Introduction to FPGAs using Homebrew Automation

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About This Talk

Everything is on Github

- https://github.com/
  - hbrc-fpga-class/
    - class-material/
      - blob/master/presentation.pdf

About This Talk

- Lots of information - $\frac{\Delta slides}{\Delta time} \propto log(time)$
- Please save questions for the end

Who are We?

- Tinkerers with a bunch of software, hardware, firmware, and gateware experience (mostly Bob and Brandon, though 😉)
- Engineers at OLogic, Inc.
- [ClusterFighters!]

What is an FPGA?

> “ To control a processor, you program it with instructions and tell it what to **do**...
>
> to control an FPGA, you describe a circuit and tell it what to **become**. ”

- Dalai Lama, probably

What is an FPGA?

- Short for **F**ield-**P**rogrammable **G**ate **A**rray
- One type of **Programmable Logic Device (PLD)**
  - Implements arbitrary digital logic equations (i.e. Boolean operations)
  - Most are re-programmable
  - Some are non-volatile, while others require external memory to save configuration

What is an FPGA?

- Other PLD's include:
  - PLA - Programmable Logic Array
  - PAL - Programmable Array Logic
  - GAL - Generic Array Logic
  - SPLD - Simple Programmable Logic Device
  - CPLD - Complex Programmable Logic Device

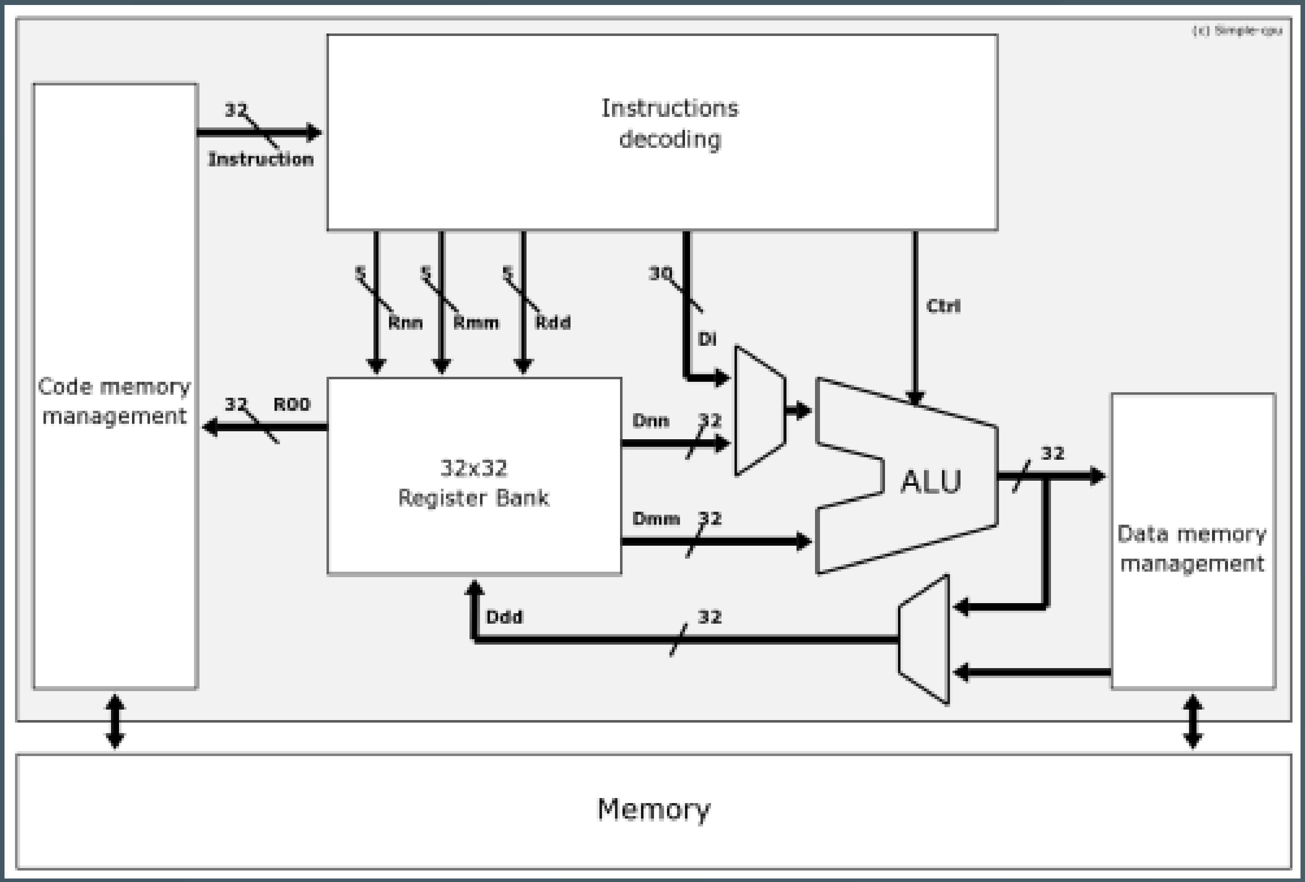
(Who names these things?)

Players

FPGA vendors by market share:

