

Animation

(Not Even an Introduction)

Chapter 23

Animation

- animated flipbooks and film (19th century)
- principles of animation (1930's and 40's)
- to animate =
 - to give life to an inanimate object, image or drawing
 - *anima*: means soul in Latin
- Animation: the art of movement expressed with images that are not taken directly from reality
- In animation, the **illusion of movement** is achieved by rapidly displaying many still images (or frames) in sequence.



Keyframing and in-betweening

□ Keyframing

- is used to define an animated sequence based on its key moments.
- Hand-drawn animation: keyframes or extremes
- Stop-motion animation: key poses

□ In-betweening

- is used once the keyframes have been established and drawn, creates all the transition or in-between drawings that fill the gaps between the keyframes.
- Interpolation
 - Interpolation of position and orientation
 - Interpolation of shape
 - Interpolation of attributes

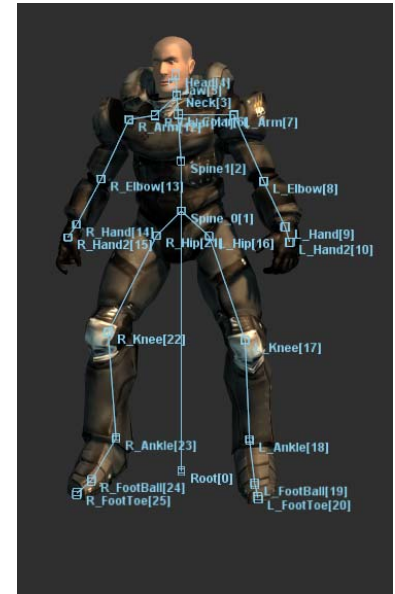
Luxo Jr. (1986)

P I X A R



Skinning

- Start with complicated mesh we want to animate
- Rigging: design a geometric hierarchical skeletal structure
- Associate each vertex with one “bone” (RBT node)
- Idea: express the vertex in its bone frame
- Manipulate the skeleton
- Vertices now move along with the bones



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Details



- Instead of actually changing the vertex coordinates,
- A rest accumulated matrix represents the relationship between the object and rest bone frame.
- A new accumulated matrix represents the relation after the bone has been moved.
- Use these matrices, in the vertex shader to move the vertex.
- In this context, we can associate a vector of bone-weights and do soft skinning.
 - We use the weights to blend the updates.
- This is used extensively in games and would make a nice project
- Example:



Aleka McAdams, Yongning Zhu, Andrew Selle, Mark Empey, Rasmus Tamstorf, Joseph Teran, and Eftychios Sifakis. 2011. Efficient elasticity for character skinning with contact and collisions. In *ACM SIGGRAPH 2011*

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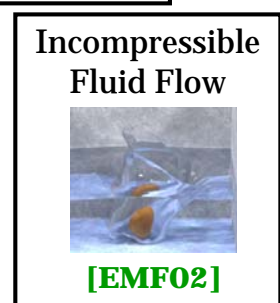
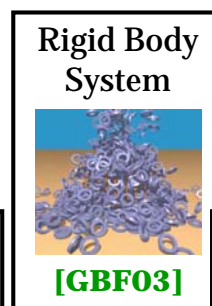
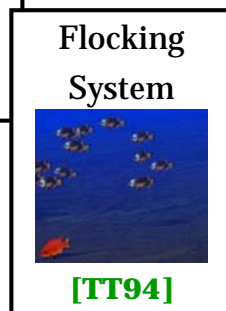
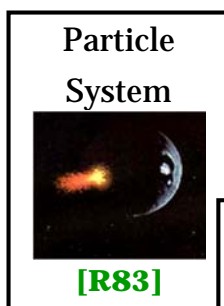
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Simulation

- Physics uses equations to describe physical processes.
- We can try to simulate these processes computationally.
- Techniques: physics and computational mathematics.
- Some methods are slow and only work for offline animation.
- Some methods can be made real-time
- Hard to control the output

