

Unsupervised Learning: Clustering Analysis

Héctor Corrada Bravo

University of Maryland, College Park, USA Fannie Mae: 2017-08-17



So far we have seen "Supervised Methods" where our goal is to analyze a response (or outcome) based on various predictors.

In many cases, especially for Exploratory Data Analysis, we want methods to extract patterns on variables without analyzing a specific response.

Methods for the latter case are called "Unsupervised Methods". Examples are Principal Component Analysis and Clustering.

Interpretation of these methods is much more subjective than in Supervised Learning.

For example: if we want to know if a given predictor is related to response, we can perform statistical inference using hypothesis testing.

If we want to know which predictors are useful for prediction: use cross-validation to do model selection.

Finally, if we want to see how well we can predict a specific response, we can use cross-validation to report on test error.

In unsupervised methods, there is no similar clean evaluation methodology.

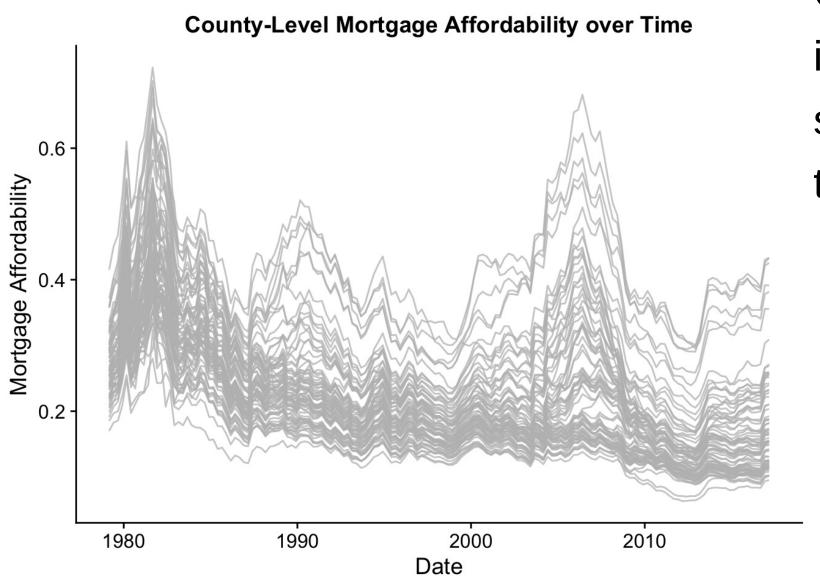
Nonetheless, they can be very useful methods to understand data at hand.

Motivating Example

Time series dataset of mortgage affordability as calculated and distributed by Zillow: https://www.zillow.com/research/data/.

The dataset consists of monthly house values for 76 counties with data from 1979 to 2017.

Motivating Example



Can we partition counties into groups of counties with similar value trends across time?

In "Supervised Learning" we were concerned with estimates that minimize some error function relative to the outcome of interest *y*:

$$\mu(x) = rg \min_{ heta} E_{Y|X} L(Y, heta)$$

In order to do this, explicitly or not, the methods we were using would be concerned with properties of the conditional probability distribution Pr(Y|X),

without concerning itself with probability distribution Pr(X) of the covariates themselves.

In unsupervised learning, we are interested in properties of Pr(X).

In our example, what can we say about the distribution of home value time series?

Since the dimensionality of $P_{r(X)}$ can be large, unsupervised learning methods seek to find structured representations of $P_{r(X)}$ that would be possible to estimate.

In clustering we assume that predictor space is partitioned and that Pr(X) is defined over those partitions.

In dimensionality reduction we assume that Pr(X) is really defined over a space (manifold) of smaller dimension. We will start studying clustering first.

Cluster Analysis

The high-level goal of cluster analysis is to organize objects (observations) that are similar to each other into groups.

We want objects within a group to be more similar to each other than objects in different groups.

