

10,2 mNm

9 W

Series 2214 ... BXT R

Values at 22°C and nominal voltage		2214 S	006 BXT R	012 BXT R	024 BXT R	
1	Nominal voltage	U_N	6	12	24	V
2	Terminal resistance, phase-phase	R	2,42	6,95	25,9	Ω
3	Efficiency, max.	$\eta_{max.}$	72	73	70	%
4	No-load speed	n_0	5 740	6 500	6 960	min ⁻¹
5	No-load current, typ. (with shaft ø 3 mm)	I_0	0,062	0,039	0,016	A
6	Starting torque	M_A	23,5	29,1	29,6	mNm
7	Speed constant	k_n	997	561	296	min ⁻¹ /V
8	Back-EMF constant	k_E	1	1,78	3,37	mV/min ⁻¹
9	Torque constant	k_M	9,58	17	32,2	mNm/A
10	Current constant	k_I	0,104	0,0588	0,031	A/mNm
11	Slope of n-M curve	$\Delta n / \Delta M$	252	229	238	min ⁻¹ /mNm
12	Terminal inductance, phase-phase	L	271	884	3 150	µH
13	Mechanical time constant	τ_m	8,7	7,92	8,22	ms
14	Rotor inertia	J	3,3	3,3	3,3	gcm ²
15	Angular acceleration	$\alpha_{max.}$	71,1	88,2	89,7	·10 ³ rad/s ²
16	Operating temperature range:					
	– motor		-40 ... +100			°C
	– winding, max. permissible		+125			°C
17	Shaft bearings		ball bearings, preloaded			
18	Shaft load max.:					
	– with shaft diameter	3				mm
	– radial at 3 000 min ⁻¹ (5 mm from mounting flange)	6				N
	– axial at 3 000 min ⁻¹ (push / pull)	2				N
	– axial at standstill (push / pull)	50				N
19	Shaft play:					
	– radial	≤	0,015			mm
	– axial	=	0			mm
20	Mass		25,5			g
21	Direction of rotation		electronically reversible			
22	Speed up to	$n_{max.}$	10 000			min ⁻¹
23	Number of pole pairs		7			
24	Hall sensors		digital			
25	Magnet material		NdFeB			

Note: Rated values are measured at nominal voltage and 22°C ambient temperature.

The display shows the range of possible operation points of the drives at a given ambient temperature of 22°C.

It includes the assembly on a plastic- as well as on a metal flange (assembly method: IM B 5).

Any points of operation above this linear slope will require a supply voltage $U_{mot} > U_N$



