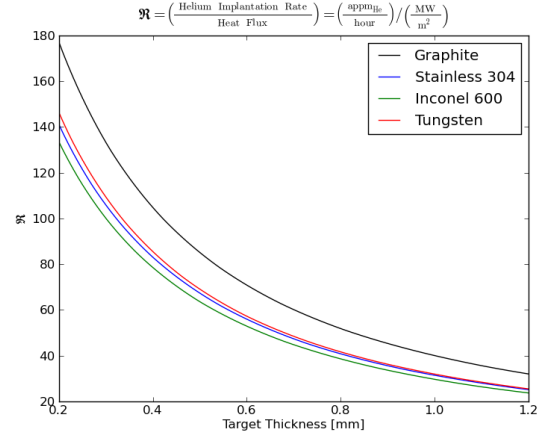


Figure 5: Hourly helium implantation rate normalized to surface heat exhaust

designs are used because they are continuous wave (CW) devices and have been demonstrated in energy ranges spanning to those required by MTF. Table 3 shows a comparison of other isochronous cyclotrons that have been designed, built, and operated with high reliability for medical and radiation source applications. MTF is well within the range of available superconducting cyclotron technology and therefore should not require significant R&D efforts beyond the cyclotron design process and is expected to not pose significant technical risk.

A study of compact high-field cyclotrons was performed to assess the feasibility of proton and helium cyclotrons for MTF in addition to a preliminary design for beam transport system was developed by T.C. Sordelet, et al [12]. Several codes were used for this analysis. Poisson Superfish [13], a 2D electromagnetic field solver, was used to determine general design parameters such as cyclotron's size and the basic characteristics of the coils, conductor, resonator, and other components.

The cyclotron design was further refined with ACFIELDS [14], a semi-analytic cyclotron design code and OPERA 3D [15], a finite element analysis code for electromagnetic field calculation and particle tracking. Numerous designs for superconducting isochronous cyclotrons were studied, ranging from 3 to 7 Tesla. These designs involved optimization of the isochronous fields with spiral magnet pole tips for transverse stabilization, coil positioning, and yoke design. It was concluded that most cost effective compact cyclotrons, posing the least techni-

Cyclotron	Energy (particle)	B-Field (magnet)	Use	Ref.
ACCEL-250	250MeV (i)	2.4T (SC)	PT	[10]
C-230.235 (IBA)	235MeV (p)	1.739–2.165T (Cu)	PT	[?]
C-400	265MeV(p), 400MeV(i)	~3.5T (SC)	PT	[6]
TRADE (IBA)	110 MeV (p)	(SC)	NS	[11]
Proposed MTF	36MeV(p), 100MeV(He)	~4T(p), 4T(He) (SC)	MTF	–
DTRA Demo	10MeV(p), 5MeV(d)	7T (SC)	DTRA	[?]

Table 3: Table of existing isochronous cyclotron designs and facilities. The design parameters for MTF are within the range of other demonstrated cyclotron facilities. The MTF’s accelerators are therefore feasible without substantial R&D. The following abbreviations are used: Proton Therapy (PT), Material Test Facility (MTF), Neutron source (ns), Detection Threat Reduction Agency (DTRA), Superconducting(SC), Copper (Cu)

cal risk were designs with average magnetic fields of 4.2T(proton) and 3.9T(helium), niobium titanium (NiTi) superconductors, and iron poles and magnetic return yokes. The final design parameters concluded from the cyclotron study [12] are given in table 4. These parameters serve to provide an estimate of the physical scope of these accelerators so that costs and facility layout can be assessed in the final design based on available fabrication resources and procurement options.