Cluster Analysis

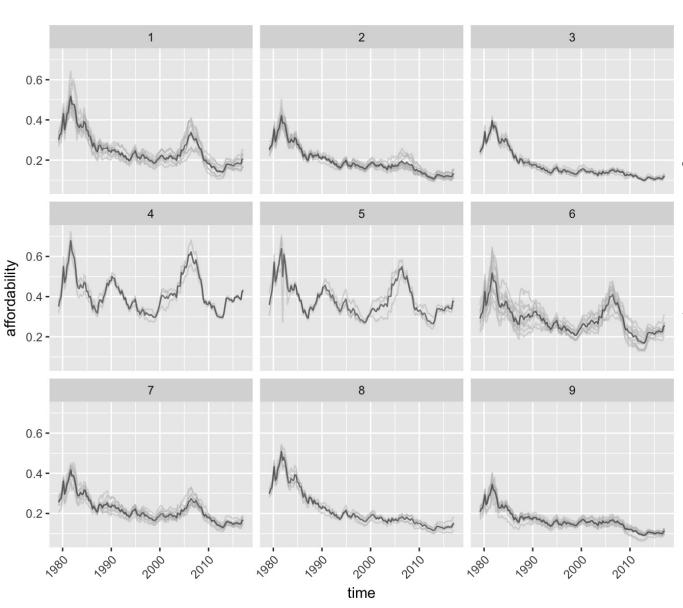
The high-level goal of cluster analysis is to organize objects (observations) that are similar to each other into groups.

We want objects within a group to be more similar to each other than objects in different groups.

Central to this high-level goal is how to measure the degree of similarity between objects.

A clustering method then uses the similarity measure provided to it to group objects into clusters.

Cluster Analysis



Result of the k-means algorithm partitioning the data into 9 clusters.

The darker series within each cluster shows the average time series within the cluster.

For certain algorithms, instead of similarity we work with dissimilarity, often represented as distances.

When we have observations defined over attributes, or predictors, we define dissimilarity based on these attributes.

Given measurements x_{ij} for $i=1,\ldots,N$ observations over $j=1,\ldots,p$ predictors.

Suppose we define a dissimilarity $d_j(x_{ij}, x_{i'j})$, we can then define a dissimilarity between objects as

$$d(x_i, x_{i'}) = \sum_{j=1}^p d_j(x_{ij}, x_{i'j})$$

In the k-means algorithm, and many other algorithms, the most common usage is squared distance

$$d_j(x_{ij},x_{i'j}) = (x_{ij}-x_{i'j})^2$$

We can use different dissimilarities, for example

$$d_j(x_{ij},x_{i^\prime j}) = |x_{ij}-x_{i^\prime j}|$$

which may affect our choice of clustering algorithm later on.

For categorical variables, we could set

$$d_j(x_{ij},x_{i'j}) = \left\{egin{array}{l} 0 ext{ if } x_{ij} = x_{i'j} \ \ 1 ext{ o.w.} \end{array}
ight.$$

If the values the categorical variable have an intrinsic similarity

Generalize using symmetric matrix *L* with elements

 $L_{rr^{\prime}}=L_{r^{\prime}r}$,

 $L_{rr}=0$ and

 $L_{rr'} \geq 0$ otherwise.

This may of course lead to a dissimilarity that is not a proper distance.

A commonly used algorithm to perform clustering is the K-means algorithm.

It is appropriate when using squared Euclidean distance as the measure of object dissimilarity.

$$egin{aligned} d(x_i, x_{i'}) &= \sum_{j=1}^p (x_{ij} - x_{i'j})^2 \ &= \|x_i - x_{i'}\|^2 \end{aligned}$$

K-means partitions observations into K clusters, with K provided as a parameter.

Given some clustering, or partition, C, denote cluster assignment of observation x_i to cluster $k \in \{1, ..., K\}$ is denoted as C(i) = k.

K-means partitions observations into K clusters, with K provided as a parameter.

Given some clustering, or partition, C, denote cluster assignment of observation x_i to cluster $k \in \{1, ..., K\}$ is denoted as C(i) = k.

