ĐẠI HỌC QUỐC GIA THÀNH PHỐ HỒ CHÍ MINH TRƯỜNG ĐẠI HỌC BÁCH KHOA KHOA CƠ KHÍ BỘ MÔN CƠ ĐIỆN TỬ



TRANG BỊ ĐIỆN - ĐIỆN TỬ TRONG MÁY CÔNG NGHIỆP

EXERCISE 4

GVHD: TS. LÊ ĐỨC HẠNH

DANH SÁCH THÀNH VIÊN:

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Mục lục

1	\mathbf{Des}	sign a control circuit for described operation below:		2
	1.1	.1 Push button start		2
		1.1.1	Motor 1 (AC1phase), Motor2(3phase) run in star mode, after 5s	
			motor 1 change direction, motor 2 change from star to delta, motor	
			3 start running	2
		1.1.2	Motor 3 (3phase) runs from left to right then meets a limit switch	
			then return to right then loop again, while in 5s later motor1 stops	
			and motor2 stop (kinematic)	4
	1.2	Circuit	have emergency stop button.	6
		1.2.1	Before the emergency stop button is pressed	6
		1.2.2	After the emergency stop button is pressed	7

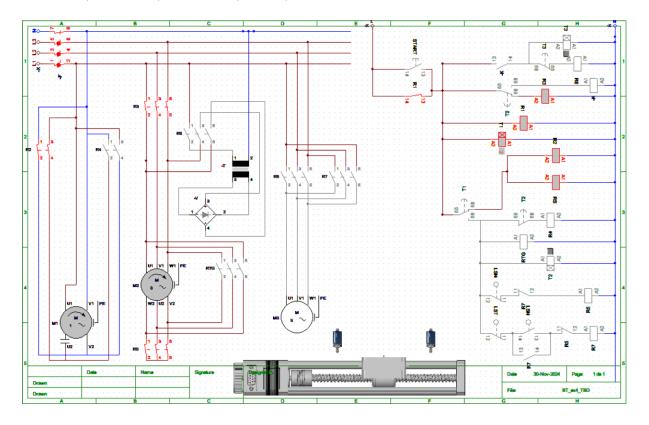


1 Design a control circuit for described operation below:

1.1 Push button start.

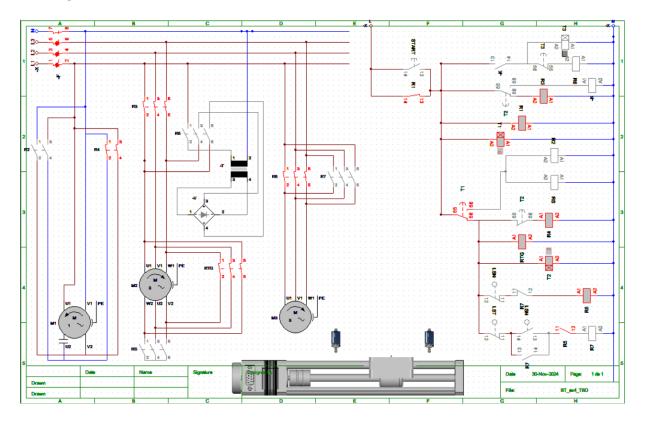
1.1.1 Motor 1 (AC1phase), Motor2(3phase) run in star mode, after 5s motor 1 change direction, motor 2 change from star to delta, motor 3 start running.