7. Beam Extraction and Transport

Positive ions are most commonly extracted by an electrostatic deflector. The electrostatic detector consists of two electrodes located at the extraction radius of the cyclotron [16]. This method is possible though efficient extraction becomes difficult when the spacing between ion orbits is small. Another possibility is negative ion stripping, whereby, negative ions are accelerated then pass through an electron stripping target at maximum orbit radius. When the electrons are stripped the, now positive, ion is deflected out of the cyclotron. For high current beams, this method may be problematic due heating and activation of the stripping target or negative ion source limitations. Yet another possibility self-extraction whereby, a magnetic field perturbation is incorporated into the design of the magnet such that ion at the maximum acceleration radius enter unstable orbits and extract themselves. All of these methods are possible however, a detailed analysis beyond the scope the preliminary design would have been necessary, so further investigation will be required to determine the most efficient method to extract of beams with currents greater than 0.1 mA. [MORE CITATIONS NEEDED].

For transport of the beam from the accelerators to the target chamber, a preliminary design was developed using TRANSPORT [17] and is described further in [12]. The beam transport system requires only standard components: magnetic quadrupole triplets for focusing and sector magnets for steering and combining the beams.

The details of energy degrader design, used for varying the beam, has been left for future investigation. The design will likely consist of using a rotating step or wedged wheel, a movable wedge, or a stack of foils [ASTM E942-96, 2011]. Heat removal will be also be required for the design, however, the thermal requirements will not be any more severe than the inside of the target chamber and are therefore expected to have a straight forward engineering solution. Also, there is considerable experience with energy degraders in the field for medical irradiations and several choices of materials for the degrader are accepted in practice by ASTM E942-96 such as aluminum, beryllium, and graphite which can be incorporated into the design.

8. Operational Range

As the beam passes through the sample it induces damage, but it also loses energy in the sample, which causes significant volumetric heating. Volumetric power deposition q''' can be calculated with equation 5 where J is the beam’s current density and S is the beam’s stopping power ($S(E) \equiv dE/dx$) for which values are available semi-empirically from SRIM [5].

$$q'''[W/m^3] = J[A/m^2] \cdot S[eV/m] \quad (5)$$

The heating of the samples results in the two primary constraints on the damage rate: heat removal and the temperature variation across the samples.

Ion	Type	Energy	Field B	R_{ext}	Dimensions	Fe Mass	NiTi Mass
H^+	isochronous	36 MeV	4.2 T	???? cm	46cm \times Ø84cm	1372 kg	18.70 kg
He^+	isochronous	100 MeV	3.9 T	???? cm	100cm \times Ø180cm	12728 kg	81.22 kg

Table 4: Parameters for MTF cyclotrons to provide an estimate of the physical scope of their designs [12].

It is therefore useful to consider the damage rate that has been normalized to volumetric heating, shown in figure 6. This plot demonstrates that the achievable damage rates depend strongly on the materials and are relatively insensitive to the beam energy.

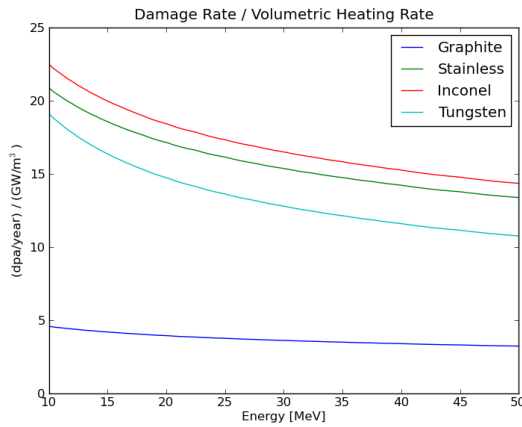


Figure 6: Damage rates normalized to volumetric heating for various materials. This shows that the achievable damage rates are relatively insensitive to beam energy and depend strongly on the materials.

For the heat removal constraint, the maximum heat removal rate is set by the surface heat flux q'' , which is determined by the heat transfer coefficient h as applied in equation 6. A more detailed calculation and discussion of the heat transfer coefficient is given in Section 8.2.

$$q'' = h \cdot (T_{surface} - T_{coolant}) \quad (6)$$

From equation 6, for a fixed inlet temperature, the maximum achievable q'' increases roughly linearly with sample temperature (with a small correction for the temperature dependence of h). Since the bulk of the sample is heated volumetrically, q'' increases linearly with the thickness. The maximum damage rate will therefore decrease roughly linearly with thickness.

