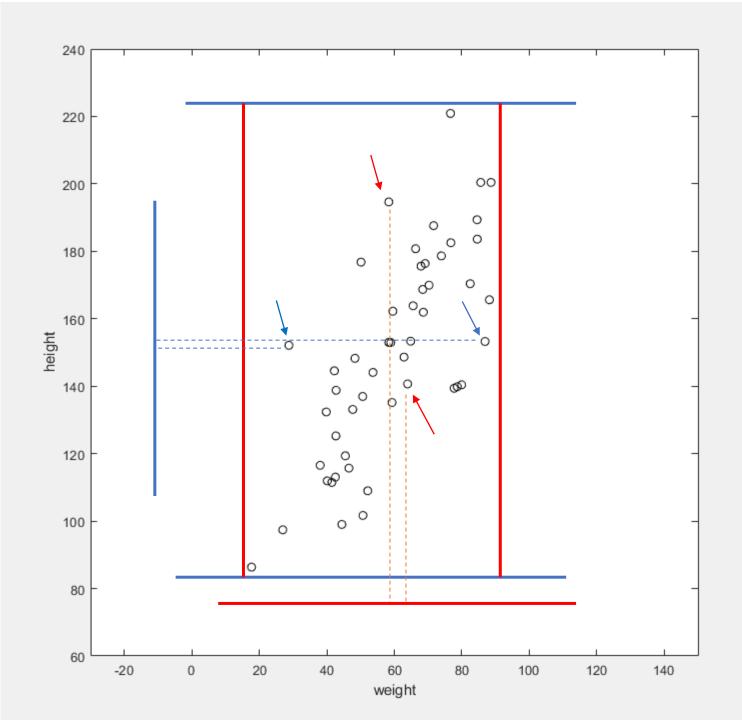
Principal Component Analysis

Halil Çağrı BİLGİ - 2231470

Muhammed Yusuf AKSEL - 2231140

- Let us say we have 50 person and 2 features of them,
- Weight and Height.
- We want to reduce this twodimensional dataset into a single variable(dimension).
- If we choose x(weight) or y(height)
 directly, we lose a considerable
 amount of variance information.
- These fundamental choices of axis are not the best.
- So, we should find/choose the one axis that will maximize the variance information conserved.
- This is where PCA plays its role!



 We start by preprocessing the data, compute the mean and subtract it from all data points so that the data set is centered around origin.

```
% Zero meanmu = mean(X);X zeromean = X - mu;
```

Now, we need to calculate the principal components of this data set.
 For this, a method called Singular Value Decomposition is used.

```
% SVD
Cov_mtx = (1/m) .* X_zeromean' * X_zeromean;
[U, S, V] = svd(Cov mtx); % Principal components
```

- Notice that the covariance matrix is Hermitian Symmetric.
- This means when we apply Singular Value Decomposition to covariance matrix what we actually find is the Spectral Decomposition. The singular values (s) correspond to eigenvalues and the left singular vectors correspond to the eigenvectors of the covariance matrix.

$$\mathbf{A} = \mathbf{U}\Lambda\mathbf{U}^{H} = \begin{bmatrix} \mathbf{u}_{1}\mathbf{u}_{2}\dots\mathbf{u}_{n} \end{bmatrix} \begin{bmatrix} \lambda_{1} & 0 & \dots & 0 \\ 0 & \lambda_{2} & \dots & 0 \\ \vdots & \vdots & \ddots & 0 \\ 0 & 0 & \dots & \lambda_{n} \end{bmatrix} \begin{bmatrix} \mathbf{u}_{1}^{H} \\ \mathbf{u}_{2}^{H} \\ \vdots \\ \mathbf{u}_{n}^{H} \end{bmatrix}$$

What do we want?

- Higher variance along the direction
- Lower reproduction error, so as close as possible projected points to the original ones.

And these two occur at the same time?? (on the violet line)

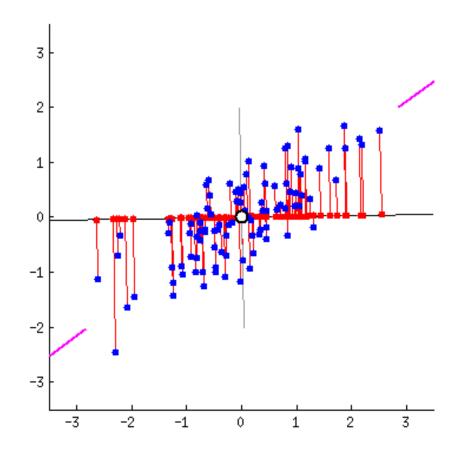
Notice that the red lines (proportional to the error in reproduction) are always perpenicular to the black line because these red lines are the closest distance of each point to the 1D black line.

We want to minimize the square of the closest distance of each point to the 1D black line. And also we don't want to lose the variance information so that at the same time we are maximizing the red dot to center distance.

Notice when the red dots(the projections) gets most seperated from each other, it is just the same moment of time when red lines are the smallest.

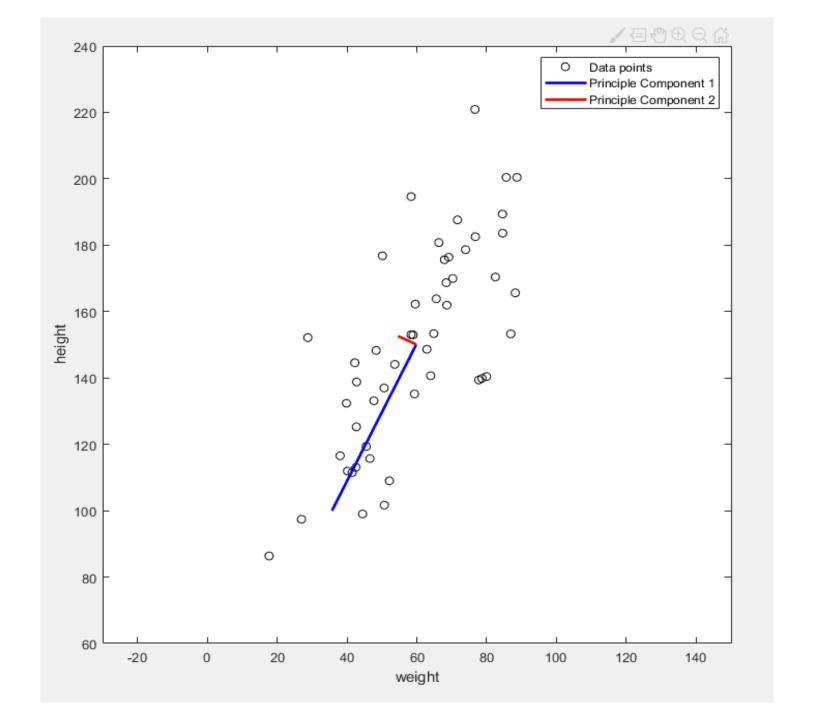
So singular value decomposition method finds this direction(the purple line) for the first principle component.

