Iterators and Ranges for numerical problems

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Outline

- Motivation and introduction
- Problem 1 Numerical sequences
- 3 Problem 2 Dynamical systems
- 4 Problem 3 Convergence methods
- Conclusion

Motivation

Problem: Find the root of a function 0 = f(x)Newtons algorithm: $x_{n+1} = x_n - f(x)/f'(x)$

```
auto newton( auto x , auto f , auto df ) {
    while( std::abs( f(x) ) > 1.0e-12 )
        x = x - f(x) / df( x );
    return x;
}
// ...
double root = newton( x , f , df );
```

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    return x;
}
// ...
double root = newton( x , f , df );
```

Idea - Return a range

```
auto newton( auto x , auto f , auto df ) { ... }
// ...
auto range = newton( x , f , df );
for( auto x : range ) cout << x << endl;
cout << "Final value: " << range.value() << endl;</pre>
```

Motivation

Use iterators and ranges for three problems:

- Numerical Sequences
- Dynamical systems
- Convergence algorithms

The range is here a proxy for the algorithm!

The user can look inside the algorithm!

 \longrightarrow Debuggin, logging, combine with other algorithms, \dots

Iterators – Overview

Operations

Increment, dereference, assign, copy, decrement, . . .

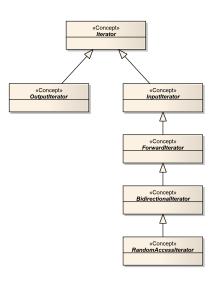
Use cases

• Traverse containers, IO, expressing algorithms

Special iterators

• zip_iterator, transform_iterator, ...

Iterator concepts



Ranges

- Simplify the usage of iterators
- Generalization of iterators
- Ranges in boost:
 - Ranges are pairs of iterators.
 - Ranges can be adapted/decorated.

```
vector< double > values;
// fill values
boost::for_each( values , []( auto x ) {
   cout << x << endl; } );</pre>
```

Ranges for the C++ standard library

Eric Niebler: N4128: Ranges for the Standard Library.

- Ranges are based on iterators
- New concepts:
 - Iterable Container, holding the elements
 - Range Lightweight adapters (decorators)
- Three kinds of ranges
 - Iterator pairs, Iterator and a count, Iterator and a predicate
- Variants of each algorithm
 - sort(in);
 - sort(in.begin() , in.end());
 - in | view::transform(op);
 - in | cont::sort(op);

In numerical algorithms one needs often sequences of numerical values

- As part of an algorithm
- Reference data
- Test data

```
int n = 1024;
auto seq = boost::counting_range( 0 , n );
for( auto x : seq )
    cout << x << " ";</pre>
```

```
0 1 2 3 ...
```

Range is a proxy object for the sequence

```
using namespace boost::adaptors;
auto seq = boost::counting_range( 0 , n );
auto seq2 = seq | transformed([]( auto x ) {
   return 0.1 * static_cast< double >( x ); } );

for( auto x : seq2 )
   cout << x << " ";</pre>
```

```
0 0.1 0.2 0.3 ...
```

Range is a proxy object for the sequence

```
auto seq = boost::counting_range( 0 , n );
auto seq2 = seq | transformed( [] ( auto x ) {
    return 0.01 * static_cast< double >( x ); } );
auto seq3 = seq2 | transformed( [] ( auto x ) { return sin(
    2.0 * x ) + 0.1; } );

for( auto x : seq3 )
    cout << x << " ";</pre>
```

```
0.1 0.298669 0.489418 0.664642 ...
```

Use a function

```
auto sequence( int n , double sampling , auto f ) {
    auto seq = boost::counting_range( 0 , n );
    return seq | transformed( [sampling,f]( auto x ) {
        return f(sampling*static_cast<double>( x ) ); } );
}

auto seq = sequence(1024 ,0.1 ,[]( auto x ) {
    return sin(2.0*x)+0.1;} );
for( auto x : seq )
    cout << x << " ";</pre>
```

```
0.1 0.298669 0.489418 0.664642 ...
```

Numerical ranges and standard C++ ranges

Infinite sequences:

```
using std::view;
auto sequence( double sampling , auto f ) {
   return iota(0) | transform( [sampling,f]( auto x ) {
     return f( sampling * x ); } );
}

for( auto x : take( sequence( 0.1 , f ) , 10 ) )
   cout << x << endl;</pre>
```

Custom break conditions:

```
auto seq = take_while( sequence( 0.1 , f ) , []( auto x ) {
    return x < 1.0; } );
for( auto x : seq )
    cout << x << endl;</pre>
```

Numerical Ranges and standard C++ ranges

Zip sequences:

```
using std::view;
auto seq1 = sequence( 1024 , 0.01 , f1 );
auto seq2 = sequence( 1024 , 0.01 , f2 );
auto seq3 = zip( seq1 , seq2 );
for( auto x : seq3 )
    cout << std::get<0>(x) << " "<< std::get<1>(x) << "\n";</pre>
```

Append sequences:

