Branch-and Bound to solve Integer Linear Programming problems

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Import the libraries

```
In [1]:
```

```
import numpy as np
from scipy.optimize import linprog
import math
```

Tuning parameters (if necessary)

Function "isInteger(x)"

```
In [2]:
```

Class "Node"

In [3]:

```
class Node:
    """
    This class models a node in the branch and bound algorithm.
    x: the solution in node
    z: the value of node
    status: the status of the node, if this node is availabe

    """

def __init__ (self, x, z, bounds, status):
    self. x = x
    self. z = z
    self. bounds = bounds
    self. status = status
```

Definition of the LP problem

Exercise 8.1

Let us consider the following ILP problem

$$max_{(x_1,x_2)\in R^2}$$
 $z = 10x_1 + 20x_2$

s.t.
$$5x_1 + 8x_2 \le 60$$

$$x_1 \leq 8$$

$$x_2 \le 4$$

$$x_1, x_2 \in N$$

Solve the ILP with Dakin's method. In each node, separate on the fractional variable which is the closest to an integer.

Exercise 8.2

Let us consider the following ILP problem

$$\max_{(x_1, x_2, x_3, x_4) \in \mathbb{R}^4} \quad z = 2x_1 + 3x_2 + x_3 + 2x_4$$

s.t.
$$5x_1 + 2x_2 + x_3 + x_4 \le 15$$

$$2x_1 + 6x_2 + 10x_3 + 8x_4 \le 60$$

$$x_1 + x_2 + x_3 + x_4 \le 8$$

$$2x_1 + 2x_2 + 3x_3 + 3x_4 \le 16$$

$$x_1 \leq 3$$

$$x_2 \le 7$$

$$x_3 \leq 5$$

$$x_4 \leq 5$$

$$x_1, x_2, x_3, x_4 \in N$$

Solve the ILP with Dakin's method. In each node, separate on the fractional variable which is the closest to an integer.

In [4]:

Initialization of the branch-and-bound algorithm

In [5]:

```
"""
Initialization of the branch-and-bound algorithm
we have three main input parameters, i.e., node, bestnode, iteration
node: the node we need to proceed
bestnode: is used to store the best solution of the branch-and-bound algorithm
iteration: the iteration of processing node
"""
# Initializing the node
init_res = linprog(-c, A, b, A_eq, b_eq)
x=init_res.x
z=init_res.fun
status=init_res.status
node = Node(x, z, bounds, status)
# Initialize the bestnode
bstnode status=0
bestnode = Node([0, 0], 0, bounds, bstnode_status)
# Initialize the iteration
iteration=0
```

Branch-and-Bound recursive processing

Dakin's method:

If $T = \emptyset$:

• Terminate the algorithm. Give the best found integer solution and its profit z (if no solution, the ILP is not feasible)

If $T \neq \emptyset$:

- ullet If $U(S_i)>z$ and the solution only contains integers, it is the best solution found since the beginning: update z
- If $U(S_i) > z$ but the solution contains at least one non-integer, choose a functional variable x_j^* and split S_i : and one child with the additional constraint $x_j \leq [x_j^*]$ and the other one with $x_j \geq [x_j^*]$. Process the two children nodes and insert them into T
- If $U(S_i) \leq z$, discard S_i (prunning): it can not improve z

```
In [6]:
```

```
def branch bound(node, bestnode, iteration):
        We implement the Dakin's method step by step
        <node> denotes T
         \denotes the best node with integer solution and best profit, and the bestnode.z stand
        <iteration> denotes the iteration
        """
        # decide the node is available or not
        if node. status != 0:
                # terminate the algorithm, return the best found integer solution and its profit z
               return (bestnode, iteration)
        # decide update the best solution or not
        if node.z < bestnode.z:
                (isIntegerOrNot, splitIndex)=isInteger(node.x)
                # decide if the solution is integer
                if isIntegerOrNot == True:
                        # update the bestnode
                        bestnode=node
                        # return the bestnode
                        return (bestnode, iteration)
                else: # split the node to find the bestnode
                        # choose a functional variable to split node
                        spValue = node.x[splitIndex]
                        # one child with conditional constraints x<=lowbound
                        lowbound = np. floor(spValue)
                        boundsL=np. array (node. bounds)
                        boundsL[splitIndex]=[0, lowbound]
                        # process the child node and insert them into the <node> to find the bestnode
                        resL=linprog(-c, A, b, A eq, b eq, boundsL)
                        nodeL = Node (resL. x, resL. fun, boundsL, resL. status)
                        iteration=iteration+1
                        print("Iteration number is: "+str(iteration) + " \nProcessed node: Solution x: {0}, Value: " \nProcessed nod
                        if nodeL.z <= bestnode.z:
                                # start the recursive processing
                                 (bestnode, iteration) = branch bound (nodeL, bestnode, iteration)
                        else:
                                # one child with conditional constraints x>=upbound
                                upbound = np. ceil(spValue)
                                boundsR=np. array (node. bounds)
                                boundsR[splitIndex]=[upbound, None]
                                # process the child node and insert them into the <node> to find the bestnode
                                resR=linprog(-c, A, b, A_eq, b_eq, boundsR)
                                nodeR= Node (resR. x, resR. fun, boundsR, resR. status)
                                iteration=iteration+1
                                print("Iteration number is: "+str(iteration)+ "\nProcessed node: Solution x:{0}, Val
                                if nodeR.z <= bestnode.z:</pre>
                                        # start the recursive processing
                                         (bestnode, iteration) = branch bound (nodeR, bestnode, iteration)
        else:
                # return the bestnode
               return (bestnode, iteration)
        # return the bestnode
        return (bestnode, iteration)
```

Final messages to the users

```
In [8]:
```

```
#print("Original node: x: {0}, Value: {1}, Bounds: {2}". format(node. x, node. z, node. bounds))
(bestnode, iteration) = branch_bound(node, bestnode, iteration)
print("\nAn integer solution is found by improvement!\n")
#print("Optimal solution x: {0}, Value: {1}, Bounds: {2}". format(bestnode. x, -bestnode. z, bestnode. bounds]

Iteration number is: 2
Processed node: Solution x: [5. 4.], Value: 130.0, Bounds: [[0 5.0]
        [0 None]]
Split on x_1
An integer solution is found by improvement!
In []:
```