Reference: https://stats.stackexchange.com/a/140579



 So, each column vector of the U matrix is the principal component direction (eigenvectors), and S is a diagonal matrix and its diagonal entries are the eigenvalues. We will now draw the principal components found on top of the data set.

```
• % Draw the eigenvectors centered at mean of data. These lines show the
• % directions of maximum variations in the dataset.
• hold on;
• drawLine(mu, mu + .05*S(1,1) * U(:,1)', '-b', 'LineWidth', 2);
• drawLine(mu, mu + .05*S(2,2) * U(:,2)', '-r', 'LineWidth', 2);
• legend('Data points', 'Principal Component 1', 'Principal Component 2');
• hold off;
```



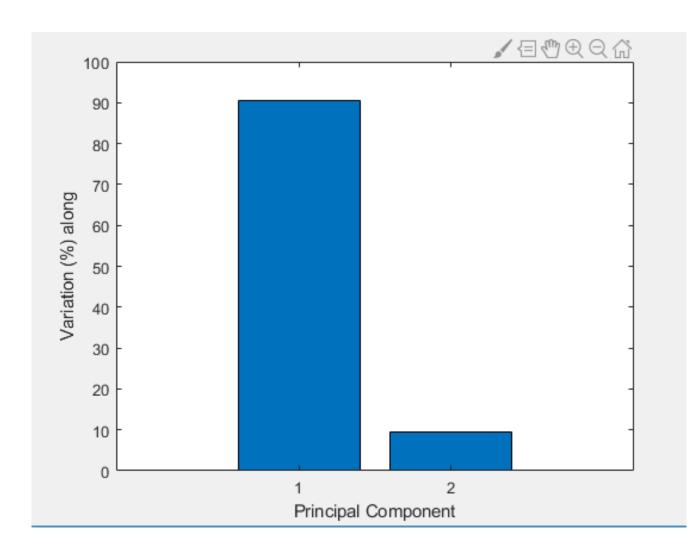
Let us see how much of the portions of variation captured by each principal component

```
• % How much of the variance is captured by these principal components?
• % S has the variance associated with that eigenvector in its diagonal
• % entries.
• total var = trace(S); % get the total variance associated with the data
 set
• percent var = 100 * [S(1, 1) ./ total var, S(2, 2) ./ total var];
• figure;
• bar(percent var);

    xlabel('Principal Component');

• ylabel('Variation (%) along');
```

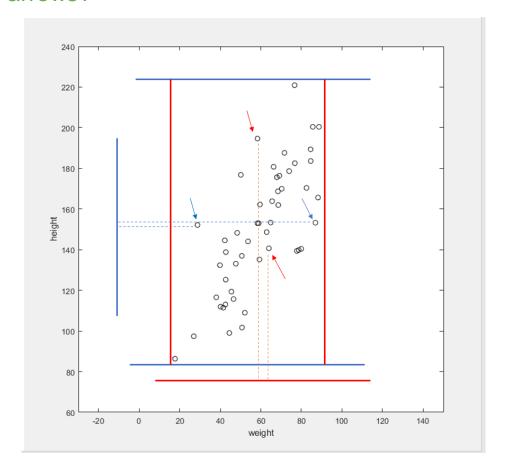
 So, we can see that almost 90 % of the variance is associated with the first principal component found. This is a good indicator that we can safely omit the second principal component and make a reduction from 2D space into 1D space by conserving a considerable amount of variation information.

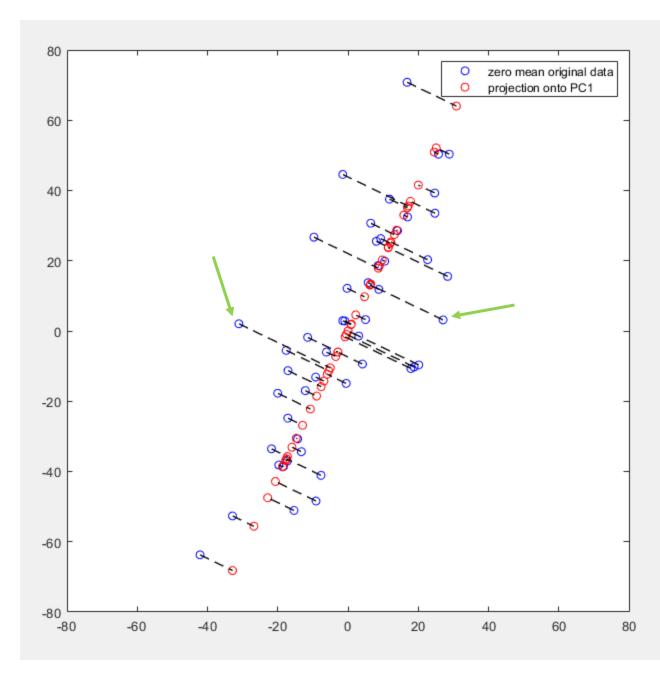


```
• % draw the zero mean version of the original data first
• figure;
• plot(X zeromean(:, 1), X zeromean(:, 2), 'bo');
• axis([-80 80 -80 80]); axis square; hold on;
• % Project the data onto first K P.C.
• K = 1; % Will reduce into K dimensional space
• U reduced = U(:, 1:K);
• Z = X zeromean * U reduced;
• % Recover the approximation data back.
• % Which means we are projecting the data points on the line
• % which is essentially the first principal component.
• X rec = Z * U reduced'; % span Z onto the space spanned by first K P.C.
• plot(X rec(:, 1), X rec(:, 2), 'ro');
• for i = 1:size(X zeromean, 1)
      drawLine(X zeromean(i,:), X rec(i,:), '--k', 'LineWidth', 1);
end
```

