# Hochul Hwang

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hchlhwang.github.io

Google Scholar

## **EDUCATION**

M.S./Ph.D	Computer Science, University of Massachusetts Amherst, MA, United States	2021-
B.S.	Robot Engineering, Hanyang University ERICA, Ansan, Republic of Korea	2013-2019

## **RESEARCH AREAS**

Visual Navigation, Human-Robot Interaction, Assistive Robotics

## **PUBLICATIONS**

#### Conference

Connerent	ue e
2024	Is it safe to cross? Interpretable Risk Assessment with GPT-4V for Safety-Aware Street Crossing H. Hwang, S. Kwon, Y. Kim, and D. Kim UR 2024 (Finalist)
2024	Towards Robotic Companions: Understanding Handler-Guide Dog Interactions for Informed Guide Dog Robot Design H. Hwang, H.T. Jung, N.A. Giudice, J. Biswas, S.I. Lee*, and D. Kim*  CHI 2024 (Best Paper Award)
2023	System Configuration and Navigation of a Guide Dog Robot: Toward Animal Guide Dog-Level Guiding Work  H. Hwang <sup>†</sup> , T. Xia <sup>†</sup> , I. Keita, K. Suzuki, J. Biswas, S.I. Lee*, and D. Kim*  ICRA 2023
2018	Control Scheme and Uncertainty Considerations for Dynamic Balancing of Passive-Ankled Bipeds and Full Humanoids D. Kim, S.J. Jorgensen, H. Hwang, and L. Sentis Humanoids 2018
2018	Computationally-Robust and Efficient Prioritized Whole-Body Controller with Contact Constraints D. Kim, J. Lee, O. Campbell, H. Hwang, and L. Sentis

## Journal

202I

**IROS 2018** 

Advanced Materials 2021.

Applications
H. Hwang, C. Jang, G. Park, J. Cho, and I.J. Kim

IEEE Access 2021.

Highly Sensitive Capacitive Pressure Sensors over a Wide Pressure Range Enabled by the Hybrid Responses of a Highly Porous Nanocomposite
K.H. Ha, W. Zhang, H. Jang, S. Kang, L. Wang, P. Tan, H. Hwang, and N. Lu

ElderSim: A Synthetic Data Generation Platform for Human Action Recognition in Eldercare

#### Workshop

2023 Dynamic Object Avoidance using Event-Data for a Quadruped Robot

S. Zhu, N. Perara, S. Yu, H. Hwang, and D. Kim

IROS IPPC workshop 2023.

#### **Patent**

2022 Human behavior recognition system and method using hierarchical class learning considering safety

J. Cho, I. J. Kim, and H. Hwang U.S. Patent Application (17/565,453)

## **RESEARCH EXPERIENCE**

2021- Graduate Research Assistant, DARoS Lab @ UMass Amherst

User-centered guide dog robot development for blind and low-vision individuals: Foundation model-based perception and planning in legged systems for safe and efficient navigation.

2019-2020 Research Intern, Center for AI @ Korea Institute of Science and Technology

Real-time human action recognition system development and synthetic data augmentation evaluation.

2017-2018 Undergraduate researcher, Human Centered Robotics Lab @ UT Austin

Testing and optimizing the 6 DOF passive-ankled biped robot, Mercury, for walking.

2018 Undergraduate Researcher, Lu Research Group @ UT Austin

Manufacturing and testing flexible resistive force sensors for lower-limb prosthetic stress distribution.

#### **AWARDS & SCHOLARSHIP**

## **Awards and Honors**

2024 Best Paper Award - ACM SIGCHI Conference on Human Factors in Computing Systems 2024

Vision Assistance Race 2nd place - CYBATHLON Challenges 2023

2017 Creative Technology and Excellence Award - STEAM CUP

#### Scholarship & Fellowships

2021 University of Massachusetts Amherst CICS Jumpstart Fellowship

2016-2017 {Hanyang University, Haksan Foundation} Academic Achievement Scholarship

## **TEACHING EXPERIENCE**

#### **Teaching Assistant @ UMass Amherst**

Spring 2023 Robotics (COMPSCI 603) – mobile robot platform setup

Fall 2022 Introduction to Robotics - Mechanics, Dynamics, and Control (COMPSCI 403) - interactive quiz

## Student Mentor @ UMass Amherst

Early Research Scholars Program - Shiven Patel, Antoinette Reid, Ron Kleinhause-Goldman, Dang Nguyen

Honors thesis - Krisha Adhikari (synthetic data), Matthew Hersey (deep learning)

Research & independent study – Tim Xia (path planning), Ken Suzuki (CAD), Millan Taranto (CAD)

# **ACADEMIC SERVICE**

Reviewer - RA-L'24, CHI'24, IROS'23, ICRA'22

UMass Korean Graduate Student Association (KGSA) President 2022-2023

# **TECHNICAL & RESEARCH SKILLS**

Programming & software: Python, C++, MATLAB, PyTorch, TensorFlow, ROS, Unreal Engine, Docker, Git Mechatronics: SOLIDWORKS (Certified SolidWorks Associate), CATIA, Onshape

Updated July 2024