

# Bide (Peter) Huang

Website: <https://hbd730.github.io/>

Email: [hbd730@gmail.com](mailto:hbd730@gmail.com)

Mobile: +61 430 001 790

## SUMMARY

---

A result-driven software and system engineer with over 8 years experience in software engineering, possess strong competency and industrial experience in areas of mapping and localization, machine learning and vision.

## EXPERIENCE

---

### Bosch

*Lead Software & System Engineer*

Melbourne, Australia

*Jun 2018 – Present*

Reporting to engineering manager, responsible for delivering software product/service for various customers including Victoria government and OEMs. Define engineering tasks as per project requirements, design system software architecture and develop feature, integrate algorithms, conduct testing and manage release, organise customer meetings and cross-regional collaborations.

- Successful PoC for electronic horizon in L2+ Hand Free function in-vehicle demonstration. Designed and implemented horizon APIs, RViz/DeckGL visualization, and behaviour layer map enrichment framework in crowd-sourced mapping pipeline.
- Regional number 1 in successful demonstration of fully automated driving system for 2.5 million dollar government funded project. End-to-end responsibility of mapping and localization including GPS/Camera/Lidar/Radar sensors integration and calibration, data extraction and visualization, development of algorithm, and conduct mapping activities and road testing.
- Designed novel approach for developing HD planner map creation pipeline to achieve centimetre accuracy. Achieved centimetre accuracy of localization accuracy through multi-beam lidar intensity calibration, multi-sensor calibration, multi-modal localization performance optimization.
- Research and develop graph based VisualSLAM algorithm with stereo video camera for EKF sensor fusion; Creation and deployment of multi-layer spatial data visualization website for analysis and critical decision making.
- Second runner-up of machine learning business innovation competition - Developed prototype of vision based lane marker detection using semantic segmentation for road quality analysis.

### Blackmagic Design

*Software Engineer*

Melbourne, Australia

*Jun 2014 – Jun 2018*

Reporting to software engineering manager, responsible for real time RTOS-based embedded software development for high performance video post-production product, development of drivers, API and multi-threaded cross platform video playback and capture applications, and engineering tools.

- Worked closely with other engineers to develop and release the world's smallest Ultra HD broadcast deck with professional 10-bit video/audio dual disk SD/UHS-II recording and playback.
- Lead engineer for successful delivery of Disney customer release for HyperDeck Mini Studio; Designed and implemented Advanced Media Protocol which enables video playback synchronization, frame-accurate timeline and slow motion control over serial and Ethernet.
- Lead engineer for Video Assist 4K product, successfully delivered and demonstrated 3D LUT video color correction preview feature and multi-language display and update in CES 2017.

### Welling & Crossley

*Electronics Engineer*

Melbourne, Australia

*Jan 2011 – Jun 2014*

Reporting to chief R&D engineer, responsible for research and develop electronic schematics and PCBs, embedded software/device drivers for engine control unit, Qt based touch screen controller, variable speed pump controller, and remote controller for irrigation and power generator system.

- Outstanding employee achievement award for successful design and deployment of engine speed sensor for diesel and petrol power generators, which saves significant manufacturing cost.
- Successful demonstration of AS-2941 compliant touch screen fire pump controller to company CEO and stakeholders.
- Critical troubleshooting for half million dollar "Black Start" 500KVA power generator for Queensland water treatment plant.

## QUALIFICATION

---

<b>Freiburg University</b>	Online
<i>Robot Mapping</i>	<i>Sep. 2018</i>
<b>Udacity</b>	Online
<i>Self-Driving Car Nano Degree Certificate</i>	<i>Nov. 2016 – Sep. 2017</i>
<b>Coursera</b>	Online
<i>Machine Learning, Robotics Specialization</i>	<i>June. 2015</i>
<b>RMIT University</b>	Melbourne, Australia
<i>Graduate Diploma in Computer Engineering (High Distinction)</i>	<i>Sep. 2010 – Nov. 2010</i>
<b>RMIT University</b>	Melbourne, Australia
<i>Master of Electronics Engineering (High Distinction)</i>	<i>Aug. 2008 – Jul. 2012</i>
<b>Fuzhou University</b>	Fuzhou, China
<i>Bachelor of Science in Applied Physics</i>	<i>Sep 2004 – Jun 2008</i>

## PROFESSIONAL SKILLS

---

- **Programming Languages:** C/C++, Python, Bash, HTML, CSS, Javascript, SQL, Objective C, Matlab, VHDL, PLC, Assembly,  $\text{\LaTeX}$ , LabView
- **OS/Middleware:** Linux, Windows, FreeRTOS, ROS
- **Software Framework/Libraries:** Qt, OpenGL, Protobuf, Boost, Matplotlib, Numpy, Scipy, Pcl, Eigen, Sophus, G2O, Ceres, OpenCV, Pytorch, Tensorflow
- **Software Tools:** CMake, SCon, Conan, Gitlab, Jenkins, Docker, AWS, Git, Confluence, Jira, Office365
- **Technical Stack:** Ultrasonic/Radar/Video/Lidar knowledge, Embedded Software Design, Data Analysis and Visualization, modelling and simulation, SLAM, Sensor Fusion, Nonlinear Optimization, Machine learning, Deep learning, Computer Vision