Physically-based modeling

- Techniques that use physics to create realistic animations automatically



Particle simulation systems

- Simplest version of physics.
- A large bunch of non-interacting particles.
- Ordinary differential equation (ODE) for the time evaluation of a point:
$$f = ma = m\dot{v} = m\ddot{x} \quad p = mv$$
- Force might be gravity or wind
- Can model flowing fall of water particles, or a stream of smoke particles in the air
- Typically each particle is rendered as a semitransparent little blob or surface

ODE integration

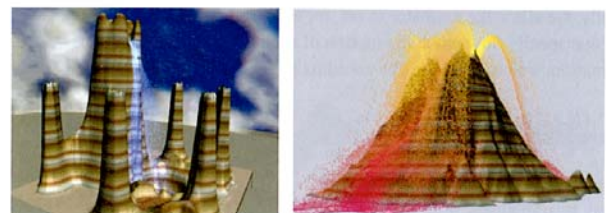
- Starting from an initial condition, we can discretize this ODE and march forward in time using so-called *Euler steps*:

$$x_{t+h} = x_t + v_t h$$

$$v_{t+h} = v_t + a_t h$$

$$a_{t+h} = f(x_{t+h}, t + h) / m$$

- Steps must be small (often need many more than 30/sec).
- There is a whole literature of more sophisticated ways to solve an ODE.



- Example:



Tobias Pfaff, Nils Thuerey, Jonathan Cohen, Sarah Tariq, and Markus Gross. 2010. Scalable fluid simulation using anisotropic turbulence particles. In ACM SIGGRAPH Asia 2010 papers (SIGGRAPH ASIA '10).

Rigid Bodies

- Upgrade from particles to solid hard finite objects (dice rolling on a table)
- Need to deal with rotational issues
- With to deal with interaction: collision detection
 - Bounding hierarchies
 - Must undo interpenetration
 - Must have the object bounce (this requires hacked physics since real objects slightly deform and undeform)
- Must deal with objects resting on objects and not endlessly bouncing

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Cloth

- Can be modeled as a grid of particles connected by springs
- Can be modeled as mesh of physical triangular elements
- Need forces to avoid stretching and shearing and oscillation

- Example:



Zhili Chen, Renguo Feng, and Huamin Wang. 2013. Modeling friction and air effects between cloth and deformable bodies. ACM Trans. Graph. 32, 4

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Hair

- Hair modeling is also often similarly dealt with as a mass-spring model

- Example:



Aleka McAdams, Andrew Selle, Kelly Ward, Eftychios Sifakis, and Joseph Teran. 2009. Detail preserving continuum simulation of straight hair. In ACM SIGGRAPH 2009 papers (SIGGRAPH '09)

Deformable materials

- Real objects are deformable
- Can be modeled as volumetric objects (mesh of 3D tetrahedra)

- Example:



Chris Wojtan, Nils Thürey, Markus Gross, and Greg Turk. 2009. Deforming meshes that split and merge. In ACM SIGGRAPH 2009 papers (SIGGRAPH '09)

Fire and water

- Special physical equations
- Modeled with combination of equations

- Example



Jeffrey N. Chadwick and Doug L. James. 2011. Animating fire with sound. In ACM SIGGRAPH 2011 papers (SIGGRAPH '11)

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Human locomotion

- Not passive objects
- Much harder than previously discussed phenomenon
- Ideas are used from robotics, control, and optimization
- Nowadays motion capture data is relied on heavily, and possibly altered or used as part of the rocket science.

- Example:



Jack M. Wang, David J. Fleet, and Aaron Hertzmann. 2010. Optimizing walking controllers for uncertain inputs and environments. In ACM SIGGRAPH 2010 papers (SIGGRAPH '10)

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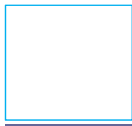
Introduction to Computer Graphics

CS380

<Lecture 1>

CS380

- This course provides a broad introduction to the field of 3D computer graphics.
- The goal of this course is to learn **how to form images by computer**.
 - We will study the basic methods used to define shapes, materials and lighting when creating computer-generated images for use in film, games and other applications.
 - Covered topics include affine and projective transformations, viewing, shading, lighting, texture mapping, modeling, animation and 3D interactive applications.
- Through a series of OpenGL programming assignments, students will become familiar with interactive 2D and 3D graphical display concepts.



