

Game Design

Car Parking Game

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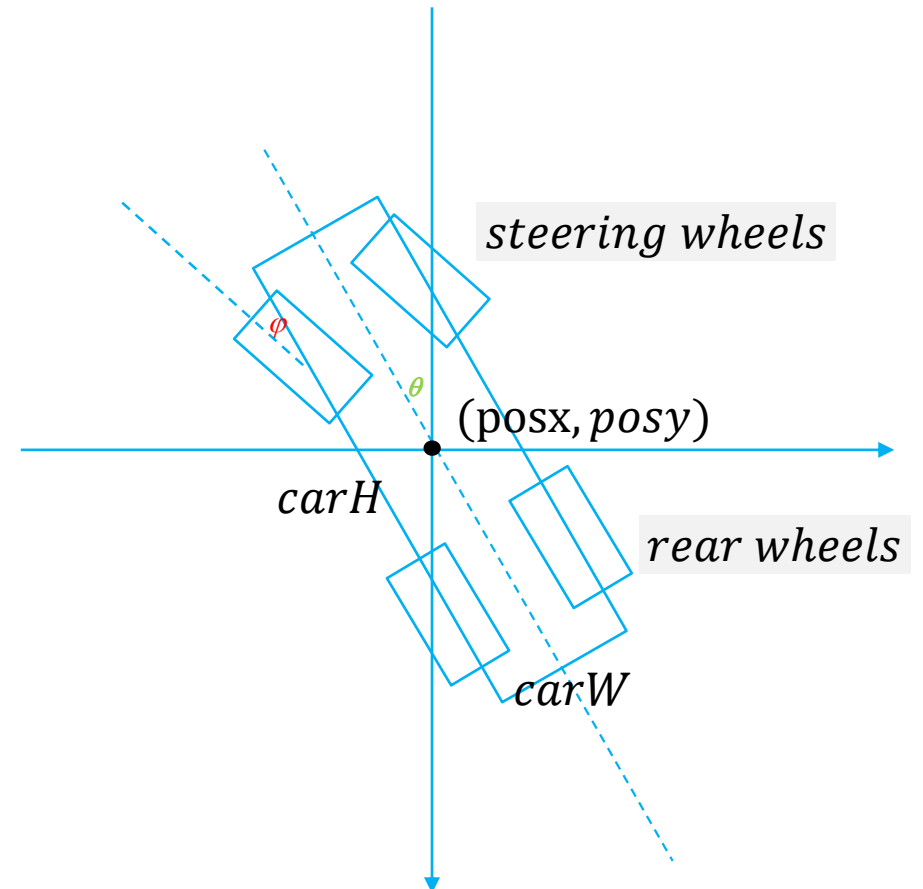
Outline

- Analysis
- Turn left
- Turn right
- Forward
- Backward
- Get the car boundaries
- Parking

