TASK 1&2 Tutorials FSE

Specify a transition systems description

 $TS = \{S, Act, \rightarrow I, AP, L\}$

 $S_0=\langle x_2=0,y_2=0,r_2=0
angle$ $S_1 = \langle x_2 = 1, y_2 = 0, r_2 = 0 \rangle$

 $S = \{S_0, S_1, S_2, S_3\}$

Name: Heja Bibani Student Number: 16301173

TASK 1

Consider the following Sequential hardware circuit:

OR

 r_2

Where x_2 is an input variable, r_2 a register, and y_2 an output variable. The control function for output variable y_2 is defined by $\lambda_{y_2}=x_2\wedge r_2$ and the register evaluation changes according to the circuit funciton $\delta_{r_2}=x_2ee r_2$. Initially, r_2 = 0, and x_2 can be 0 or 1. Once r_2 is evaluated to be 1 (according to $\delta_{r_2}=x_2ee r_2$), it will keep that value.

 $S_2 = \langle x_2 = 0, y_2 = 0, r_2 = 1 \rangle$ $S_3=\langle x_2=1,y_2=1,r_2=1
angle$ $Act = \{input0, input1\}$ $(S_3, input1, S_3)$ $I = \{S_0, S_1\}$ $AP = \{x_2, y_2, r_2\}$ $L(S_0) = \emptyset$ $L(S_1) = \{x_2\}$

 $\rightarrow = \{(S_0, input0, S_0), (S_0, input1, S_1), (S_1, input0, S_2), (S_1, input1, S_3), (S_2, input0, S_2), (S_2, input1, S_3), (S_3, input0, S_2), (S_4, input0, S_4), (S_6, input0, S_6), (S_6, input0, S_6),$ $L(S_2) = \{r_2\}$ $L(S_3) = \{x_2, r_2, y_2\}$ Specify a transition systems diagram S₀ **S1** $\{x_{2}\}$ $\{x_2 = 0, r_2 = 0, y_2 = 0\}$ $\{x_2=1, r_2=0, y_2=0\}$

0 $\{x_2, r_2, y_2\}$ $\{r_{2}\}$ $\{x_2=0, r_2=1, y_2=0\}$ **S2** S₃ PG₂ PG₁ PG3

Consider the following Parallel Program $x := x + 1 \mid \mid \mid x := 2.x - 1 \mid \mid \mid x := 2^x$ We assume that initially x = 3. Describe the program graph (graph only) and transition system of this parallel program. For the transition system, you need to provide both the transition system graph, and the transition system description. **Program Graph** x := x + 1x := 2x - 1

PG1 ||| PG2 l_1l_2 x := 2x - 1

x := 2x - 1x := x + 1 $x := 2^x$ $l_1l_2^{'}l_3$ $l_1 l_2 l_3$ $l_{1}^{'}l_{2}l_{3}$ x := x + 1x := 2x - 1x := 2x - 1 $x := 2^{x}$ $l_{1}l_{2}l_{3}$ $l_1l_2^{\prime}l_3^{\prime}$ $l_{1}^{'}l_{2}l_{3}^{'}$ x := 2x - 1 $l_{1}^{'}l_{2}^{'}l_{3}^{'}$ **Transition Graph** TS(PG1 ||| PG2 ||| PG3) $l_1l_2l_3$ x = 3β $l_{1}^{'}l_{2}l_{3}$ $l_{1}l_{2}^{'}l_{3}$ $l_{1}l_{2}l_{3}^{'}$ x = 4x = 8x = 5β $l_{1}^{'}l_{2}^{'}l_{3}$ $l_{1}^{'}l_{2}l_{3}^{'}$ $l_{1}^{'}l_{2}^{'}l_{3}$ $l_{1}l_{2}^{'}l_{3}^{'}$ $l_{1}^{'}l_{2}l_{3}^{'}$ $l_{1}l_{2}^{'}l_{3}^{'}$ x = 16x = 32x = 9x = 15β β α $l_{1}^{'}l_{2}^{'}l_{3}^{'}$ $l_{1}^{'}l_{2}^{'}l_{3}^{'}$ $l_{1}^{'}l_{2}^{'}l_{3}^{'}$ $l_{1}^{'}l_{2}^{'}l_{3}^{'}$ $l_{1}^{'}l_{2}^{'}l_{3}^{'}$ $l_{1}^{'}l_{2}^{'}l_{3}^{'}$