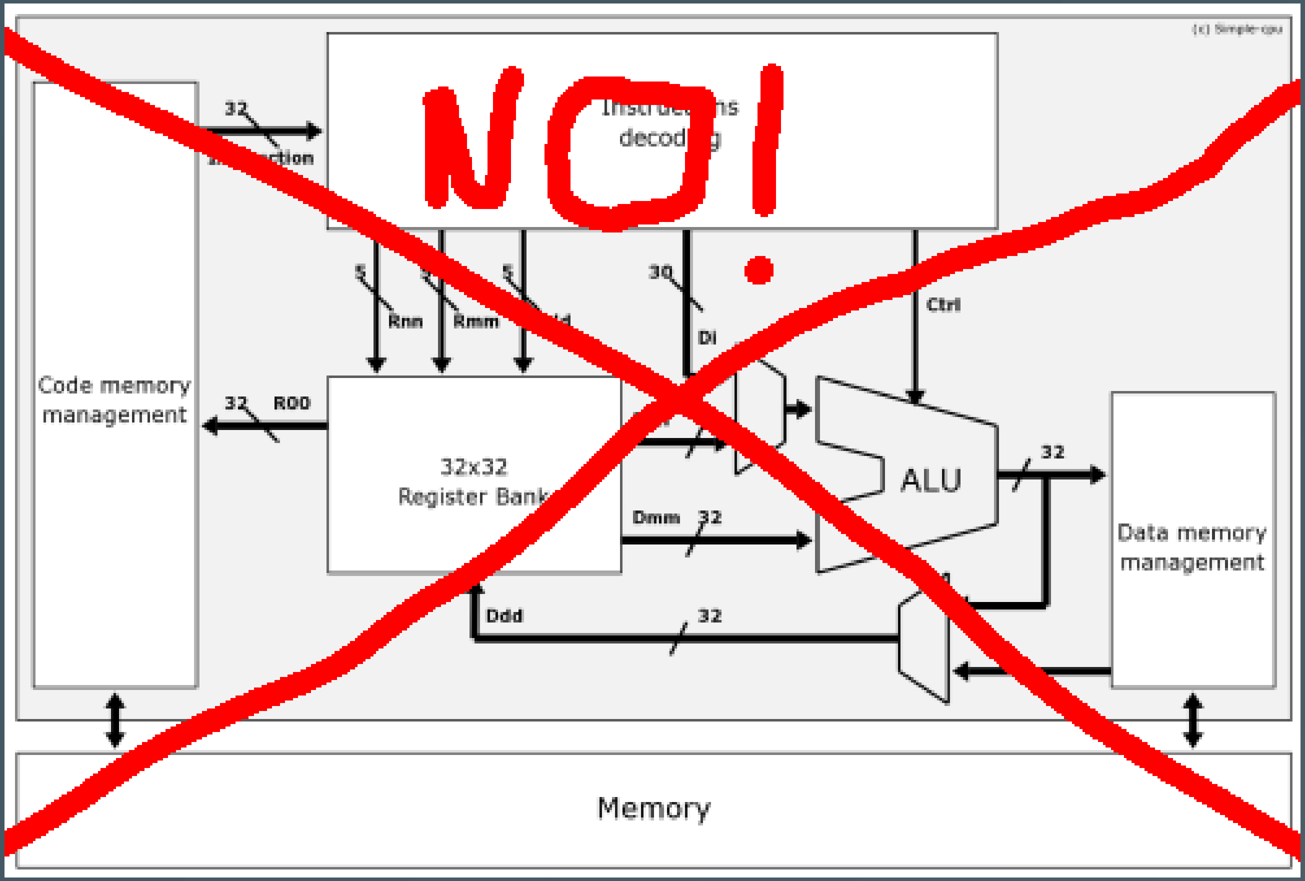
- **Xilinx** - ~50%
- **Intel** (Altera) - ~40%
- **Lattice** - >5%
- **Microchip** (Microsemi (Actel)) - <5%
- Everyone else (QuickLogic, Gowin, etc.) - ~1%

What's *Inside* an FPGA?



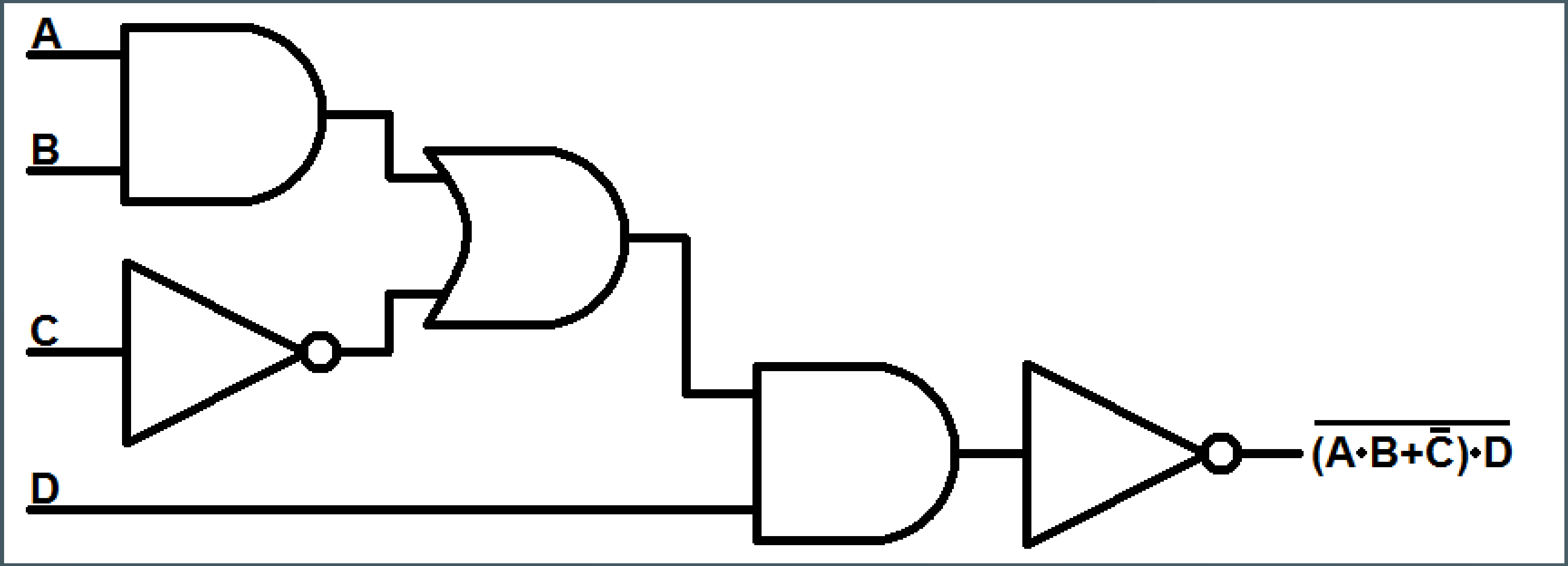
- Is it a special type processor?

What's *Inside* an FPGA?



