Machine Learning Cheat Sheet

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Distributions

Expectation: $\mathbb{E}[x] = \int xp(x)dx$
Mean: $\mathbb{E}[\mathbf{x}]$
Variance: $\sigma^2 = \mathbb{E}[(x-\mu)^2]$
$\text{Cov}(\mathbf{x}) = \mathbb{E}[(\mathbf{x}-\mu)(\mathbf{x}-\mu)^T]$
Normal: $p(x) = \frac{1}{\sqrt{2\pi\sigma^2}}\exp(-\frac{(x-\mu)^2}{2\sigma^2})$
Binomial: $p(x) = \binom{n}{k}p^k(1-p)^{n-k}$
Multinomial: $p(x) = \frac{n!}{x_1!\cdots x_k!}p_1^{x_1}\cdots p_k^{x_k}$
Poisson: $p(x) = \frac{\lambda^k e^{-\lambda}}{k!}$
Multivariate Normal:
$p(x) = \det(2\pi\Sigma)^{-\frac{1}{2}}\exp(-\frac{1}{2}(\mathbf{x}-\mu)^T\Sigma^{-1}(\mathbf{x}-\mu))$

Common Functions

$\varsigma(x) = \frac{1}{1+\exp(-x)}$ (Posterior class probability)
$\varsigma' = \varsigma(1-\varsigma)$
Likelihood: $L(\theta|\mathcal{X}) = p(\mathcal{X}|\theta))$
Cross-entropy: $E(\theta|\mathcal{X}) = -\log L(\theta|\mathcal{X})$
$\sigma_i = \sigma(x_i) = \frac{\exp(x_i)}{\sum_j \exp(x_j)}$ (Posterior class probability)
$\frac{\partial\sigma_i}{x_i} = \sigma_i(1-\sigma_i)$
$\frac{\partial\sigma_i}{x_j} = -\sigma_i\sigma_j, i \neq j$
Lagrangian: $\mathcal{L} = a - \sum_l \alpha_l b_l, \alpha_l \geq 0 \quad \forall l$
for minimize a subject to $b_l \geq 0 \quad \forall l$
Kernel: $K(a,b) = \phi(a)^T\phi(b)$
Polynomial kernel: $(a^Tb+1)^q$
RBF kernel: $exp(-\frac{||a-b||^2}{2s^2})$ OR
$exp(-\frac{\mathcal{D}(a,b)}{2s^2})$ for some distance function $\mathcal{D}$ Sigmoidal kernel: $\tanh(2a^Tb+1)$
Leaky ReLU: $f(x) = \begin{cases} x \text{ if } x \geq 0 \\ \alpha \text{ else} \end{cases}$
Exponantial linear: $f(x) = \begin{cases} x \text{ if } x \geq 0 \\ \alpha(e^x - 1) \text{ else} \end{cases}$

Expectation Maximization

Expectation: $\mathcal{Q}(\Phi|\Phi^t) = \mathbb{E}[\mathcal{L}_C(\Phi|\mathcal{X},\mathcal{Z})|\mathcal{X},\Phi^t]$
Maximization: $\Phi^{t+1} = \arg\max_\Phi \mathcal{Q}(\Phi|\Phi^t)$

Deep-learning Concepts

Xavier Initialization: (for sigmoid activation)
- Zero-mean normal with variance: $\frac{2}{n_{\text{in}}+n_{\text{out}}}$
- Uniform in $[-r,r]$ where $r = \sqrt{\frac{6}{n_{\text{in}}+n_{\text{out}}}}$

He Initialization: (for ReLUs activation)
- Zero-mean normal with variance: $\frac{4}{n_{\text{in}}+n_{\text{out}}}$
- Uniform in $[-r,r]$ where $r = \sqrt{\frac{12}{n_{\text{in}}+n_{\text{out}}}}$

Batch normalization: zero-center and normalize every layer.
Dropout: probabilistically set some hidden unit to 0.
Data augmentation: Translate, scale, shift, light/dim, flip to generate new data.
AdaGrad:

$$s \leftarrow s + \bigtriangledown_w L \circ \bigtriangledown_w L$$
$$w \leftarrow w - \eta \bigtriangledown_w L \oslash \sqrt{s+\epsilon}$$

RMSProp:

$$s \leftarrow \beta s + (1-\beta)\bigtriangledown_w L \circ \bigtriangledown_w L$$
$$w \leftarrow w - \eta \bigtriangledown_w L \oslash \sqrt{s+\epsilon}$$

Adam:

$$\Delta w \leftarrow \frac{\beta_1\Delta w - (1-\beta_1)\bigtriangledown_w L}{1-\beta_1^t}$$
$$s \leftarrow \frac{\beta_2 s + (1-\beta_2)\bigtriangledown_w L \circ \bigtriangledown_w L}{1-\beta_2^t}$$
$$w \leftarrow w - \eta\Delta w \oslash \sqrt{s+\epsilon}$$

Derivative Rules

c	0	e^x	e^x
x	1	a^x	$\ln(a)a^x$
cx	c	$\ln(x)$	$\frac{1}{x}$
x^n	nx^{n-1}	fg	$f'g \cdot fg'$

