```
clear, clc;
close all;
%problem 3
%3A
%declare and initialize variables
n = 8;
a = ones(1,n);
b = -2.*ones(1,n);
c = -5.*ones(1,n);
d = -1.*ones(1,n);
e = ones(1,n);
f = [-5 -7 -6 -6 -6 -6 -7 -6];
z = pent(a,b,c,d,e,f,n)
function x = pent(a,b,c,d,e,f,n)
      initial condition 1
    cbar(1) = c(1);
    dbar(1) = d(1);
    ebar(1) = e(1);
    fbar(1) = f(1);
      initial condition 2
    bbar(2) = b(2);
    cbar(2) = c(2);
    dbar(2) = d(2);
    ebar(2) = e(2);
    fbar(2) = f(2);
      downward elimination for a
    for i = 3:n
        multiplier = a(i)/bbar(i-1);
        abar(i) = a(i)-multiplier*bbar(i-1);
        bbar(i) = b(i)-multiplier*cbar(i-1);
        cbar(i) = c(i)-multiplier*dbar(i-1);
        dbar(i) = d(i)-multiplier*ebar(i-1);
        ebar(i) = e(i);
        fbar(i) = f(i)-multiplier*fbar(i-1);
    end
      downward elimination for b
    for i = 2:n
        multiplier2 = bbar(i)/cbar(i-1);
        bbar(i) = bbar(i)-multiplier2*cbar(i-1);
        cbar(i) = cbar(i)-multiplier2*dbar(i-1);
        dbar(i) = dbar(i)-multiplier2*ebar(i-1);
        ebar(i) = e(i);
        fbar(i) = fbar(i)-multiplier2*fbar(i-1);
    end
```

```
preallocate x
   x = ones(1,n);
     initial conditions for upward substitution
   x(n) = fbar(n)/cbar(n);
   x(n-1) = (fbar(n-1)-(dbar(n-1)*x(n)))/cbar(n-1);
     upward substitution
    for i = n-2:1
       x(i) = (fbar(i)-ebar(i)*x(i+2)-dbar(i)*x(i+1))/cbar(i);
    end
end
z =
 Columns 1 through 7
   1.0000
             1.0000
                      1.0000 1.0000 1.0000
                                                     1.0000
                                                              1.0000
 Column 8
    1.0000
```

Published with MATLAB® R2021b