```
auto seq3 = join( seq1 , seq2 );
```

Cartesian sequences - missing yet

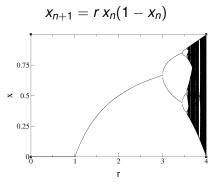
Dynamical systems

Dynamical systems - Maps

Map – time discrete dynamical system:

$$x_{n+1} = f(x_n)$$

Example: Logistic map



Map range

Abstraction for $x_{n+1} = f(x_n)$

Two versions:

- map_range stop predicate
- 2 counted_map_range iterates n-times

Models the SinglePassRange concept

Map range

```
template< typename T , typename F , typename C >
class map_range
   struct iterator { ... };
  public:
    map_range( T value , F func , C condition )
    : m value { std::move( value ) }
    , m_func { std::move(func) }
    , m_condition( condition )
    { }
    iterator begin() const { return iterator( this ); }
    iterator end() const { return iterator( nullptr ); }
private:
    mutable T m_value;
    mutable F m_func;
    C m condition;
};
```

Map range

```
struct iterator {
   iterator( map_range const* _r ) : r( _r ) {}
    iterator& operator++() {
        r->m value = r->m func( r->m value );
        if ( r->m condition ( r->m value ) ) {
            r = nullptr:
        return *this:
    T& operator*() const {
        return r->m value; }
   bool operator == ( iterator const& o ) const {
        return ( r == o.r ); }
    bool operator!=( iterator const& o ) const {
        return ! ( *this == o );
    map_range const* r;
};
```

Factory functions

```
template< typename T , typename F , typename C >
auto make_map_range( T t , F f , C condition )
{
   return map_range< T , F , C >(
        std::move( t ) ,
        std::move( f ) ,
        std::move( condition ) );
}
```

```
template< typename T , typename F >
auto make_counted_map_range( T t , F f , size_t
    max_iterations )
{
    return counted_map_range< T , F >(
        std::move( t ) ,
        std::move( f ) ,
        max_iterations );
}
```

Example - logistic map

```
double r = 3.2;
auto l = [r]( auto x ) {return r * x * ( 1.0 - x ); };

auto range = make_counted_map_range( 0.5 , l , 1000 );
for( auto x : range )
{
    cout << x << endl;
}</pre>
```

Dynamical system – cellular automaton

Cellular automaton: Time-discrete and value-discrete

Conway's Game of Life

- Each cell has two states: alive or dead
- Transition rules
 - Less then two neighbors -> dead (under-population)
 - Two or three neighbors -> alive
 - More then three neighbors -> dead (over-population)
 - Dead cell with three neighbors -> alive (reproduction)

Game of life – patterns









Still lifes: Oscillators:

Conway's game of life

```
using board = vector< vector< bool > >;
auto show_board = []( board const& b ) { ... }
auto next_board = []( board const& b ) -> board { ... }

board b;
// initialize b

auto r = make_counted_map_range( b , next_board , 1000 );
for( auto b : r )
{
    show_board( b );
}
```

Map range for time discrete dynamical systems

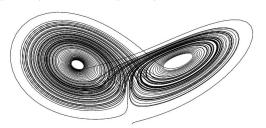
- The range is a proxy for the dynamical system
 - Customizable iteration body
 - Custom stopping criterions
 - N-times iteration
- Not optimized a custom range could be optimized

Dynamical systems – ODEs

$$\frac{\mathrm{d}x}{\mathrm{d}t}=f(x,t)$$

Example: Lorenz attractor

$$\dot{\mathbf{x}} = \sigma(\mathbf{y} - \mathbf{x})$$
 , $\dot{\mathbf{y}} = \mathbf{x}(\rho - \mathbf{z}) - \mathbf{y}$, $\dot{\mathbf{z}} = \mathbf{x}\mathbf{y} - \beta\mathbf{z}$



Numerical solution: $x(t + \Delta t) = F(x(t))$

Example – ODE solver

Solve $\dot{x} = f(x, t)$, Solver $F : x(t + \delta t) = F(x(t))$ Example Boost.Odeint:

Integrate functions:

```
auto obs = []( auto x , auto t ) { std::cout << t << " " << x[0] << "\n"; }; odeint::integrate_const( stepper , lorenz , x , 0.0 , 10.0 , dt , obs );
```

Example – ODE solver

```
auto make_ode_range( auto sys , auto stepper , auto x ,
    auto t0 , auto dt , auto t1 )
{
    auto solve = [sys,stepper,dt]( auto x ) mutable {
        stepper.do_step( sys , x.first , x.second , dt );
        x.second += dt;
        return x; );
    auto cond = [t1]( auto const& x ) { return x.second > t1; };
    auto range = make_map_range( std::make_pair(x,t0) , solver , cond );
    return range;
}
```

Can be used as