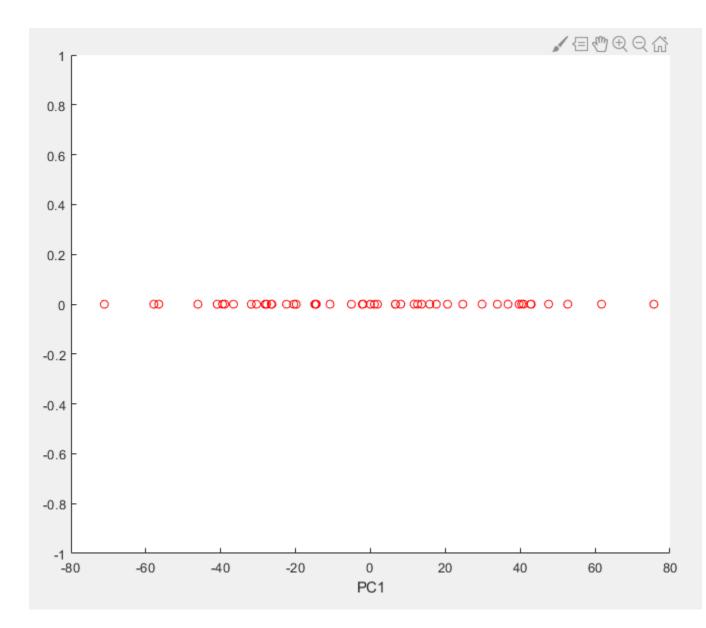
hold off

- As seen, we projected all data points onto principal component 1.
- We have the highest variation along one direction that we could get.
- Remembered those two points pointed by green arrows?



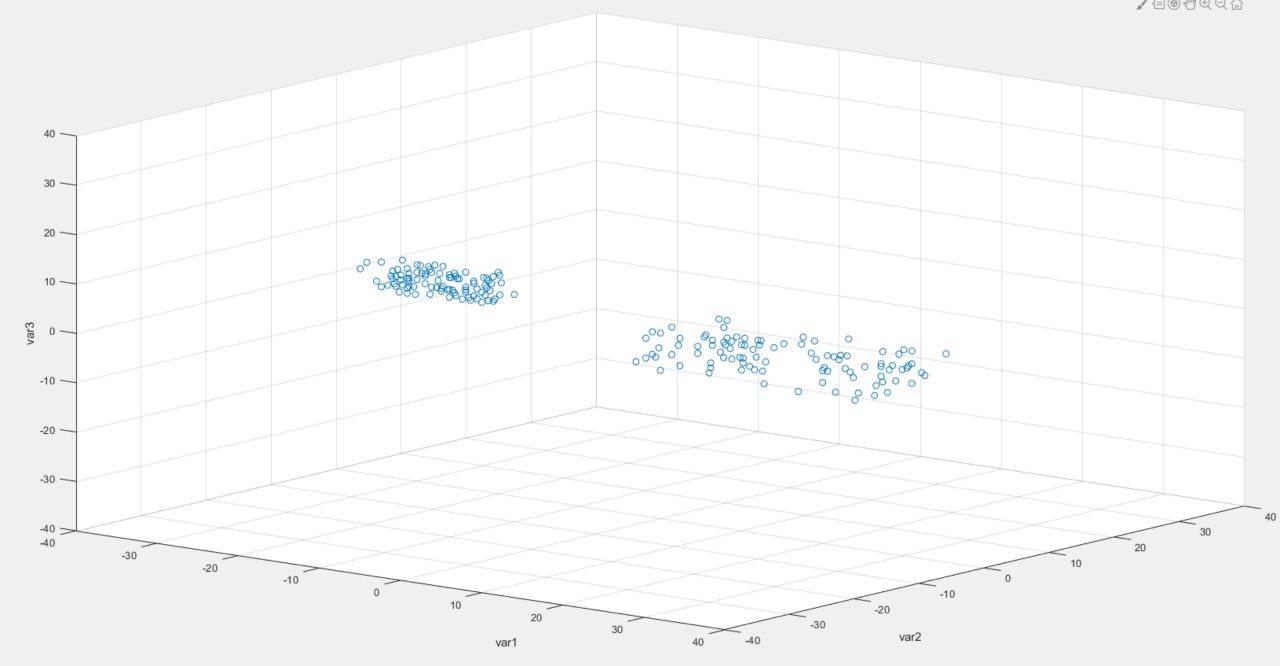


- Finally, plot this result on a more 1D looking view.
- % plot the 1D reduced points on PC1
- figure;
- scatter(Z, zeros(1, length(Z)), 'ro');



An example of reduction from 3D space to 2D space

- We have a data set with 3 features(variables), namely as var1, var2, and var3
- We have 200 randomly distributed data points on two regions(clusters).



Preprocess the data and convert it to zeromean form

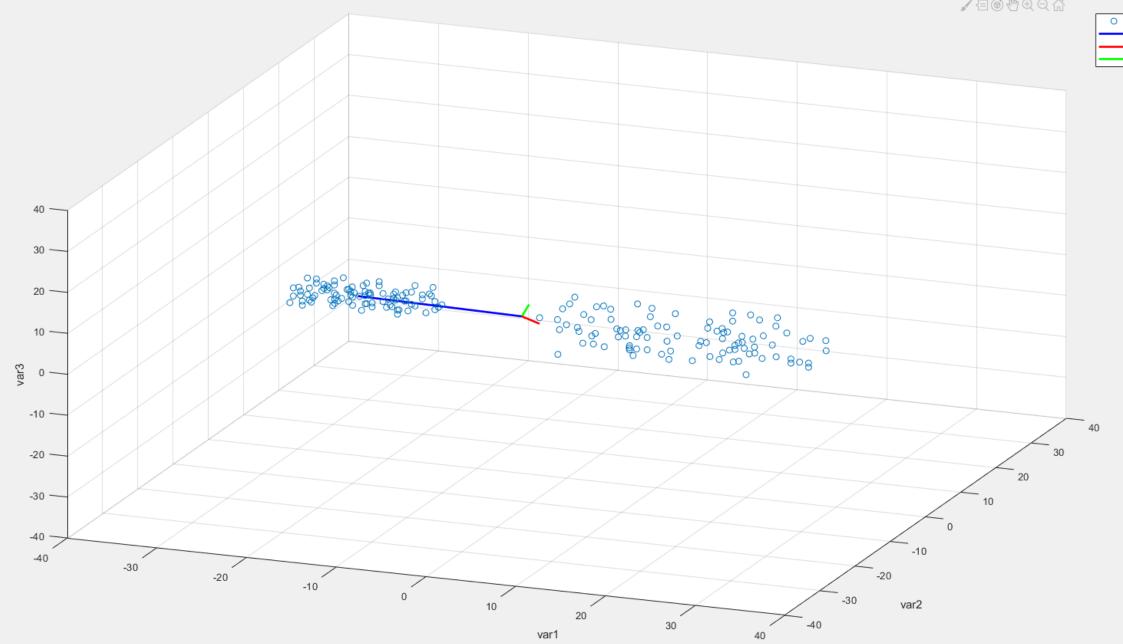
```
% Zero meanmu = mean(X);X_zeromean = X - mu;
```

 Compute principal components of this data (apply Singular Value Decomposition)

```
% SVD
Cov_mtx = (1./m) .* X_zeromean' * X_zeromean;
[U, S, V] = svd(Cov_mtx); % Principal components
```

• In other words, find the directions along which we can capture maximum amount of variance.