Computer Graphics

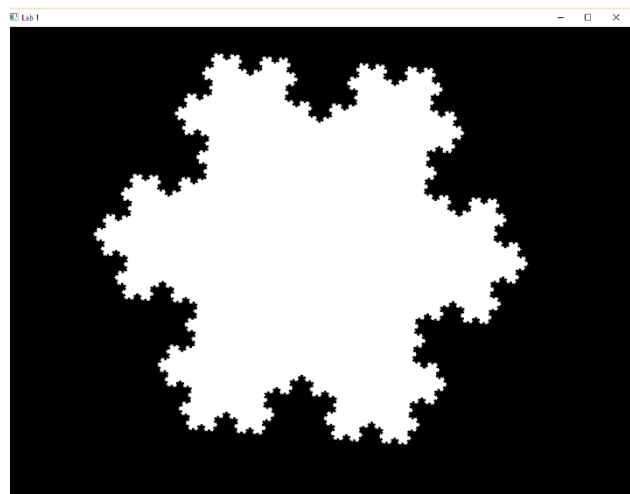
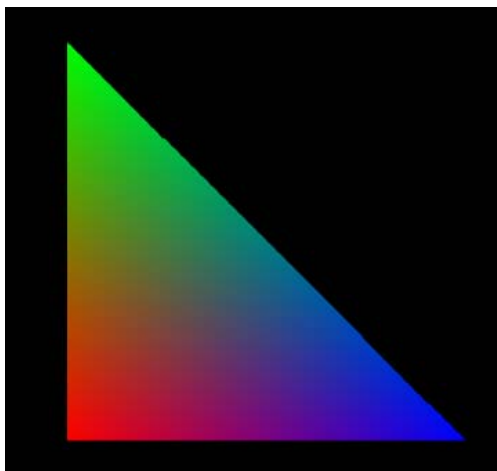
- Concerns with all aspects of producing pictures or images using a computer
- Algorithm for visual simulation

- Applications of Computer Graphics
 - Display of information
 - Design
 - Simulation and animation
 - User interfaces

Main Theme

- Imaging
 - Representing 2D images
- Modeling
 - Representing 3D objects
- Rendering
 - Constructing 2D images from 3D models
- Animation
 - Simulating changes over time

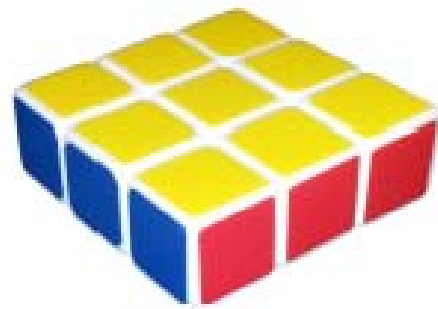
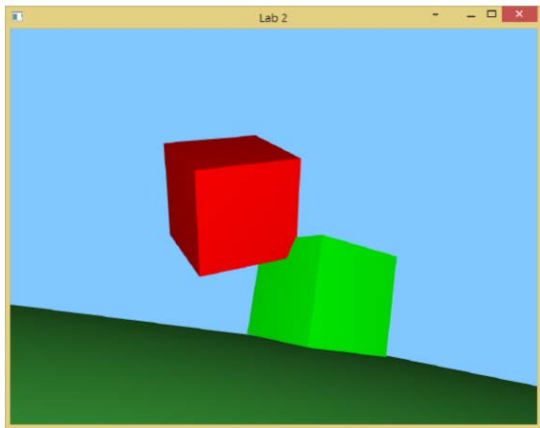
Homework & Lab



- Snowflake 2D animation

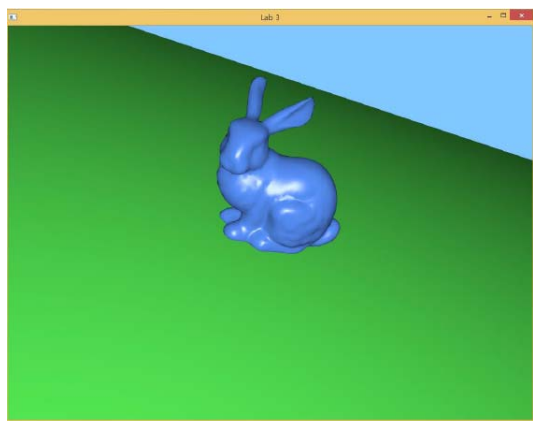
Homework & Lab

- ❑ Object Manipulation with Arcball Interface
- ❑ 3x3x1 Floppy Cube Manipulation with Arcball Interface