Car

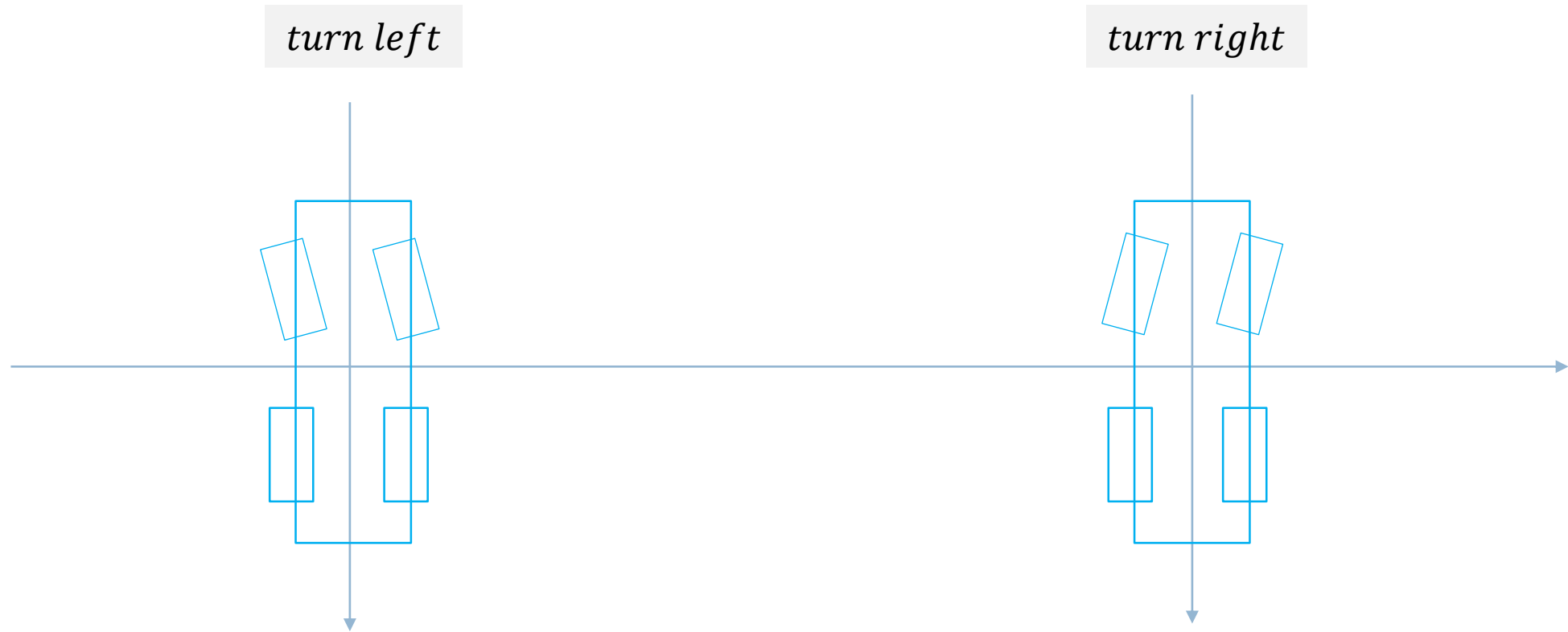
- CarSystem (posx, posy, Wdir, Cdir, carW, carH)
 - ▣ width of the car: carW
 - ▣ height of the car: carH
 - ▣ position of the car: posx, posy
 - ▣ car direction: θ
 - ▣ wheel direction
 - steering wheels: $\theta + \varphi$
 - rear wheels: θ