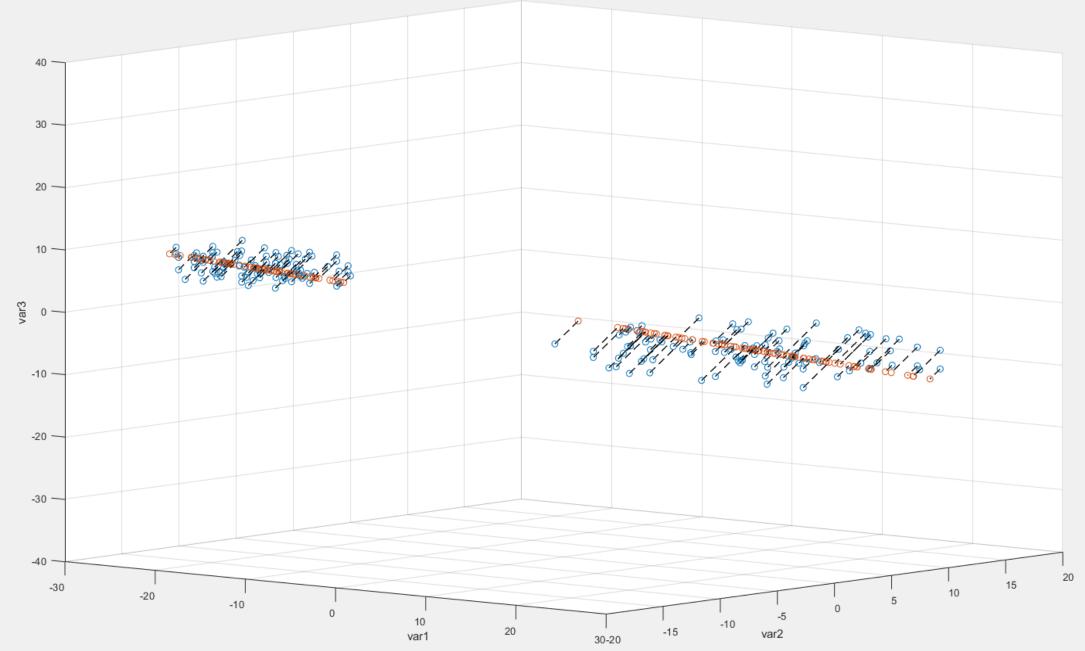
 Data points Principle Component 1(1/20)
Principle Component 2(1/4) Principle Component 3(1/2)

- Now we have the new basis for our new 2D system, PC1 and PC2.
- Project each data point onto this new plane spanned by PC1 and PC2.

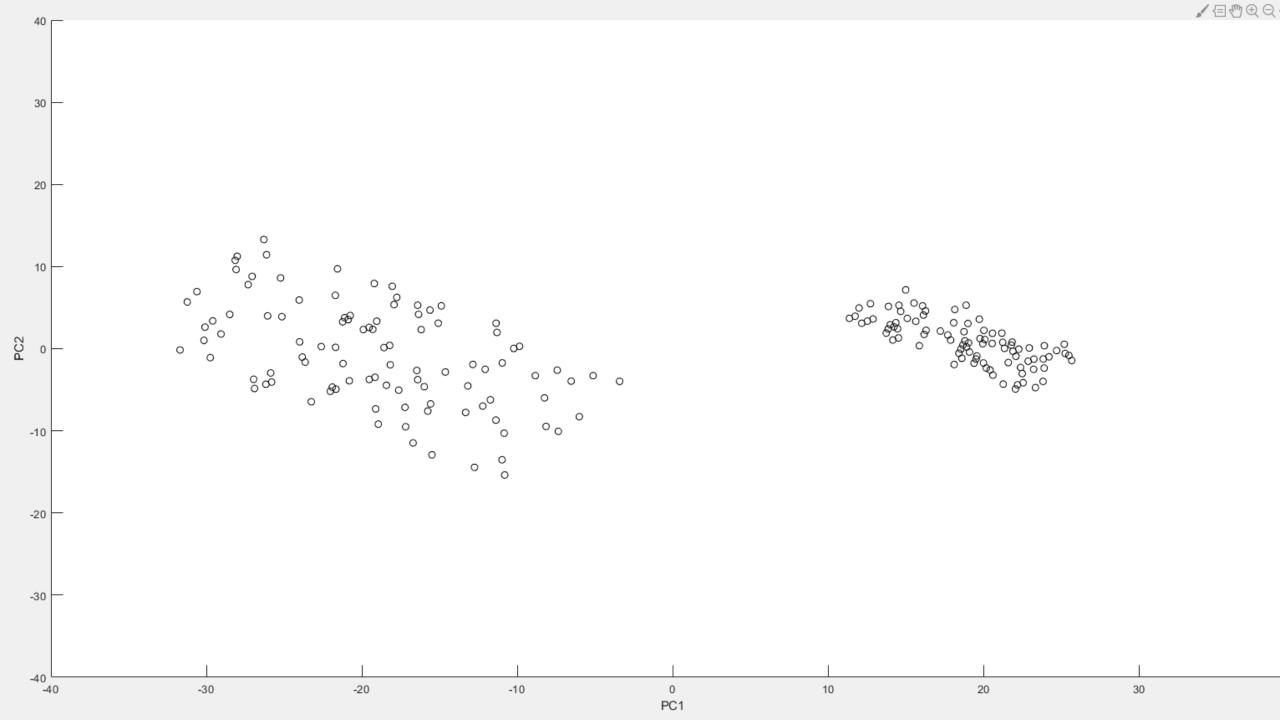
```
• % Project the data on PC1 PC2 plane
• K = 2;
• % get only first 2 principal components
• U reduced = U(:, 1:K);
• % y is the results in the new 2-dimension space (PC1 PC2 plane)
• y = U reduced' * (X zeromean)';
• y = y';
• % Recover the approximation data back with error. Which means we are
• % visualizing data on the plane which spanned by principal components
• U reduced = U(:,1:K);
• X rec = y * U reduced';
• X rec = X rec + mu; % add the mean back
```



