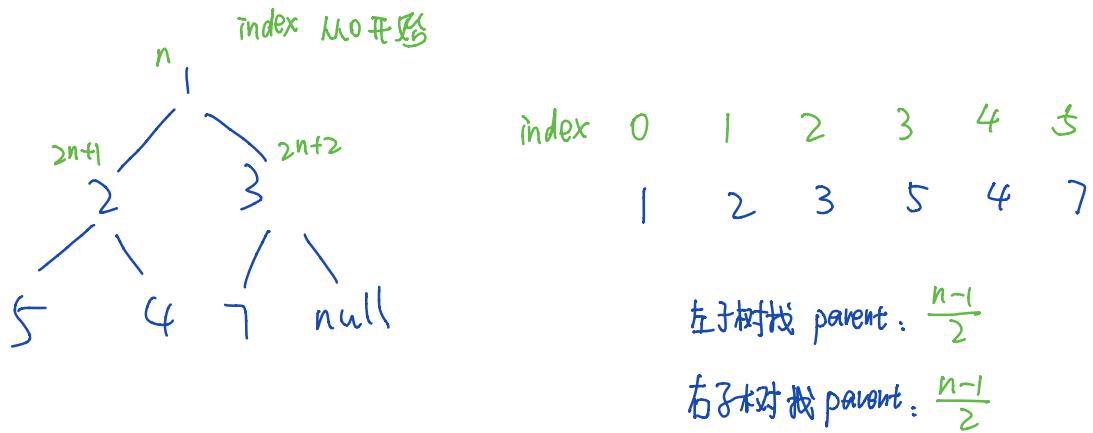


Heap 堆 ( $\min/\max$ ) = Priority Queue 优先队列

维护一个变化数据集的最优值

Complete BT: 气泡只能出现在最后一行的右侧.



1. Heap is always a Complete binary tree.
2. Every node is smaller than all its descendant.  
[Root 最小]  $\Leftarrow$  for MinHeap      后裔 (堆序性)

Insert: 放在气泡位置, 再和 root 依次交换.

Time:  $O(\log n)$

Update:

$x \leftarrow 8$   
5 4

~~5  
8  
4~~

5 4  
8 ✓

MinHeap 要和小的语.

Time:  $O(\log n)$  定点打击, 告诉 index, 并更新的情况下.

删掉顶端元素 POP

思考

1. 如果一个一个往下删, 容易破坏 tree 的结构. (Incomplete).
2. 把最后一个元素放到 root 上, 再一个一个往下换

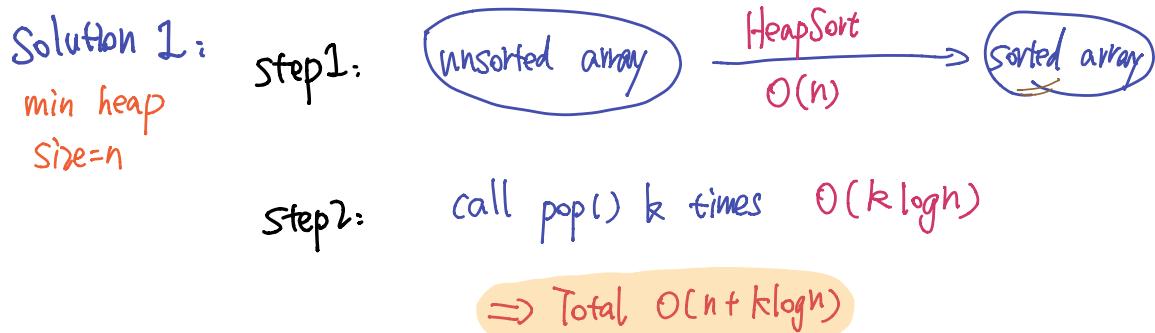
逻辑上是 Tree, 物理上是 array.

| 可以有重复元素

- 支持 search.