Front-wheel drive



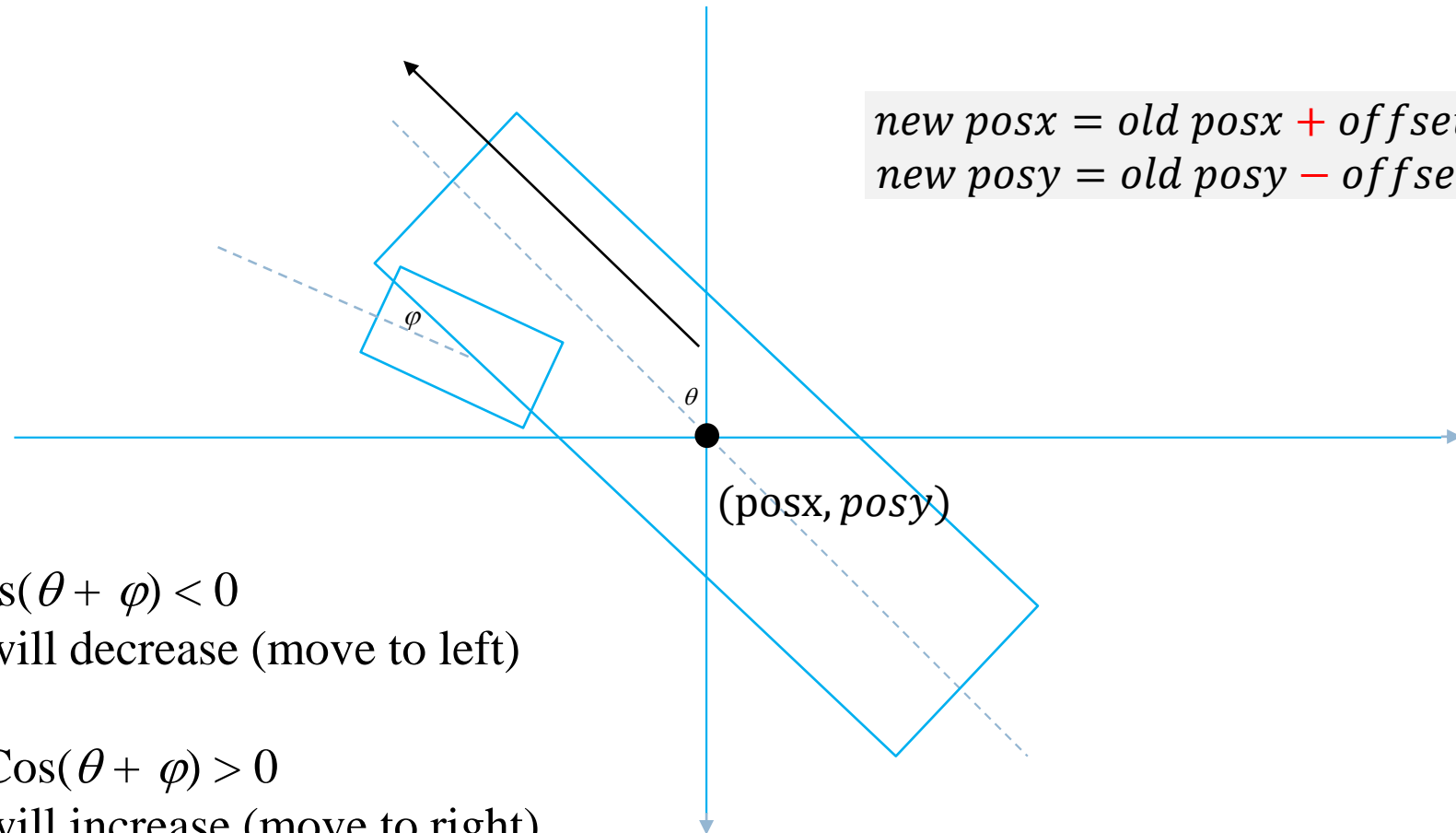
Turn left / right

- wheel direction is changed, but **car direction isn't changed**



Forward

- **posx** and **posy** are changed



$$\begin{aligned} new\ posx &= old\ posx + offset * \cos(\theta + \varphi) \\ new\ posy &= old\ posy - offset * \sin(\theta + \varphi) \end{aligned}$$

Turn left: $\theta + \varphi > 90^\circ$, $\cos(\theta + \varphi) < 0$

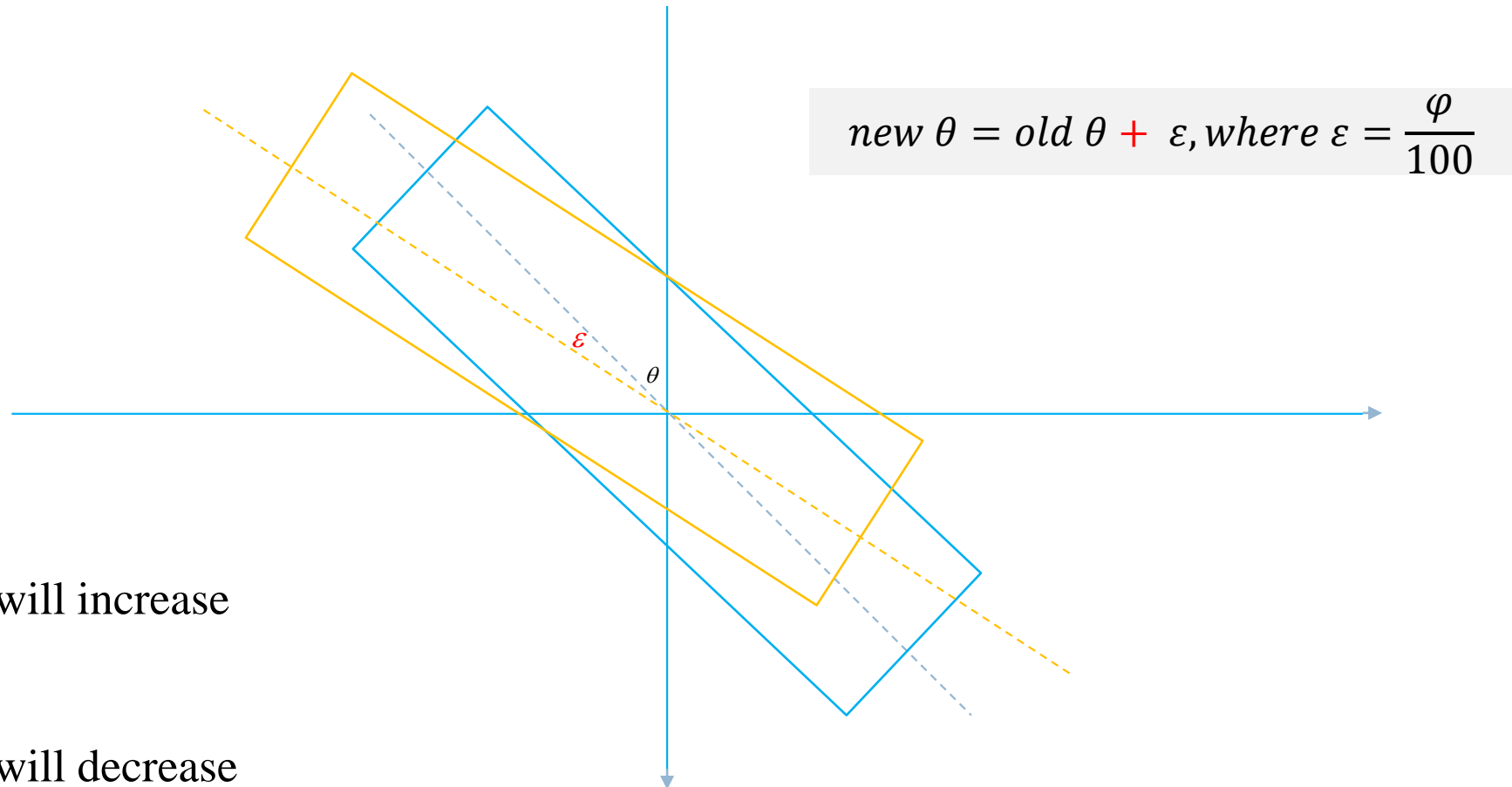
Therefore, the new posx will decrease (move to left)