K-means minimizes this clustering criterion:

$$W(C) = rac{1}{2} \sum_{k=1}^K \sum_{i: \, C(i) = k} \sum_{i': \, C(i') = k} \|x_i - x_{i'}\|^2$$

This is equivalent to minimizing

$$W(C) = rac{1}{2} \sum_{k=1}^K N_k \sum_{i: \, C(i)=k} \|x_i - ar{x}_k\|^2$$

with:

- $ullet ar x_k = (ar x_{k1}, \ldots, ar x_{kp})$
- \bar{x}_{kj} is the average of predictor j over the observations assigned to cluster k,
- N_k is the number of observations assigned to cluster k

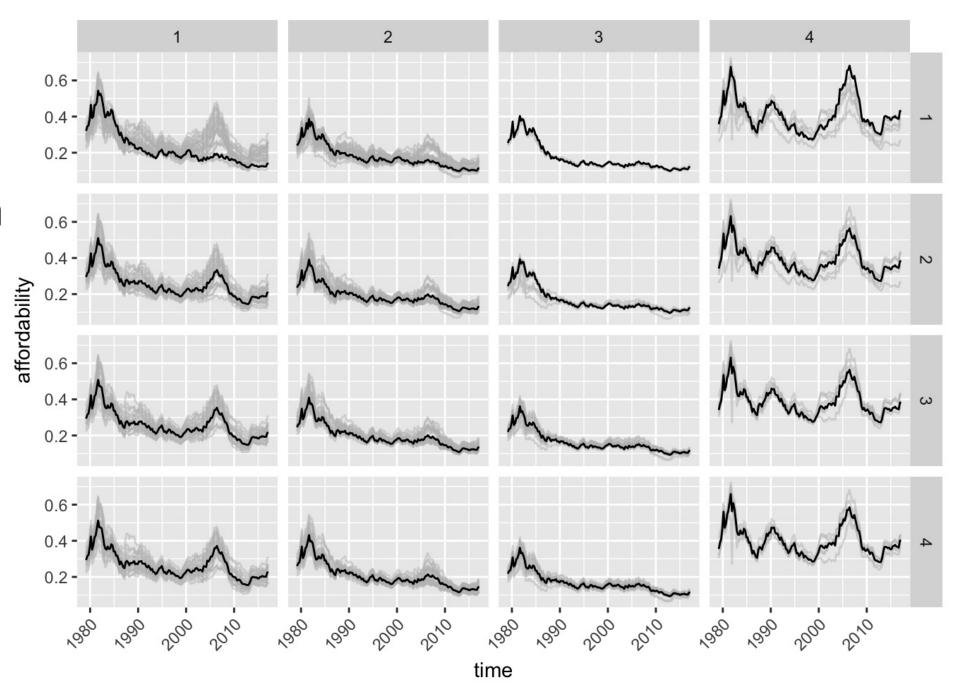
$$W(C) = rac{1}{2} \sum_{k=1}^K N_k \sum_{i:\, C(i)=k} \|x_i - ar{x}_k\|^2$$

Minimize the total distance given by each observation to the mean (centroid) of the cluster to which the observation is assigned.

An iterative algorithm is used to minimize this criterion

- 1. Initialize by choosing K observations as centroids m_1, m_2, \ldots, m_k
- 2. Assign each observation i to the cluster with the nearest centroid, i.e., set $C(i) = \arg\min_{1 \le k \le K} ||x_i m_k||^2$
- 3. Update centroids $m_k = \bar{x}_k$
- 4. Iterate steps 1 and 2 until convergence

Here we illustrate the k-means algorithm over four iterations on our example data with K = 4.



Criterion W(C) is reduced in each iteration so the algorithm is assured to converge.

Not a convex criterion, the clustering we obtain may not be globally optimal.

In practice, the algorithm is run with multiple initializations (step 0) and the best clustering achieved is used.