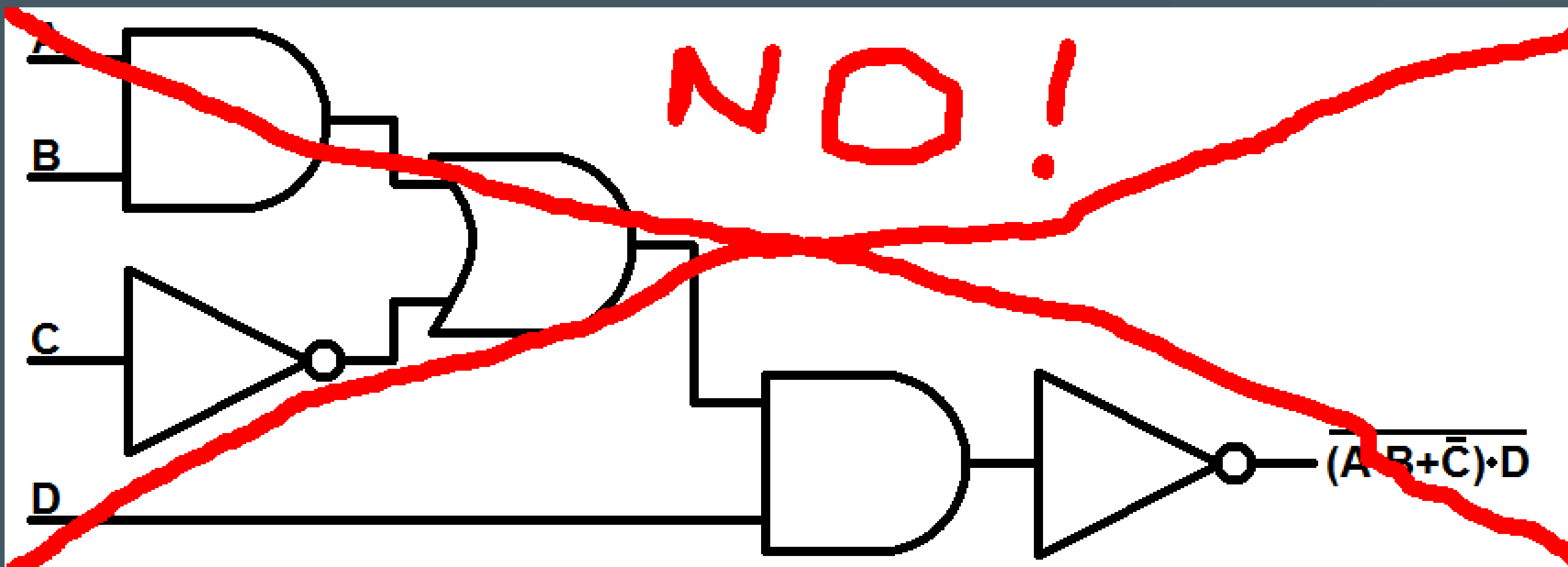
- But an FPGA can be used to *implement* CPUs (known as "soft cores")

What's *Inside* an FPGA?



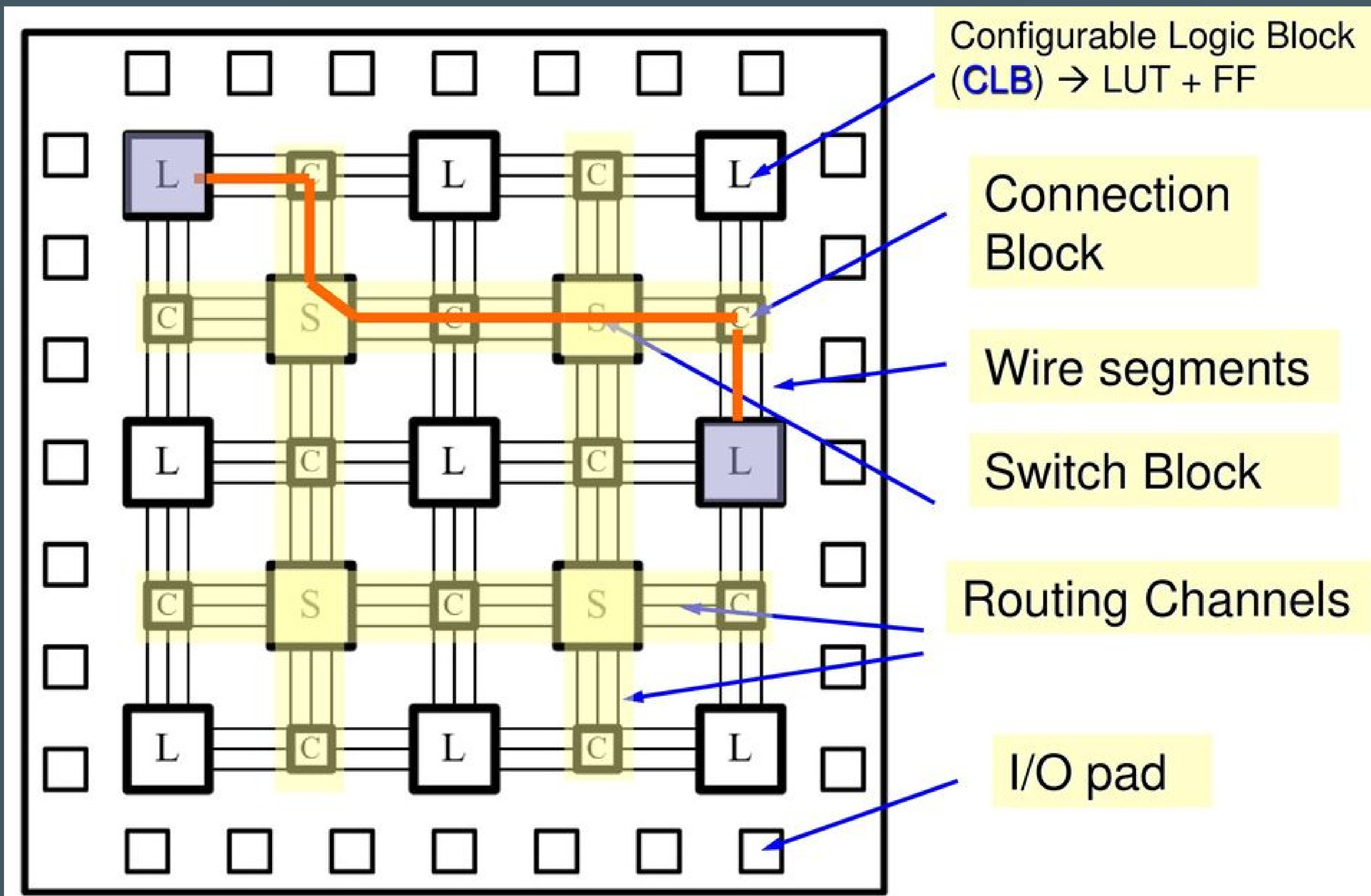
- Is it a big collection of AND / OR / NOT / NOR / NAND / NOR gates? Perhaps even a *gate array* of sorts?

What's *Inside* an FPGA?