Turn right: $\theta + \varphi < 90^\circ$, $\cos(\theta + \varphi) > 0$

Therefore, the new posx will increase (move to right)

Forward (cont'd)

- **car direction** is also changed (related to φ)



Turn left: $\varepsilon > 0$

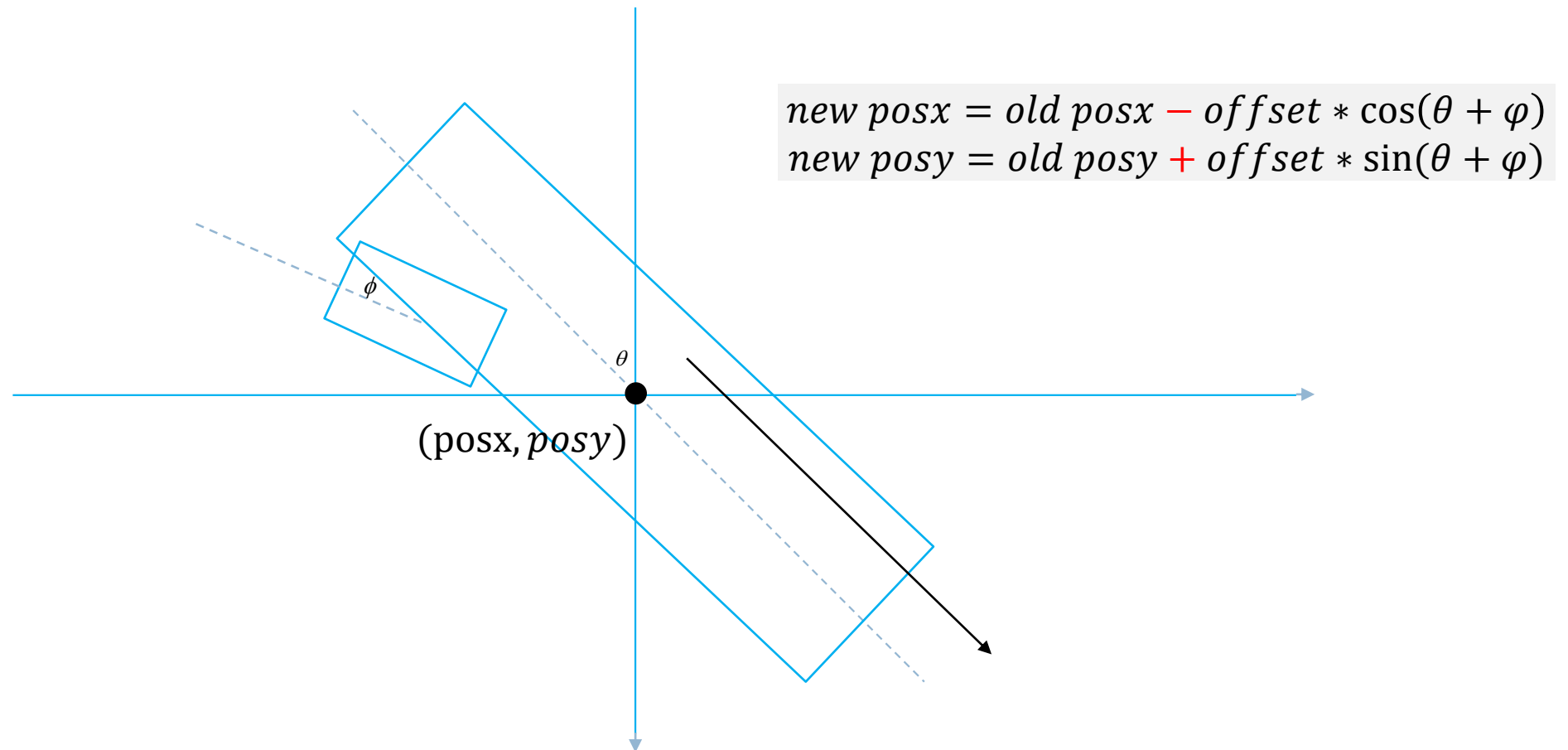
Therefore, car direction will increase

Turn right: $\varepsilon < 0$

Therefore, car direction will decrease

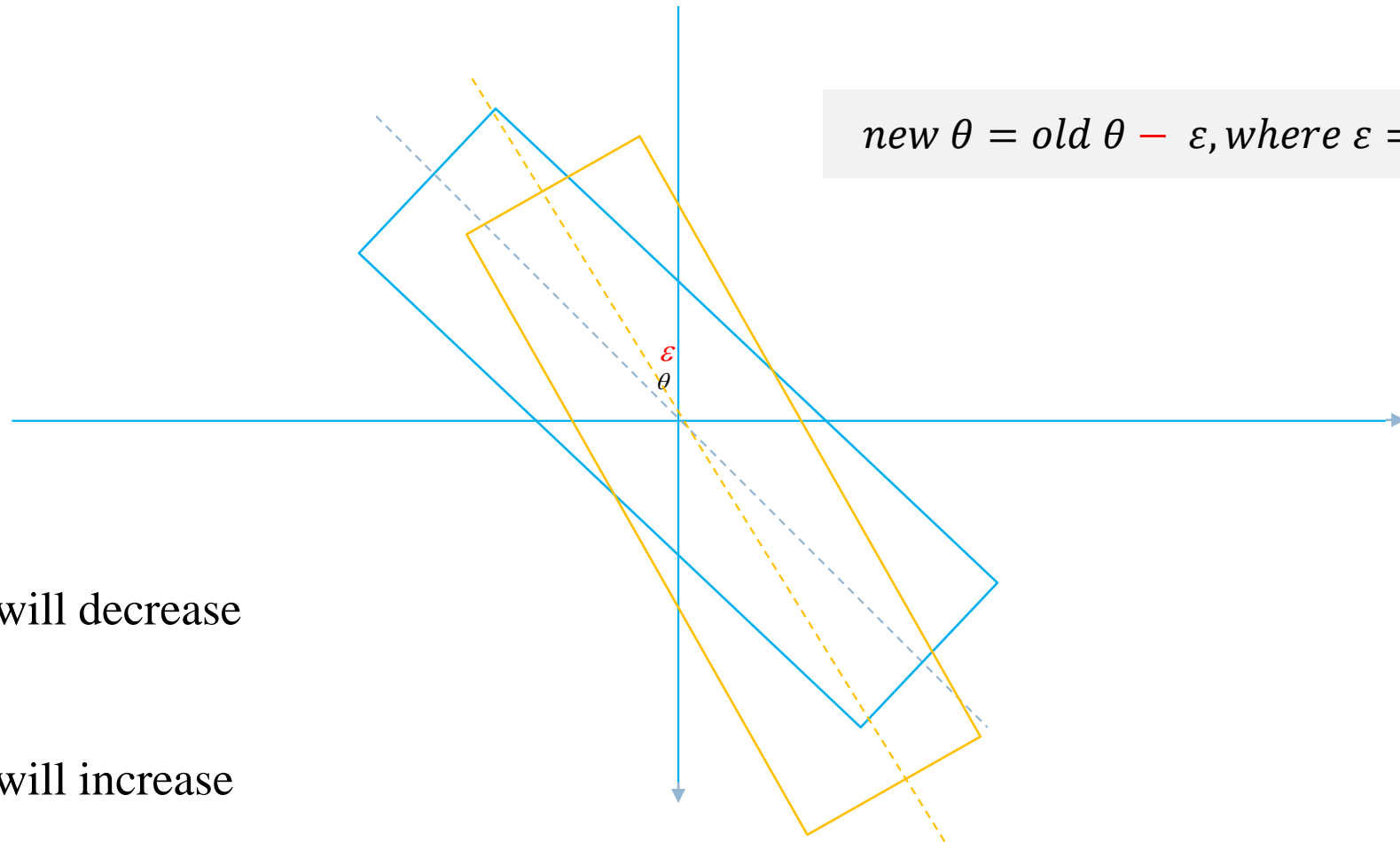
Backward (opposite operation of forward)