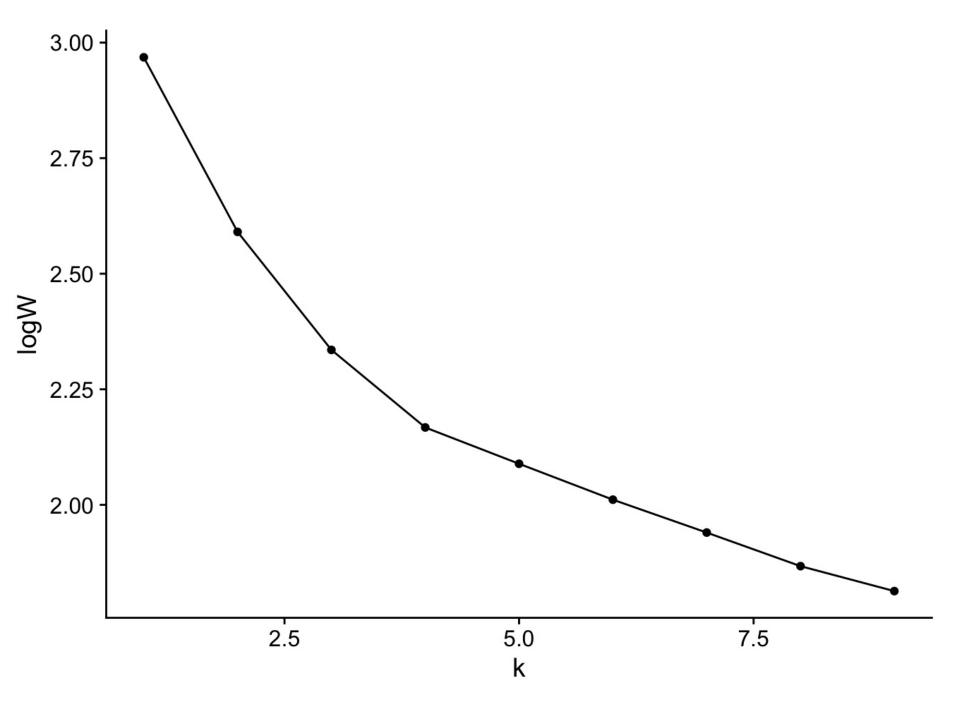
Also, selection of observations as centroids can be improved using the K-means++ algorithm:

- 1. Choose an observation as centroid m_1 uniformly at random
- 2. To choose centroid m_k , compute for each observation i not chosen as a centroid the distance to the nearest centroid $d_i = \min_{1 \le l \le k} ||x_i m_l||^2$
- 3. Set centroid m_k to an observation randomly chosen with probability $\frac{e_i^d}{\sum_{l'}e_{l'}^d}$
- 4. Iterate steps 1 and 2 until K centroids are chosen

The number of parameters must be determined before running the K-means algorithm.

There is no clean direct method for choosing the number of clusters to use in the K-means algorithm (e.g. no cross-validation method)

Looking at criterion W(C) alone is not sufficient as the criterion will become smaller as the value of K is reduced.



We can use properties of this plot for ad-hoc selection.

Suppose there is a true underlying number K^* of clusters in the data,

- improvement in the $W_K(C)$ statistic will be fast for values of $K \leq K^*$
- slower for values of $K > K^*$.

Improvement in the $W_K(C)$ statistic will be fast for values of $K \leq K^*$

In this case, there will be a cluster which will contain observations belonging to two of the true underlying clusters, and therefore will have poor within cluster similarity.

