

view_frames Result
Recorded at time: 266.719

tb3_0/odom

Broadcaster: /gazebo
Average rate: 30.205 Hz
Most recent transform: 266.706 (0.013 sec old)
Buffer length: 4.966 sec

tb3_1/odom

Broadcaster: /gazebo
Average rate: 30.205 Hz
Most recent transform: 266.696 (0.023 sec old)
Buffer length: 4.933 sec

tb3_0/base_footprint

Broadcaster: /tb3_0/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (266.719 sec old)
Buffer length: 0.000 sec

tb3_1/base_footprint

Broadcaster: /tb3_1/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (266.719 sec old)
Buffer length: 0.000 sec

tb3_0/base_link

tb3_1/base_link

tb3_0/camera_link

Broadcaster: /tb3_0/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (266.719 sec old)
Buffer length: 0.000 sec

tb3_0/camera_rgb_frame

Broadcaster: /tb3_0/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (266.719 sec old)
Buffer length: 0.000 sec

tb3_0/camera_rgb_optical_frame

tb3_0/caster_back_left_link

Broadcaster: /tb3_0/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (266.719 sec old)
Buffer length: 0.000 sec

tb3_0/caster_back_right_link

Broadcaster: /tb3_0/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (266.719 sec old)
Buffer length: 0.000 sec

tb3_0/imu_link

Broadcaster: /tb3_0/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (266.719 sec old)
Buffer length: 0.000 sec

tb3_0/base_scan

Broadcaster: /tb3_0/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (266.719 sec old)
Buffer length: 0.000 sec

tb3_0/wheel_left_link

Broadcaster: /tb3_0/robot_state_publisher
Average rate: 30.205 Hz
Most recent transform: 266.706 (0.013 sec old)
Buffer length: 4.966 sec

tb3_0/wheel_right_link

Broadcaster: /tb3_0/robot_state_publisher
Average rate: 30.205 Hz
Most recent transform: 266.706 (0.013 sec old)
Buffer length: 4.966 sec

tb3_1/camera_link

Broadcaster: /tb3_1/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (266.719 sec old)
Buffer length: 0.000 sec

tb3_1/camera_rgb_frame

Broadcaster: /tb3_1/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (266.719 sec old)
Buffer length: 0.000 sec

tb3_1/camera_rgb_optical_frame

tb3_1/caster_back_left_link

Broadcaster: /tb3_1/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (266.719 sec old)
Buffer length: 0.000 sec

tb3_1/caster_back_right_link

Broadcaster: /tb3_1/robot_state_publisher
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tb3_1/imu_link

Broadcaster: /tb3_1/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (266.719 sec old)
Buffer length: 0.000 sec

tb3_1/base_scan

Broadcaster: /tb3_1/robot_state_publisher
Average rate: 10000.000 Hz
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tb3_1/wheel_left_link

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tb3_1/wheel_right_link

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