- **posx** and **posy** are changed



Backward (cont'd)

- **car direction** is also changed (related to φ)



$$\text{new } \theta = \text{old } \theta - \varepsilon, \text{ where } \varepsilon = \frac{\varphi}{100}$$

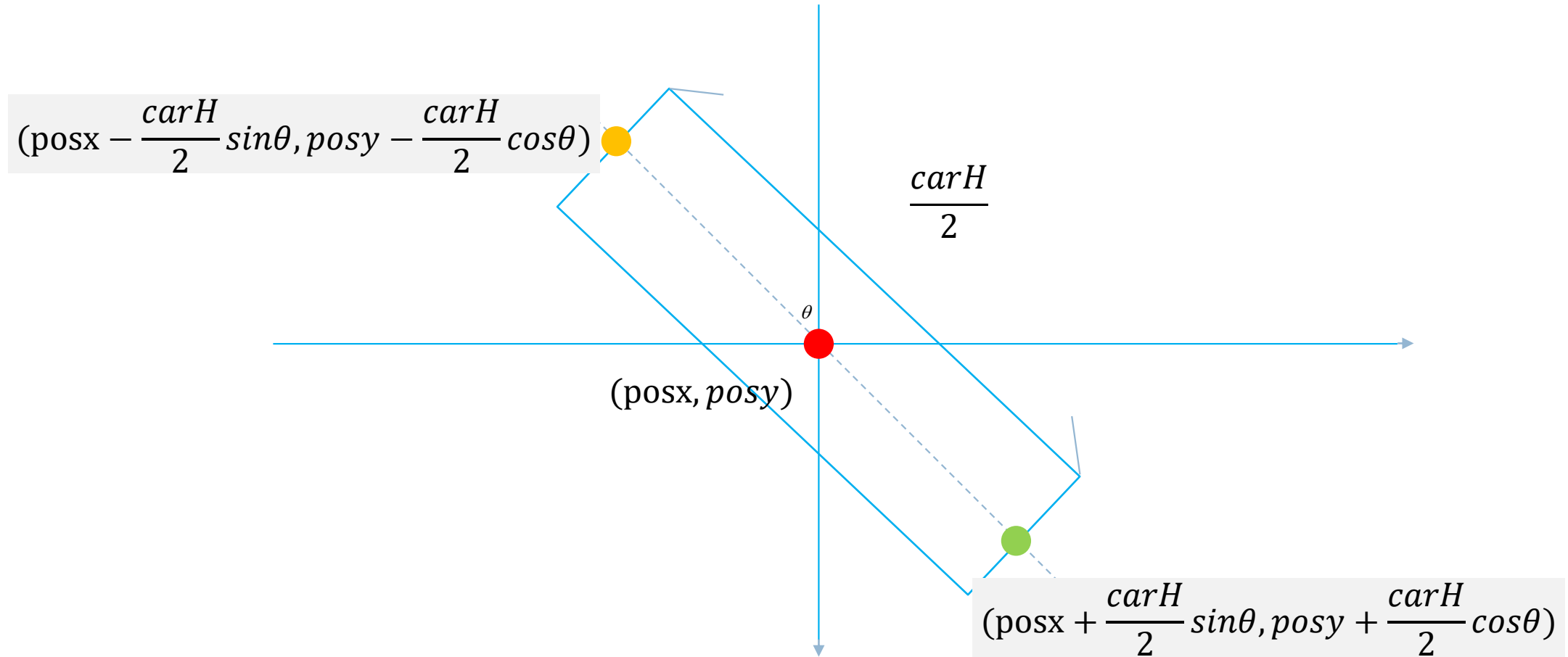