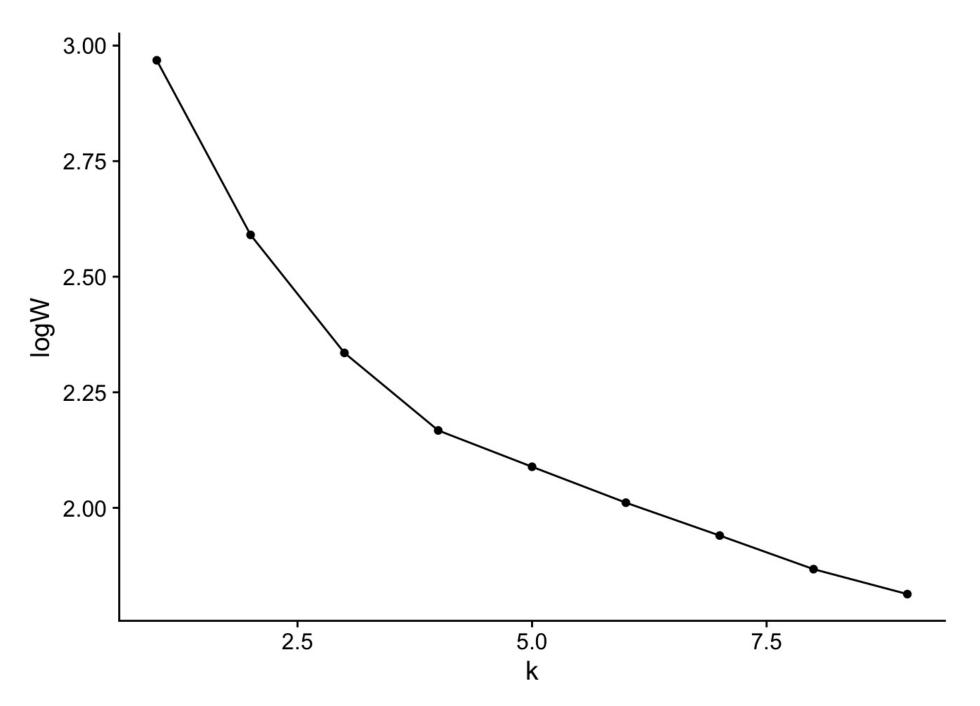
As K is increased, observations may then be separated into separate clusters, providing a sharp improvement in the $W_K(C)$ statistic.

Improvement in the $W_K(C)$ statistic will be slower for values of $K > K^*$

In this case, observations belonging to a single true cluster are split into multiple cluster, all with generally high within-cluster similarity,

Splitting these clusters further will not improve the $W_K(C)$ statistic very sharply.

The curve will therefore have an inflection point around K^* .



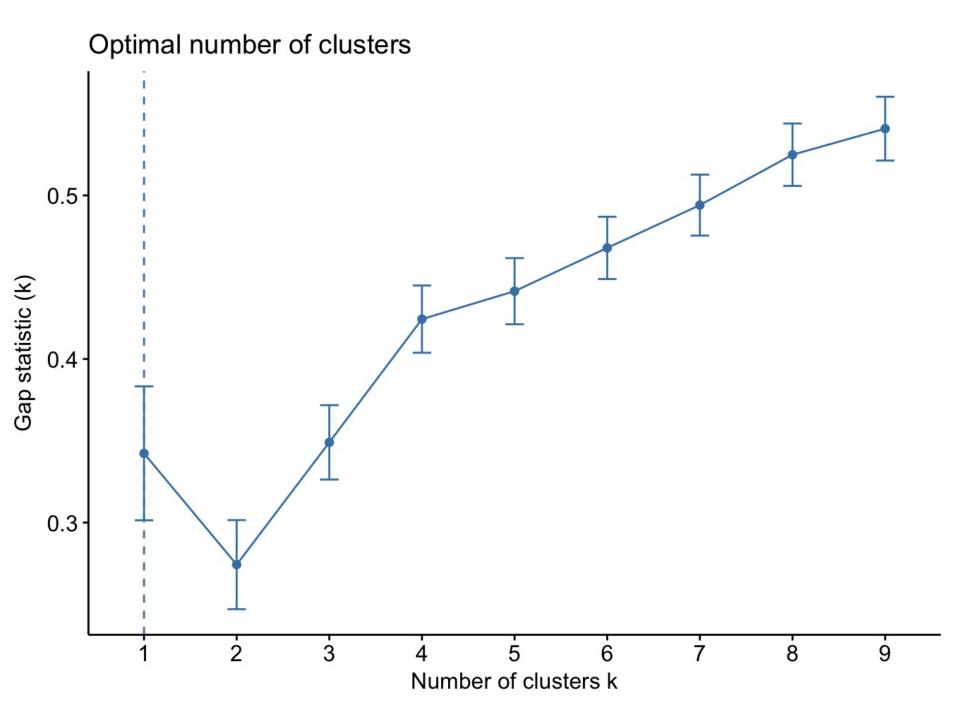
The gap statistic is used to identify the inflection point in the curve.