A simultaneous operating constrain is the temperature profile within the sample, which is set by

the thermal conductivity k . Since material properties can be highly sensitive to temperature, it is necessary minimize the temperature variation ΔT across the sample. Equation 7 derived from a simple 1-D slab which can be used to approximate ΔT for volumetric heating q''' and heat flux q'' (on both sides of the sample).

$$\Delta T = \frac{qt^2}{2k} \quad (7)$$

Considering thermal conductivity k , the limits on ΔT will constrain the damage rates of the samples, especially for materials with low k . These heat removal limitations are illustrated by the calculation of maximum heat flux for a given ΔT , using equation 8.

$$q'' = \frac{4\Delta T \cdot k}{t} \quad (8)$$

For this study, $\Delta T = 20$ K was used because the ASTM standards require the temperature to be reported with $\Delta T \pm 10$ K for irradiation damage studies [2]. A plot of heat flux q'' versus k , with $\Delta T = 20$ K is shown in Figure 7.

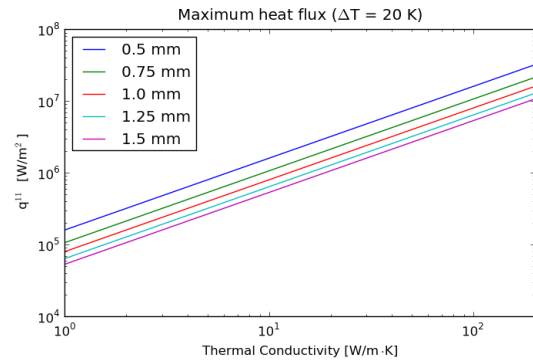


Figure 7: Heat flux limitations for maintaining less than $\Delta T = 20$ K across the sample.

8.1. Discussion of Operating Limits

Combining the two constraints gives operating limits for the samples maximum damage rate. For

the heat removal constraint, a heat transfer coefficient h of 25 kW/m²K was assumed. This is a conservative estimate based on h predicted from modeling results in Section 8.2 and reference [?]. For the ΔT constraint, temperature-dependent thermal conductivity data was used from the *Handbook of Heat Transfer (3rd Edition)*, Ed. Rohsenow, et al. [18]. The resulting operating limits are summarized in Figure 8.

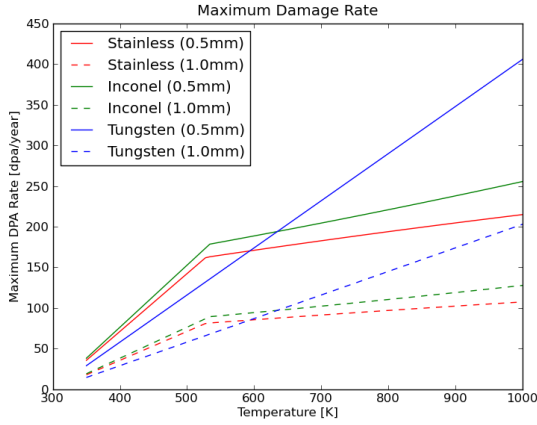


Figure 8: Operating limits for maximizing damage rate, constrained by heat removal and ΔT .

Figure 8 demonstrates that the operating limits behave differently based on the thermal properties and the dimensions of the sample. For refractory metals with high thermal conductivity (>150 W/mK) such as tungsten, the heat removal is the dominant constraint on the damage rate. However, with structural materials like Inconel and stainless steel, which have much lower thermal conductivities (10-30 W/mK), the operation is limited by heat removal at low temperature and ΔT at high temperature. Furthermore, the maximum damage rate decreases linearly with sample thickness.

8.2. Thermal Modeling

The primary limitation to accelerating DPA rates is heat removal from the samples. Helium jet impingement cooling is used because of the high heat transfer coefficients h that it can provide and because of experience in fusion divertor design [?]. Due the large heat fluxes involved and temperature requirements of the samples, accurate modeling of heat transfer is essential for temperature control and adequate heat removal.