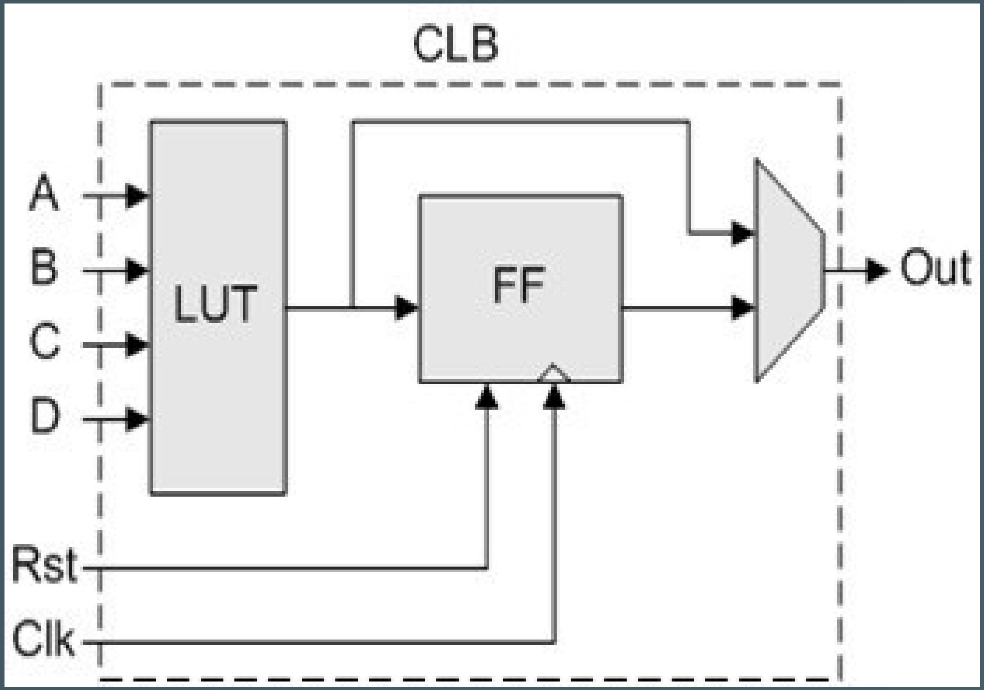


- But an FPGA can be used to *implement* arbitrary logic equations

What's *Inside* an FPGA?



Configurable Logic Blocks



- Lookup table (LUT)
- D-Type Flip-Flop (D-FF)
- Multiplexer (MUX)

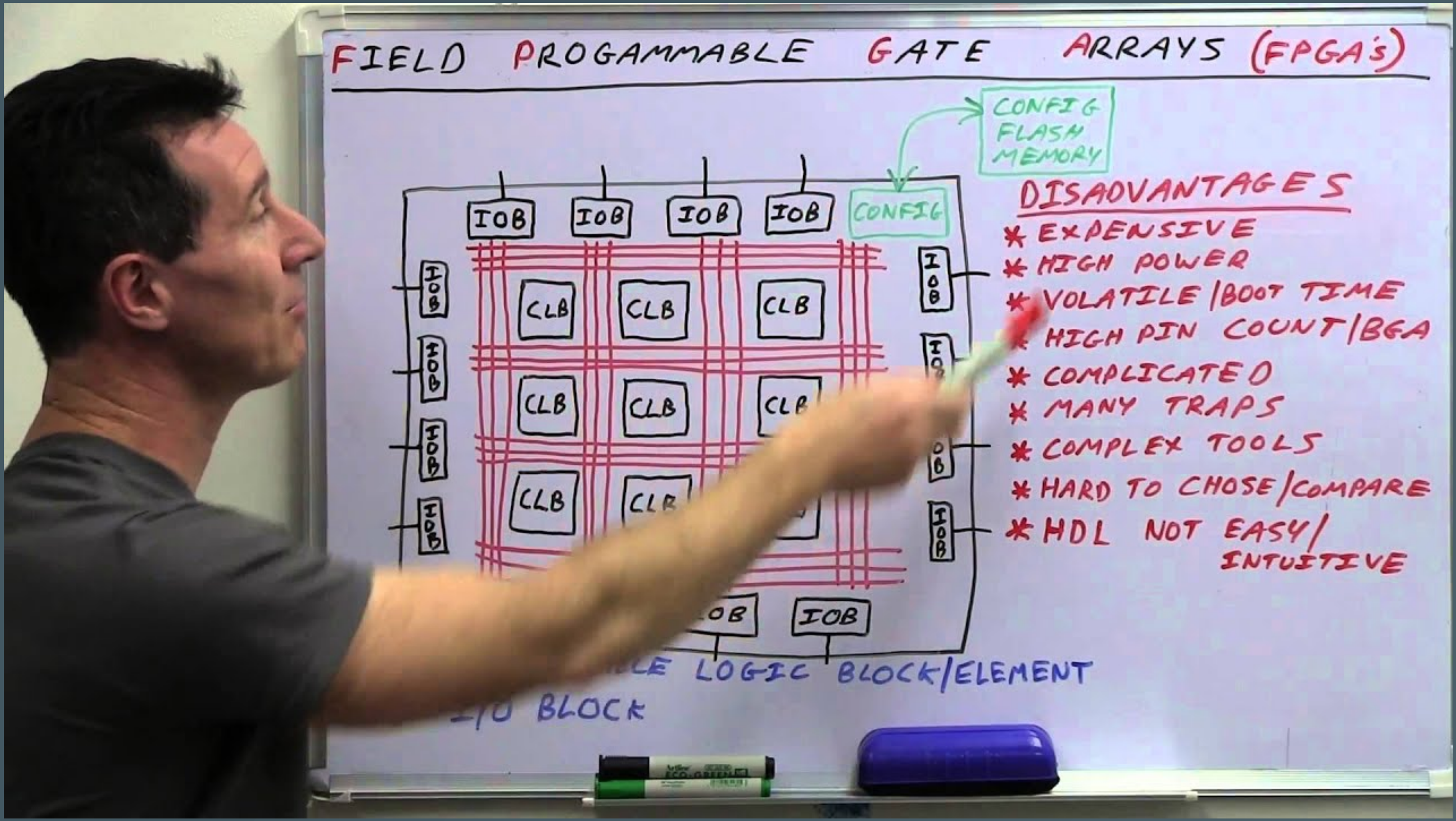
Open-Source Applications

- ASIC prototyping [RISC-V]
- Chip emulation [MiSTer]
- DSP - filters, transforms, convolution, decimation, digital synthesis, etc.
  - Software-defined radio [1] [2] [3]
  - Audio Synthesizers [1] [2]

Open-Source Applications

- Accelerator cores
  - Cryptography - [MD5] [AES]
  - Video encode / decode [H.264]
  - Very high speed networking [Intel 100G NIC]
- In general, FPGAs are great at applications that can leverage fixed-point math, high memory bandwidth, pipelining, & parallelism

It can't be all good, right?



