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# Learning Stochastic Differential Equations with Bridge Sampling

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## Abstract

1       The abstract paragraph should be indented 1/2 inch (3 picas) on both the left- and  
2       right-hand margins. Use 10 point type, with a vertical spacing (leading) of 11 points.  
3       The word **Abstract** must be centered, bold, and in point size 12. Two line spaces  
4       precede the abstract. The abstract must be limited to one paragraph.

5   Points to cover:

- 6       • data specification
- 7       • Hermite polynomial and drift function representation
- 8       • Expectation and maximization formulas assuming data is filled in
- 9       • Filling data in with Brownian bridge
- 10      • MCMC iterations of brownian bridge using girsanov likelihood
- 11      • how synthetic data is generated
- 12      • results: 1D, 2D, 3D damped duffing, 3D lorenz
- 13      • plots: error of theta vs noise, error vs amount of data (number of data points) parametric
- 14      curves for noise levels, brownian bridge plots for illustration, ...
- 15      • Note: constant noise case, not inferring the gvec

## 16   1   Model Setup

17   Our goal here is to start with  $\mathbb{R}^d$  dimensional time series data and a non-parametric model to infer the  
18   coefficients of the Hermite basis functions which would result in a parametric equation. The general  
19   form of the governing equation is:

$$dX(t) = f(X(t)) dt + \Gamma dW(t) \tag{1}$$

20   where  $\Gamma$  is a constant diagonal matrix of noise levels. For these experiments, we assume that the  
21   noise levels are known beforehand and are not inferred.

22   To model the general form of the drift function, we represent the drift function as an additive function  
23   of the Hermite basis polynomials of maximum degree  $D$ . The  $\zeta$  parameters will be inferred. Through  
24   the combination of inferred parameters and the Hermite polynomial basis, the governing equation  
25   can be discovered.

$$f(x) = \sum_{i=0}^M \zeta_i \psi_i(x) \tag{2}$$

26 The orthonormal Hermite basis functions have the general form

$$H_n(x) = (-1)^n e^{x^2/2} \frac{d^n}{dx^n} e^{-x^2/2} \quad (3)$$

27 which results in the following set of polynomials:

$$\begin{aligned} H_0(x) &= 1/c_0, & c_0 &= \sqrt{2\pi\sqrt{0!}} \\ H_1(x) &= x/c_1, & c_1 &= \sqrt{2\pi\sqrt{1!}} \\ H_2(x) &= (x^2 - 1)/c_2, & c_2 &= \sqrt{2\pi\sqrt{2!}} \\ H_3(x) &= (x^3 - 3x)/c_3, & c_3 &= \sqrt{2\pi\sqrt{3!}} \end{aligned}$$

28 We demonstrate the method for 1, 2 and 3 dimensional systems.

29 • For the 1-dimensional system, we use the ? oscillator:

$$dX(t) = (\alpha X(t) + \beta X(t)^2 + \gamma) dt + g dW(t) \quad (4)$$

30 • For the 2-dimensional system, we use the undamped Duffing oscillator:

$$\begin{aligned} dX_1(t) &= X_2(t)dt + g_1 dW_1(t) \\ dX_2(t) &= (-X_1(t) - X_1^3(t))dt + g_2 dW_2(t) \end{aligned}$$

31 • For the 3-dimensional case, we consider 2 different form of equations. The first one is  
32 the damped Duffing oscillator, a general form of the damped oscillator considered in the  
33 2-dimensional case:

$$\begin{aligned} dX_1(t) &= X_2(t) dt + g_1 dW_1(t) \\ dX_2(t) &= (\alpha X_1(t) - \beta X_1(t) - \delta X_2(t) + \gamma \cos(X_3(t))) dt + g_2 dW_2(t) \\ dX_3(t) &= \omega dt + g_3 dW_3(t) \end{aligned}$$

34 • Another example considered for the 3-dimensional case is the Lorenz oscillator:

$$\begin{aligned} dX_1(t) &= \sigma(X_2(t) - X_1(t)) dt + g_1 dW_1(t) \\ dX_2(t) &= (X_1(t)(\rho - X_3(t)))dt + g_2 dW_2(t) \\ dX_3(t) &= (X_1(t)X_2(t) - \beta X_3(t)) dt + g_3 dW_3(t) \end{aligned}$$

35 For the general case where  $X = (x_1, \dots, x_d) \in \mathbb{R}^d$  case, the general form of the drift function  
36  $\vec{f} = (f_1(x_1, \dots, x_d), \dots, f_d(x_1, \dots, x_d))$  includes cross interactions between the dimensions of  
37  $X$  to create an additive function of Hermite polynomial of maximum degree  $M$ :

$$f(x_1, \dots, x_d) = \sum_{m=0}^M \sum_{\sum i_m=m} \zeta_{i_m}^d \psi_{i_m}^d \quad (5)$$

38 For simplicity, consider the example where the  $X \in \mathbb{R}^2$  and the highest degree of the Hermite  
39 polynomial is three, including four Hermite polynomials:

$$\begin{aligned} f(x_1, x_2) &= \sum_{m=0}^2 \sum_{i+j=m} \zeta_{i,j} \psi_{i,j} \\ &= \sum_{d=0}^3 \sum_{i+j=d} \zeta_{i,j} H_i(x_1) H_j(x_2) \\ &= \sum_{i+j=0} \zeta_{i,j} H_i(x_1) H_j(x_2) + \sum_{i+j=1} \zeta_{i,j} H_i(x_1) H_j(x_2) + \sum_{i+j=2} \zeta_{i,j} H_i(x_1) H_j(x_2) + \sum_{i+j=3} \zeta_{i,j} H_i(x_1) H_j(x_2) \\ &= \zeta_{0,0} H_0(x_1) H_0(x_2) + \zeta_{0,1} H_0(x_1) H_1(x_2) + \zeta_{1,0} H_1(x_1) H_0(x_2) + \zeta_{0,2} H_0(x_1) H_2(x_2) \\ &\quad + \zeta_{2,0} H_2(x_1) H_0(x_2) + \zeta_{1,1} H_1(x_1) H_1(x_2) + \zeta_{0,3} H_0(x_1) H_3(x_2) + \zeta_{3,0} H_3(x_1) H_0(x_2) \\ &\quad + \zeta_{2,1} H_2(x_1) H_1(x_2) + \zeta_{1,2} H_1(x_1) H_2(x_2) \end{aligned}$$

## 40 **2 Expectation Maximization Steps**

41 The data provided is in the form of a time series,  $X \in \mathbb{R}^d$  at regular time points  $t_l, 0 \leq l \leq L$ . Note:  
42 EM step in the sampling writeup.

## 43 **3 Brownian bridge sampling**

44 When the inter-observation time of the observed data  $X$  is large, the expectation step becomes less  
45 accurate. To mitigate this problem, we can fill in the observed data with a Brownian bridge. We  
46 generate many samples of the  $N$ –dimensional Brownian bridge and accept-reject samples using the  
47 Metropolis-Hastings algorithm. The approximation of the likelihood is obtained using the Girsanov  
48 likelihood function.

### 49 **3.1 Brownian bridge**

50 The  $\mathbb{R}^N$  dimensional Brownian bridge is defined by the integral:

$$I(t) = \int_0^t \frac{1-t}{1-T} dW(t) \tag{6}$$

### 51 **3.2 Metropolis Algorithm**