

# **Data Clustering**

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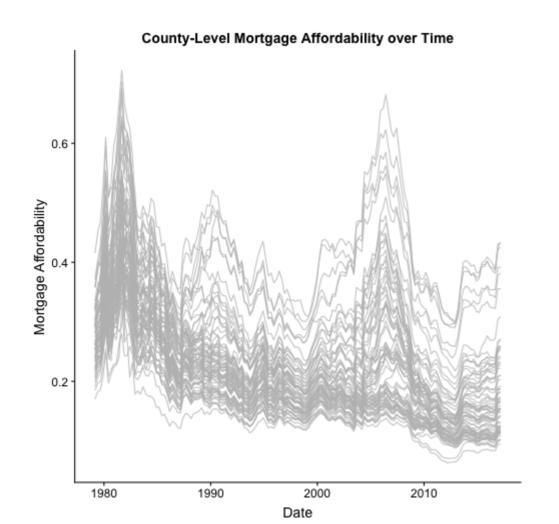


Time series dataset of mortgage affordability as calculated and distributed by Zillow: https://www.zillow.com/research/data/.

The dataset consists of monthly mortgage affordability values for 76 counties with data from 1979 to 2017.

"To calculate mortgage affordability, we first calculate the mortgage payment for the median-valued home in a metropolitan area by using the metro-level Zillow Home Value Index for a given quarter and the 30-year fixed mortgage interest rate during that time period, provided by the Freddie Mac Primary Mortgage Market Survey (based on a 20 percent down payment)."

"Then, we consider what portion of the monthly median household income (U.S. Census) goes toward this monthly mortgage payment. Median household income is available with a lag."



Can we partition counties into groups of counties with similar value trends across time?

## Cluster Analysis

The high-level goal of cluster analysis is to organize objects (observations) that are *similar* to each other into groups.

We want objects within a group to be more *similar* to each other than objects in different groups.

# Cluster Analysis

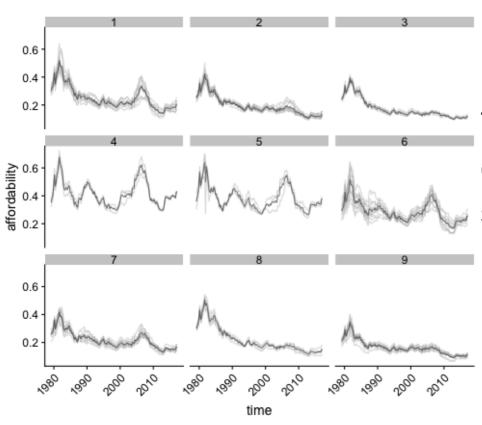
The high-level goal of cluster analysis is to organize objects (observations) that are *similar* to each other into groups.

We want objects within a group to be more *similar* to each other than objects in different groups.

Central to this high-level goal is how to measure the degree of *similarity* between objects.

A clustering method then uses the *similarity* measure provided to it to group objects into clusters.

# Cluster Analysis



Result of the k-means algorithm partitioning the data into 9 clusters.

The darker series within each cluster shows the average time series within the cluster.

For certain algorithms, instead of similarity we work with dissimilarity, often represented as distances.

When we have observations defined over attributes, or predictors, we define dissimilarity based on these attributes.

Given measurements  $x_{ij}$  for i = 1, ..., N observations over j = 1, ..., p predictors.

Suppose we define a dissimilarity  $d_j(x_{ij}, x_{i'j})$ , we can then define a dissimilarity between objects as

$$d(x_i,x_{i'})=\sum_{j=1}^p d_j(x_{ij},x_{i'j})$$

In the k-means algorithm, and many other algorithms, the most common usage is squared distance

$$d_j(x_{ij},x_{i^\prime j})=(x_{ij}-x_{i^\prime j})^2$$

We can use different dissimilarities, for example

$$d_j(x_{ij},x_{i^\prime j})=|x_{ij}-x_{i^\prime j}|$$

which may affect our choice of clustering algorithm later on.