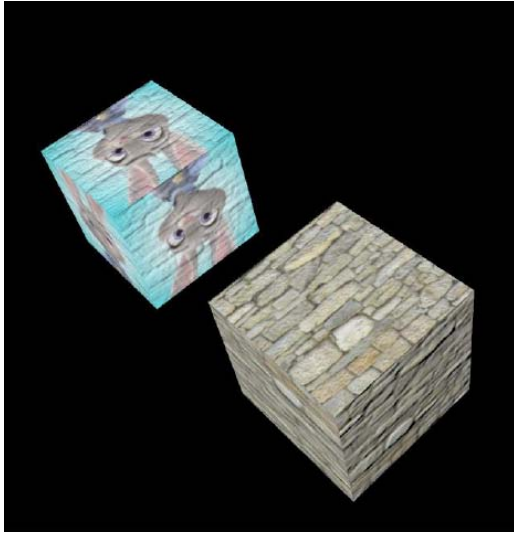
Homework & Lab

- ❑ Multiple Lights Animation with Multiple Shaders



Homework & Lab

▣ AWESOME virtual 3D Rubik's cube



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Contest

<optional but highly-recommended!>

▣ Best image of a virtual floppy cube

- Created by you
- 512 x 512 (any standard image format is fine)
- High quality rendered output
- Title & short description will be nice to have
- Enter by June 15 Midnight to KLMS
- **Winner(s)** will be announced at the final on June 21 and receive a prize!

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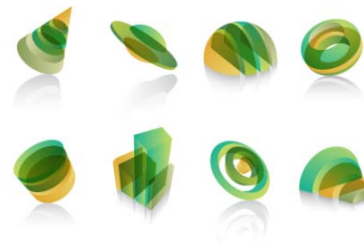
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3D Computer Graphics

- I. Getting Started
 - **Introduction** / Linear / Affine / Respect
 - **Frames in graphics** / Hello World 3D
- II. Rotations and Interpolation
 - Quaternions / **Balls: Track and Arc**
 - Smooth interpolation
- III. Cameras and Rasterization
 - **Projection / Depth**
 - From vertex to pixel / Varying variables
- IV. Pixels and Such
 - **Materials / Texture mapping**
 - Sampling / Reconstruction / Resampling
- V. Advanced Topics
 - **Color** / **What's ray tracing?** / **Light**
 - Geometric modeling / **Animation**
- Appendix
 - Hello World 2D
 - Affine functions

FOUNDATIONS OF
3D COMPUTER GRAPHICS

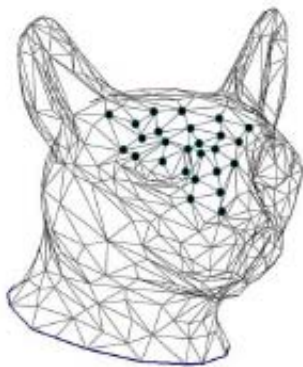
Steven J. Gortler



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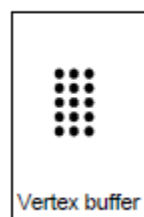
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Ch.1 Introduction



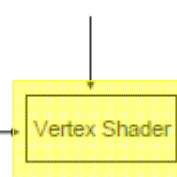
$$\tilde{p} = \vec{o}^t c = \vec{w}^t O c$$

$$= \vec{e}^t E^{-1} O c$$



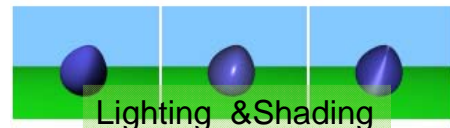
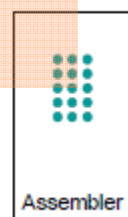
Attributes