Motor 1 (AC1phase), Motor 2 (3phase) run in star mode:





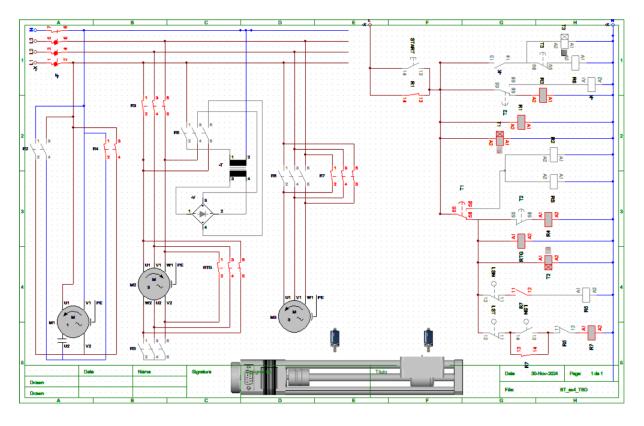
After 5s motor 1 change direction, motor 2 change from star to delta, motor 3 start running:





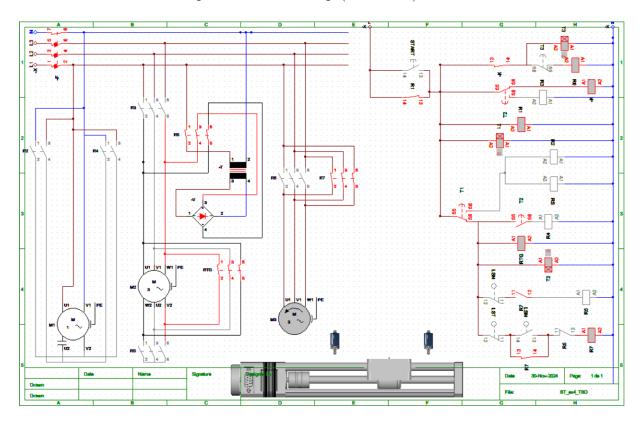
1.1.2 Motor 3 (3phase) runs from left to right then meets a limit switch then return to right then loop again, while in 5s later motor1 stops and motor2 stop (kinematic).

Motor 3 (3phase) runs from left to right then meets a limit switch then return to right then loop again:





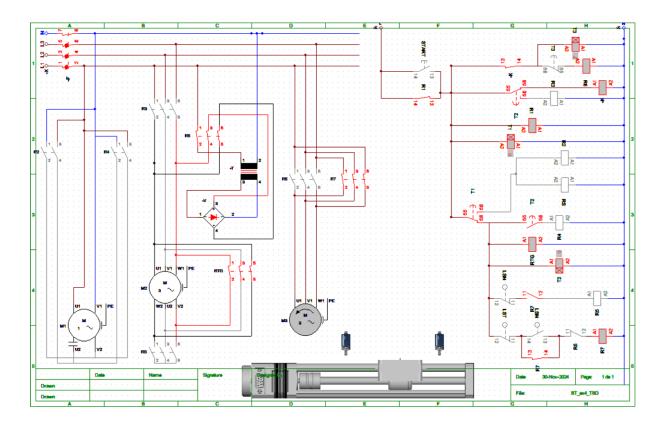
In 5s later motor 1 stops and motor 2 stop (kinematic):





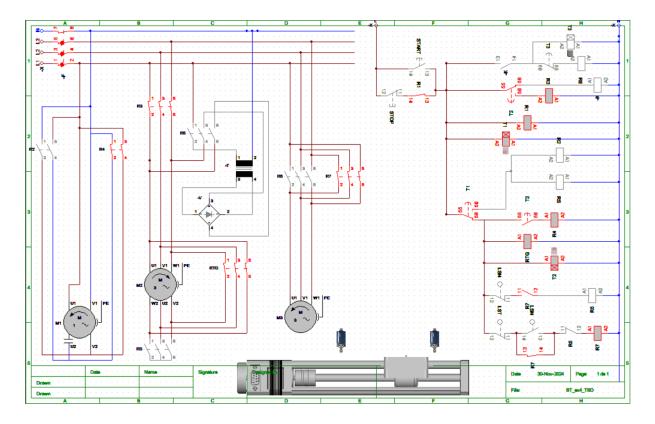
1.2 Circuit have emergency stop button.

1.2.1 Before the emergency stop button is pressed





1.2.2 After the emergency stop button is pressed



 \Rightarrow After the emergency stop button is pressed, all motors stop immediately and will not reactivate until the start button is pressed.