- Jet impingement cooling experience in fusion/industry.
- Heat transfer calculation/extrapolation to show feasibility.
- It is not unreasonable to expect adequate heat removal given the extrapolations, however further modeling is required.
- Calculated requirements for helium flow.
- Feasibility of pumps / survey of required pumping technology.

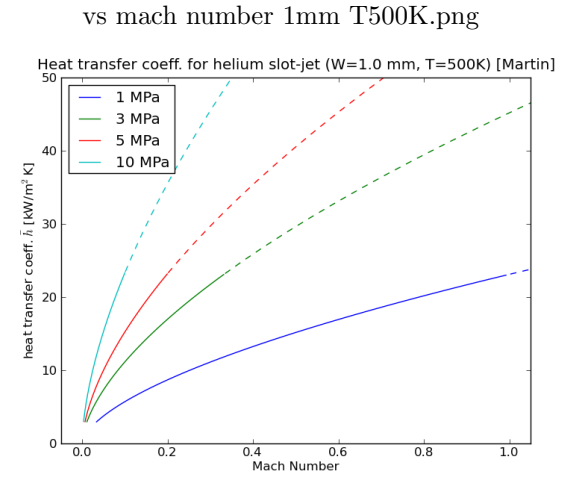


Figure 9: Calculated heat transfer coefficients calculated with the Martin [?] correlation vs helium mach number. The dotted region of the curves indicate extrapolations beyond the correlation's range.

8.3. Irradiated Sample Volume

- Discussion of estimated irradiated volume.
- Possible shape and size of of samples.

- Comparison to other techniques.

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9. DPA Calculations

When simulating neutron damage, it is important to have a model for calculating the induced damage rates in materials, so that samples can be irradiated for the appropriate exposure time. Damage rates typically decrease with energy at beam energies in the 10s of MeV, and vary significantly between materials. Calculating these damage rates is not necessarily straightforward because of the complicated physics involved with the production of primary knock-on atoms (PKA), the damage cascades that follow, and the subsequent migration of vacancies and interstitials [1].

For this study, two methods were used for calculating DPA rates. The Monte Carlo code, SRIM 2008, which includes a detailed damage calculations [5], was used to calculate damage rates and an analytical model from reference [1] was used to validate the order of magnitude of the results.

These calculations scale inversely with the displacement threshold energy E_d of the material, so selection of the proper value is important. In the literature, there is a significant variation in the values for E_d . Due to large uncertainties and the effects of crystal structure, it is not uncommon for quoted E_d values for to vary by as much as factor of 2. For these DPA rate calculations, E_d values from the ASTM E521 *Standard Practice for Neutron Radiation Damage Simulation by Charged-Particle Irradiation* [2] were used. These are also given in a table in the G. Was book [1].

These methods give results in units of displacements per ion per unit length. The results were converted to a more informative unit of displacement per atom (dpa) per unit time, which was then normalized to a reasonable beam current density. This was done to provide damage rates that be easily related to the facility's performance and beam parameters

9.1. DPA Rates from SRIM 2008

Monte Carlo codes are typically used to make displacement calculations in order to capture complicated physics of damage cascades. In this study, SRIM 2008 [5] was used to perform detailed damage cascade calculations using the minimum threshold energies listed in ASTM E521 [2]. The results are shown in Figure 10.

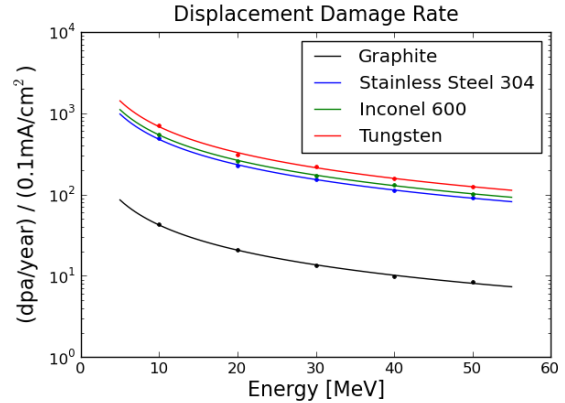


Figure 10: Monte Carlo simulation results for displacement damage rates for various materials, calculated with SRIM 2008.

