# Hannah DeFazio

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### PROFESSIONAL EXPERIENCE

## **SOFTWARE ENGINEER, MACHINE LEARNING** | RED HAT

June 2024 - present | Raleigh, NC

- Spearheaded the implementation of a critical pause-and-resume feature for Kserve models, enabling more efficient resource management and cost savings
- Engineered critical stability and observability features for new LLM-D inference services by implementing robust API schema validation and aggregating backend pool statuses, which simplified debugging and enabled reliable automation
- Resolved numerous high-impact bugs and CVEs, enhancing product security and stability across multiple releases
- Authored and maintained essential documentation for complex processes, including source synchronization, upstream release procedures, and local end-to-end testing, improving team efficiency and onboarding
- Developed and executed a new branch strategy for the team's repos, improving the development workflow and release process

## RESEARCH AND DEVELOPMENT ENGINEER | KITWARE, INC.

May 2020 - May 2024 | Carrboro, NC

- Head programmer and scrum master on the DARPA PTG Kitware team
- Contributed to Kitware's open-source platforms (KWIVER, SMQTK, Girder) on the Computer Vision team
- Handled machine learning experiments; Presented and documented results for evaluation with the team
- Integrated machine learning models into our ROS system for real-time deployment and testing
- Containerized and integrated disinformation analytics into APIs for evaluation on the DARPA SemaFor project
- Led the code review process on multiple teams, including teaching new interns about best software practices, the code review process, and agile development as the Intern Team Leader

## **RESEARCH**

## TARS, TERASCALE ALL-SENSING RESEARCH STUDIO

October 2017 - May 2022 | Clarkson University

- Developed tools to allow the allocation of nodes in a drone cluster to be determined by hardware quality and additional resources such as cameras [M.S. Thesis]
- Led a multidisciplinary 7 person team on creating the hardware and software architecture of an assistive robot prototype [Honors Thesis]
- Performed system integration to demonstrate that the prototype robotic arm could be controlled based on whether a person was predicted to need assistance

## **LEADERSHIP**

## **SCRUM MASTER** | RED HAT

January 2025 - present | Raleigh, NC

- Expertly managed the team's agile framework by facilitating all scrum ceremonies, overseeing the entire Jira sprint lifecycle from planning to reporting, and authoring weekly leadership updates
- Drove significant process improvements by introducing mini-refinement groups, creating clearer Ready/Done checklists, and developing a workshop on writing effective impact statements to enhance team communication and efficiency

#### **EDUCATION**

## **CLARKSON UNIVERSITY**

## M.S. Computer Science

May 2022 | Potsdam, NY

• Summa cum laude

## B.S. Computer Science Minor in Mathematics

May 2020 | Potsdam, NY

- Honors Program
- Magna cum laude
- Presidential Scholar (Fall '19, Spring '18, '20)
- Dean's List (Fall '17, '18)

## **SKILLS**

## PROGRAMMING LANGUAGES

Golang | Python | C++ | Docker | CMake

### SOFTWARE EXPERIENCE

Kubernetes | Openshift | Robot Operating System (ROS) | SLURM | Overleaf/LaTex | Git/Github | UNIX/Linux

## **TECHNICAL EXPERIENCE**

Software Engineering
Open Source Development
Agile Development
Artificial Intelligence
Containerization

## **HONORS**

National Grid Stipend for Research Opportunities in Sustainable Energy

## **Honorable Mention Poster**

Presentation in Computer Science and Engineering at Research and Project Showcase (RAPS)

## ADDITIONAL LEADERSHIP

Kitware's PTG Team's Scrum Master Kitware's Intern Team Leader TARS Research Team Leader Resident Advisor Honors Recruiter & Peer Mentor Society of Women Engineers