For categorical variables, we could set

$$d_j(x_{ij},x_{i'j}) = \left\{egin{aligned} 0 ext{ if } x_{ij} = x_{i'j} \ & \ 1 ext{ o.w.} \end{aligned}
ight.$$

If the values the categorical variable have an intrinsic similarity

Generalize using symmetric matrix *L* with elements

 $L_{rr^{\prime}}=L_{r^{\prime}r}$  ,

 $L_{rr}=0$  and

 $L_{rr'} \geq 0$  otherwise.

This may of course lead to a dissimilarity that is not a proper distance.

# Limitations of Distance-based clustering

When working with distances, we are quickly confronted with the *curse* of dimensionality.

One flavor: in high dimensions: all points are equi-distant

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Basically, we need to define distance and look for small multidimensional "balls" around the data points. With many covariates this becomes difficult.

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If we have p covariates and we are forming p-dimensional cubes, then each side of the cube must have size l determined by  $l \times l \times \cdots \times l = l^p = .10$ .

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If we keep reducing the size of the neighborhoods we will end up with very small number of data points in each cluster and require a large number of clusters.

A commonly used algorithm to perform clustering is the K-means algorithm.

It is appropriate when using squared Euclidean distance as the measure of object dissimilarity.

$$egin{aligned} d(x_i, x_{i'}) &= \sum_{j=1}^p (x_{ij} - x_{i'j})^2 \ &= \|x_i - x_{i'}\|^2 \end{aligned}$$

K-means partitions observations into K clusters, with K provided as a parameter.

Given some clustering, or partition, C, denote cluster assignment of observation  $x_i$  to cluster  $k \in \{1, ..., K\}$  is denoted as C(i) = k.

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Given some clustering, or partition, C, denote cluster assignment of observation  $x_i$  to cluster  $k \in \{1, ..., K\}$  is denoted as C(i) = k.

K-means minimizes this clustering criterion:

$$W(C) = rac{1}{2} \sum_{k=1}^K \sum_{i: \ C(i)=k} \sum_{i': \ C(i')=k} \|x_i - x_{i'}\|^2$$

This is equivalent to minimizing

$$W(C) = rac{1}{2} \sum_{k=1}^K N_k \sum_{i: \, C(i)=k} \|x_i - ar{x}_k\|^2$$

with:

- $ullet ar x_k = (ar x_{k1}, \dots, ar x_{kp})$
- $\bar{x}_{kj}$  is the average of predictor j over the observations assigned to cluster k,
- $N_k$  is the number of observations assigned to cluster k

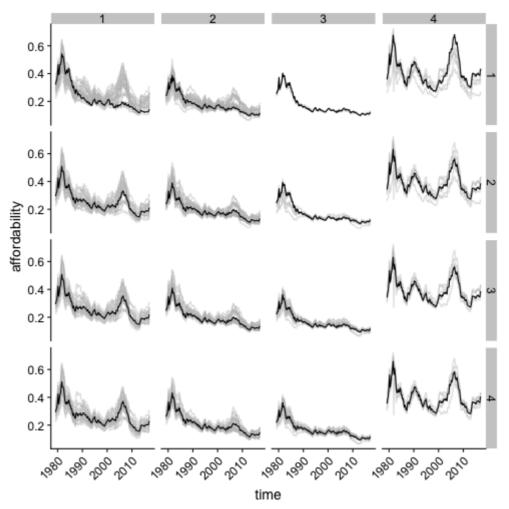
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Minimize the total distance given by each observation to the mean (centroid) of the cluster to which the observation is assigned.

An iterative algorithm is used to minimize this criterion

- 1. Initialize by choosing K observations as centroids  $m_1, m_2, \ldots, m_k$
- 2. Assign each observation i to the cluster with the nearest centroid, i.e., set  $C(i) = \arg\min_{1 \le k \le K} ||x_i m_k||^2$
- 3. Update centroids  $m_k = \bar{x}_k$
- 4. Iterate steps 1 and 2 until convergence

Here we illustrate the k-means algorithm over four iterations on our example data with K = 4.



Criterion W(C) is reduced in each iteration so the algorithm is assured to converge.

Not a convex criterion, the clustering we obtain may not be globally optimal.

In practice, the algorithm is run with multiple initializations (step 0) and the best clustering achieved is used.