9.2. Discussion of Damage Simulation

The potential differences between displacements caused by neutrons versus protons must be addressed in order to validate results from MTF. Damage from protons is caused long range coulomb scattering in addition to large angle scattering. Damage from neutrons however is dominated by large angle scattering causing higher average recoil energies. These differences in recoil spectra will likely have an effect on the distribution and average length of damage cascades. The effects on the material properties however, are unclear and require further study.

The recoil spectra for mono-energetic protons versus neutrons can have similar distributions for high energy recoils [?], but vary substantially for low energy recoils. Recoils from protons typically span a broad range of energies whereas recoils from neutrons have a much narrower distribution [1]. Despite this disparity however, since reactors typically have broad neutron spectra, their recoil spectra will also span a broad range of energies. This means that the characteristic broad recoil spectrum from

a mono-energetic proton beam could be beneficial in simulating realistic reactor conditions. Analysis of the recoil spectra requires further study with computational codes such as MCNP and GEANT4.

10. Beam Window

The sample must be surrounded by high pressure helium gas to achieve sufficient helium jet impingement cooling on both sides. However, accelerators must be kept under high vacuum in order to operate. A thin vacuum–gas boundary must therefore be designed to accommodate these requirements. Since both the strength of the window and the beam energy loss increase with window thickness, optimization is required to minimize energy loss of the beam while maintaining its structural integrity. The window material is also important. It must be resilient to radiation damage, and should be made of material of low nuclear charge in order to reduce energy loss and window heating. A schematic of the window geometry is shown in figure 11.

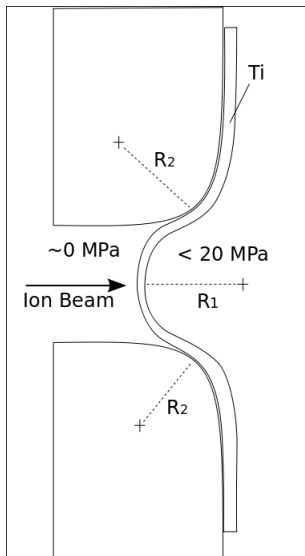


Figure 11: The schematic of the beam window. The gas pressure of the window causes it to deform in the vacuum region. The edges of the supporting aperture must be smooth to minimize the shear stress at the edge of the window.

The design requires a long (~ 10 cm) and narrow (1–3 mm) window with a thickness of 10–100 μm . Since the length of the window L is much longer the width w of the window aperture, and the thickness τ of the window is much less than the width

width w [mm]	5 MPa τ [μm]	10 MPa τ [μm]	15 MPa τ [μm]	20 MPa τ [μm]
1	2.8	5.6	8.4	11.2
2	5.6	11.2	16.8	22.3
3	8.4	16.8	25.1	33.5

Table 5: Minimum thickness τ for a titanium beam window with $L \gg w \gg \tau$ and $\sigma_{max} = 895$ MPa.

($L \gg w \gg \tau$), the window can be modeled as a thin walled cylinder. The minimum thickness can thus be calculated using equation 9, where P_o is the pressure in the target chamber, r is the radius of curvature of the window surface, and σ is the stress in azimuthal direction.

$$\sigma_\theta = \frac{P_o \cdot r}{\tau} \quad \longrightarrow \quad \tau_{min} = \frac{P_o \cdot r_{min}}{\sigma_{max}} \quad (9)$$

Beam windows are a well established technique for producing external (in-air) ion beams which are used extensively for ion beam analysis [19] and have applications in biology and medicine [20]. Since the window used for this project requires higher pressures and beam currents, a semi-empirical design approach is preferred. The window thickness should be chosen from the minimum calculated thicknesses from Table 5 and multiplied by an engineering safety factor to account for degradation due to heating and radiation damage. Since failure of the window could have serious consequences for the vacuum system and other components, the window dimensions should be experimentally validated.