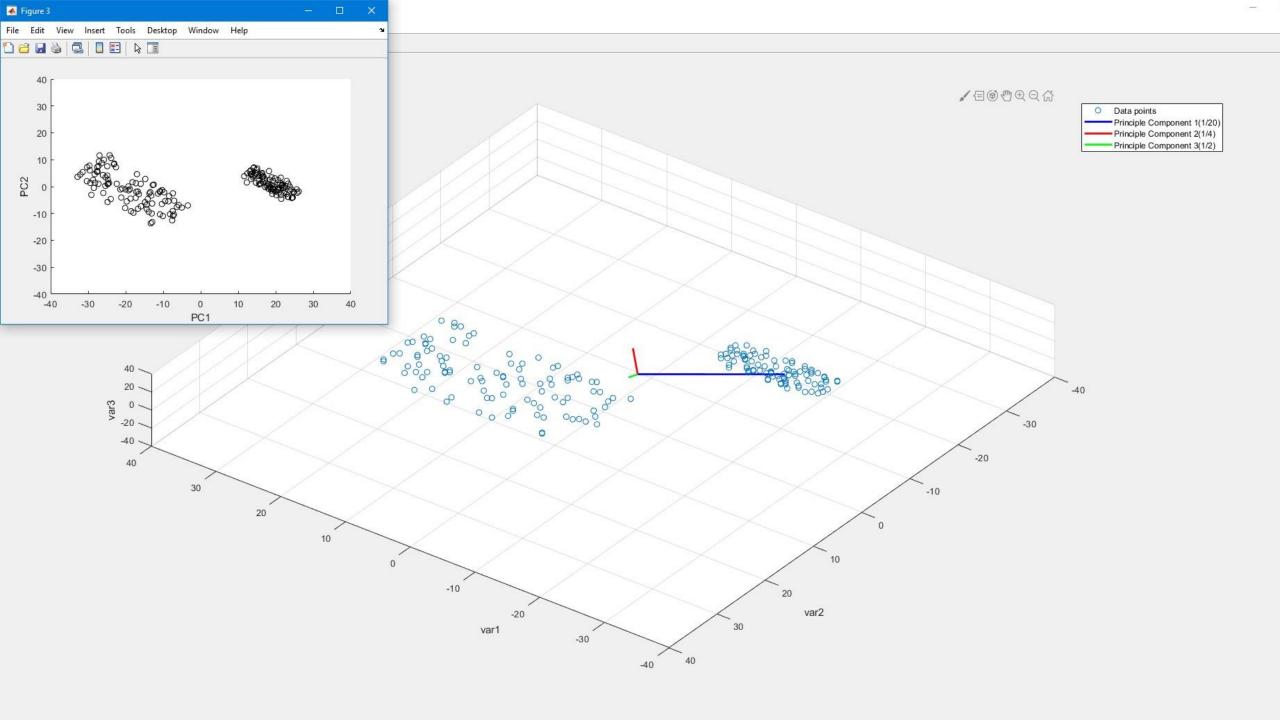
- original points
- projection onto PC1 PC2 plane



Finally, we can plot the data reduced into PC1xPC2 plane.	



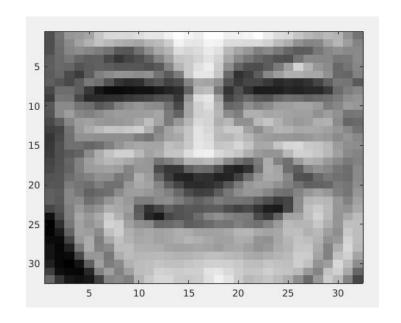
• If we see the 3D plot with the principal components and this 2D reduced plot at the same time, we can notice the relation between them.



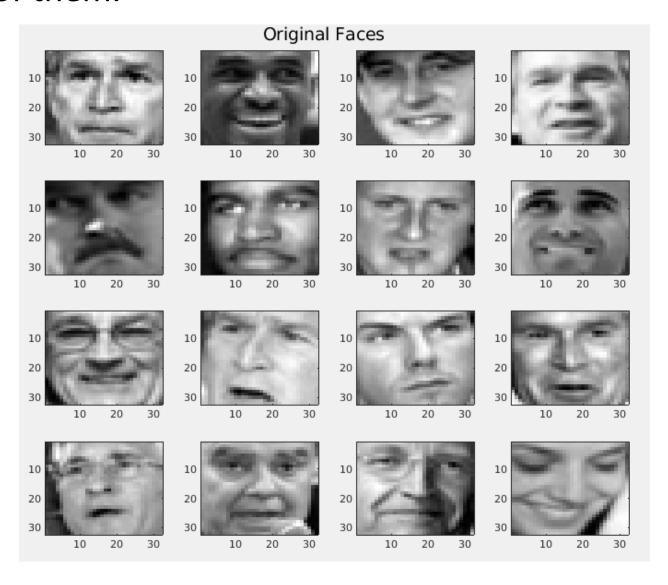
Practical Utilization of PCA

- Can we use PCA to reduces the number of features significantly?
- Can we use 10 times reduced dimensions?
- How much information we lose?

- To see the effect of PCA, we run a small demonstration.
- We collected 5000 grayscale face images from an existing dataset
- Each face picture is 32 x 32 which makes 1024 pixels for each image.
- 1024 pixels are the features, and we have total 5000 examples.
- Our data matrix is 5000 x 1024 where each image is in lexicographic ordering.



• Lets see 16 of them.

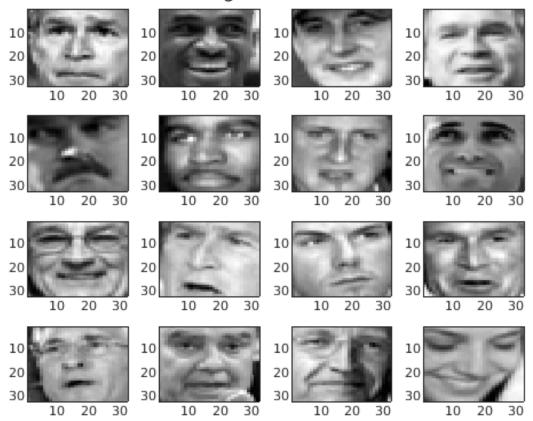


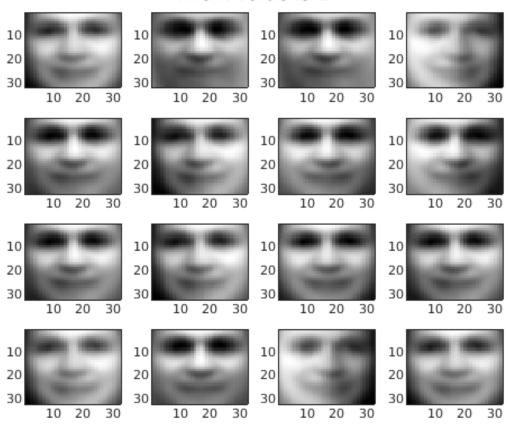
 In this practical application in addition to zero mean, we also normalize the variance of each pixel values. We obtain a X_norm which is zero mean and unit variance data set.

