



NEUROBOT Z-TRACK 2 V-2k SERIES

FACTORY CALIBRATED HIGH-PERFORMANCE 3D PROFILE SENSORS

SPECIFICATION

Function	Description	Function	Description
Scanning Rate Connectors	AOI: Up to 10K profiles/sec 1 x M12 17-pin: Controls 1 x M12 8-pin X-Coded: Data Ethernet port Single cond UDD	Scan Control	Profile Trigger Encoder input, Internal timer/counter Fixed Scan External input; Software; Timer/counter Variable Scan Part in place; Start/Stop pulse
Image Enhancements	Single scan HDR Reflection elimination Specular configuration Filters: programmable median Horizontal and vertical flip Unified Measurement Space	Unified Measurement Space	Intuitive GUI for rapid setup Up to 16 sensors Supports multiple sensors in side-by-side, circular and in-line configurations Combine red and blue laser models Supports models with different measurement
Multi-Sensor Sync	Single low-cost wiring using off-the-shelf network switches Sensor grouping Configuration wizard to ease timing setup	Power Supply	ranges PoE via 8-pin X-code circular connector (option Separate power via 12M 17-pin connector +12V to 36VDC +/-10% with surge protection
Lasers	• Red: 660 nm 2M or 3R • Blue: 405 nm 2M or 3R	Enclosure	Machined aluminum IP67
Reflectance Management	Time integration Laser power control: Automatic or manual Gain control		4 x mounting holes Microsoft Windows10 (32/64-bit) compatible Linux 32/64-bit: Ubuntu/Debian, RHEL/CentOS/Fedora, SLES/openSUSE Kernel: 2.6.32 or higher Fully supported by Teledyne DALSA's software packages (bundled free): Free Software Sherlock 8.0 Sapera LT 8.60 (or higher), Sapera Processing 8.0 (or higher) RTL Linux: Teledyne DALSA GevAPI Framework (SDK) ver. 2.40 or higher -3rd party software: MVTec Halcon
Output Format	Individual profile, range map and 3D point cloud Depth (Z), Lateral (X), Reflectance (R) or Laser Peak Width (W) GenlCam 3.0 (SFNC 2.3) compatible 3D Data output formats compatible with Calibrated Z; Rectified Z, Calibrated ZR/ZR+W Native values and world units (microns/mm/inch) 16-bit mono (1D line-scan mode) 10-bit mono (2D area-scan mode)	Software	
Temperature	Storage: 40°C to +80°C (-4°F to +176° F) temperature - 20% to 80% non-condensing relative humidity - Operating: -10° C (50°F) to 50° C (122°F) - Relative Humidity: up to 90%		NI Max/Labview Cognex VisionPro Stemmer CVB Application development using C++ and Microsoft .Net (C++, C# or Visual Basic) FCC Class B, CE, ICE
	Relative Humidity: up to 90% (non-condensing)	Markings 	· ROHS, China RoHS
System Requirements	1 Gigabit Ethernet 4 GB or higher system memory		
1/0	- 2 opto-isolated input - Configurable as a trigger input or as a start/stop trigger - 2 opto-isolated output - Serial communication port or Analog output 4 – 20 mA		

 \cdot Quadrature (AB) shaft-encoder inputs

Encoder Input

SPECIFICATION

Models	V2K-0004-B3 ²	V2K-0015-B3	V2K-0030-B3	V2K-0100-B3
Z-Range (mm)	4	15	30	100
Standoff Distance (mm)	33.15	32.7	43.7	64.5
Data Interface		10	igE	
Z-Resolution (um)	1-1	1-2	3 - 5	8 - 14
NFOV-FFOV (mm)	14.3 - 15.3	27 - 32	53 - 72	97 - 185
X-Resolution (µm)	7.03 - 7.80	14 - 17	27 - 37	50 - 95
Repeatability (+/-µm)	0.15 - 0.15	0.25 - 0.25	0.3 - 0.4	0.5 - 0.75
Linearity (% of F.S.)	<0.05%	<0.04%	<0.03%	<0.02%
Laser (nm²)	405	405	405	405
Laser Class	2M / 3R	2M/3R	2M / 3R	2M/3R
Housing Type	TIO	T20	T20	T20

Models	V2K-0150-R3	V2K-0250-R3	V2K-0300-R3	V2K-0400-R3 ²	V2K-0650-R3 ²
Z-Range (mm)	150	250	300	400	650
Standoff Distance (mm)	140	180	200	450	550
Data Interface			1 GigE		
Z-Resolution (um)	14 - 25	22 - 45	34 - 74	43 - 71	81 - 156
NFOV-FFOV (mm)	129 - 228	157 - 325	230 - 508	400 - 659	624 - 1211
X-Resolution (µm)	66 - 117	81 - 167	118 - 261	206 - 339	321 - 623
Repeatability (+/-µm)	1 - 1.5	1.5 - 2	2 - 4	3 - 10	4 - 12.5
Linearity (% of F.S.)	<0.02%	<0.02%	<0.02%	<0.02%	<0.02%
Laser (nm)	660	660	660	660	660
Laser Class	2M / 3R	2M/3R	2M/3R	2M / 3R	2M/3R
Housing Type	T30	T30	T30	T40	T40

Housing Type	Size (L x H x W) (mm)
TIO	165 x 97 x 49
T20	116 x 83 x 49
T30	177 x 83 x 49
T40	380 x 83 x 49

CONTACT INFO

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