11. Time Structure of the Beam Interactions

Proton irradiation for simulation of damage has the benefit of very high damage rates compared to those incurred by neutrons. Accelerated damage, however, has the potential to introduce non-linearity in the materials response due to interference between damage cascades if the damage rates are too high.

Cyclotrons produce inherently pulsed beams, even when operating in continuous wave (CW) mode. A 35 MeV cyclotron will typically have a frequency of ~ 100 MHz and a duty factor of $\sim 10\%$. This makes the instantaneous damage rate higher than the time averaged damage rate by roughly a factor of 10. This could further contribute to the unrealistic damage effects. Analysis is therefore

necessary to show the constraints on accelerating the damage rates in the samples.

A simple but adequate approach to this issue is a comparison between the volumetric displacement rate and characteristic timescales of the cyclotron pulses and the damage cascades. The volumetric displacement rate R_d can be calculated from the DPA rate R_{dpa} from equation 10.

$$R_{dpa} \left[\frac{\text{disp.}}{\text{atom} \cdot \text{s}} \right] \cdot n \left[\frac{\text{atom}}{\text{m}^3} \right] = R_d \left[\frac{\text{disp}}{\text{m}^3 \cdot \text{s}} \right] \quad (10)$$

The mean time τ between the displacements can then be calculated using the volume of a displacement cascade, which can be approximated from the range and lateral straggling of the PKAs. The range of the PKA, R_{pka} , can be determined from the from elastic scattering kinematics. Range data and the lateral straggling L_{pka} can be calculated with SRIM 2008 [5]. For a conservative estimate, a sphere can be used for the damage volume $V_{sphere} = 4/3\pi R_{pka}^3$. For a more realistic estimate, the damage cascade can be modeled as a cone with volume $V_{cone} = \frac{1}{3}\pi R_{pka}^2 L_{pka}$. The mean time between displacements in the maximum energetically allowed cascade volume is shown as a function of beam energy in figure 12. The relevant damage timescales are also superimposed.

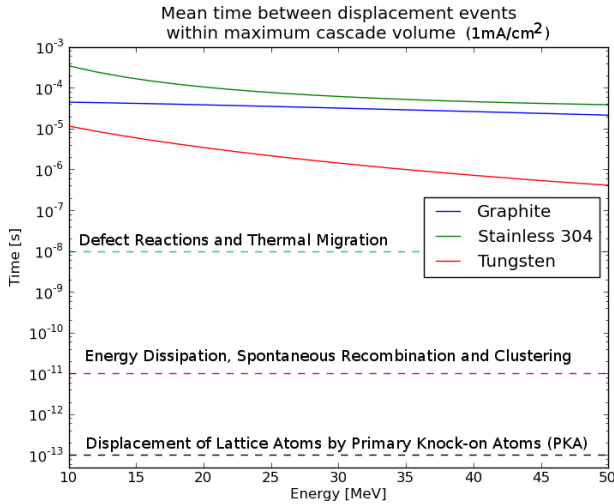


Figure 12: Mean time between displacements events per cascade volume is shown assuming a conical volume and an instantaneous beam current density of 1mA/cm². This demonstrates that

For a modest time averaged beam current density of 0.1 mA/cm² corresponding to 1 mA/cm²

of instantaneous current density, the time between displacements in a given cascade volume τ_d is on the order of micro-seconds or longer. This means that after the initiation of a damage cascade, all of the damage processes, including the formation of a PKA, its energy dissipation, and finally recombination and thermal migration of defects, have time to reach equilibrium before the next cascade is initiated within that volume. Similarly, the beam cyclotron period is roughly 10⁻⁸ seconds, which is also much shorter than τ_d .

Since the displacement timescale within a cascade volume τ_d is at least two orders of magnitude longer than the damage processes involved, it is unlikely that overlapping damage cascades from the accelerated damage rate or the beam's time structure will have any affect on the damage physics.

12. Future work

- Detailed engineering design
- Further simulation of damage physics in the 35MeV energy range
- Activation and shielding analysis of the facility
- Experimental and CFD modeling of heat removal

13. Conclusions

- Summary
- Discussion of advantages
- Discussion of technical risk

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