Transition System Description $TS = \{S, Act,
ightarrow I, AP, L\}$ $S = \{S_0, S_1, S_2, S_3, S_4, S_5, S_6, S_7, S_8, S_9, S_{10}, S_{11}, S_{12}, S_{13}, S_{14}, S_{15}\}$ Where $S_0=\langle l_1,l_2,l_3,x=3
angle$ $S_1=\langle l_1^{'}, l_2, l_3, x=4
angle$ $S_2=\langle l_1^{\prime}, l_2^{\prime}, l_3, x=7
angle$ $S_3 = \langle l_1^{'}, l_2^{'}, l_3^{'}, x = 128
angle$ $S_4 = \langle l_1^{'}, l_2, l_3^{'}, x = 16
angle$ $S_5=\langle l_1^{\prime}, l_2^{\prime}, l_3^{\prime}, x=31
angle$ $S_6=\langle l_1,l_2',l_3,x=5
angle$ $S_7=\langle l_1^{\prime}, l_2^{\prime}, l_3, x=6
angle$ $S_8 = \langle l_1', l_2', l_3', x = 64
angle$ $S_9 = \langle l_1, l_2', l_3', x = 32
angle$ $S_{10} = \langle l_{1}^{'}, l_{2}^{'}, l_{3}^{'}, x = 33
angle$ $S_{11} = \langle l_1, l_2, l_3', x = 8 \rangle$ $S_{12}=\langle l_{1}^{'},l_{2},l_{3}^{'},x=9
angle$ $S_{13} = \langle l_{1}^{'}, l_{2}^{'}, l_{3}^{'}, x = 17
angle$ $S_{14} = \langle l_1, 1_2^{'}, l_3^{'}, x = 15
angle$ $S_{15} = \langle l_1^{'}, l_2^{'}, l_3^{'}, x = 16
angle$ $Act = \{\alpha, \beta, \gamma\}$ Where $\alpha \equiv x := x+1$, $\beta \equiv x := 2x-1$, $\gamma \equiv x := 2^x$ $\rightarrow = \{(S_0,\alpha,S_1),(S_1,\beta,S_2),(S_2,\gamma,S_3),(S_1,\gamma,S_4),(S_4,\beta,S_5),(S_0,\beta,S_6),(S_6,\alpha,S_7),(S_7,\gamma,S_8),(S_6,\gamma,S_9),(S_9,\alpha,S_{10}),(S_9,\alpha,S_{1$

 $L(S_0) = \{l_1, l_2, l_3, x = 3\}$ $L(S_1) = \{l_1', l_2, l_3, x = 4\}$ $L(S_2) = \{l_1^{'}, l_2^{'}, l_3, x = 7\}$ $L(S_3) = \{l_1', l_2', l_3', x = 128\}$

 $L(S_{12}) = \{l'_1, l_2, l'_2, x = 9\}$

 $L(S_{13}) = \{l_{1}^{'}, l_{2}^{'}, l_{3}^{'}, x = 17\}$

 $L(S_{14}) = \{l_1, l_2^{'}, l_3^{'}, x = 15\}$

 $L(S_{15}) = \{l_1^{\prime}, l_2^{\prime}, l_3^{\prime}, x = 16\}$

get_soda

soda

 $I = \{pay\}$

 $L(pay) = \emptyset$

 $TS = \{S, Act,
ightarrow I, AP, L\}$ $S = \{pay, select, beer, soda\}$

 $AP = \{paid, soda, beer\}$

 $L(soda) = \{paid, soda\}$

 $Act = \{insert_coin, \tau, get_soda, get_beer\}$

 $I = \{S_0\}$

 $(S_0, \gamma, S_{11}), (S_{11}, \alpha, S_{12}), (S_{12}, \beta, S_{13}), (S_{11}, \beta, S_{14}), (S_{14}, \alpha, S_{15})$

Task 2 **Question 1** Consider the following transition system T S of the simple beverage vending machine:

 $insert_coin$

Prove that $TS \models \Box \diamond (soda \lor beer), TS \nvDash \Box soda$ and $TS \nvDash \Box \diamond (soda \land beer)$

select

get_beer

 $\rightarrow = \{pay, insert_coin, select), (select, \tau, soda), (soda, get_soda, pay), (select, \tau, beer), (beer, get_beer, pay)\}$