Uniform Variables

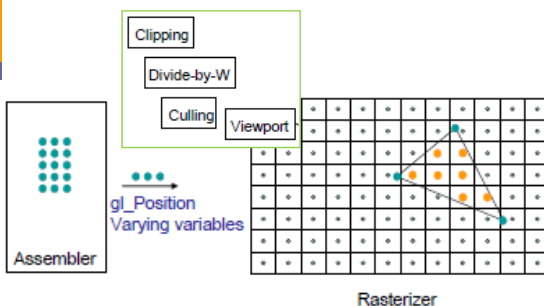


Transformation
Affine
Perspective
4x4 Matrix

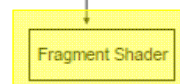
gl_Position
Varying variables



Lighting & Shading

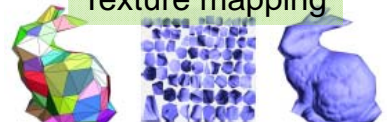


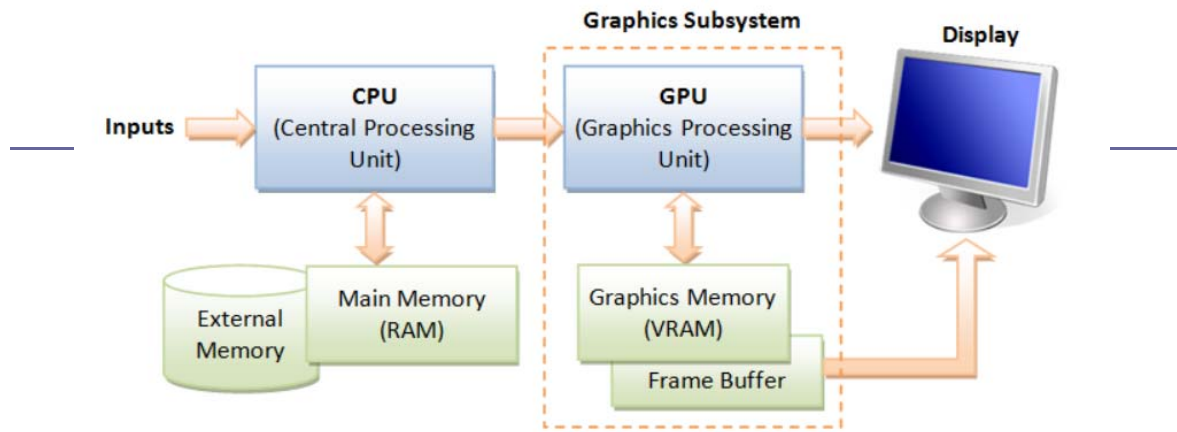
Uniform Variables



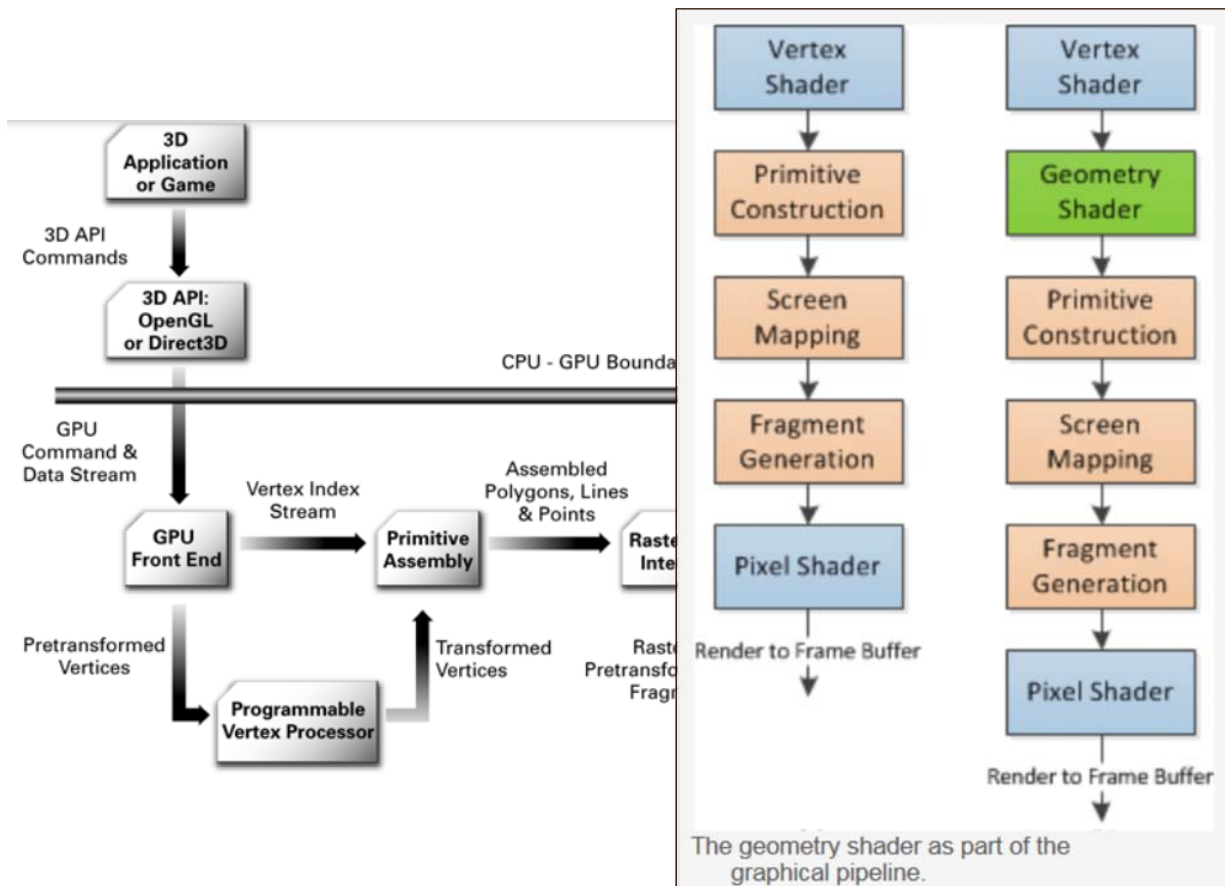
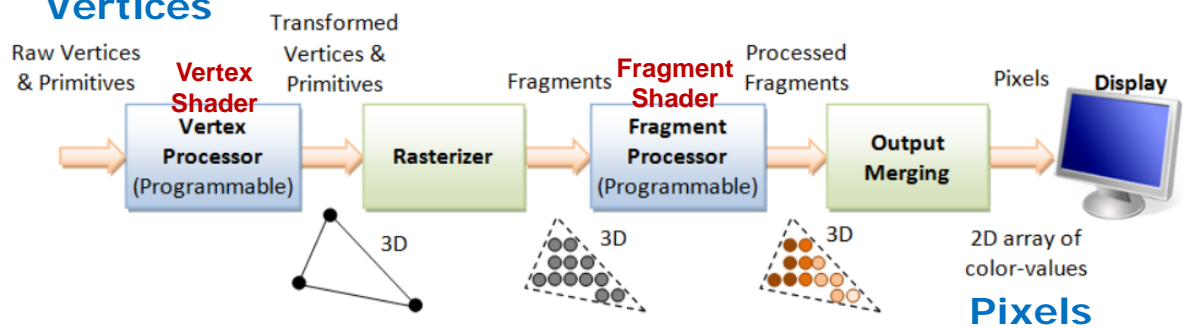
Screen color