Turn left: $\varepsilon > 0$

Therefore, car direction will decrease

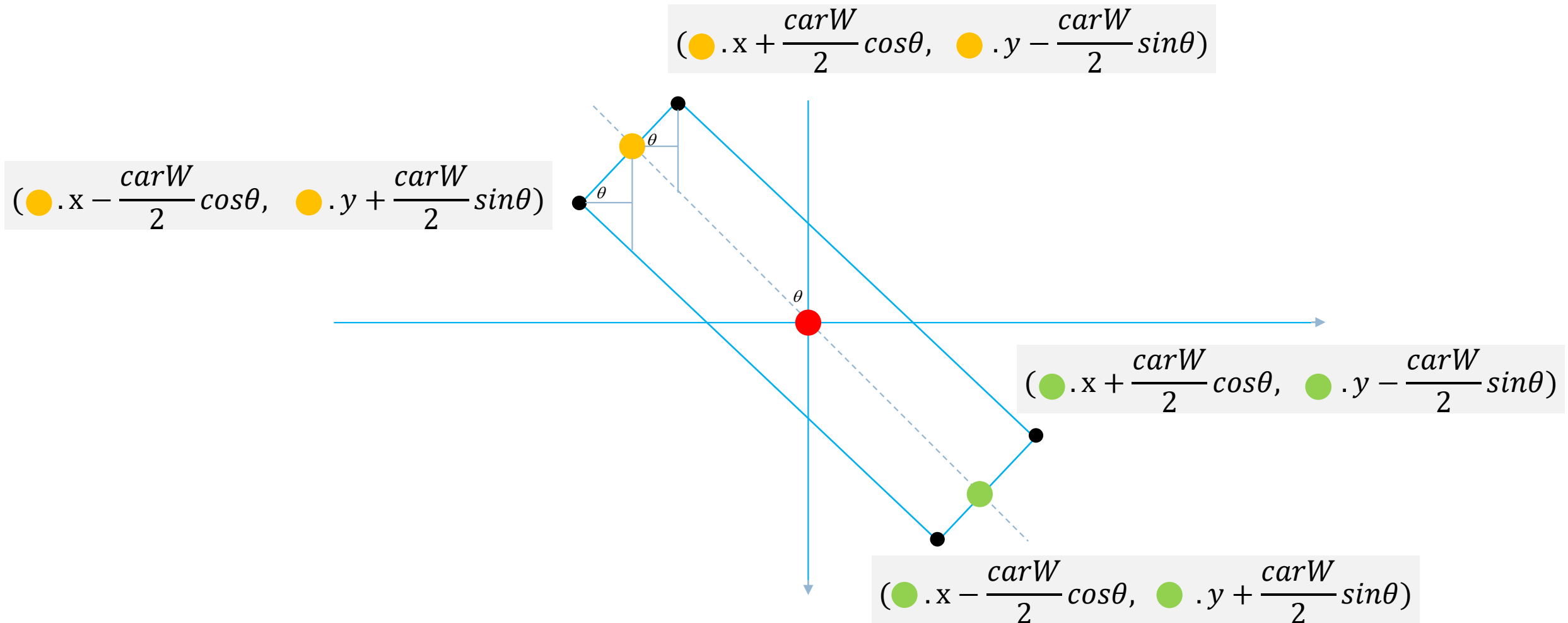
Turn right: $\varepsilon < 0$

Therefore, car direction will increase

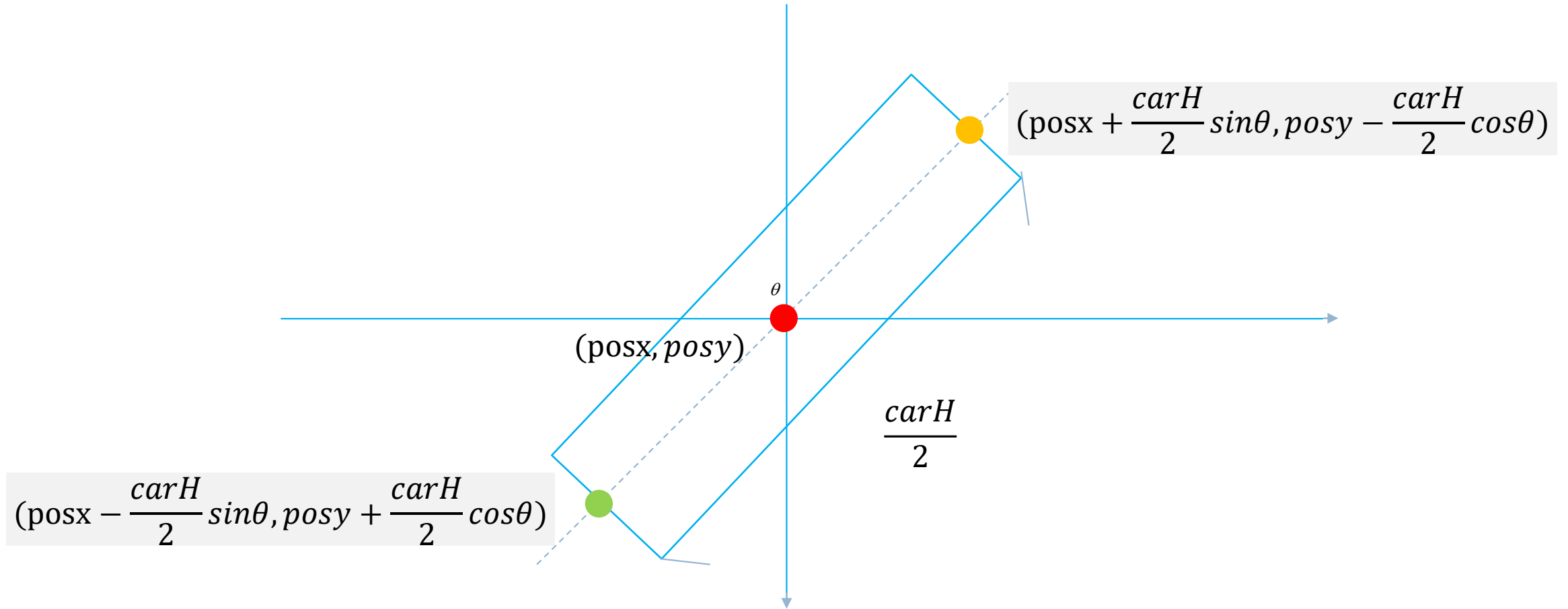
Get boundaries (turn left)



