

# CE394M: Linear Elasticity

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# Isotropic linear elastic stress-strain relations

The relationship between the stress and strain tensor is a linear one. The stress component is a linear combination of the strain tensor. The most general form for *linear* stress-strain relations for a *Cauchy elastic* material is given by:

Where  $\sigma_{ij}^0$  is the components of initial stress tensor corresponding to the initial strain free (when all strain components  $\varepsilon_{kl} = 0$ ).  $D_{ijkl}$  is the tensor of material *elastic constants*.

If it is assumed that the initial strain free state corresponds to an *initial stress free state*, that is  $\sigma_{ij}^0 = 0$ , the equations reduces to:

# Observation on linear elasticity

- 1  $\sigma_{ij} = D_{ijkl}\varepsilon_{kl}$  is a general expression relating stress to strains for a linear solid.
- 2  $D_{ijkl}$  is a 4th order tensor containing 81 terms (we trick using symmetry and reduce order).
- 3  $D_{ijkl}$  material response functions having dimensions  $F/L^2$ .
- 4 Homogeneous:  $D_{ijkl}$  independent of position
- 5 Isotropic:  $D_{ijkl}$  independent of frame of reference.
- 6 Because the stress is symmetric:  $\sigma_{ij} = \sigma_{ji}$ ,  $D_{ijkl} = D_{jikl}$ . Strain is symmetric  $\varepsilon_{kl} = \varepsilon_{lk}$  and  $D_{ijkl} = D_{ijlk}$ . Hence the number of independent variables drop from 81 to 36.
- 7 Both the stress and the strain tensor have only 6 independent values, therefor write them as vectors, then the stiffness tensor can be written as a matrix (compromise I can not rotate tensor).

# Stress-strain relationship

$$\begin{bmatrix} \sigma_{11} \\ \sigma_{22} \\ \sigma_{33} \\ \sigma_{12} \\ \sigma_{23} \\ \sigma_{31} \end{bmatrix} = \begin{bmatrix} D_{11} & D_{12} & D_{13} & D_{14} & D_{15} & D_{16} \\ D_{21} & D_{22} & D_{23} & D_{24} & D_{25} & D_{26} \\ D_{31} & D_{32} & D_{33} & D_{34} & D_{35} & D_{36} \\ D_{41} & D_{42} & D_{43} & D_{44} & D_{45} & D_{46} \\ D_{51} & D_{52} & D_{53} & D_{54} & D_{55} & D_{56} \\ D_{61} & D_{62} & D_{63} & D_{64} & D_{65} & D_{66} \end{bmatrix} \begin{bmatrix} \varepsilon_{11} \\ \varepsilon_{22} \\ \varepsilon_{33} \\ \varepsilon_{12} \\ \varepsilon_{23} \\ \varepsilon_{31} \end{bmatrix}$$

$D_{ijkl}$  is a tensor of material *elastic constants*. However, the above  $[\mathbf{D}]$  is not a tensor anymore. So we can not rotate the matrix to another frame of reference. This relationship is useful for isotropic materials, where  $\mathbf{D}$  is independent of the frame of reference.

The inverse of the relationship (Compliance matrix):

# Hooke's law

Empirical observation:

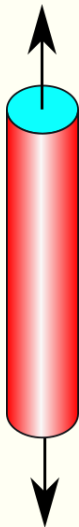
Where  $E$  is defined as the *Young's modulus*.  
The lateral strains are defined as:

Using superposition for principal stresses:

$$\varepsilon_{11} = (1/E) [\sigma_{11} - \nu\sigma_{22} - \nu\sigma_{33}]$$

$$\varepsilon_{22} = (1/E) [-\nu\sigma_{11} + \sigma_{22} - \nu\sigma_{33}]$$

$$\varepsilon_{33} = (1/E) [-\nu\sigma_{11} - \nu\sigma_{22} + \sigma_{33}]$$



# Hooke's law

$$\begin{Bmatrix} \varepsilon_{11} \\ \varepsilon_{22} \\ \varepsilon_{33} \end{Bmatrix} = \frac{1}{E} \begin{bmatrix} 1 & -\nu & -\nu \\ -\nu & 1 & -\nu \\ -\nu & -\nu & 1 \end{bmatrix} \begin{Bmatrix} \sigma_{11} \\ \sigma_{22} \\ \sigma_{33} \end{Bmatrix}$$