Texture mapping

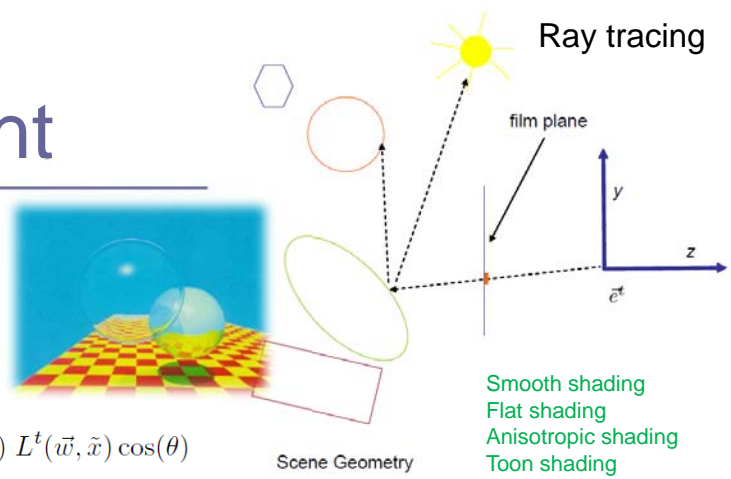




Vertices

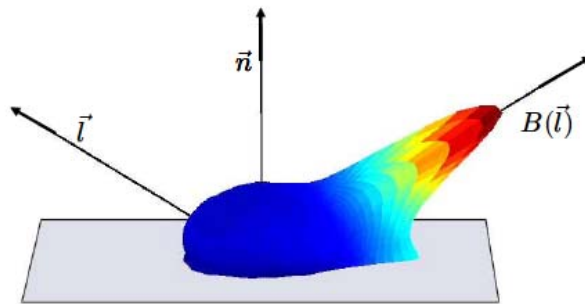


Material / Light

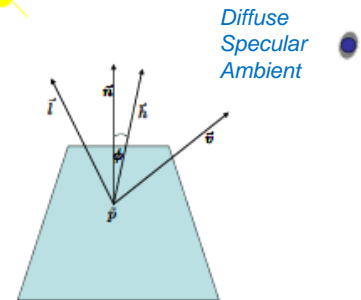


Rendering equation

$$L^t(\tilde{x}, \vec{v}) = L^e(\tilde{x}, \vec{v}) + \int_H dw f_{\tilde{x}, \vec{n}}(\vec{w}, \vec{v}) L^t(\vec{w}, \tilde{x}) \cos(\theta)$$

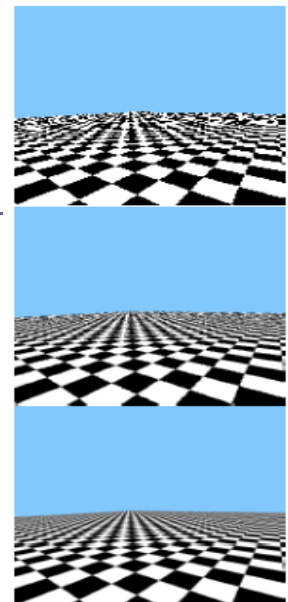
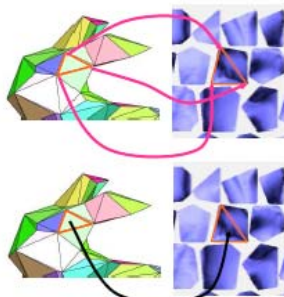


Phong illumination model



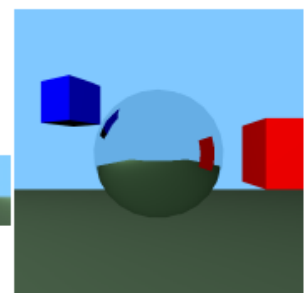
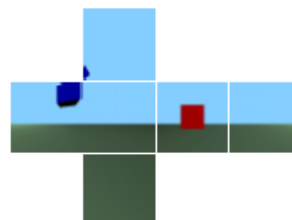
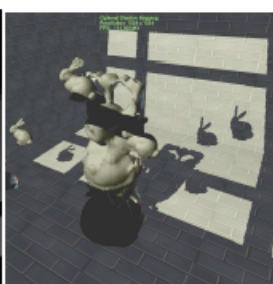
Texture mapping

Sampling problems

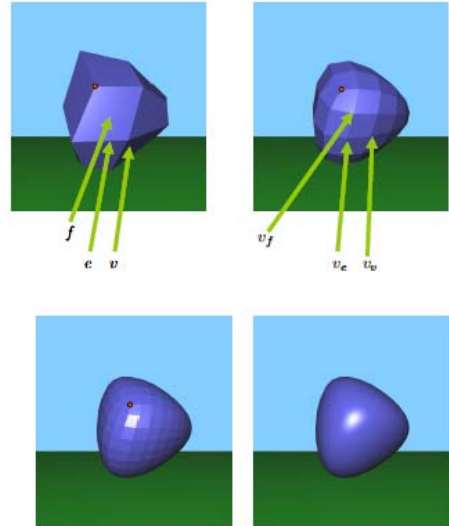
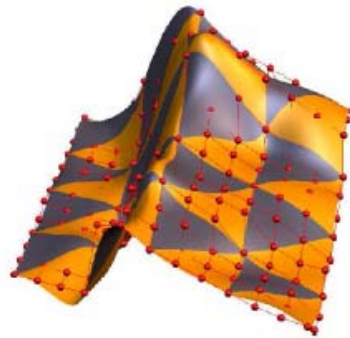