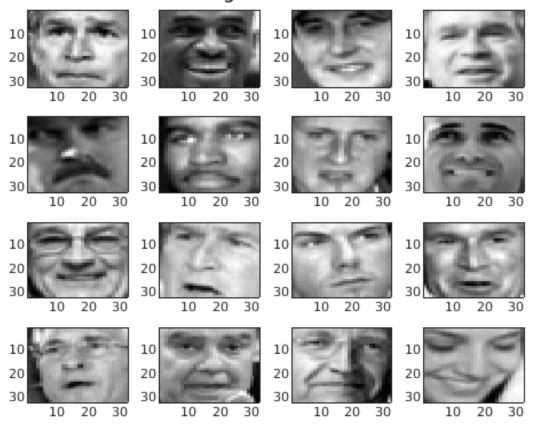
```
% How much variation each PC captures from the data.
var perc = [];
[m, n] = size(X); % m # of examples, n # of features (variables)
% Zero mean and normalization
mu = mean(X);
X = x - mu;
sigma = std(X zeromean);
X norm = X zeromean./sigma;
% SVD
Cov mtx = (1/m).*X norm'*X norm;
[U,S,V] = svd(Cov mtx); % Principal components
```

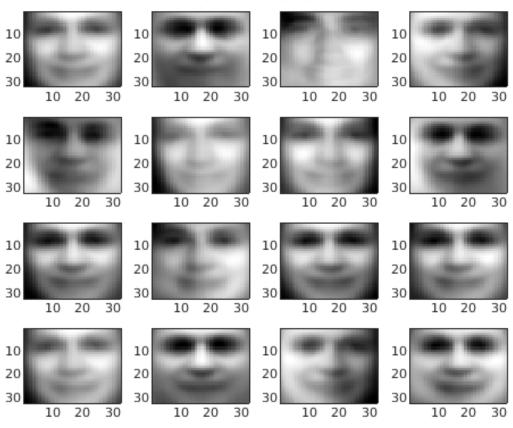
 After finding the principal components the steps are identical with the first and second examples

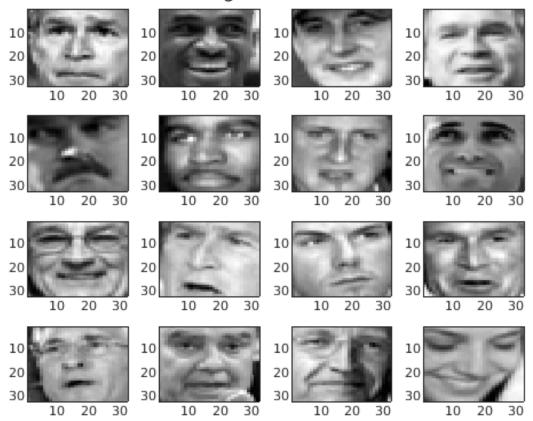
```
K \text{ set} = [512 \ 256 \ 128 \ 64 \ 32 \ 16 \ 8 \ 4 \ 2 \ 1];
for k = 1:length(K set)
    % Project data
    K = round(1024/K set(k));
    U \text{ reduced} = U(:, 1:K);
    Z = X_norm * U_reduced;
    % Recover the approximation data back with error. Which means we are
    % visualizing data on the line which spanned by principal components
    U \text{ reduced} = U(:,1:K);
    X rec = Z*U reduced';
    % Revert the preprocessing step
    X rec = X rec.*sigma;
    X rec = X rec + mu;
```