 $L(beer) = \{paid, beer\}$ $L(select) = \{paid\}$ states $s_0 \in I, s_0 \models \varphi$

This implies that $\pi_1 \models \Box \diamond beer$ since $beer(state) \models beer$ which satsifies $\pi_1 \models \Box \diamond (soda \lor beer)$ because now and for all future points, there is a point further up in the future where *beer* will hold. 1. Let $trace(\pi_2) = (\emptyset, \{paid\}, \{paid, soda\})^\omega$

To prove that this satisifies the formula above we will look at each path to see if there is a counter-example, we are expecting that there

When we look at all the paths we notice that they must hold since $beer(state) \models beer$ and $soda(state) \models soda$. When we look at each

This implies that $\pi_2 \models \Box \diamond soda$ since $soda(state) \models soda$ which satsifies $\pi_2 \models \Box \diamond (soda \lor beer)$ because now and for all future

 $\pi_3 \models \Box \diamond (soda \lor beer)$ because now and for all future points, there is a point further up in the future where $soda \lor beer$ will hold.

This shows that $\pi_3 \models \Box \diamond soda \ or \ \pi_3 \models \Box \diamond beer \ since \ beer(state) \models beer \ and \ soda(state) \models soda \ which \ satisfies \ that$

from the intitial state pay satisfy the formula. Thus we have proved, $TS \models \Box \diamond (soda \lor beer)$ (2) $TS \nvDash \Box soda$ iff for all initial states $pay \in I, pay \nvDash \Box soda$, $\exists \pi \in Paths(pay)$. From our intuition we expect that this satisfication will

not hold. What we are going to do is find a path which does not satisfy the condition always soda (counter-example).

1. $\pi_1 = [pay, select, beer, pay, select, beer, \dots] = [pay, select, beer]^{\omega}$ 2. $trace(\pi_1) = (\emptyset, \{paid\}, \{paid, beer\})^{\omega}$ We notice that $pay \nvDash soda \land beer, select \nvDash soda \land beer, beer(state) \nvDash soda \land beer$ thus we state that $\pi_1 \nvDash \Box \diamond (soda \land beer)$. This counter-example demonstrates that the satisification cannot hold and: Thus we have proved, $TS \nvDash \Box \diamond (soda \wedge beer)$. **Question 2**

 $S_3 \models a \land b$, $S_1 \models a$, $S_2 \models a$ thus $\pi_2 \models \Box \diamond a$, this is because there will always be a point further up in time where a will hold and this will continue forever. We have shown for all paths that the satisftication relation holds and thus: $TS \models \Box \diamond a$

 $TS \models \circ a$

holds.

transition system:

1. Let $Paths(S4) = \{\pi_1\}$ 2. Let $Paths(S3) = \{\pi_2\}$

1. $\pi_1 = [S_4, S_2, S_3, S_1, S_2, S_3, \ldots] = [S_4, (S_2, S_3, S_1)^\omega]$

(1) $TS \models \Box \diamond a$ iff for all initial states $s \in I, s \models \Box \diamond a$, $\forall \pi \in Paths(s)$

2. $\pi_2 = [S_3, S_1, S_2, S_3 \dots] = [(S_3, S_1, S_2)^\omega]$

The traces of the path are the following:

2. $trace(\pi_2) = (\{a,b\},\{a\},\{a\})^{\omega}$

1. $trace(\pi_1) = (\{b\}, (\{a\}, \{a,b\}, \{a\})^{\omega})$

We must prove the following:

1. $trace(\pi_1) = (\{b\}, (\{a\}, \{a,b\}, \{a\})^{\omega})$

b. For $\pi_2 = [S_3, S_1, S_2, S_3 \dots] = [(S_3, S_1, S_2)^\omega]$

b. For $\pi_2 = [S_3, S_1, S_2, S_3 \dots] = [(S_3, S_1, S_2)^\omega]$

 $S_1 \models a$, thus $\pi_2 \models \circ a$ as S_1 is the next step in the path.

a. For $\pi_1 = [S_4, S_2, S_3, S_1, S_2, S_3, \dots] = [S_4, (S_2, S_3, S_1)^\omega]$

satisifed which means that $\pi^1_1
ot \vdash (a o \Box (a \wedge b))$

 $TS
ot = \circ(a
ightarrow \Box(a \wedge b))$

 $S_3 \models b$.