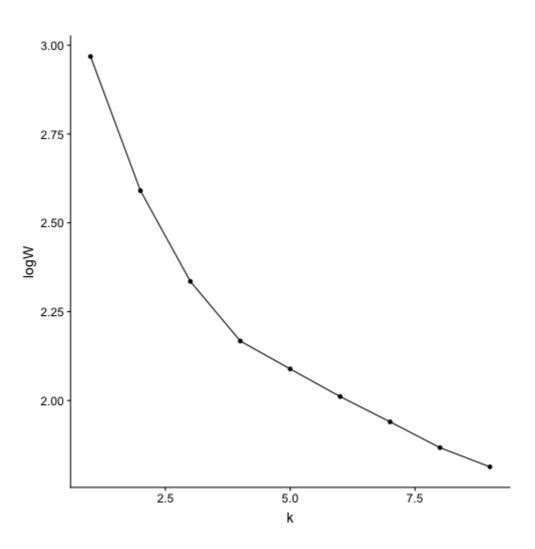
Also, selection of observations as centroids can be improved using the K-means++ algorithm:

- 1. Choose an observation as centroid  $m_1$  uniformly at random
- 2. To choose centroid  $m_k$ , compute for each observation i not chosen as a centroid the distance to the nearest centroid  $d_i = \min_{1 \le l \le k} ||x_i m_l||^2$
- 3. Set centroid  $m_k$  to an observation randomly chosen with probability  $\frac{e^d_i}{\sum_{l'}e^d_{l'}}$
- 4. Iterate steps 1 and 2 until K centroids are chosen

The number of parameters must be determined before running the K-means algorithm.

There is no clean direct method for choosing the number of clusters to use in the K-means algorithm (e.g. no cross-validation method)

Looking at criterion W(C) alone is not sufficient as the criterion will become smaller as the value of K is reduced.



We can use properties of this plot for ad-hoc selection.

Suppose there is a true underlying number  $K^*$  of clusters in the data,

- improvement in the  $W_K(C)$  statistic will be fast for values of  $K \leq K^*$
- slower for values of  $K > K^*$ .

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In this case, there will be a cluster which will contain observations belonging to two of the true underlying clusters, and therefore will have poor within cluster similarity.

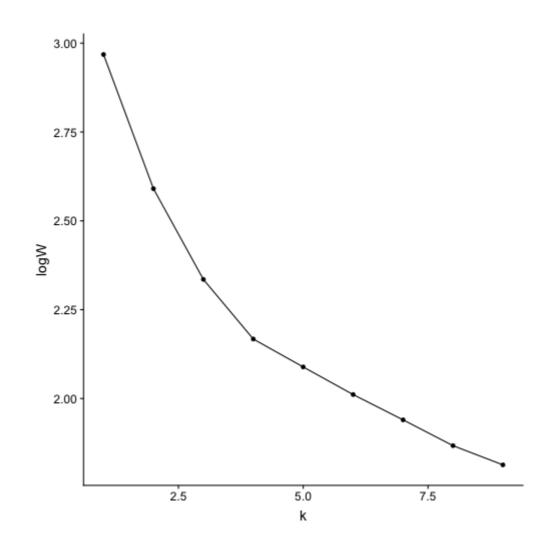
As K is increased, observations may then be separated into separate clusters, providing a sharp improvement in the  $W_K(C)$  statistic.

*Improvement in the*  $W_K(C)$  *statistic will be slower for values of*  $K > K^*$ 

In this case, observations belonging to a single true cluster are split into multiple cluster, all with generally high within-cluster similarity,

Splitting these clusters further will not improve the  $W_K(C)$  statistic very sharply.

The curve will therefore have an inflection point around  $K^*$ .



The *gap statistic* is used to identify the inflection point in the curve.

