Hochul Hwang

hochulhwang@cs.umass.edu

hchlhwang.github.io

Google Scholar

EDUCATION

M.S./Ph.D Computer Science, University of Massachusetts Amherst, MA, United States

B.S. Robot Engineering, Hanyang University ERICA, Ansan, Republic of Korea

2013–2019

RESEARCH AREAS

Visual Navigation, Human-Robot Interaction, Assistive Robotics

PUBLICATIONS

Conference

Synthetic data augmentation for robotic mobility aids to support blind and low vision people
H. Hwang, K. Adhikari, S. Shodhaka, and D. Kim

RiTA

Is it safe to cross? Interpretable Risk Assessment with GPT-4V for Safety-Aware Street Crossing
H. Hwang, S. Kwon, Y. Kim, and D. Kim

UR (Finalist)

Towards Robotic Companions: Understanding Handler-Guide Dog Interactions for Informed Guide
Dog Robot Design
H. Hwang, H.T. Jung, N.A. Giudice, J. Biswas, S.I. Lee*, and D. Kim*

CHI (Best Paper Award)

System Configuration and Navigation of a Guide Dog Robot: Toward Animal Guide Dog-Level

System Configuration and Navigation of a Guide Dog Robot: Toward Animal Guide Dog-Level Guiding Work

H. Hwang[†], T. Xia[†], I. Keita, K. Suzuki, J. Biswas, S.I. Lee*, and D. Kim*

ICRA

Control Scheme and Uncertainty Considerations for Dynamic Balancing of Passive-Ankled Bipeds and Full Humanoids

D. Kim, S.J. Jorgensen, H. Hwang, and L. Sentis

Humanoids

Computationally-Robust and Efficient Prioritized Whole-Body Controller with Contact Constraints D. Kim, J. Lee, O. Campbell, <u>H. Hwang</u>, and L. Sentis **IROS**

Journal

ElderSim: A Synthetic Data Generation Platform for Human Action Recognition in Eldercare Applications
H. Hwang, C. Jang, G. Park, J. Cho, and I.J. Kim

IEEE Access.

Highly Sensitive Capacitive Pressure Sensors over a Wide Pressure Range Enabled by the Hybrid Responses of a Highly Porous Nanocomposite K.H. Ha, W. Zhang, H. Jang, S. Kang, L. Wang, P. Tan, H. Hwang, and N. Lu Advanced Materials.

Workshop

Lessons Learned from Developing a Human-Centered Guide Dog Robot for Mobility Assistance H. Hwang, K. Suzuki, N.A. Giudice, J. Biswas, S.I. Lee, and D. Kim

ASSETS UrbanAccess.

Dynamic Object Avoidance using Event-Data for a Quadruped Robot S. Zhu, N. Perara, S. Yu, H. Hwang, and D. Kim

IROS IPPC.

Patent

Human behavior recognition system and method using hierarchical class learning considering safety J. Cho, I. J. Kim, and H. Hwang

U.S. Patent

RESEARCH EXPERIENCE

2021- Graduate Research Assistant, DARoS Lab @ UMass Amherst

User-centered guide dog robot development for blind and low-vision individuals: Foundation model-based perception and planning in legged systems for safe and efficient navigation.

2019-2020 Research Intern, Center for AI @ Korea Institute of Science and Technology

Real-time human action recognition system development and synthetic data augmentation evaluation.

2017–2018 Undergraduate researcher, Human Centered Robotics Lab @ UT Austin

Testing and optimizing the 6 DOF passive-ankled biped robot, Mercury, for walking.

2018 Undergraduate Researcher, Lu Research Group @ UT Austin

Manufacturing and testing flexible resistive force sensors for lower-limb prosthetic stress distribution.

AWARDS & SCHOLARSHIP

Awards & Honors

2024	Best Paper Finalist - International Conference on Ubiquitous Robots 2024
2024	Best Paper Award - ACM SIGCHI Conference on Human Factors in Computing Systems 2024
2023	Vision Assistance Race 2nd place - CYBATHLON Challenges 2023
2017	Creative Technology and Excellence Award - STEAM CUP

Scholarship & Fellowships

2024 Robert and Deanna Hagerty Robotics Scholarship
2021 UMass Amherst CICS Jumpstart Fellowship

2016-2017 {Hanyang University, Haksan Foundation} Academic Achievement Scholarship

Media

IEEE Spectrum Video Friday (2024), UMass Amherst (2024), Westside News (2022)

TEACHING EXPERIENCE

Teaching Assistant @ UMass Amherst

Fall 2024 Reasoning Under Uncertainty (COMPSCI 240) – teach discussion sessions

Spring 2023 Robotics (COMPSCI 603) – mobile robot platform setup

Fall 2022 Introduction to Robotics - Mechanics, Dynamics, and Control (COMPSCI 403) – interactive quiz

Student Mentor @ UMass Amherst

Early Research Scholars Program - Shiven Patel, Antoinette Reid, Ron Kleinhause-Goldman, Dang Nguyen

Honors thesis - Krisha Adhikari (synthetic data), Matthew Hersey (deep learning)

Research & independent study – Shiven Patel (audio tracking - ACM TAPIA Competition'24 1st Place), Tim Xia (path planning), Ken Suzuki (CAD), Millan Taranto (CAD)

ACADEMIC SERVICE

Reviewer - RiTA'24, ACI'24, Humanoids'24, RA-L'24, CHI'24, IROS'23, ICRA'22

Robot demonstration – Research for Inherited Retinal Diseases @ Foundation Fighting Blindness X UMass (10.19.24), Summer school @ The Carroll Center for the Blind (7.30.24), Research @ Fidelco Guide Dog Foundation Inc. (5.5.22)

UMass Korean Graduate Student Association (KGSA) President 2022-2023

TECHNICAL & RESEARCH SKILLS

Programming & software: Python, C++, MATLAB, PyTorch, TensorFlow, ROS, Unreal Engine, Docker, Git Mechatronics: SOLIDWORKS (Certified SolidWorks Associate), CATIA, Onshape