It is possible to invert the matrix to obtain the generalized Hooke's law:

$$\begin{Bmatrix} \sigma_{11} \\ \sigma_{22} \\ \sigma_{33} \\ \sigma_{12} \\ \sigma_{13} \\ \sigma_{23} \end{Bmatrix} = \alpha \begin{bmatrix} (1-\nu) & \nu & \nu & 0 & 0 & 0 \\ & (1-\nu) & \nu & 0 & 0 & 0 \\ & & (1-\nu) & 0 & 0 & 0 \\ & & & \frac{(1-2\nu)}{2} & 0 & 0 \\ & & & & \frac{(1-2\nu)}{2} & 0 \\ & & & & & \frac{(1-2\nu)}{2} \end{bmatrix} \begin{Bmatrix} \varepsilon_{11} \\ \varepsilon_{22} \\ \varepsilon_{33} \\ 2\varepsilon_{12} \\ 2\varepsilon_{13} \\ 2\varepsilon_{23} \end{Bmatrix}$$

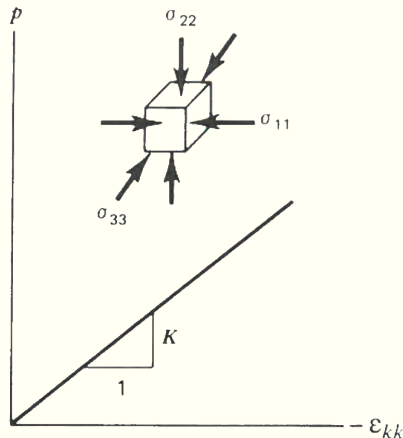
Where  $\alpha = E/((1+\nu)(1-2\nu))$ . Similarly, we can obtain the inverse matrix.

# Hooke's law

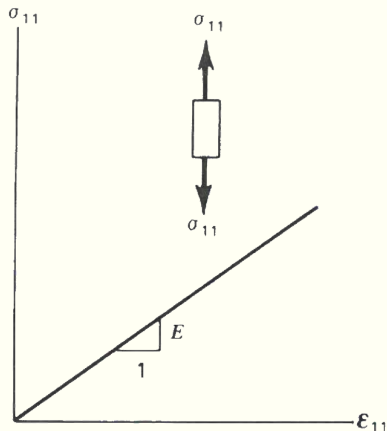
The matrices  $[\mathbf{C}]$  and  $[\mathbf{D}]$  contains two independent variables  $E$  and  $\nu$ , where  $E > 0$  and  $-1 \leq \nu \leq 0.5$ . The matrix can also be defined in terms of Lamé's constants.

$$\left\{ \begin{array}{ll} \lambda = \frac{E\nu}{(1+\nu)(1-2\nu)} & \text{Lamé's modulus (wave propagation)} \\ \mu = G = \frac{E}{2(1+\nu)} & \text{Shear modulus (shear behavior)} \\ K = \frac{E}{3(1-2\nu)} & \text{Bulk modulus (volumetric behavior)} \end{array} \right.$$

# Isotropic linear elastic



(a)



(b)

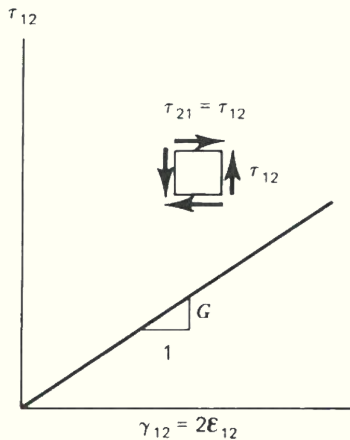
Behavior of isotropic linear elastic material in simple tests: (a) hydrostatic compression test ( $\sigma_{11} = \sigma_{22} = \sigma_{33} = p$ ) and (b) simple tension test (Chen 1994)



