The Ising Model

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Abstract. TODO

Preface

Although the coursework was initially presented as a C++ project, I took the liberty of rewriting the Ising Model system in a programming language called Google Go (https://golang.org). The motivation for this is Go has been designed to accommodate systems with high concurrency. This means that instead of simulating 1 system at a time, 10,000 different systems can be simulated simultaneously in different threads. This greatly increases time efficiency and has allowed me to achieve a significant level of statistical significance in my ensemble averages. Furthermore, this has also allowed me to use ergodicity to calculate time averages for the same system with many different values of beta at the same time. The source code for my implementation is accessible on Github: http://tiny.cc/brb75y.

1. Introduction and Computational Method

Ferromagnetism is the property of a material to exhibit speontaneous magnetisation in the absence of an external magnetic field. The Ising Model is a mathematical model that uses the results of thermodynamics and statistical mechanics to describe how magnetic structure in some metals leads to ferromagnetism.

In the Ising Model presented in this paper, a magnetic material is modelled by a regular L x L dimensional square lattice Π . A given grid point on this lattice $\pi_{(i,j)} \in \Pi$ is indexed by cartesian coordinates (i,j) where $i,j \in [0,L]$. These coordinates are not strictly unique as periodic boundary conditions are applied so that a closed system is modelled. This is to say the grid follows the mappings $(i+\Lambda_i D,j+\Lambda_j D) \to (i,j)$ for $\Lambda_i,\Lambda_j \in \mathbb{Z}$. Each grid point $\pi_{(i,j)} \in \Pi$ on this square lattice is assigned a discrete variable $s_{(i,j)} \in \{0,1\}$ that corresponds to the spin of the grid point. The system is therefore composed of $N \equiv L^2$ spins. We arbitrarily define $s_{(i,j)} = 1$ to represent 'spin up' and $s_{(i,j)} = -1$ to represent 'spin down'.

For a given grid point $\pi_{(i,j)}$, the convention of nearest neighbours is defined as representing the grid points directly adjacent to the grid point, both vertically and horizontally. Using this convention, the energy of a given spin on the grid is defined by

$$E_{(i,j)} = -h_{(i,j)}s_{(i,j)} \tag{1}$$

where

$$h_{(i,j)} = \sum_{(\alpha,\beta) \text{ n.n. of } (i,j)} \left[Js_{(\alpha,\beta)} \right]$$
(2)

Here "n.n" represents a sum over the nearest neighbours and J is a positive real number that indicates the strength of the interactions between spins. Qualitatively this set of equations defines the energy of a given spin as the sum of the interaction energies between the spin and it's nearest neighbours,

where the interaction energy between two nearest neighbour spins is defined to be -J if the two spins are aligned and -J if the two spins are antiparallel.

From this definition of the energy for a single spin in the system, the total energy for the system is defined as

$$E = \frac{1}{2} \sum_{i,j} E_{(i,j)} \tag{3}$$

where the summation simply runs over every grid point in the square lattice. Furthermore, the magnetisation (per spin) of the system is defined as

$$\mathcal{M} = \frac{1}{N} \sum_{i,j} s_{(i,j)} \tag{4}$$

As the number of spins in the system is fixed, a canonical thermodynamic ensemble is used. If we let a microstate S be defined by the instantaneous configuration of all the spins in the system, then the probability of finding the system in a microstate S in thermal equilibrium at temperature T is given by statistical mechanics as

$$p_{eq}(\mathcal{S}) = \frac{1}{Z(T)} e^{-E(S)/k_B T} \tag{5}$$

where E(S) is the energy of microstate S as given by equation (3). The canonical partition function Z = Z(T) is used to enforce the normalisation condition $\sum_{S} p_{eq}(S) = 1$ which gives the expression for Z as

$$Z(T) = \sum_{S} e^{-E(S)/k_B T} \tag{6}$$

where the summations here run over all 2^N possible microstates S of the system.

In this paper, a Metropolis Monte Carlo method is used to investigate the properties E and \mathcal{M} of two dimensional Ising Model systems for different thermodynamic temperatures T.

2. Method

3. Results

- 3.1. Convergence to Equilibrium
- 3.2. Measuring Equilibrium Averages

4. Discussion

- 4.1. Determining the Fractal Dimension of DLA Aggregates where $p_{stick} = 1$
- 4.2. Suggestions for Improvement

5. Conclusion

References

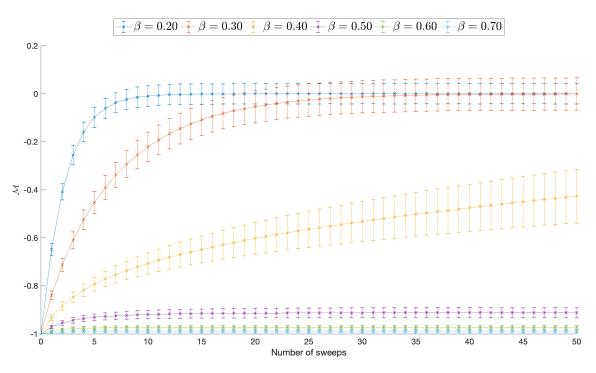


Figure 1: Evolution of system magnetisation per spin as a function of the number of Monte Carlo sweeps completed for a 2D Ising model with all spins initially down. The simulation was ran for a set of systems with different thermodynamic temperatures, as defined by the parameter β . Each data point represents the ensemble average over n=10,000 independent sub-systems, each initialised with different pesudo-random number generator seeds. Error bars represent the standard deviation in the values of \mathcal{M} across the ensemble of systems.

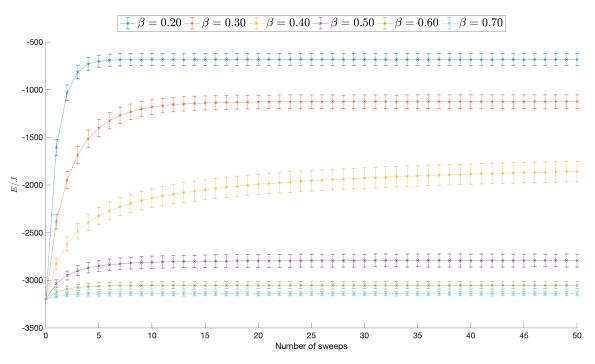


Figure 2: Evolution of dimensionless system energy as a function of the number of Monte Carlo sweeps completed for a 2D Ising model with all spins initially down. The simulation was ran for a set of systems with different thermodynamic temperatures, as defined by the parameter β . Each data point represents the ensemble average over n=10,000 independent sub-systems, each initialised with different pesudo-random number generator seeds. Error bars represent the standard deviation in the values for E/J across the ensemble of systems.