Disadvantages

FPGAs are ill-suited for certain tasks:

- Floating point operations
- Protocol handling
- Complex rulesets
- P-complete problems that are sequential & not easily parallelized (think "Conway's Game of Life")
- Developing solutions quickly (maybe)

The Case for Robotics

- Access to *tons* of flexible, reconfigurable I/O pins
- Timers & counters are trivial to impement
  - PWM for motor control (brushed, BLDC, servos)
  - Pulse decoding (encoders, IR remotes, RC controllers, SONAR)
- Swappable, on-demand peripherals like UART, SPI, I2C, 1-wire, etc.

The Case for Robotics

- PID controllers
  - Very fast execution and consistent timing
  - Fixed point
- Finite state machines
  - Line following
  - Obstacle avoidance

FPGA Workflow

- Design entry
- Simulation
- Synthesis
- Technology mapping
- Placement
- Routing
- Bitstream generation
- Flashing device

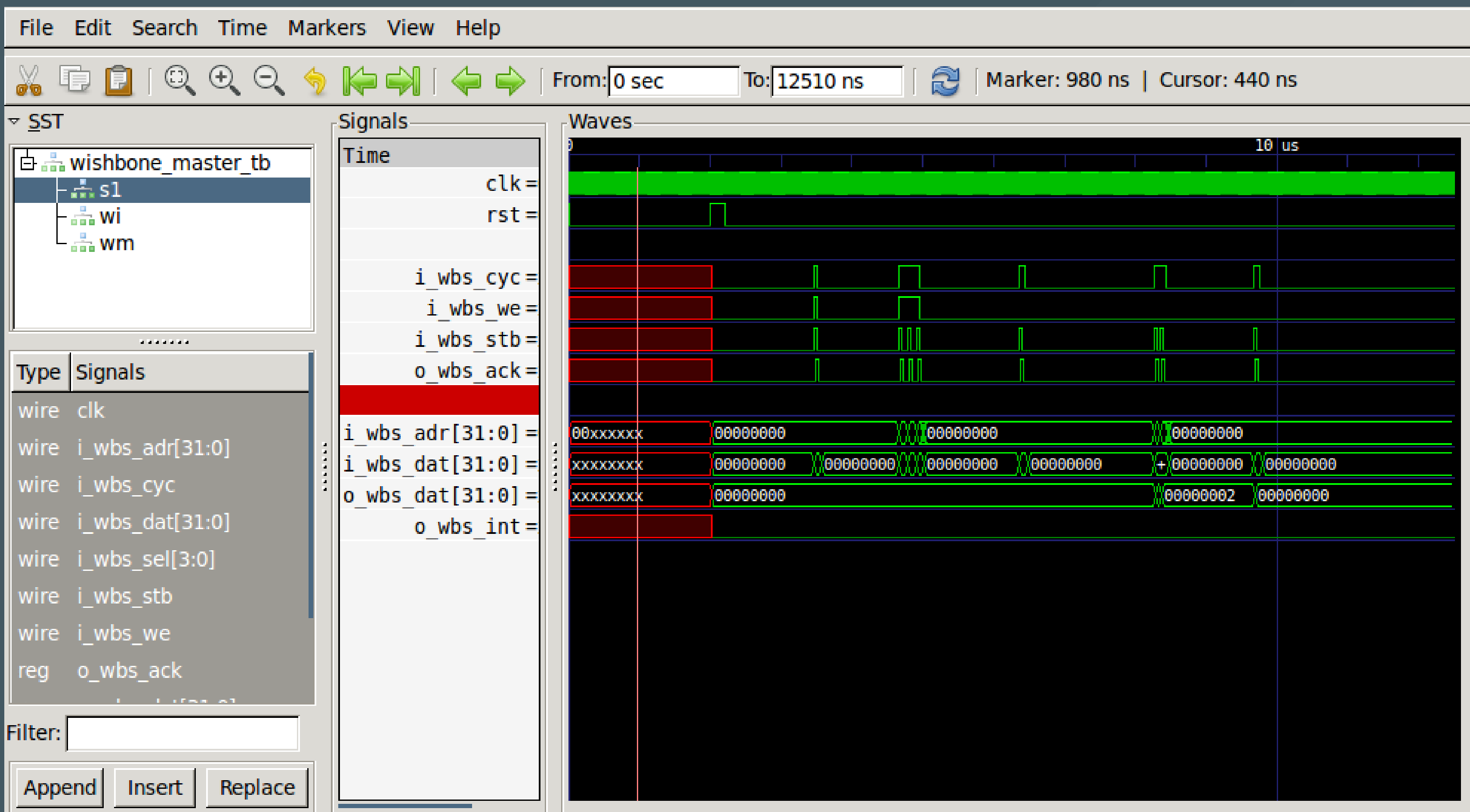
Design Entry

- FPGA internals are *described* using a hardware description language (HDL)
  - **Verilog** (C-like, weakly-typed)
    - Popular in open source, consumer electronics, & the west coast
  - **VHDL** (Ada-like, strongly typed)
    - Popular in defense / aerospace, academia, & the east coast
- Tools: Your favorite text editor

Simulation

- Allows designs to be verified as individual blocks or as a full system
- Only simulates *functionality* of a design, not the physics. This means a design can work in simulation but fail when trying to work with real hardware
- Tools:
  - Simulator - Icarus Verilog, Verilator
  - Waveform Viewer - GTKWave

Simulation


File Edit Search Time Markers View Help
From: 0 sec
To: 12510 ns
Marker: 980 ns | Cursor: 440 ns
SST
wishbone_master_tb
s1
wi
wm
Type Signals
wire clk
wire i_wbs_adr[31:0]
wire i_wbs_cyc
wire i_wbs_dat[31:0]
wire i_wbs_sel[3:0]
wire i_wbs_stb
wire i_wbs_we
reg o_wbs_ack
Filter:
Append
Insert
Replace
Signals
Time
clk =
rst =
i_wbs_cyc =
i_wbs_we =
i_wbs_stb =
o_wbs_ack =
i_wbs_adr[31:0] =
i_wbs_dat[31:0] =
o_wbs_dat[31:0] =
o_wbs_int =
Waves
10 us
00xxxxxx
00000000
xxxxxxxx
00000002