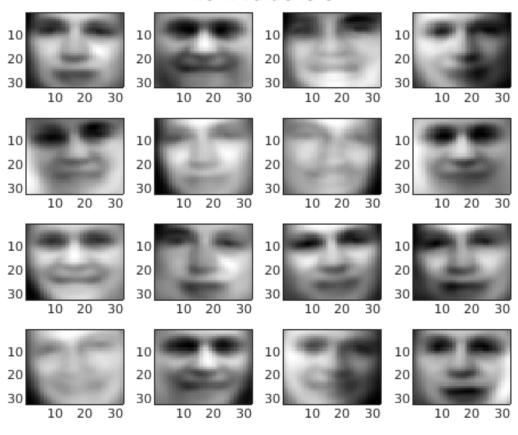


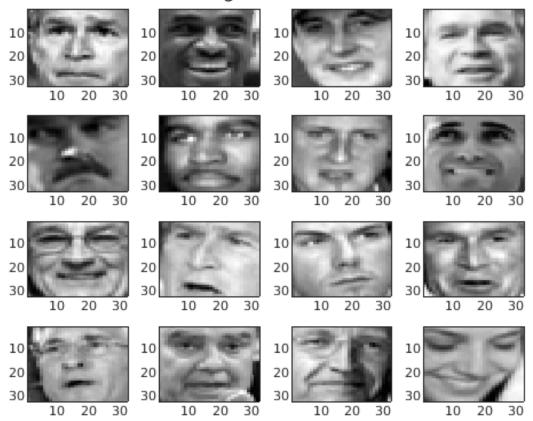


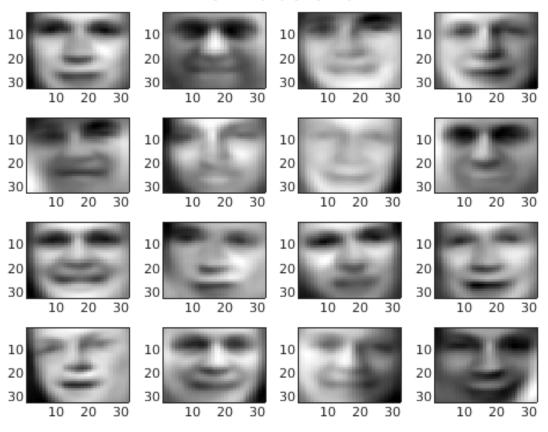


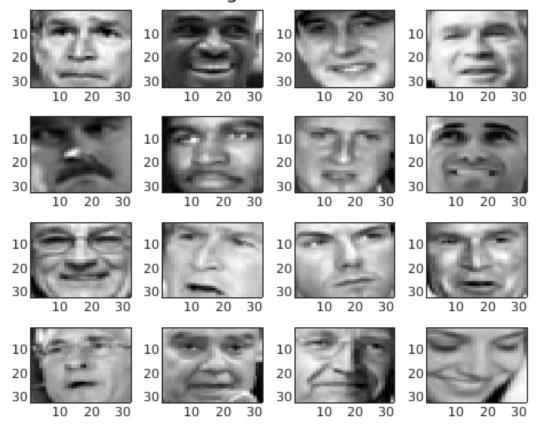


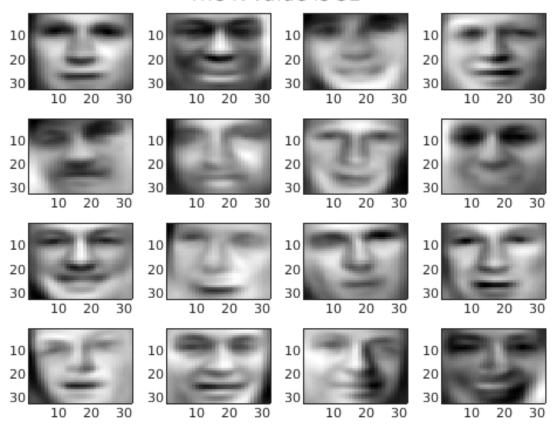


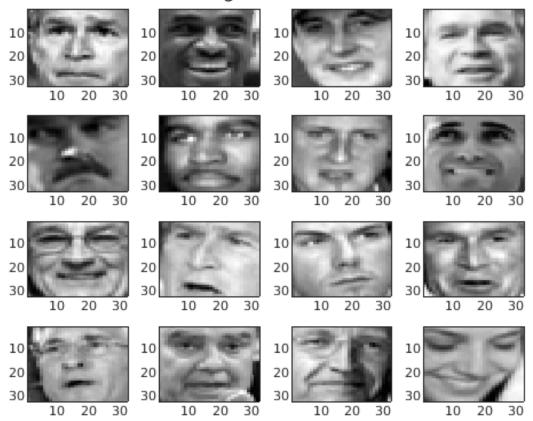


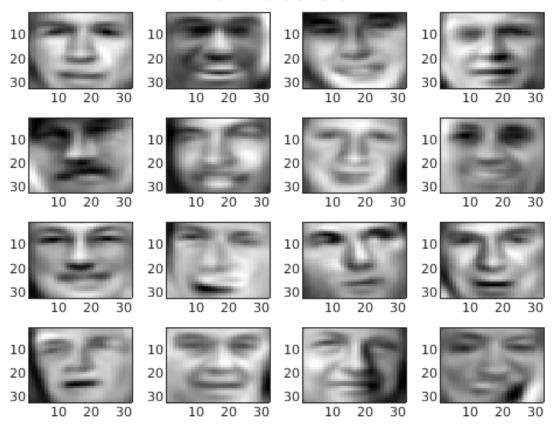


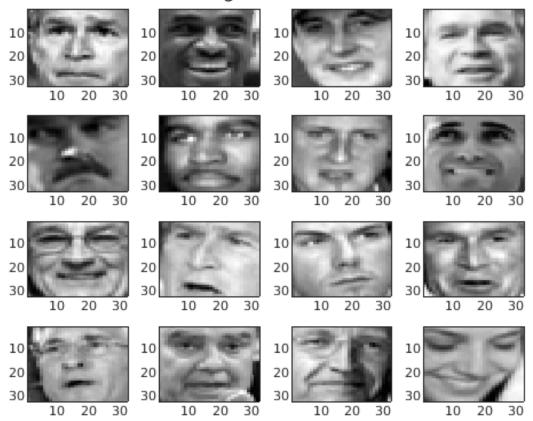


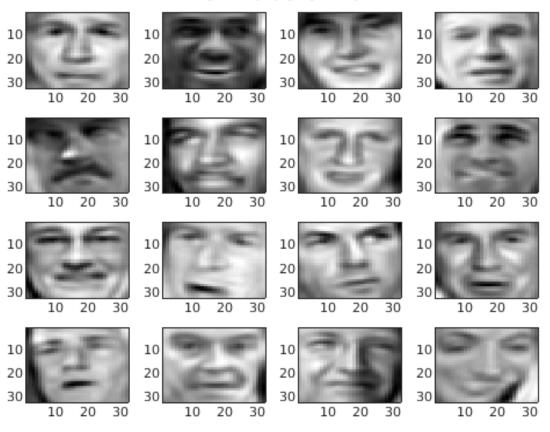


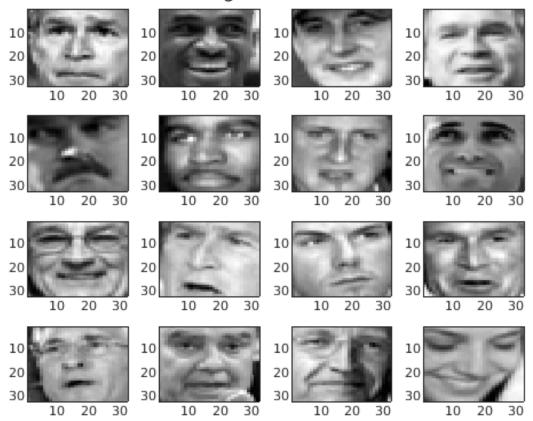


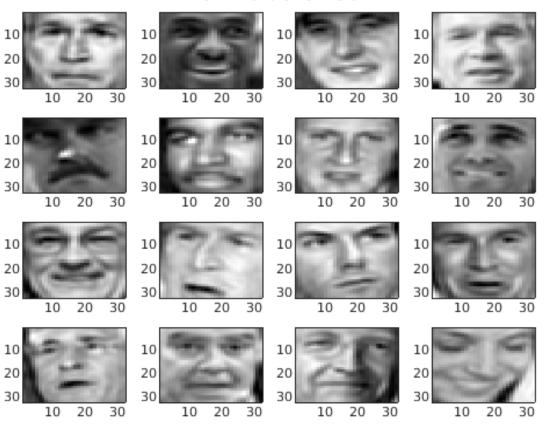


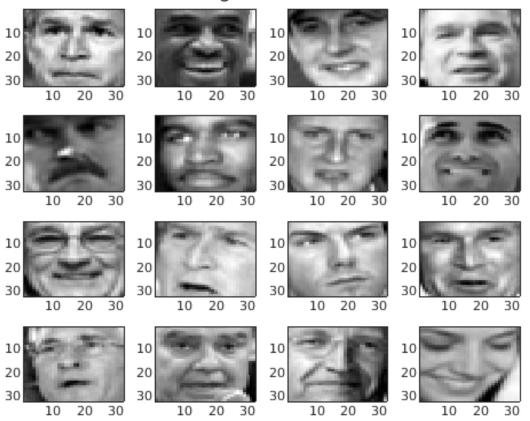


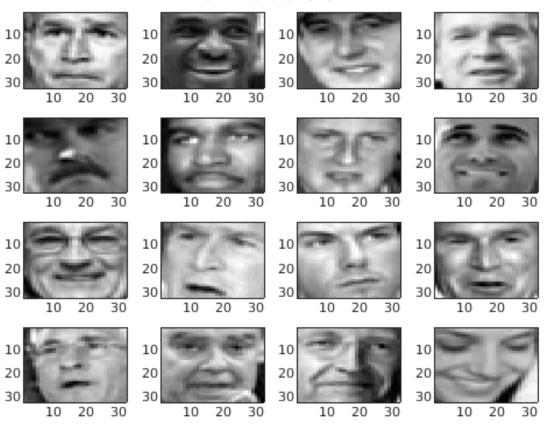


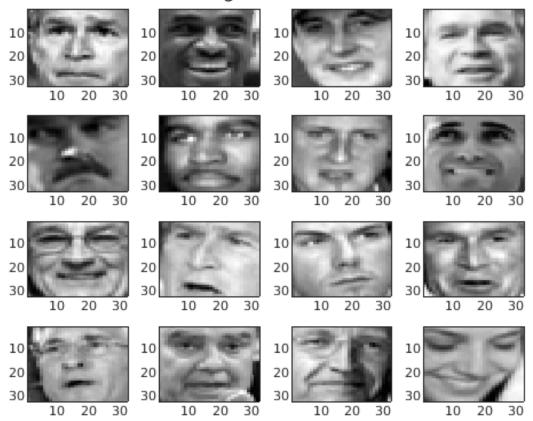


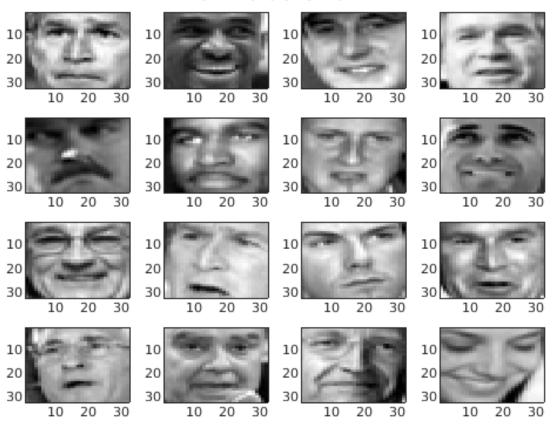