 $TS \models \diamond(a \cup b)$

Question 4

processes created

processes created

0.291

0.534

We notice the following statement:

pan:1: assertion violated (x>0) (at depth 512)

128.000

128.730

actual memory usage for states

total actual memory usage

memory used for hash table (-w24)

memory used for DFS stack (-m10000)

Indicating that the value of x is not always greater than 0, as we have demonstrated earlier.

a. For $\pi_1 = [S_4, S_2, S_3, S_1, S_2, S_3 \dots] = [S_4, (S_2, S_3, S_1)^\omega]$

2. $trace(\pi_2) = (\{a,b\},\{a\},\{a\})^{\omega}$

and this will continue forever.

1. $trace(\pi_1) = (\{b\}, (\{a\}, \{a,b\}, \{a\})^{\omega})$ 2. $trace(\pi_2) = (\{a,b\},\{a\},\{a\})^{\omega}$ a. For $\pi_1 = [S_4, S_2, S_3, S_1, S_2, S_3, \dots] = [S_4, (S_2, S_3, S_1)^\omega]$ $S_2 \models a$, thus $\pi_1 \models \circ a$ as S_2 is the next step in the path.

We have shown for all paths that the satisftication relation holds and thus:

We see that $S_4 \models b$, and we can refer to the formula for equivalence, and note that $\phi \cup \psi \equiv \psi \lor (\phi \land \circ (\phi \cup \psi))$, thus S_4 satisfies this state. Thus, $\pi_1\models \diamond(a\cup b)$, since eventually is defined as now or at some future point in time and $\pi_1^0\models (a\cup b)$ because $S_4\models b$. b. For $\pi_2 = [S_3, S_1, S_2, S_3.\dots] = [(S_3, S_1, S_2)^\omega]$ We see that, $S_3 \models a \land b$ and we can refer to the formula for equivalence, and note that $\phi \cup \psi \equiv \psi \lor (\phi \land \circ (\phi \cup \psi))$, since $S_3 \models b$,thus

We have shown for all paths that the satisftication relation holds and thus:

ja@DESKTOP-0853IOK:/mnt/d\$ spin task4.pml

ja@DESKTOP-0853IOK:/mnt/d\$ spin task4.pml

@DESKTOP-0853IOK:/mnt/d\$ spin task4.pml

We see that it does not hold for all execution paths.

ja@DESKTOP-0853IOK:/mnt/d\$ spin task4.pml counter = 2 eja@DESKTOP-0853IOK:/mnt/d\$ spin task4.pml counter = 2 processes created eja@DESKTOP-0853IOK:/mnt/d\$ spin task4.pml counter = 0 processes created ja@DESKTOP-0853IOK:/mnt/d\$ spin task4.pml counter = 0 processes created

complicated programs it would be too difficult to re-run the program and find an execution path which violates the assertion. proctype testcount (byte x) 2 { 3 do :: (x != 0) -> 4 5 6 X ++ 7 X --8 break fi 9 :: else -> break 10 11 od; printf("counter = %d\n", x); 12 assert(x > 0);13 14 15 16 init {run testcount(1)} We can then verify the above program with the following commands: a. spin -a task4.pml b. gcc ./pan.c -o pan c. ./pan pan:1: assertion violated (x>0) (at depth 512) pan: wrote task4.pml.trail (Spin Version 6.4.9 -- 17 December 2018) Warning: Search not completed + Partial Order Reduction Full statespace search for: never claim (none specified) assertion violations

x := 2x - 1x := x + 1PG1 ||| PG2 ||| PG3 $l_1 l_2 l_3$

x = 64x = 17x = 128x = 31x = 33x=16

x = 128 $L(S_4) = \{l_1', l_2, l_3', x = 16\}$ $L(S_5) = \{l_1', l_2', l_3', x = 31\}$ $L(S_6) = \{l_1, l_2', l_3, x = 5\}$ $L(S_7) = \{l_1^{'}, l_2^{'}, l_3, x = 6\}$ $L(S_8) = \{l_1^{'}, l_2^{'}, l_3^{'}, x = 64\}$ $L(S_9) = \{l_1, l_2', l_3', x = 32\}$ $L(S_{10}) = \{l_{1}^{'}, l_{2}^{'}, l_{3}^{'}, x = 33\}$ $L(S_{11}) = \{l_1, l_2, l_2', x = 8\}$