Synthesis

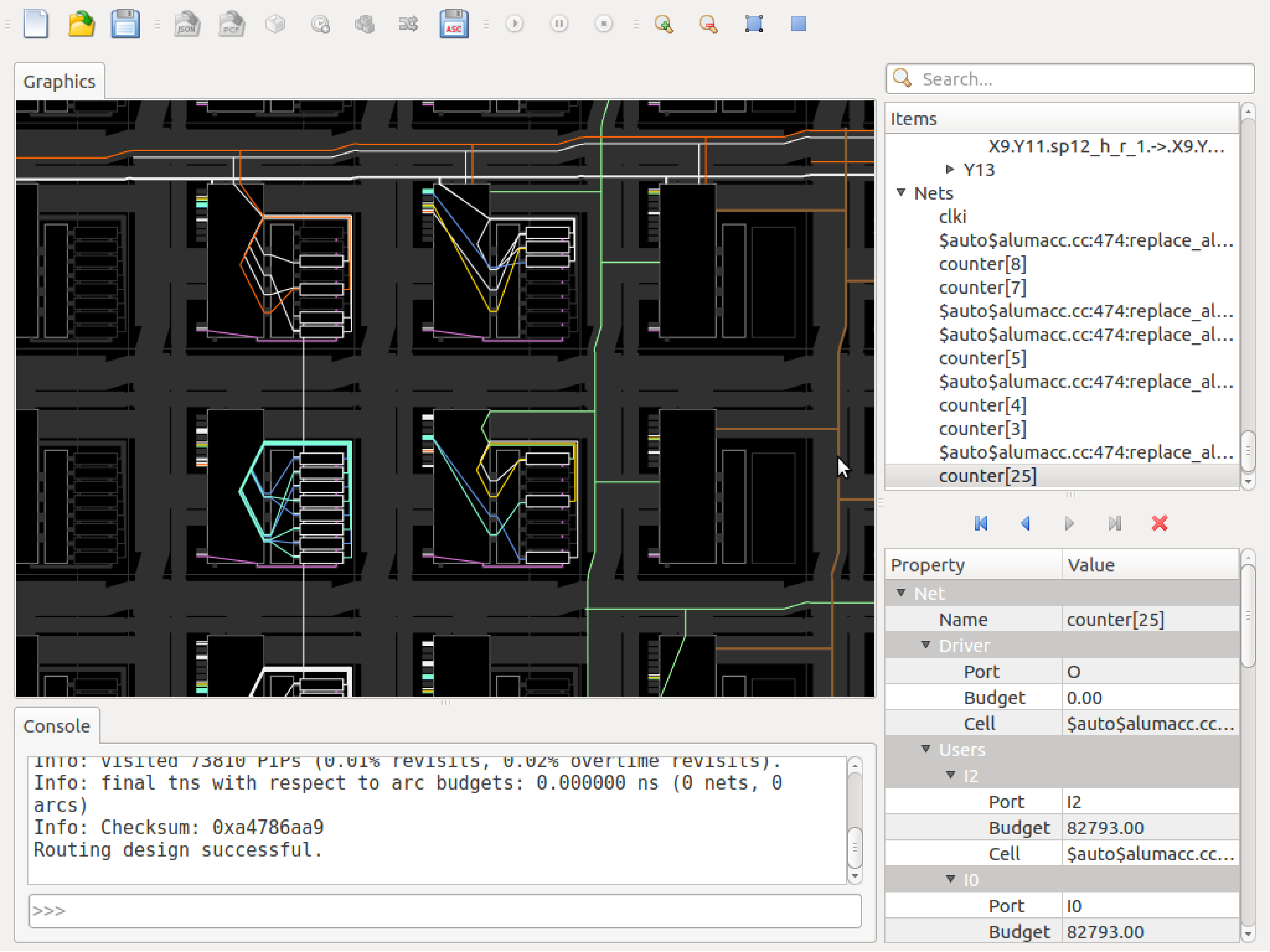
- Convert Verilog into generic logic circuits. Also known as behavioral to RTL conversion.
- Some logic optimization happens here
- Output saved as an intermediate file format not really intended for human interaction
- Tools: [Yosys]
    - `synth` command provides good set of defaults that can be used as basis for synthesis scripts
        - `yosys> read_verilog mydesign.v # import design`
        - `yosys> synth -top mytop # default synthesis`

Technology Mapping

- Synthesis output needs to be mapped to the specific hardware architecture of the FPGA (i.e. CLBs, DSP, SERDES, etc.)
- Tools: [Yosys]
  - Multiple scripts are used to map the design
    - `yosys> dfflibmap # map flip-flops`
    - `yosys> abc # map logic`
  - Supports **extensible, custom techmaps!**
  - Returns text file to be consumed by P&R tool

Placement & Routing

- Tool consumes techmapped design, tries to fit it into the FPGA, and connect everything together
- NP-hard optimization problem (think "travelling FPGA salesman")
- Timing constraints factor in at this step
- Tools:
  - Nextpnr - Actively developed, still buggy, GUI
  - Arachne-pnr - No more development, works for ICE40 only (but reliably)


Graphics
Search...
Items
X9.Y11.sp12_h_r_1.->.X9.Y...
Y13
Nets
clki
$auto$alumacc.cc:474:replace_al...
counter[8]
counter[7]
$auto$alumacc.cc:474:replace_al...
$auto$alumacc.cc:474:replace_al...
counter[5]
$auto$alumacc.cc:474:replace_al...
counter[4]
counter[3]
$auto$alumacc.cc:474:replace_al...
counter[25]
Property
Value
Net
Name
counter[25]
Driver
Port
O
Budget
0.00
Cell
$auto$alumacc.cc...
Users
I2
Port
I2
Budget
82793.00
Cell
$auto$alumacc.cc...
I0
Port
I0
Budget
82793.00
Console
Info: final tns with respect to arc budgets: 0.000000 ns (0 nets, 0 arcs)
Info: Checksum: 0xa4786aa9
Routing design successful.
>>>

Bitmap Generation

- The P&R tool generates a binary file known as the **bitstream**
- Morally equivalent to an ELF or EXE
- Each bit controls the configuration state and initial conditions of every CLB and interconnect in the device
- Previously very secret sauce
- Slowy being reverse engineered by hackers *fuzzing* the vendor tools

Device Flashing

- Chip-specific (SPI, JTAG, or some custom protocol)
- SRAM (fast, volatile) vs. external flash (slow, non-volatile)
- Tools:
  - `iceprog` - ICE40 dev boards only
  - `openocd` - Popular tool to program & debug with
  - `flashrom` - External SPI/I2C flash

Holy cow we're done!