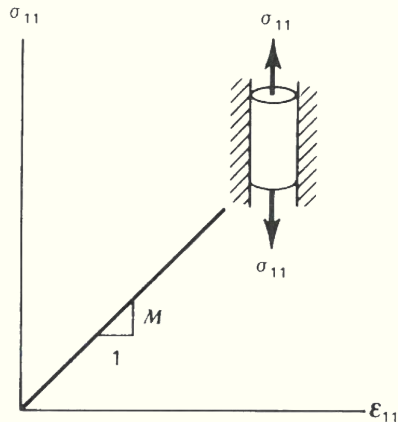
**Hydrostatic compression test** The non-zero components of stress:  
The *Bulk modulus*,  $K$ , is defined as the ratio between the *hydrostatic pressure*  $p$  and the corresponding volume change  $\delta\varepsilon_v = \varepsilon_{kk}$ .

**Simple tension test** The only non-zero components of stress:  
The *Young's modulus*,  $E$ , and *Poisson's ratio*,  $\nu$  as.

# Isotropic linear elastic



(c)



(d)

Behavior of isotropic linear elastic material in simple tests: (c) pure shear test, and (d) uniaxial strain test (Chen 1994)

## Simple shear test

The non-zero components of stress:

The *Shear modulus*,  $G$  or  $\mu$ , is defined as:

**Uniaxial strain test** The test is carried out by applying a uniaxial stress component  $\sigma_{11}$  in the axial direction of a cylindrical sample, whose lateral surface is *restrained* against lateral movement (Oedometer test). Axial strain  $\varepsilon_{11}$  is the only nonvanishing component. The *constrained modulus*  $M$  or as PLAXIS calls it  $E_{oed}$  is defined as the ratio between  $\sigma_{11}$  and  $\varepsilon_{11}$ .

# Plane stress v Plane strain

For a frame with an axis perpendicular to the plane of interest,  $x_3$  or  $z$ :

## Plane stress

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The strain in  $z$  is written as:

## Plane strain

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The stress in  $z$  is written as:

# Elastic solution for settlement under foundations

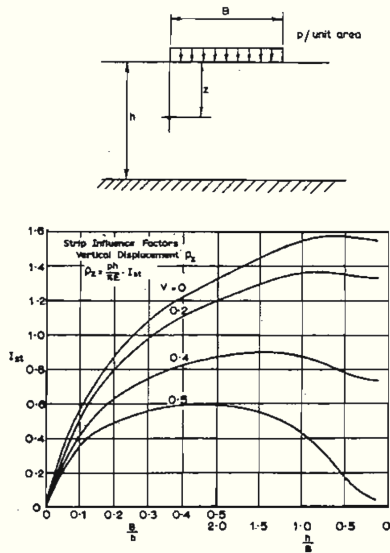


FIG.5.2 Strip curves for  $\rho_z$ .

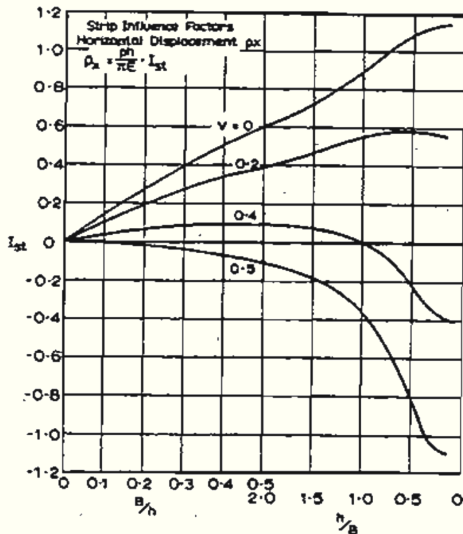
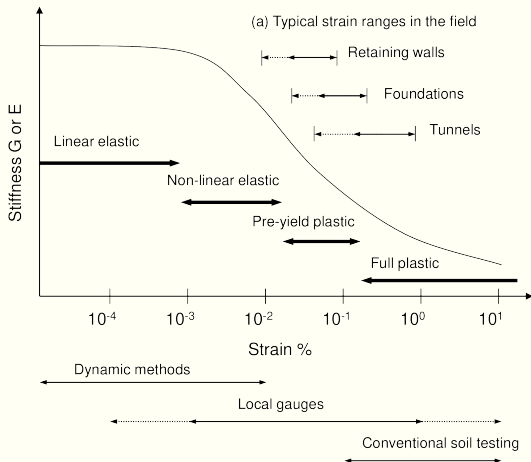


FIG.5.3 Strip curves for  $\rho_x$ .