It compares the behavior of the $W_K(C)$ statistic based on the data with the behavior of the $W_K(C)$ statistic for data generated uniformly at random over the range of the data.

Chooses the K that maximizes the gap between these two $W_K(C)$ curves.

For this dataset, the gap statistic suggests there is no clear cluster structure and therefore K = 1 is the best choice.

A choice of K = 4 is also appropriate.



Instead of the combinatorial approach of the K-means algorithm, take a more direct probabilistic approach to modeling distribution Pr(X).

Assume each of the K clusters corresponds to a multivariate distribution $Pr_k(X)$,

Pr(X) is given by mixture of these distributions as $Pr(X) = \sum_{k=1}^{K} \pi_k Pr_k(X)$.

Specifically, take $Pr_k(X)$ as a multivariate normal distribution $f_k(X) = N(\mu_k, \sigma_k^2 I)$ and mixture density $f(X) = \sum_{k=1}^K \pi_k f_k(X)$.

Use Maximum Likelihood to estimate parameters

$$heta = (\mu_1, \ldots, \mu_K, \sigma_1^2, \ldots, \sigma_K^2, \pi_1, \ldots, \pi_K)$$

based on their log-likelihood

$$\ell(heta;X) = \sum_{i=1}^N \log \Biggl[\sum_{k=1}^K \pi_k f_k(x_i; heta) \Biggr]$$

$$\ell(heta;X) = \sum_{i=1}^N \log \Biggl[\sum_{k=1}^K \pi_k f_k(x_i; heta) \Biggr]$$

Maximizing this likelihood directly is computationally difficult

Use Expectation Maximization algorithm (EM) instead.

Consider unobserved latent variables Δ_{ik} taking values 0 or 1,

 $\Delta_{ij} = 1$ specifies observation x_i was generated by component k of the mixture distribution.

Now set $Pr(\Delta_{ik} = 1) = \pi_k$, and assume we observed values for indicator variables Δ_{ik} .

We can write the log-likelihood of our parameters in this case as

$$\ell_0(heta;X,\Delta) = \sum_{i=1}^N \sum_{k=1}^K \Delta_{ik} \log f_k(x_i; heta) + \sum_{i=1}^N \sum_{k=1}^K \Delta_{ik} \log \pi_k$$

Maximum likelihood estimates:

$$\hat{\mu}_k = rac{\sum_{i=1}^N \Delta_{ik} x_i}{\sum_{i=1}^N \Delta_{ik}}$$

$$\hat{\sigma}_k^2 = rac{\sum_{i=1}^N \Delta_{ik} (x_i - \hat{\mu}_k)^2}{\sum_{i=1}^N \Delta_{ik}}$$

$$\hat{\pi}_k = rac{\sum_{i=1}^K}{N}$$
 .

Of course, this result depends on observing values for Δ_{ik} which we don't observe. Use an iterative approach as well:

- given current estimate of parameters θ ,
- maximize

$$E(\ell_0(\theta'; X, \Delta)|X, \theta)$$

Of course, this result depends on observing values for Δ_{ik} which we don't observe. Use an iterative approach as well:

- given current estimate of parameters θ ,
- maximize

$$E(\ell_0(\theta'; X, \Delta)|X, \theta)$$

We can prove that maximizing this quantity also maximizes the likelihood we need $\ell(\theta; X)$.

