Hochul Hwang

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hchlhwang.github.io

Google Scholar

EDUCATION

M.S./Ph.D Computer Science, University of Massachusetts Amherst, MA, United States

B.S. Robot Engineering, Hanyang University ERICA, Ansan, Republic of Korea

2021–2019

RESEARCH AREAS

Assistive Robotics, Human-Robot Interaction, Computer Vision

PUBLICATIONS

Conference

Is it safe to cross? Interpretable Risk Assessment with GPT-4V for Safety-Aware Street Crossing 2024 H. Hwang, S. Kwon, Y. Kim, and D. Kim UR 2024 (Finalist) Towards Robotic Companions: Understanding Handler-Guide Dog Interactions for Informed Guide 2024 Dog Robot Design H. Hwang, H.T. Jung, N.A. Giudice, J. Biswas, S.I. Lee*, and D. Kim* CHI 2024 (Best Paper Award) System Configuration and Navigation of a Guide Dog Robot: Toward Animal Guide Dog-Level 2023 Guiding Work H. Hwang[†], T. Xia[†], I. Keita, K. Suzuki, J. Biswas, S.I. Lee^{*}, and D. Kim^{*} ICRA 2023 Control Scheme and Uncertainty Considerations for Dynamic Balancing of Passive-Ankled Bipeds and 2018 Full Humanoids D. Kim, S.J. Jorgensen, H. Hwang, and L. Sentis

Computationally-Robust and Efficient Prioritized Whole-Body Controller with Contact Constraints

Journal

2018

Humanoids 2018

IROS 2018

ElderSim: A Synthetic Data Generation Platform for Human Action Recognition in Eldercare Applications
H. Hwang, C. Jang, G. Park, J. Cho, and I.J. Kim

IEFE Access 2021.

Highly Sensitive Capacitive Pressure Sensors over a Wide Pressure Range Enabled by the Hybrid

D. Kim, J. Lee, O. Campbell, H. Hwang, and L. Sentis

Responses of a Highly Porous Nanocomposite
K.H. Ha, W. Zhang, H. Jang, S. Kang, L. Wang, P. Tan, H. Hwang, and N. Lu

Advanced Materials 2021.

Workshop

2023 Dynamic Object Avoidance using Event-Data for a Quadruped Robot

S. Zhu, N. Perara, S. Yu, H. Hwang, and D. Kim

IROS IPPC workshop 2023.

Patent

2022 Human behavior recognition system and method using hierarchical class learning considering safety

J. Cho, I. J. Kim, and H. Hwang U.S. Patent Application (17/565,453)

RESEARCH EXPERIENCE

2021- Graduate Research Assistant, DARoS Lab @ UMass Amherst

User-centered guide dog robot development for blind and low-vision individuals: Foundation model-based perception and planning in legged systems for safe and efficient navigation.

2019-2020 Research Intern, Center for AI @ Korea Institute of Science and Technology

Real-time human action recognition system development and synthetic data augmentation evaluation.

2017-2018 Undergraduate researcher, Human Centered Robotics Lab @ UT Austin

Testing and optimizing the 6 DOF passive-ankled biped robot, Mercury, for walking.

2018 Undergraduate Researcher, Lu Research Group @ UT Austin

Manufacturing and testing flexible resistive force sensors for lower-limb prosthetic stress distribution.

AWARDS & SCHOLARSHIP

Awards and Honors

2024 ACM SIGCHI Conference on Human Factors in Computing Systems 2024 - Best Paper Award

2023 CYBATHLON Challenges 2023 - Vision Assistance Race 2nd place

2017 STEAM CUP - Creative Technology and Excellence Award

Scholarship & Fellowships

2021 University of Massachusetts Amherst CICS Jumpstart Fellowship

2016-2017 {Hanyang University, Haksan Foundation} Academic Achievement Scholarship

TEACHING EXPERIENCE

Teaching Assistant @ UMass Amherst

Spring 2023 Robotics (COMPSCI 603) – mobile robot platform setup

Fall 2022 Introduction to Robotics - Mechanics, Dynamics, and Control (COMPSCI 403) - interactive quiz

Student Mentor @ UMass Amherst

Early Research Scholars Program - Shiven Patel, Antoinette Reid, Ron Kleinhause-Goldman, Dang Nguyen

Honors thesis - Krisha Adhikari (synthetic data), Matthew Hersey (deep learning)

Research & independent study – Tim Xia (path planning), Ken Suzuki (CAD), Millan Taranto (CAD)

ACADEMIC SERVICE

Reviewer - RA-L'24, CHI'24, IROS'23, ICRA'22

UMass Korean Graduate Student Association (KGSA) President 2022-2023

TECHNICAL & RESEARCH SKILLS

Programming & software: Python, C++, MATLAB, PyTorch, TensorFlow, ROS, Unreal Engine, Docker, Git Mechatronics: SOLIDWORKS (Certified SolidWorks Associate), CATIA, Onshape

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