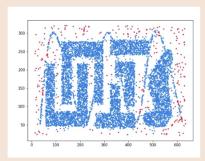
& Density-based Clustering

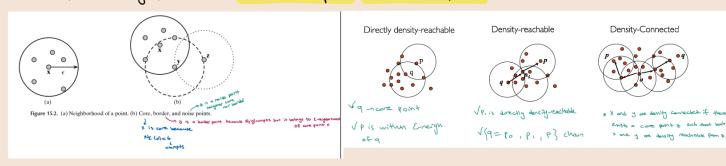
- It can mine non-convex clusters. (Representative based or after methods have trouble with non-convex clusters)



- Clustermy based on density
- Major features; · Discover clusters of arbitrary shape
 - · Handle mise
 - · One scan
 - · Need density parameters as termination condition

3 DBSCAN

- Density corresponds to have at least minpts points within specific radius &
- Core point contains at least minpts objects in its E-neighborhood
- Border point has fewer than minpts within E, but is in the neighborhood of a core point
- Noise point is any point that is not a core point nor a noise point



- · Directly density reachable: x is directly density-reachable from y if x is within the E-neighborhood of y and y is a core point.
- · Density reachable: X is density-reachable from object y if there is a chain X,,..., Xn where X,=X and Xn=y such that X:+1 is directly density reachable from X;
- Density Connected: P is density connected to q with respect to E and Minpts if there is "0" such that both p and q are density reachable from o
- Density-Based Cluster: Maximal set of density connected points.

-Pseudocode: Algorithm 15.1: Density-based Clustering Algorithm **DBSCAN (D,** ϵ , minpts): Core ← Ø $_2$ foreach $x_{\it i} \in D$ do // Find the core points Compute $N_{\epsilon}(\mathbf{x}_i)$ $id(\mathbf{x}_i) \leftarrow \emptyset \ / / \ \text{cluster id for } \mathbf{x}_i$ 5 **lif** $N_{\epsilon}(\mathbf{x}_i) \ge minpts$ **then** $Core \leftarrow Core \cup \{\mathbf{x}_i\}$ 6 $k \leftarrow 0 \text{//}$ cluster id 7 foreach $\mathbf{x}_i \in Core$, such that $id(\mathbf{x}_i) = \emptyset$ do $k \leftarrow k + 1$ $id(\mathbf{x}_i) \leftarrow k \hspace{0.1cm} / / \hspace{0.1cm} \text{assign} \hspace{0.1cm} \mathbf{x}_i \hspace{0.1cm} \text{to} \hspace{0.1cm} \text{cluster} \hspace{0.1cm} \text{id} \hspace{0.1cm} k$ 10 DENSITYCONNECTED (\mathbf{x}_i, k) 11 $C \leftarrow \{C_i\}_{i=1}^k$, where $C_i \leftarrow \{\mathbf{x} \in \mathbf{D} \mid id(\mathbf{x}) = i\}$ 12 Noise $\leftarrow \{\mathbf{x} \in \mathbf{D} \mid id(\mathbf{x}) = \emptyset\}$ 13 $Border \leftarrow \mathbf{D} \setminus \{Core \cup Noise\}$ 14 return C, Core, Border, Noise **DENSITYCONNECTED** (x, k): 15 foreach $y \in N_{\epsilon}(x)$ do $id(\mathbf{y}) \leftarrow k \hspace{0.1cm} / / \hspace{0.1cm} \text{assign } \mathbf{y} \hspace{0.1cm} \text{to cluster id} \hspace{0.1cm} k$ if $y \in Core$ then DENSITYCONNECTED (y, k)

- -DBSCAN fails when applied to data of varying donsity
- HDBS can convert DBSCAN into a Nierarchical clustering algorithm