 $AP = \{l_1, l_2, l_3, l_1', l_2', l_3', x = 3, x = 4, x = 5, x = 6, x = 7, x = 8, x = 9, x = 15, x = 16, x = 17, x = 31, x = 32, x = 33, x = 64, x = 17, x =$

We note the following to be true and we will use this as a means to prove the three satisfication relations. $Lets \in S$, we write $s \models \varphi$, iff for every execution path π of TS starting at s, that is, $\pi \in Paths(s)$, we have $\pi \models \varphi$. $TS \models \varphi$ iff for all initial To prove that TS satisfies or does not satisfy a LTL formula we have to find a path which is a counter-example. Thus, for each of the proof we will proves these in this way. For this transition system all paths start at pay. Thus, (1) $TS \models \Box \diamond (soda \lor beer)$ iff for all initial states $pay \in I, pay \models \Box \diamond (soda \lor beer)$, $\forall \pi \in Paths(pay)$ A path of transition system TS is an initial, maximal path fragment. There are two main paths in the transition system that always lead to beer or soda, and the re-arrangement of the paths are arbitrary considering only these two outcomes are possible. The only difference is that some of the paths lead to both outcomes of soda and beer. These are the main paths that are in the transition system: Let $Paths(pay) = \{\pi_1, \pi_2, \pi_3, \pi_4\}$ 1. $\pi_1 = [(pay, select, beer, pay, select, beer, \dots)] = (pay, select, beer)^{\omega}$ 2. $\pi_2 = [(pay, select, soda, pay, select, soda, \dots)] = (pay, select, soda)^{\omega}$ 3. $\pi_3 = [(pay, select, soda, pay, select, beer, pay...)] = ((pay, select, soda)^{\omega}, (pay, select, beer)^{\omega})^{\omega}$ 4. $\pi_4 = [(pay, select, beer, pay, select, soda, pay...)] = ((pay, select, beer)^\omega, (pay, select, soda)^\omega)^\omega$ The traces for each path:

1. $trace(\pi_1) = (\emptyset, \{paid\}, \{paid, beer\})^{\omega}$ 2. $trace(\pi_2) = (\emptyset, \{paid\}, \{paid, soda\})^{\omega}$

should be no counter-example:

path we see that they hold in each case:

1. Let $trace(\pi_1) = (\emptyset, \{paid\}, \{paid, beer\})^{\omega}$

3. $trace(\pi_3)=((\emptyset,\{paid\},\{paid,soda\})^\omega,(\emptyset,\{paid\},\{paid,beer\})^\omega)^\omega$ 4. $trace(\pi_4) = ((\emptyset, \{paid\}, \{paid, beer\})^{\omega}, (\emptyset, \{paid\}, \{paid, soda\})^{\omega})^{\omega}$

points, there is a point further up in the future where soda will hold.

1. Let $trace(\pi_3) = ((\emptyset, \{paid\}, \{paid, soda\})^\omega, (\emptyset, \{paid\}, \{paid, beer\})^\omega)^\omega$

1. Let $trace(\pi_4) = ((\emptyset, \{paid\}, \{paid, beer\})^{\omega}, (\emptyset, \{paid\}, \{paid, soda\})^{\omega})^{\omega}$

This shows that $\pi_4 \models \Box \diamond soda \ or \ \pi_4 \models \Box \diamond beer \ \text{since} \ beer(state) \models beer \ \text{and} \ soda(state) \models soda \ \text{which satisfies that}$ $\pi_4 \models \Box \diamond (soda \lor beer)$ because now and for all future points, there is a point further up in the future where $soda \lor beer$ will hold. Given that $Paths(pay) = \{\pi_1, \pi_2, \pi_3, \pi_4\}, \forall \pi \in Paths(pay), \ pay \models \Box \diamond soda \ or \ pay \models \Box \diamond beer$. In otherwords, all paths starting

reftues the satisification relation and: Thus we have proved, $TS \nvDash \Box soda$ (3) $TS \nvDash \Box \diamond (soda \land beer)$ iff for all initial states $pay \in I, pay \nvDash \Box \diamond (soda \land beer)$, $\exists \pi \in Paths(pay)$. In this case, all we want to do is find a path starting from the initial state in which the satisfication relation does not hold. We already notice that there is no state that holds either of the propositions to be true, so it would be impossible that this transition system can satisfy this state. We only need to find one path and use π_1 to demonstrate it as a counter-example:

If we look to $\pi_1 = [pay, select, beer, pay, select, beer, \dots] = [pay, select, beer]^{\omega}, trace(\pi_1) = (\emptyset, \{paid\}, \{paid, beer\})^{\omega}$ we notice that $pay \nvDash soda, select \nvDash soda, beer(state) \nvDash soda$ thus it is definately the case that $\pi_1 \nvDash \Box soda$. This is a counter-example which

83 Decide for each of the following LTL formulas φ_i , whether $TS \models \varphi_i$. If $TS \models \varphi_i$, provide a proof; if $TS \nvDash \varphi_i$, then provide a path π such that $\pi \nvDash \varphi_i$.

There are two intial states I = {S4, S3}. A path of transition system TS is an initial, maximal path fragment. There are two paths on this

This means that Always eventually a holds. In other words: Now and for all future points, there is a point further up in the future where a

 $S_4 \nvDash a$, but $S_2 \models a$, $S_3 \models a \land b$, $S_1 \models a$ thus $\pi_1 \models \Box \diamond a$ this is because there will always be a point further up in time where a will hold

When we examine the traces we see indeed that it should satisfy the relation. We will move forward and prove that it is the case.

Consider the following transition system TS of the simple beverage vending machine:

(2) $TS \models \circ a$ iff for all initial states $s \in I, s \models \circ a$, $\forall \pi \in Paths(s)$ This means that the on each of the paths next step must be a. When we examine the traces we see indeed that it should satisfy the relation. We will move forward and prove that it is the case.

(3) $TS
ot (a o \Box(a \wedge b))$ iff for all initial states $s \in I, s
ot (a o \Box(a \wedge b)), \exists \pi \in Paths(s)$

We have shown a counter-example for a single path in which the satisfication relation does not hold and thus:

We have to prove that $\pi_1^1 \nvDash (a \to \Box (a \land b)$ because this is the next step. And since $S_2 \models a$ it implies that $\pi_1^1 \models a$ and after this we test

the implication and we notice that $S_3 \models a \land b$, but $S_1 \nvDash a \land b$ and $S_2 \nvDash a \land b$ and it is impossible the implication $\Box(a \land b)$ can be

When we examine the traces we see indeed that it should satisfy the relation. We will move forward and prove that it is the case.

 S_3 satisfies this state. Thus, $\pi_2\models \diamond(a\cup b)$, since eventually is defined as now or at some future point in time and $\pi_2^0\models (a\cup b)$ because

1. $trace(\pi_1) = (\{b\}, (\{a\}, \{a,b\}, \{a\})^{\omega})$ 2. $trace(\pi_2) = (\{a,b\},\{a\},\{a\})^{\omega}$ a. For $\pi_1 = [S_4, S_2, S_3, S_1, S_2, S_3, \dots] = [S_4, (S_2, S_3, S_1)^\omega]$

(4) $TS \models \diamond(a \cup b)$ iff for all initial states $s \in I, s \models \diamond(a \cup b), \forall \pi \in Paths(s)$

This means eventually, it will reach a state in which a will hold until b hold.

When we are looking at the code, x is 1 to begin with and we notice that after the guard x !=0, the value x after the if statements are either added, subtracted or breaks randomly. This could lead to an execution path where the value = 0. We can test this a few ways, firstly we kept re-running the program and found that our intution was correct and there was a path where the value of x = 0. And then we used an assertion at the bottom of the program and verified this using spin. These are detailed below. (1) Continue re-running the program and see if there is an execution path which leads to the value being 0. ja@DESKTOP-0853IOK:/mnt/d\$ spin task4.pml

(2) We can add an assertion function and verify that the value is greater than 0. This is more of an ideal way of doing it since for more

- (not selected) acceptance cycles invalid end states State-vector 20 byte, depth reached 512, errors: 1 513 states, stored 0 states, matched 513 transitions (= stored+matched) 0 atomic steps hash conflicts: 0 (resolved) Stats on memory usage (in Megabytes): 0.023 equivalent memory usage for states (stored*(State-vector + overhead))