- ① *Ease of use* Only two parameters, choose equivalent values representative of strain/stress levels.
- ② *Disadvantage*: No failure criteria.
- ③ Validate code with chart solutions ("*Exact solutions*"), e.g., Poulos and Davis (1974).
- ④ Useful to get feeling of problem (low stress levels) not wide distribution of plastic zones.

# Stiffness: small to large strains

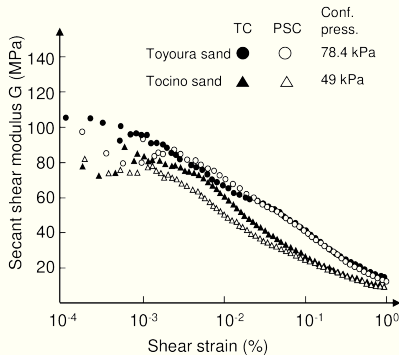


Local gauges

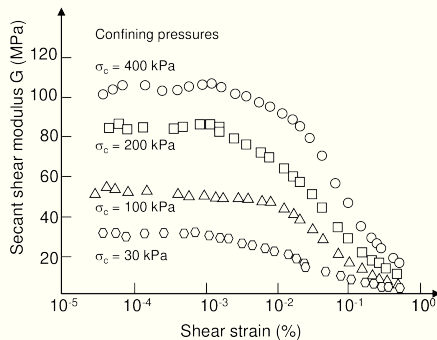


Bender element (GDS)

# Stiffness: small to large strains



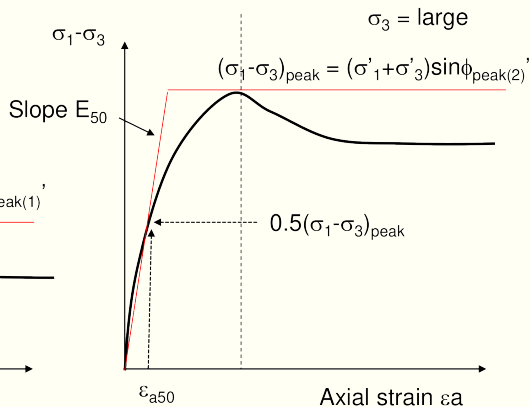
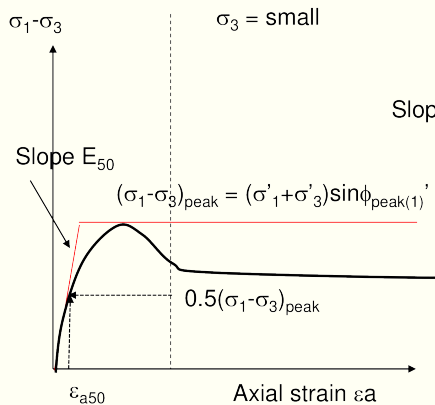
(a) Toyoura and Tocino sands