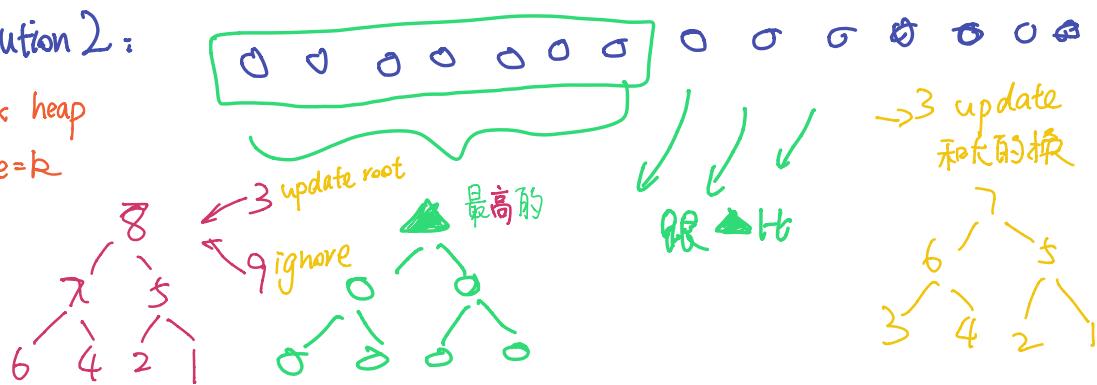
Q1. Find smallest  $k$  elements from unsorted array of size  $n$ .

Solution 0: Sort  $\rightarrow O(n \log n)$



Solution 2:

max heap  
size =  $k$



Step 1: Heapify the first  $k$  elements  $O(k)$

Step 2: Iterate

Case 1:  $> \text{root}$ : ignore

Case 2:  $< \text{root}$ : update ( $\text{root} \rightarrow \text{new element}$ )

Step 3: Finally, all elements remaining in the heap is the result.

Time =  $O(k + (n-k) \log k)$

(Compare  $O(n+k \log n)$  and  $O(k + (n-k) \log k)$ )

$k \ll \ll n$	$O(n + \text{constant})$	$O(n \log k)$	hard to say
$k \sim n$	$O(n \log h)$	$O(n + n \log h) = O(n \log h)$	hard to say hard

Space  $O(n)$  >  $O(k)$  ✓ better.

## Offline      Online

要贏得所有 data 有 data streaming 時, better.

才能傳

Solution): Quick Select: similar to quicksort.

$$k = 20$$

$$\text{Average time: } O(n + \frac{n}{2} + \frac{n}{4} + \dots) = O(n)$$

Worst time:  $O(n+n-1+n-2+\dots+1) = O(n^2)$

Graph 有向 directed  
无向 undirected

表示方法

1. Adjacency Matrix

0	Q	1	2	3	.
1					
2					
3					
4					

时间查找  $\Theta(1)$

浪费空间, 大部分情况为 sparse

2. Adjacency List

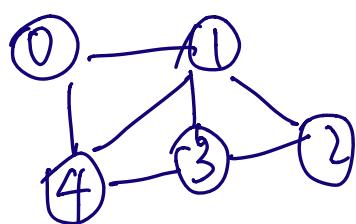
$0 \rightarrow 1 \rightarrow 4$

$1 \rightarrow 0 \rightarrow 4 \rightarrow 3 \rightarrow 2$

$2 \rightarrow ;$  {接上所有邻居}

$3 \rightarrow ;$

$4 \rightarrow$



vertices

点:  $O(V)$

边:  $O(E)$

Edges

缺点: 查找不方便

需要 traverse the linked list

Space =  $O(V+E)$

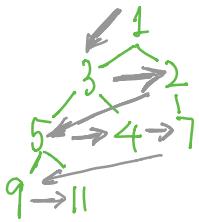
## 常见的 Graph Search Algo 怎么 traverse 一张图.

### 1. Breadth-First Search (BFS-1)

一层一层地搜索

宽度优先搜索算法

经典问题：分层打印一个 binary tree.



过程：

① 选一个 FIFO queue,



Queue = {2} ←

② Expand a node,

③ generate s's neighbor nodes,

④ Termination Condition:

do a loop until the queue is empty.