Shadow map

Environment map

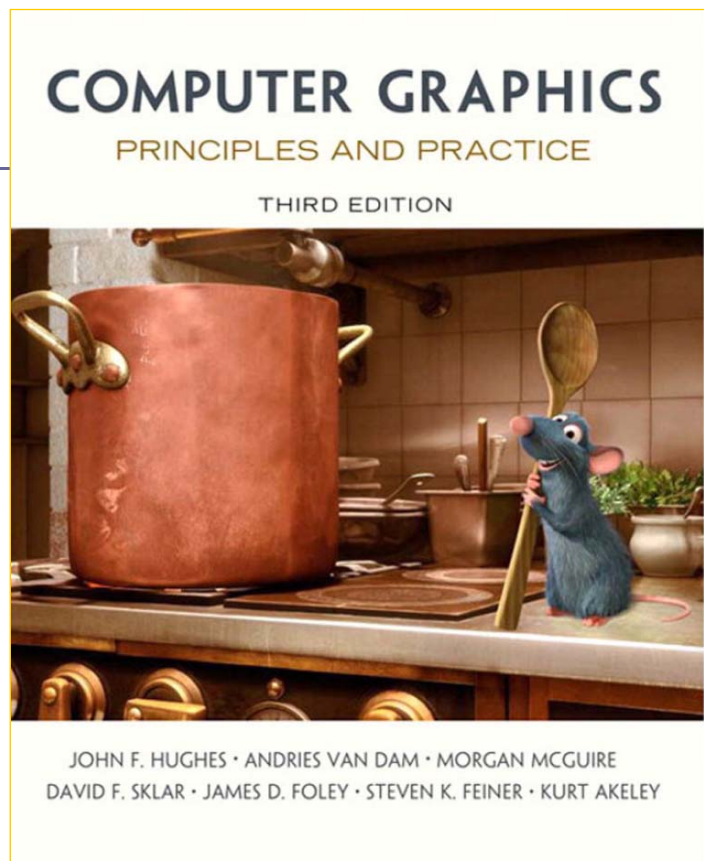
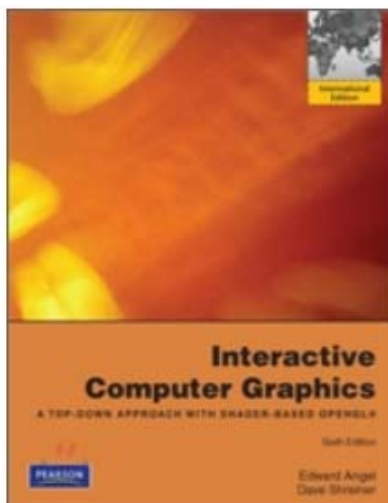


Modeling



Book Recommendation

- Traditional topics
- OpenGL



Grading

- Attendance and Participation (including Labs) 10%
- Homework Assignments 40%
- Midterm Exam 25%
- Final Exam 25%

Mon	Tue	Wed	Thur	Fri
4 PM	Lecture		Lecture	
5:30				
		Lab TA's help Hour	7 PM	
			10	

Final Exam

- **Tuesday June 21 4PM E3-1, #1501**
- **Reading: all chapters covered**
 - omit 19, 23 (Color, Animation)
- You may bring 1 page help sheet for your own use during the exam.
 - Hand written only on 1 side
 - A4-size paper
 - Will hand-in with your exam
- **Announcement**
 - **Homework #5 Due June 14 (Midnight)**
 - Late submission allowed only upto *June 21*.
 - **Contest entry by June 15 Midnight to KLMS**