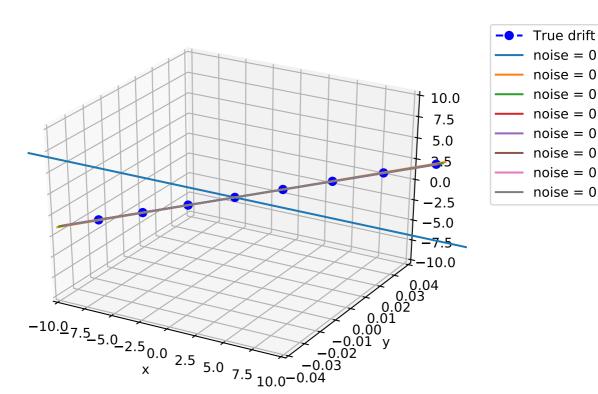
3D comparison of true drift function vs estimated drift functions in 4D system



noise = 0.5noise = 0.1noise = 0.05

noise = 0.01

noise = 0.005

noise = 0.001

noise = 0.0005

noise = 0.0001