

Function Types

First-Order Functions: Statics

exp, e

$::=$

| x
| $num[n]$
| $str[s]$
| $plus(e_1; e_2)$
| $mult(e_1; e_2)$
| $cat(e_1; e_2)$
| $len(e)$
| $let(e_1; x.e_2)$
| $fun[T_1; T_2](x.e_1; f.e_2)$
| $call[f](e)$

Γ

$::=$

| \emptyset
| $x : T$
| $f(T_1) : T_2$
| Γ_1, Γ_2

First-Order Functions: Statics

$\text{fun}[T_1, T_2](x.e_1; f.e_2)$

```
1. fun f (x:T1) : T2 {  
2.   e1  
3. }  
4.  
5. e2
```

First-Order Functions: Statics

`fun[Num, Num](x . plus(x; x); double . call[double](num[2]))`

```
1. fun double (x:Num) : Num {  
2.   plus (x, x)  
3. }  
4. double (2)
```

First-Order Functions: Statics

```
fun[Num, Num](x . plus(x; x); double .  
  fun[Str; Num](y . call[double](length(y)); dl .  
    plus(call[dl](str["statics"]); num[1])))
```

```
1. fun double(x:Num) : Num {  
2.   plus(x, x)  
3. }  
4. fun dl(y:Str) : Num {  
5.   double(length(y))  
6. }  
4. plus(dl("statics"); 1)
```

First-Order Functions: Statics

$$\frac{\Gamma, x : T_1 \vdash e_1 : T_2 \quad \Gamma, f(T_1) : T_2 \vdash e_2 : T}{\Gamma \vdash \text{fun } [T_1; T_2](x.e_1; f.e_2) : T} \text{FUN}$$

$$\Gamma ::= \begin{array}{l} \emptyset \\ x : T \\ f(T_1) : T_2 \\ \Gamma_1, \Gamma_2 \end{array}$$

$$\boxed{\Gamma \vdash f(T_1) : T_2} \quad \text{Function Header}$$

$$\frac{}{\Gamma, f(T_1) : T_2 \vdash f(T_1) : T_2} \text{FUNH}$$

$$\frac{\Gamma \vdash f(T_1) : T_2 \quad \Gamma \vdash e : T_1}{\Gamma \vdash \text{call } [f](e) : T_2} \text{CALL}$$

First-Order Functions: Dynamics

$$\overline{\text{fun } [T_1; T_2](x.e_1; f.e_2) \mapsto \llbracket x.e_1/f \rrbracket e_2} \quad \text{FUNVAL}$$

$$\llbracket x.e_1/f \rrbracket \text{call } [f](e_2) \equiv \text{let } (\llbracket x.e_1/f \rrbracket e_2; x.e_1)$$

Dynamics Example

$\text{fun}[\text{Num}, \text{Num}](x.\text{plus}(x; x); \text{double.call}[\text{double}](\text{num}[2]))$
 $\mapsto \llbracket x.\text{plus}(x; x) / \text{double} \rrbracket (\text{call}[\text{double}](\text{num}[2]))$
 $\equiv \text{let}(\text{num}[2], x.\text{plus}(x; x))$
 $\mapsto \text{plus}(\text{num}[2]; \text{num}[2])$
 $\mapsto \text{num}[4]$

First-Order Functions: Dynamics

$$\overline{\text{fun } [T_1; T_2](x.e_1; f.e_2) \mapsto \llbracket x.e_1/f \rrbracket e_2} \quad \text{FUNVAL}$$

$$\llbracket x.e_1/f \rrbracket \text{call } [f](e_2) \equiv \text{let } (\llbracket x.e_1/f \rrbracket e_2; x.e_1)$$

First-Order Functions

$$\begin{array}{lcl} \Gamma & ::= & \\ & | & \emptyset \\ & | & x : T \\ & | & f(T_1) : T_2 \\ & | & \Gamma_1, \Gamma_2 \end{array}$$

$$\frac{}{\Gamma, f(T_1) : T_2 \vdash f(T_1) : T_2} \text{FUNH}$$

$$\frac{}{\Gamma, x : T \vdash x : T} \text{VAR}$$

$$[x.e_1/f]e_2$$

$$[e_1/x]e_2$$

Higher-Order Functions