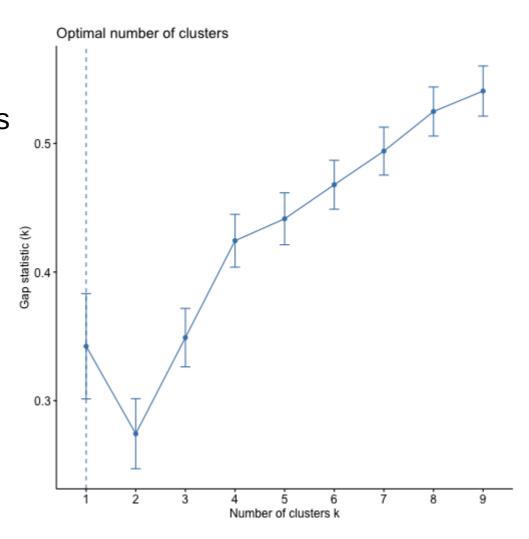
It compares the behavior of the  $W_K(C)$  statistic based on the data with the behavior of the  $W_K(C)$  statistic for data generated uniformly at random over the range of the data.

Chooses the K that maximizes the gap between these two  $W_K(C)$  curves.

# Choosing the number of clusters

For this dataset, the gap statistic suggests there is no clear cluster structure and therefore K = 1 is the best choice.

A choice of K = 4 is also appropriate.



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Can we do this in "almost" a single pass?

- 1. Select *k* points as before
- 2. Process data file in chunks:
  - Set chunk size so each can be processed in main memory
  - Will use memory for workspace so not entire memory available

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 All points sufficiently close to the centroid of one of the k clusters is assigned to that cluster (Discard Set)

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  - Clusters with more than one point (Compressed Set)
  - Singleton clusters (Retained Set)
- Try to merge clusters in *Compressed Set*

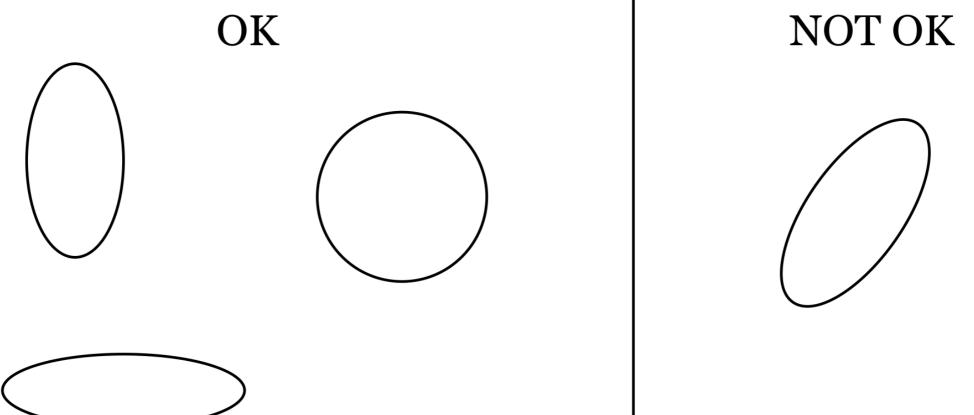
What is sufficiently close?

• "Weighted" distance to centroid below some threshold.

$$\sqrt{\sum_{i=1}^d rac{(p_i-c_i)^2}{\sigma_i}}$$

- c<sub>i</sub>: cluster mean for feature i
- $\sigma_i$ : cluster standard deviation of feature i

Assumption: points are distributed along axis-parallel ellipses



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*Exercise.* show these are sufficient to calculate weighted distance

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Points outside of *Retained Set* are never kept in memory (written out along with cluster assignment)

Merging clusters in Compressed Set

Example: Merge if the variance of combined clusters is sufficiently close to variance of separate clusters

After all data is processed:

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- Merge partial clusters in Compressed Set with final clusters in Discarded Set

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Or,

Flag all of these as *outliers* 

Instead of the combinatorial approach of the K-means algorithm, take a more direct probabilistic approach to modeling distribution Pr(X).

Assume each of the K clusters corresponds to a multivariate distribution  $Pr_k(X)$ ,

Pr(X) is given by *mixture* of these distributions as  $Pr(X) = \sum_{k=1}^{K} \pi_k Pr_k(X)$ .

Specifically, take  $Pr_k(X)$  as a multivariate normal distribution  $f_k(X) = N(\mu_k, \sigma_k^2 I)$  and mixture density  $f(X) = \sum_{k=1}^K \pi_k f_k(X)$ .

