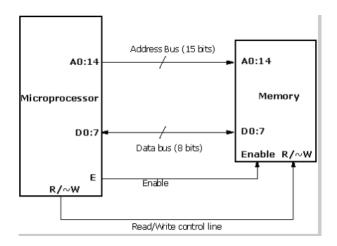
C Programming and Assembly

August 27, 2022

Basic overview of μP 1

The main purpose of μP is to execute a program store in a memory.



Address Bus: logically address 2^N addresses where N is the no. of address bits. Control Signal: RD(Read), WR(Write)

1.1 Logical Memory Map

Consider ADDR[0:N-1], we have 2^N reference location and DATA[0:k-1], k bits of information in each locations. e,g $0,1,\ldots 2^N-1$ location and each with k=8 bits of data

1.2 **Instruction Cycle**

- 1. Fetch(F)
- 2. Decode(D)
- 3. Execute(E)

Following cycle: $FI_1DI_1EI_1, FI_2DI_2EI_2...FI_mDI_mEI_m$, where I stands for Instruc-

For performing FDE what do we need?

For **FETCH**: fetching instructions from memory

- Need something to store(Instructions)
- Instructions Pointer: always points to next instructions in the memory

For **EXECUTE** we have following general purpose registers:
$$a)\frac{E|\frac{AH(8bit)|AL(8bit)}{AX(16bit)}}{EAX(32bit)} \ b)\frac{E|\frac{BH(8bit)|BL(8bit)}{BX(16bit)}}{EBX(32bit)} \ c)\frac{E|\frac{CH(8bit)|CL(8bit)}{CX(16bit)}}{ECX(32bit)} \ d)\frac{E|\frac{DH(8bit)|DL(8bit)}{DX(16bit)}}{EDX(32bit)}$$

For array/string manipulation at the Hardware level:

- 1. Source Index(SI) Register: $\frac{E|SI(16bit)}{ESI(32bit)}$
- 2. Destination Index(DI) Register: $\frac{E|DI(16bit)}{EDI(32bit)}$

1.3 Partitioning of Memory

Segmentation of Code, Data, Function in memory

MEMORY CODE DATA STACK EXTRA SEGMENT

Segment register are associated with:

• CODE: E|CS

• DATA: E|DS

• STACK: E|SS

• EXTRA SEGMENT: E|ES

1.4 x86 Instructions

1.4.1 Data Transfer

1. MOV[DEST][SRC]

Register direct addressing: $MOVAX, BX (AX \leftarrow BX)$

Immediate addressing: MOVAX, 0×40 ($AX \leftarrow 0 \times 40$)

Direct addressing: $MOV \ 0 \times 1320, AX \ (0 \times 1320 \leftarrow AX)$

Register indirect addressing: MOVAX, [BX] $(AX \leftarrow [BX])$ content of BX is moved to

AX WORD-16 bit & DWORD-32 bit

1.4.2 ALU Instruction

 $ADD\ AX, BX\ (AX \leftarrow AX + BX)$ $SUB\ AX, BX\ (AX \leftarrow AX - BX)$

 $MUL\ [REG]$: for multiplication it takes only one register the other is assume to be the prior register.

Listing 1: MUL example

MOV AX, 0x4500 ; AX <- 0x4500 MUL BX ; AX <- AX*BX

 $INC \ AL|AX|EAX \ (AL \leftarrow AL + 1)$ $DEC \ AL|AX|EAX \ (AL \leftarrow AL - 1)$

 $CMP \ AX, BX \ (AX - BX)$ the value of this is evaluated using FLAG Register

Clearing Register $XOR AX, BX (AX \leftarrow 0)$

1.4.3 Stack Operation

STACK POINTER (ESP) - Last In First Out (LIFO) Operation

- 1. $PUSH \ AL|AX|EAX \ [ESP \leftarrow ESP 1/2/4]$
- 2. $POP AL|AX|EAX [ESP \leftarrow ESP + 1/2/4]$

BASE POINTER (EBP) - Random access operation on stack

1.5 Call and Return Instructions

1.5.1 Subroutine (Function in C)

CALL: two way branching goes to subroutine then comes back to where it left. $EIP \leftarrow EIP + N$ where, N is the address of next instructions to be executed.

Listing 2: subroutine example

```
LOC_FUN: ADD EBX, 0x0002;
ADD EAX, 0x0003;
SUB ECX, 0x0004;
RET

MAIN: XOR EBX, EBX;
XOR EAX, EAX;
XOR ECX, ECX;
CALL LOC_FUN;
XOR EBX, EBX;
XOR EAX, EAX;
XOR EAX, EAX;
XOR EAX, EAX;
XOR EAX, EAX;
XOR ECX, ECX;
CALL LOC_FUN;
```

When CALL LOC_FUN is executed PUSH EIP is performed on stack and EIP \leftarrow LOC_FUN, RET simply pops the top of stack into EIP.

1.6 Inline Assembly

Interoperation between C ans Assembly. Consider the following C code

Listing 3: Inline Example

```
void main() {
   int x=2;
   x = x + 2;
   printf("%d", x);
}
```

Say, we want to speed up x = x + 2 then we write the assembly version of those segment.

Listing 4: Inline Example

```
void main() {
   int x=2;
   //x = x + 2;
   _-asm{
      MOV EAX, x ; EAX <- x
      ADD EAX, 0x002 ; EAX <- EAX+2
      MOV x, EAX ; x <- EAX
   }
   printf("%d", x); // 4
}</pre>
```

1.6.1 Commonly used Data Types in C

- BYTE OF DATA: char
- WORD OF DATA: short int or int
- DWORD OF DATA: long int or int

```
main() {
    // z=x*y
    short int x=2, y=3;
    int z=0;
    __asm{
        XOR EAX, EAX // EAX <- 0
        MOV ECX, y

MULT: ADD EAX, x
        DEC ECX // ECX <- ECX-1
        JNZ MULT // as long as ECX != 0 repeat adding
        MOV z, EAX // z=x*y
    }
}</pre>
```

Listing 6: Optimised vs unoptimised

```
int a,b,c,d;
int x=10,y=5;
a=x+y;
b=a-y;
c=b*y;
d=c/y
//----- Un Optimised -----//
mov x, 0x000a
mov y, 0x0005
mov eax,x
add eax,y
mov a,eax
mov ebx,a
sub ebx,y
mov b,ebx
mov eax,b
imul y
mov c,eax
mov ebx,c
idiv y
mov d,ebx
//----/
mov eax,x
add eax,y // eax <- x+y
mov a,eax
sub ebx,y
mov b,ebx
imul y
mov c,eax
                // eax <- a-y
                 // eax <- b*y
idiv y mov d,ebx
                 // eax <- c/y
```

1.7 Pointer

Listing 7: pointer arithmetic

```
main() {
    char *pa=0; // mov pa,0x0000
    char *pb=0; // mov pb,0x0000
    /*
    mov eax,pa
    add eax,0x0001
    mov pa,eax
    */
    pa++; // pa=pa+1
    /*
    mov eax,pb
    add eax,0x0004
    mov pb,eax
    */
    pb++; // pb=pb+4
}
```

Listing 8: character pointer

```
main () {
    char *s = "This is all nonsense";
    int i=0;
    for(i;s[i]!='\0';i++){}
}
//-----asm optimised-----//
int i=0;
int cnt=0;
__asm {
    mov ecx,0
    mov ebx,s
cm :cmp byte ptr [ebx],0x00
    jz done
    inc ecx
    in ebx
    jmp cm
done: mov cnt, ecx
}
```