Integration Rules

$\int uvdx = u\int vdx + \int u'(\int vdx)dx$
$\int f(g(x))g'(x)dx = \int f(u)du$

Nonparametric Methods

Histogram Estimator:
$\hat{p}(x) = \frac{\#\{x^{(l)} \text{ in the same bin as } x\}}{Nh}$
Naive Estimator: $\hat{p}(x) = \frac{\sum_l w(\frac{x-x^{(l)}}{h})}{Nh}$
where $w(u) = \begin{cases} 1 \text{ if } |u| < 1/2 \\ 0 \text{ else} \end{cases}$
Kernel Estimator: $\hat{p}(x) = \frac{\sum_l K(\frac{x-x^{(l)}}{h})}{Nh}$
K-nearest neighbour: $\hat{p}(x) = \frac{k}{2Nd_k(x)}$
where $d_k(x)$ is the distance of x and k-th nearest neighbour of x
KNN-kernel: $\hat{p}(x) = \frac{\sum_l K(\frac{x-x^{(l)}}{d_k(x)})}{Nd_k(x)}$
Regressogram: Mean of the same bin
Running-mean smoother: Mean of the bin around x
Kernel smoother: $\hat{g}(x) = \frac{\sum_l K(\frac{x-x^{(l)}}{h})y^{(l)}}{\sum_l K(\frac{x-x^{(l)}}{h})}$
Running line smoother: With piecewise linear fit

Dimensionality Reduction

Feature selection: Choose k from d features
Forward search v.s. Backward search
Feature extraction: Project $\mathbf{x}$ to $\mathcal{R}^k$
Principal Component Analysis:
Map $\mathbf{x}$ to k orthogonal dimensions
$\mathbf{z}_n = \mathbf{w}_n^T\mathbf{x}, \text{Var}(\mathbf{z}_1) = \mathbf{w}_1^T\mathbf{\Sigma}\mathbf{w}_1, \mathbf{\Sigma} = \text{Cov}(x)$
Maximize $\text{Var}(\mathbf{z}_1)$ s.t. $||\mathbf{w}_1|| = 1$ is eigenvalue of $\mathbf{\Sigma}$
Factor Analysis: Sample $\mathcal{X}$, $\mathbb{E}[\mathbf{x}] = \mu$, $\text{Cov}(\mathbf{x}) = \mathbf{\Sigma}$
Factors z_j, $\mathbb{E}[z_j] = 0$, $\text{Var}(z_j) = 1$, $\text{Cov}(\mathbf{z}) = \mathbf{I}$
Noise ϵ_i, $\mathbb{E}[\epsilon_i] = 0$, $\text{Var}(\epsilon_i) = \Psi_i$, $\text{Cov}(\epsilon) = \mathbf{\Psi I}$
$\mathbf{x} - \mu = \mathbf{V}\mathbf{z} + \epsilon$, $\mathbf{\Sigma} = \mathbf{V}\mathbf{V}^T + \mathbf{\Psi}$
Multidimensional Scaling:
$\mathbf{B} = \mathbf{X}\mathbf{X}^T = \mathbf{C}\mathbf{D}\mathbf{C}^T = (\mathbf{C}\mathbf{D}^{1/2})(\mathbf{C}\mathbf{D}^{1/2})^T$
where $\mathbf{C}$ is eigenvectors as columns and
$\mathbf{D}^{1/2}$ is diagonal matrix of square root of eigenvalues
Drop eigenvectors with low eigenvalues in $\mathbf{C}$ and $\mathbf{D}$
Linear Discriminant Analysis:
Between-class scatter: $\mathbf{w}^T\mathbf{S}_B\mathbf{w}$,
$\mathbf{S}_b = (\mathbf{m}_1-\mathbf{m}_2)(\mathbf{m}_1-\mathbf{m}_2)^T, \sum_i N_i(\mathbf{m}_i-\mathbf{m})(\mathbf{m}i-\mathbf{m})^T$
Within-class scatter: $\mathbf{w}^T\mathbf{S}_W\mathbf{w}$,
$\mathbf{S}_W = \sum_i \mathbf{S}_i, \mathbf{S}_i = \sum_l y_i^{(l)}(x^{(l)}-\mathbf{m}_i)(x^{(l)}-\mathbf{m}_i)^T$

Ensemble Learning

No-free-lunch theory: No single model is the best
Combine several simple models into group
Voting: Convex combination of base learners
$y = f(d_1, \cdots, d_L|\mathbf{\Phi}) = \sum_{j=1}^{L} w_j d_j$
Other voting rules: Weighted sum, median, min, max, product
Mixture of experts, Gating: $y = \sum_{j=1}^{L} w_j(x) d_j$
Bayesian model combination:
$P(C_i|x) = \sum_{\mathcal{M}_j} P(C_i|x, \mathcal{M}_j) P(\mathcal{M}_j)$,
w_j estimates prior model probability $P(\mathcal{M}_j)$
Bagging, Bootstrap aggregating: Base learners trained on slightly different training sets.
Draw N from $\mathcal{X}$ with replacement
Boosting: Combine weak learner into strong learner
AdaBoost: Make wrongly-labeled data have higher weight in next learner's training set