In the mixture case, what is the function we would maximize?

Define

$$\gamma_{ik}(\theta) = E(\Delta_{ik}|X_i, \theta) = Pr(\Delta_{ik} = 1|X_i, \theta)$$

Use Bayes' Rule to write this in terms of the multivariate normal densities with respect to current estimates θ :

$$egin{aligned} \gamma_{ik} &= rac{Pr(X_i|\Delta_{ik}=1)Pr(\Delta_{ik}=1)}{Pr(X_i)} \ &= rac{f_k(x_i;\mu_k,\sigma_k^2)\pi_k}{\sum_{l=1}^K f_l(x_i;\mu_l,\sigma_l^2)\pi_l} \end{aligned}$$

Quantity $\gamma_{ik}(\theta)$ is referred to as the responsibility of cluster k for observation i, according to current parameter estimate θ .

Then the expectation we are maximizing is given by

$$E(\ell_0(heta';X,\Delta)|X, heta) = \sum_{i=1}^N \sum_{k=1}^K \gamma_{ik}(heta) \log f_k(x_i; heta') + \sum_{i=1}^N \sum_{k=1}^K \gamma_{ik}(heta) \log \pi_k'$$

We can now give a complete specification of the EM algorithm for mixture model clustering.

- 1. Take initial guesses for parameters θ
- 2. Expectation Step: Compute responsibilities $\gamma_{ik}(\theta)$
- 3. Maximization Step: Estimate new parameters based on responsibilities as below.
- 4. Iterate steps 1 and 2 until convergence

Soft K-means Algorithm

Estimates in the Maximization step are given by

$$\hat{\mu}_k = rac{\sum_{i=1}^N \gamma_{ik}(heta) x_i}{\sum_{i=1}^N \gamma_{ik}}$$

$$\hat{\sigma}_k^2 = rac{\sum i = 1^N \gamma_{ik}(heta)(x_i - \mu_k)}{\sum_{i=1}^N \gamma_{ik}(heta)}$$

and

$$\hat{\pi}_k = rac{\sum_{i=1}^N \gamma_{ik}(heta)}{N}$$

Soft K-means Algorithm

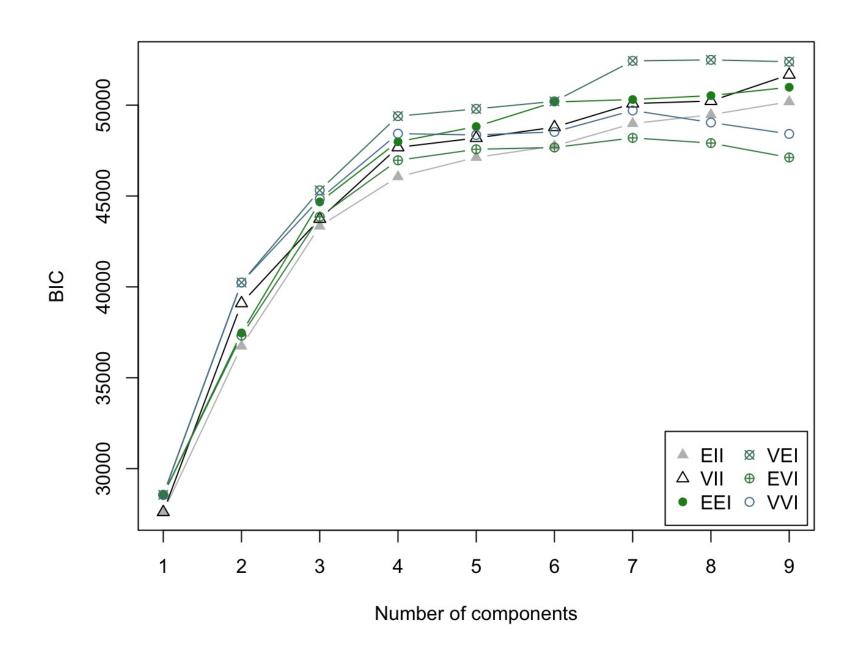
The name "soft" K-means refers to the fact that parameter estimates for each cluster are obtained by weighted averages across all observations.