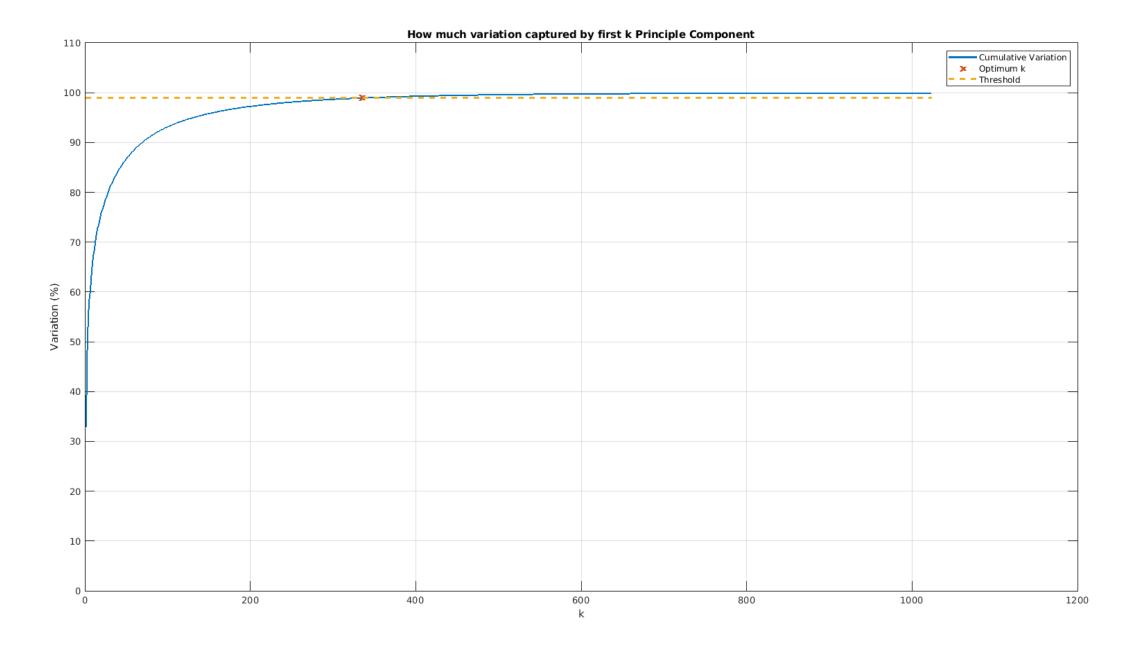
Is there a better way to find the optimum K value?

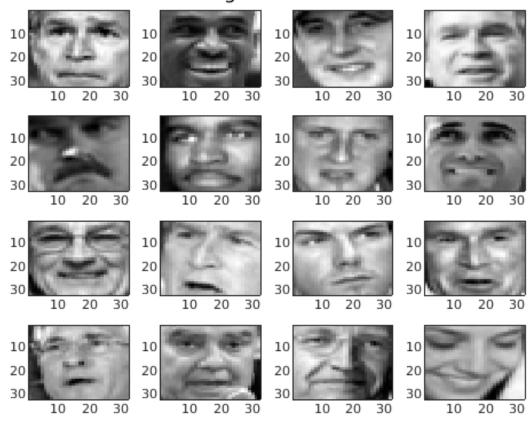
$$\frac{\frac{1}{m} \sum_{i=1}^{m} \left\| x^{(i)} - x_{rec}^{(i)} \right\|^{2}}{\frac{1}{m} \sum_{i=1}^{m} \left\| x^{(i)} \right\|} \leq 0.01$$

$$\frac{\sum_{i=1}^{k} S_{ii}}{\sum_{i=1}^{n} S_{ii}} \ge 0.99$$

```
total_var = trace(S);
opt_k = 1;
thresh_vec = [];
THRESHOLD = 99;
for j = 1:n
  thresh = 100*trace(S(1:j, 1:j))./total_var; % in percentage
  thresh_vec(end+1) = thresh;
  if thresh > THRESHOLD
    continue;
  else
    opt_k = opt_k +1;
  end
```

end





Faces Recovered with Optimum K = 335