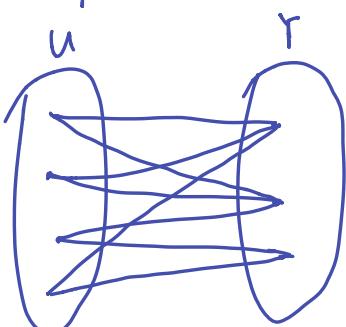
Queue {1}      expand(1) → generate(3) generate(2)

Queue {3, 2}    expand(3) → generate(5) generate(5)  
expand(2) → generate(7)

Queue {5, 4, 7} expand(5) → generate(9) generate(11)

执行问题？ 要先看要 expand N 个元素.

### 2. Bipartite 二分图



X 相连, 同色, return false.

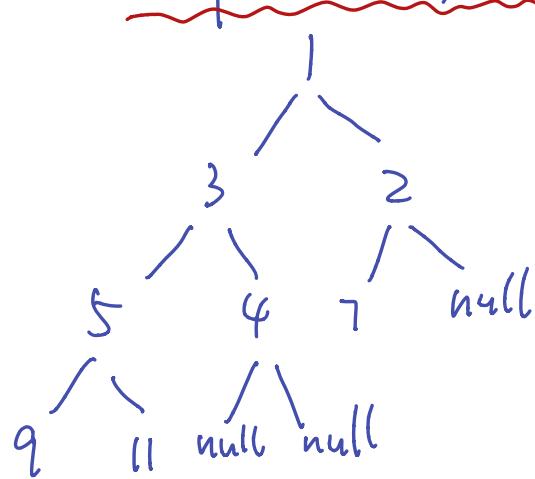
expand(1) → generate(2) generate(3)

Queue = {2, 3}

expand(2) → generate(1) (3) (4)

如果全都上完了, 没出现问题, return true

### 3. Complete binary tree 的判断.



expand      generate

1      3      2  
3      5      4  
2      7      null

一旦气泡发现  
后面不能再 generate 出任何数字了。

```
if (generate null) {  
    flag = true;  
}
```

讨论：能用 BFS-1 解决最短路径问题吗？

Nope. 因为每条边加了权重有 weight.

只有 every edge has the same weight,  
才可以用 BFS-1 找到最短路径.

## Best First Search (BFS-2) 找最短路径.

经典算法 Dijkstra's Algo. [假设 cost > 0]

Usage: Find the shortest path cost from a single node (source node) to any other nodes in the graph. 到哪里

例子: 从北京到中国其他所有主要城市的最短距离是多少. priority-queue (min-heap)

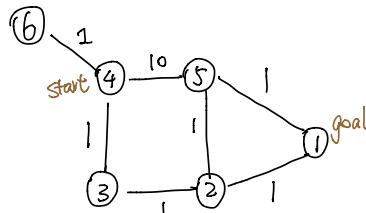
1. initial state

2. while() expansion/generation rule

a. Expand a node

b. Generate all neighbors

3. Termination condition



$$PQ = (3, 1)$$

- (5, 10)
- (6, 1)
- > expand (5, 10)
- > expand (6, 1)
- > expand (2, 2)
- > expand (1, 3)
- > expand (5, 3)

已经出现过了挑小的。  
或者先比较，只把小的放进 heap  
注意，即使 generate out goal 了，  
还需要继续，因为可能有更小的。

性质:

1. one node can be expanded only once.

2. one node can be generated more than once.

3. 所有从 PQ 里 pop 出来的元素的值是单调递增的

4. Time:  $O(n \log n)$  Dijkstra's

e.g. 4-connected grid 曼哈顿棋盘格

5. 一旦一个 node 被 expand 了, 它的最短距离就不会再变了.

General graph,

$$O((V+E)\log V) = O(E \log V)$$

经典考题  $N \times N$ . 每行排好序了. 找第 k 小的元素.

1	2	3	5	6
2	3	4	6	8
3	4	5	7	9
4	5	6	8	10
5	6	9	10	11

$$\begin{aligned} \text{Time} &= O(k \log n) \\ \text{Space} &= O(k + n^2) \end{aligned}$$

$N \times N$

boolean array 要存下来

## BFS2

1. initial state:  $\text{array}[0][0]$

2. Expansion / Generation Rule:

expand node  $[i][j]$

generate  $[i+1][j]$

generate  $[i][j+1]$

3. Termination condition:

when the k-th element is expanded

(popped out of the PQ)

4. Deduplication: 重复的只 generate 一次.

$\text{boolean}[i][j]$  generated = true / false.