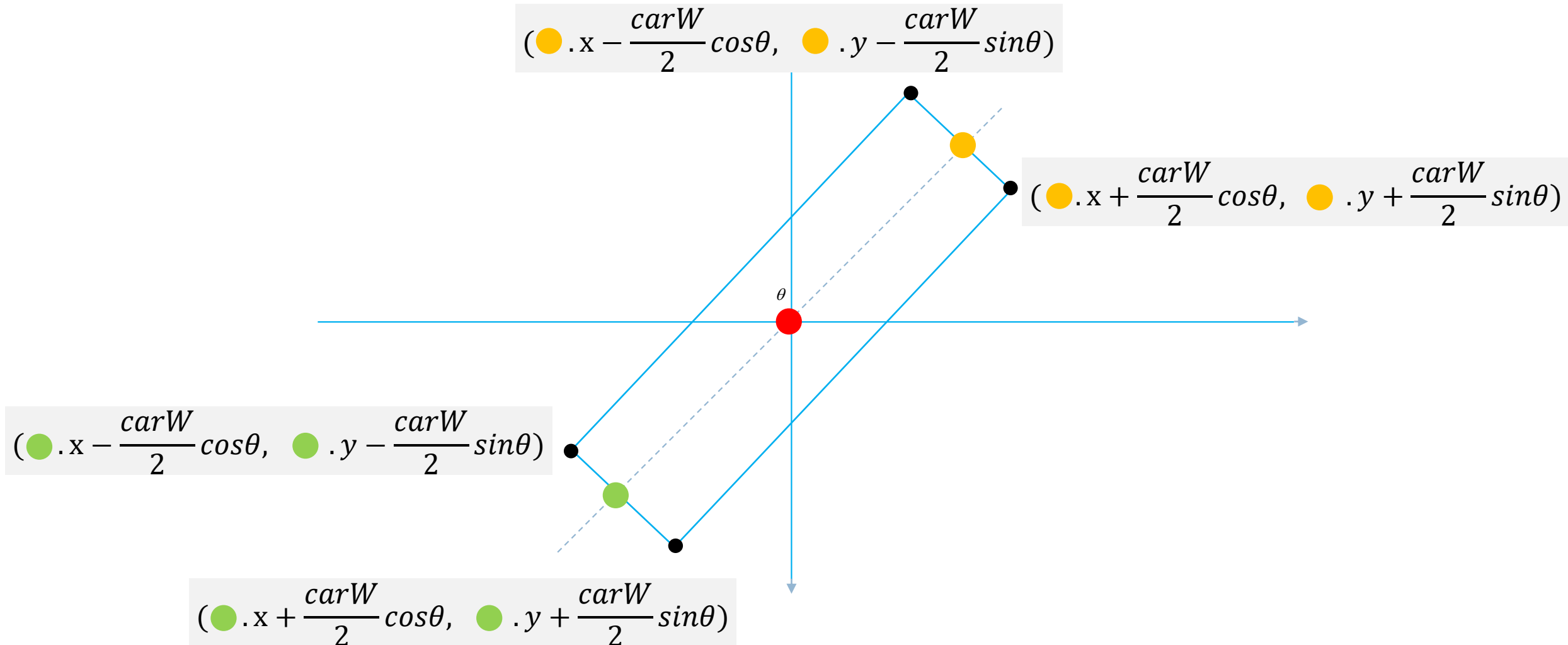
Four boundaries of the car (turn left)



Get boundaries (turn right)



Four boundaries of the car (turn right)



Parking

- If four boundaries of the car are inside the parking space