Just kidding! Now we can finally start.

How to Write Less Verilog

- Code reuse has historically been challenging for FPGA designs
- How to abstract away complexity:
  - High-level synthesis tools
    - **MATLAB** HDL Coder, VivadoHLS (**C/C++**), Intel HLS Compiler (**C**), Synphony (**C**), Migen (**Python**), Litex (**Python**)
  - Configurable IP Megablocks
    - Vendor clock & PLL configuration
    - Schematic representation

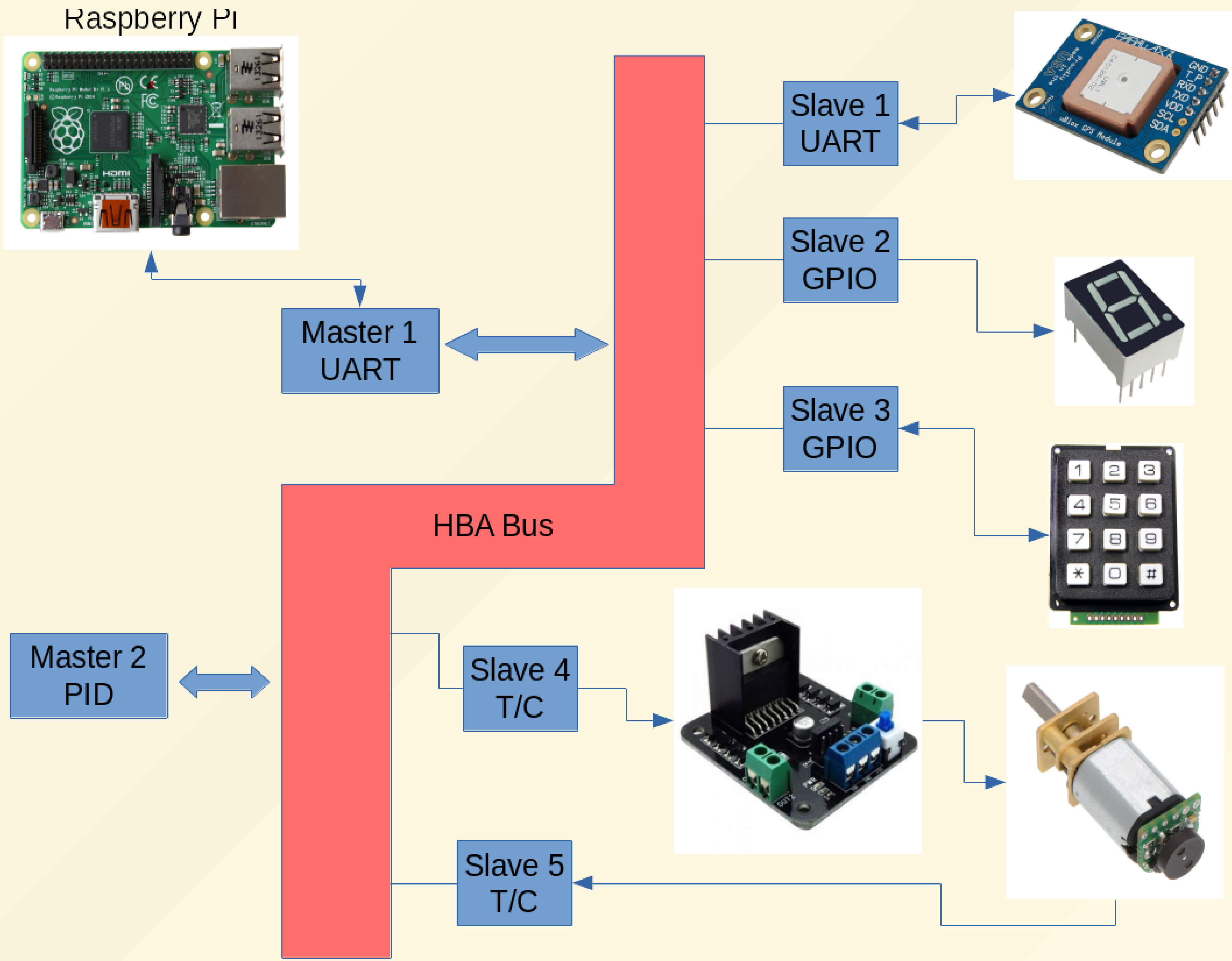
How to Write Less Verilog

- Connect the FPGA to a Linux computer & leverage the strengths of both devices

Homebrew Automation

HBA Gateware (FPGA)

- Based on TinyFPGA BX (Lattice ICE40)
- Consists of small, modular peripherals
- Provides standardized interface to a simple bus
- Up to four master peripherals
  - E.g. Raspberry Pi interface or PID controller
- Up to sixteen slave peripherals
  - e.g. timer/counter, SPI, UART


Raspberry Pi
Master 1
UART
HBA Bus
Slave 1
UART
Slave 2
GPIO
Slave 3
GPIO
Master 2
PID
Slave 4
T/C
Slave 5
T/C

HBA Software (Linux)

- UNIX-like interface design - everything is ASCII and can be piped ('|') into other tools
- Abstracts all the FPGA complexity into command and data registers for each peripheral (think I2C)
- Three basic commands:
  - `hba_get [PERIPHERAL] [REGISTER]` - read
  - `hba_set [PERIPHERAL] [REGISTER] [VALUE]` - write
  - `hba_cat [PERIPHERAL] [REGISTER]` - open stream

HBA Software (Linux)

```
# Read slave configuration from FPGA
$ SLAVE_NUM = $(hba_get 0 0)
6

# Read peripheral types for slaves on bus
$ for i in {1..$SLAVE_NUM}; do hba_get i 0; done
uart
gpio
gpio
tc
tc
pid

# Turn on status LED by setting register 3 for the
# GPIO peripheral in block 2 to a value of 1
$ hba_set 2 3 1
```

