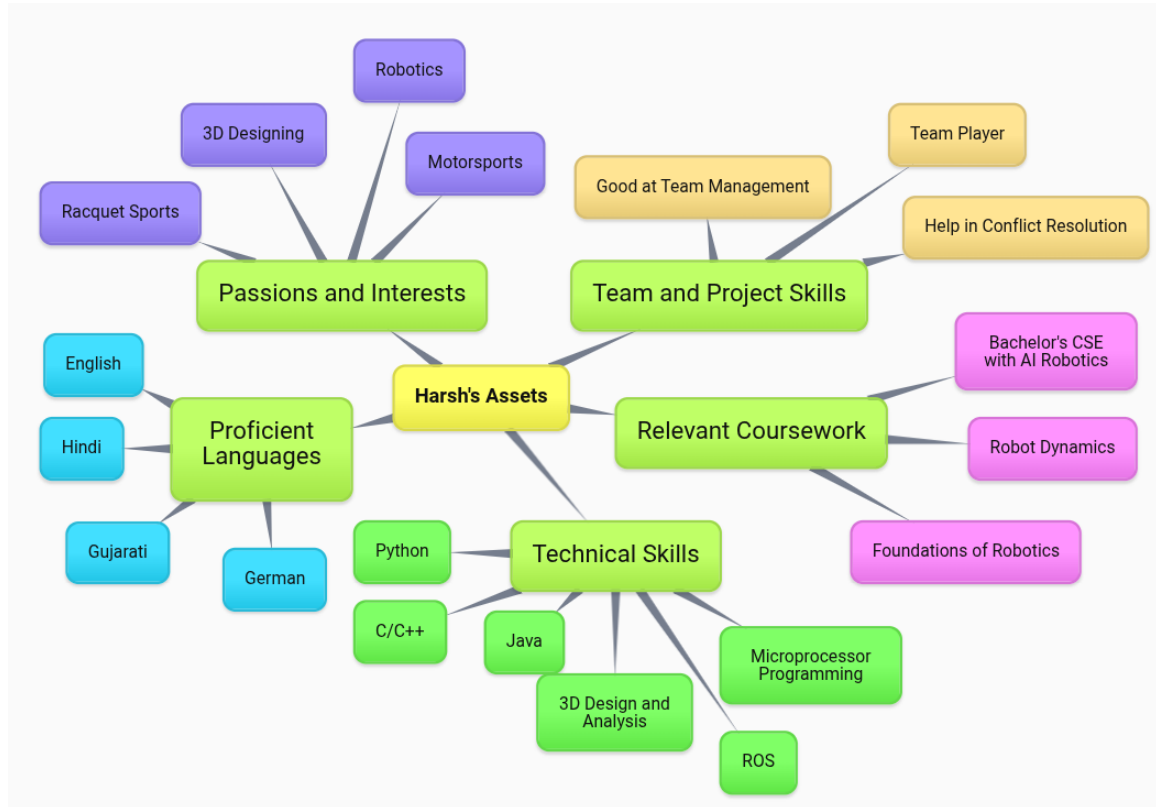


RBE500 – Foundations of Robotics

Asset Maps of Every Team Member

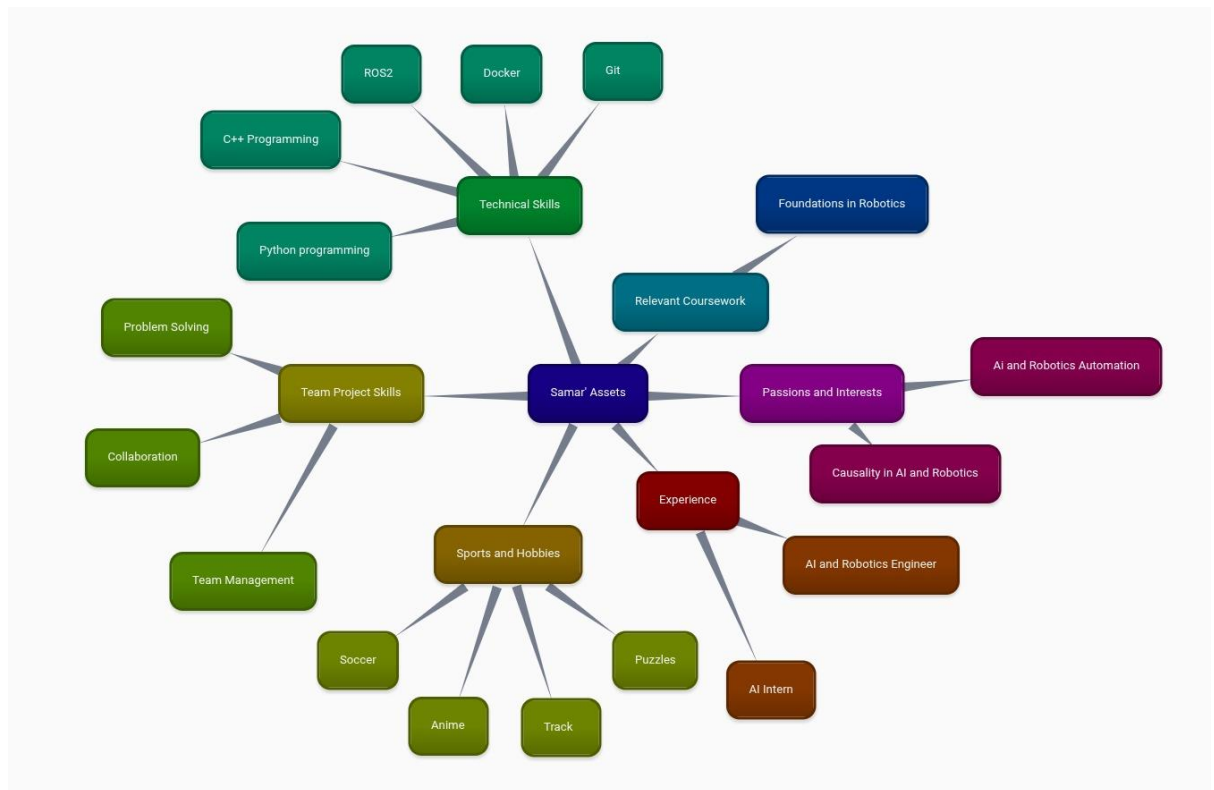
1. Harsh Deval Shah – Asset Map



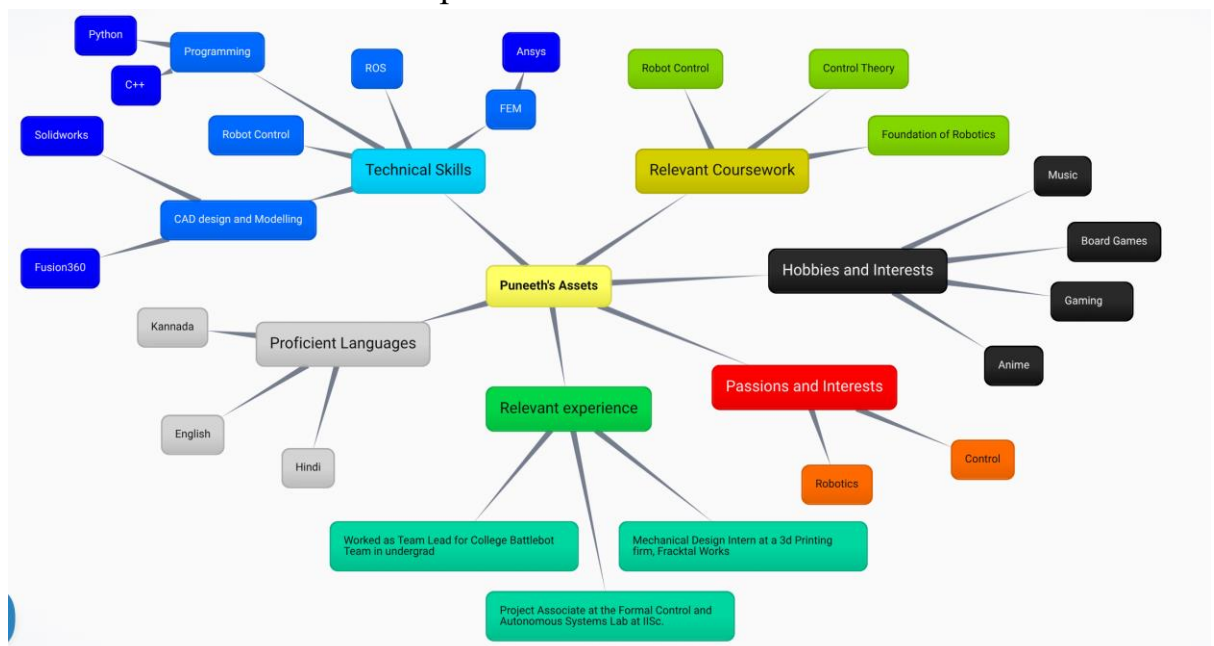
2. Sri Satya Satwik Sirigineedi – Asset Map



3. Samar Kale – Asset Map



4. Puneeth Shankar – Asset Map



Growth Areas

1. Harsh Deval Shah

Want to try and meet deadlines while working with the team in the best way I can.

2. Sri Satya Satwik Sirigineedi

Work more with Python interfacing and get acquainted with Linux.

3. Samar Kale

Want to work more closely with hardware components.

4. Puneeth Shankar

Be more involved with the team while working on the projects.