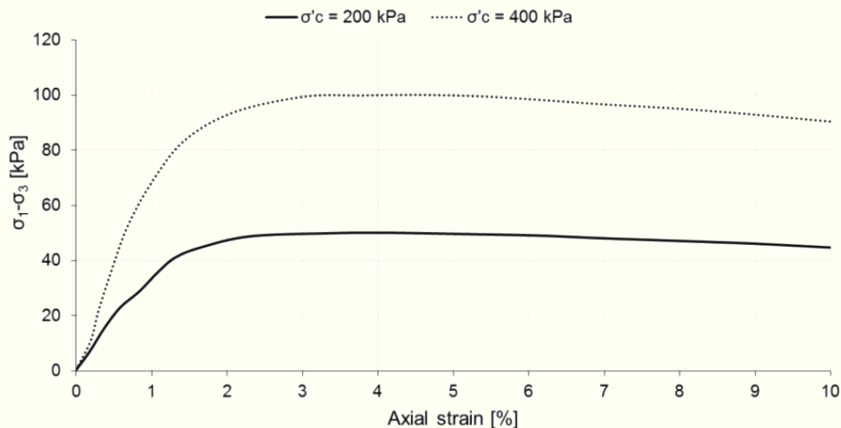
(b) Kaolin clay



# Stiffness at intermediate strains

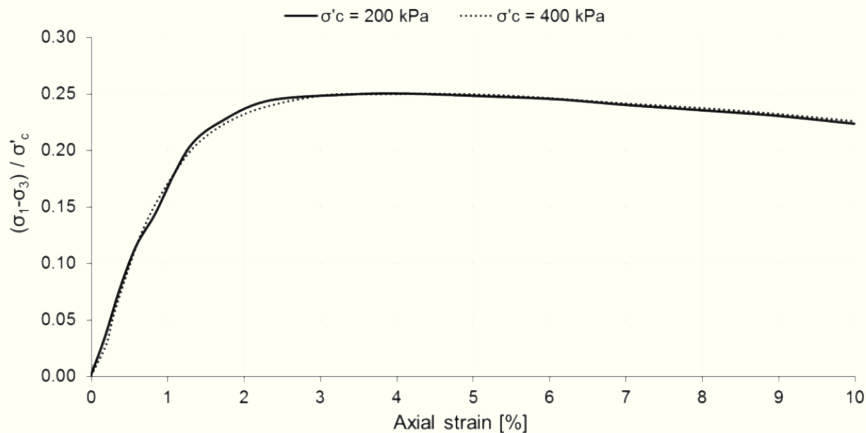


# Undrained strength



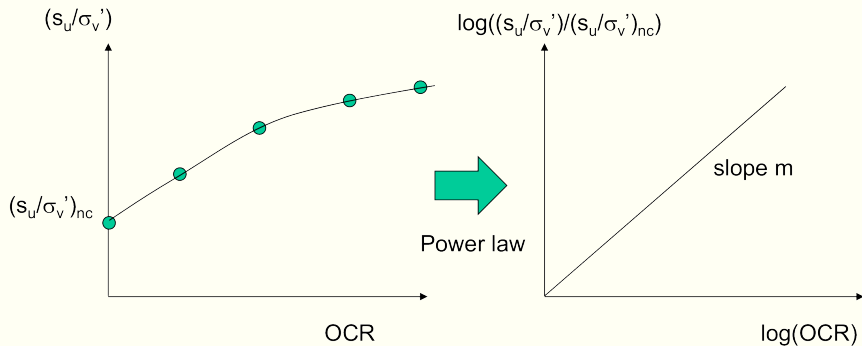
Triaxial compression test data of homogeneous clay (Ladd & Foott, 1974)

# Normalized undrained strength



Normalised triaxial compression test data of homogeneous clay (Ladd & Foott, 1974)

# Stress History and Normalized Soil Engineering Properties (SHANSEP) (Ladd and Foote, 1974)



# Isotropic Linear Elastic Stress-strain relationship

The *isotropic tensor*  $D_{ijkl}$ :

$$D_{ijkl} = \lambda \delta_{ij} \delta_{kl} + \mu (\delta_{ik} \delta_{jl} + \delta_{il} \delta_{jk}) + \alpha (\delta_{ik} \delta_{jl} - \delta_{il} \delta_{jk})$$

Where  $\lambda$ ,  $\mu$ , and  $\alpha$  are scalar constants. Since  $D_{ijkl}$  must satisfy symmetry,  $\alpha = 0$ .

So the stress:

Hence for an isotropic linear elastic material, there are only two independent material constants,  $\lambda$  and  $\mu$ , which are called *Lame's constants*.

# SHANSEP procedure