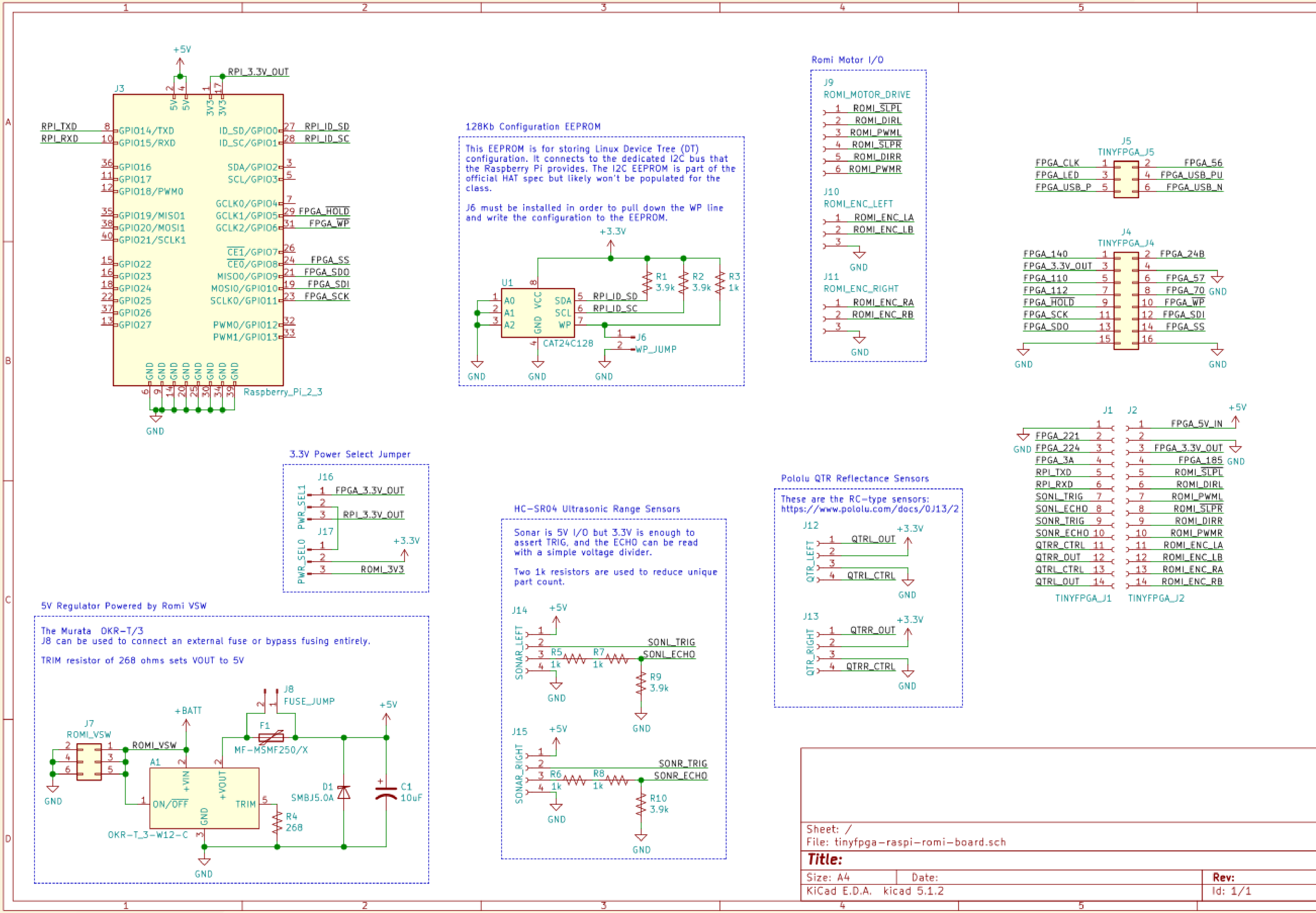
HBA Software (Linux)

```
# open a stream to the UART FIFO located at register 1
# of peripheral 1
$ hba_cat 1 1

$GNGGA,132002.448,,,,,0,0,,,M,,M,,*5C
$GPGSA,A,1,,,,,,,,,,,,,,,*1E
$GLGSA,A,1,,,,,,,,,,,,,,,*02
$GPGSV,1,1,00*79
$GLGSV,1,1,00*65
$GNRMC,132002.448,V,,,,,0.00,0.00,100417,,,N*5A
$GNVTG,0.00,T,,M,0.00,N,0.00,K,N*2C
```

HBA Hardware

- Raspberry Pi 3 Model B+ - $45 (incl. extras)
- TinyFPGA BX - $40
- Pololu Romi Chassis Kit - $30
- Pololu Romi Encoder Pair Kit - $10
- Pololu Motor Driver and PDB - $20
- 2x HC-SR04 SONAR sensors - $10
- 2x Pololu QTR IR reflectance sensors - $5
- Custom PCB (power supply & interconnect) - $10?



128Kb Configuration EEPROM
This EEPROM is for storing Linux Device Tree (DT) configuration. It connects to the dedicated I2C bus that the Raspberry Pi provides. The I2C EEPROM is part of the official HAT spec but likely won't be populated for the class.
J6 must be installed in order to pull down the WP line and write the configuration to the EEPROM.
Romi Motor I/O
3.3V Power Select Jumper
Pololu QTR Reflectance Sensors
These are the RC-type sensors: https://www.pololu.com/docs/0J13/2
HC-SR04 Ultrasonic Range Sensors
Sonar is 5V I/O but 3.3V is enough to assert TRIG, and the ECHO can be read with a simple voltage divider.
Two 1k resistors are used to reduce unique part count.
5V Regulator Powered by Romi VSW
The Murata OKR-T/3
J8 can be used to connect an external fuse or bypass fusing entirely.
TRIM resistor of 268 ohms sets VOUT to 5V
Raspberry_Pi_2_3
CAT24C128
OKR-T_3-W12-C
MF-MSMF250/X
SMBJ5.0A
TINYFPGA_J5
TINYFPGA_J4
TINYFPGA_J1
TINYFPGA_J2
Sheet: /
File: tinyfpga-raspi-romi-board.sch
Title:
Size: A4
Date:
Rev:
KiCad E.D.A. kicad 5.1.2
Id: 1/1

Class Details

- Where: **Hacker Dojo**
- When: **Wednesday, June 19, 2019**
- Cost - **$200** (we'll refund you if materials end up being less)

Questions?

All HBA material is on GitHub:

- https://github.com/
  - hbrc-fpga-class/
    - class-material/
      - blob/master/presentation.pdf