Use Maximum Likelihood to estimate parameters

$$heta = (\mu_1, \ldots, \mu_K, \sigma_1^2, \ldots, \sigma_K^2, \pi_1, \ldots, \pi_K)$$

based on their log-likelihood

$$\ell( heta;X) = \sum_{i=1}^N \log \Biggl[\sum_{k=1}^K \pi_k f_k(x_i; heta) \Biggr]$$

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Maximizing this likelihood directly is computationally difficult

Use Expectation Maximization algorithm (EM) instead.

Consider unobserved latent variables  $\Delta_{ik}$  taking values 0 or 1,

 $\Delta_{ij} = 1$  specifies observation  $x_i$  was generated by component k of the mixture distribution.

Now set  $Pr(\Delta_{ik} = 1) = \pi_k$ , and assume we *observed* values for indicator variables  $\Delta_{ik}$ .

We can write the log-likelihood of our parameters in this case as

$$\ell_0( heta;X,\Delta) = \sum_{i=1}^N \sum_{k=1}^K \Delta_{ik} \log f_k(x_i; heta) + \sum_{i=1}^N \sum_{k=1}^K \Delta_{ik} \log \pi_k$$

#### Maximum likelihood estimates:

$$\hat{\mu}_k = rac{\sum_{i=1}^N \Delta_{ik} x_i}{\sum_{i=1}^N \Delta_{ik}}$$

$$\hat{\sigma}_k^2 = rac{\sum_{i=1}^N \Delta_{ik} (x_i - \hat{\mu}_k)^2}{\sum_{i=1}^N \Delta_{ik}}$$

$$\hat{\pi}_k = rac{\sum_{i=1}^K}{N}$$
 .

Of course, this result depends on observing values for  $\Delta_{ik}$  which we don't observe. Use an iterative approach as well:

- given current estimate of parameters  $\theta$ ,
- maximize

$$E(\ell_0( heta';X,\Delta)|X, heta)$$

.

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We can prove that maximizing this quantity also maximizes the likelihood we need  $\ell(\theta; X)$ .

In the mixture case, what is the function we would maximize?

Define

$$\gamma_{ik}( heta) = E(\Delta_{ik}|X_i, heta) = Pr(\Delta_{ik} = 1|X_i, heta)$$

Use Bayes' Rule to write this in terms of the multivariate normal densities with respect to current estimates  $\theta$ :

$$egin{aligned} \gamma_{ik} &= rac{Pr(X_i|\Delta_{ik}=1)Pr(\Delta_{ik}=1)}{Pr(X_i)} \ &= rac{f_k(x_i;\mu_k,\sigma_k^2)\pi_k}{\sum_{l=1}^K f_l(x_i;\mu_l,\sigma_l^2)\pi_l} \end{aligned}$$

Quantity  $\gamma_{ik}(\theta)$  is referred to as the *responsibility* of cluster k for observation i, according to current parameter estimate  $\theta$ .

Then the expectation we are maximizing is given by

$$E(\ell_0( heta';X,\Delta)|X, heta) = \sum_{i=1}^N \sum_{k=1}^K \gamma_{ik}( heta) \log f_k(x_i; heta') + \sum_{i=1}^N \sum_{k=1}^K \gamma_{ik}( heta) \log \pi_k'$$

We can now give a complete specification of the EM algorithm for mixture model clustering.

- 1. Take initial guesses for parameters  $\theta$
- 2. *Expectation Step*: Compute responsibilities  $\gamma_{ik}(\theta)$
- 3. *Maximization Step*: Estimate new parameters based on responsibilities as below.
- 4. Iterate steps 1 and 2 until convergence

# Soft K-means Algorithm

Estimates in the Maximization step are given by

$$\hat{\mu}_k = rac{\sum_{i=1}^N \gamma_{ik}( heta) x_i}{\sum_{i=1}^N \gamma_{ik}}$$

$$\hat{\sigma}_k^2 = rac{\sum i = 1^N \gamma_{ik}( heta)(x_i - \mu_k)}{\sum_{i=1}^N \gamma_{ik}( heta)}$$

and

$$\hat{\pi}_k = rac{\sum_{i=1}^N \gamma_{ik}( heta)}{N}$$

# Soft K-means Algorithm

The name "soft" K-means refers to the fact that parameter estimates for each cluster are obtained by weighted averages across all observations.

This is an instance of the *Expectation-Maximization Algorithm* which we will see again later this semester.