Clustering by mixtures can be generalized in many directions.

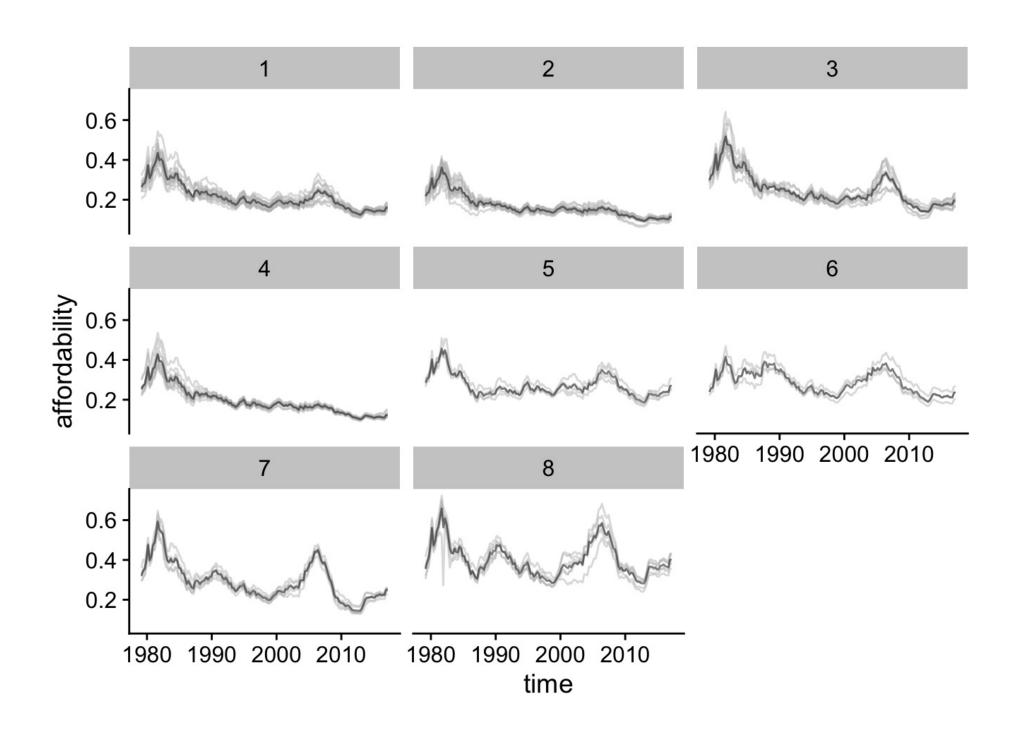
For instance, we can expand the multivariate normal model used in each cluster such that $f_k(X) \approx N(\mu_k, \Sigma_k)$ where Σ_k is covariance matrix.

Since estimates based on likelihood, use criteria applicable to likelihood methods for model selection, e.g., Bayesian Information Criterion (BIC).

This permits selection of the number of mixture components, and covariance parameterization.



For our example data, we obtain a more reasonable result where the optimal number of clusters (K=8) rather than (K=1) obtained with the standard K-means algorithm.



Applying other cluster conditional distributions, the cluster mixture model can also be used for other datatypes where the normal distribution is not appropriate.

There are also kernel-based methods, where a kernel function is used to define a dissimilarity measure, that apply clustering algorithms to situations where non-linearity via kernel methods is applicable.

Summary

Clustering methods are intuitive methods useful to understand structure within unlabeled observations.

Model-based methods, using the EM algorithm, provide a large amount of flexibility over simpler methods like the K-means algorithm.

Kernel-based methods permit the clustering of observations based on non-linear similarity functions.