```
state_type x {{ 10.0 , 10.0 , 10.0 }};
stepper_type stepper;
auto range = make_ode_range( lorenz , stepper , x , 0.0 , 0.1 , 100.0 );

for( auto r : range )
    std::cout << r.second << " " << r.first[0] << " " << r.first[1] << "\n";</pre>
```

ODE ranges

Superior to integrate functions:

- Break conditions are easy
- ODE-Ranges can be used in a natural C++ way, find, transform, etc.

Map implementation has drawbacks -> custom implementation

- Better performance.
- Step size control complicated iteration.
- Break condition can use the last two values.

Convergence methods

Newton method

Find the root: 0 = f(x)

Newtons method

- Choose x_0
- Iterate $x_{n+1} = x_n \frac{f(x_n)}{f'(x_n)}$

Newton method – Implementation

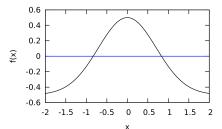
```
auto newton_range(
  auto x , auto f , auto df ,
  auto break_condition )
{
  return make_map_range(
          x ,
          [f,df]( auto x ) { return x - f( x ) / df( x ); } ,
          break_condition );
}
```

Newton method – Example

Solve $\exp(-x^2) - 0.5 = 0$

```
auto f = []( auto x ) { return exp(-x*x) - 0.5; };
auto df = []( auto x ) { return -2.0*x * exp(-x*x); };
auto cond = [f]( auto x ) {
   return std::abs(f(x)) < 1.0e-12; };
auto range = newton_range( 1.0 , f , df , cond );

for( auto r : range )
   std::cout << r << " : " << f( r ) << std::endl;</pre>
```



Similar problems

- Optimizations methods
 - Broyden-Fletcher-Goldfarb-Shanno algorithm (BFGS)
 - Simulated annealing
 - Genetic algorithms
 - Genetic programming
 - ...
- Approximation of functions
- ...

Conclusion

- Iterators and ranges can be used for numerical problems
 - Numerical sequences, dynamical systems, optimization methods, ...
- Range is a proxy for the algorithm
- Custom range implementation needed for optimal performance

Outlook - open points

- Break condition on last two values, e.g. $|v_k v_{k-1}| < \epsilon$
- More complicated break condition, e.g. count and predicate

References

- www.odeint.com
- github.com/headmyshoulder/iterator-talks
- github.com/headmyshoulder/map_iterator

Backup

Example – basic use

```
for( auto iter = values.begin() ;
    iter != values.end() ;
    ++iter )
{
    cout << *iter << endl;
}</pre>
```

Example – basic use

```
for( auto iter = values.begin() ;
    iter != values.end() ;
    ++iter )
{
    cout << *iter << endl;
}</pre>
```

C++11 - use range based for

```
for( auto v : values )
{
    cout << v << endl;
}</pre>
```

Example – Container traversal

```
list< double > values;
list< double > values2( values.size() );
```

Can be used in

Example – Container traversal

```
vector< double > values;
vector< double > values2( values.size() );
```

Can be used in

Examples – IO

Input

Output

Algorithms

F find_end F iter_swap R nth element B new I,F find_first_if B reverse F lower_bound F ion F adjacent_find B,O reverse_copy F upper_bound F ion F search F rotate F search_n F,O rotate_copy I,O copy R random_shuffle I,O more I,O copy_n F unique I includes I,O unique_copy I,O set_difference I,O set_difference I,O set_symmetric_difference I,O transform F generate I includes I,O set_unition I,O set_				
	I any_of I none_of I none_of I for_each I count I count_if I mismatch I equal I find I find_if I find_if, I find_first_if F adjacent_find F search F search I,0 copy I,0 copy_if I,0 copy_n B,0 copy_backward I,0 move B,0 move_backward F fill F fill_n I,0 transform	F remove_if I,O remove_copy I,O remove_copy_if F replace F replace_if I,O replace_copy I,O replace_copy_if F swap_ranges F iter_swap B reverse B,O reverse_copy F rotate F,O rotate_copy R random_shuffle R shuffle F unique	F,B partition I,O partition_copy B stable_partition F partition_point F is_sorted F is_sorted_until R sort R partial_sort I,R partial_sort_copy R stable_sort R nth element F lower_bound F upper_bound F binary_search F equal_range I,O merge B inplace_merge I includes I,O set_difference I,O set_symmetric_difference	R is R male R pus R pos R sooj F mar F mir I les B pre F iot I acc

```
s_heap
s heap until
ake_heap
ush_heap
op_heap
ort_heap
ax element
in element
inmax element
exicographical_compare
s_permutation
ext_permutation
rev_permutation
ccumulate
nner_product
adjacent_difference
partial sum
```

Examples – generalized iota

Generalized lota:

```
size_t n = 10;
auto iota = make_counted_map_range( 1 , []( auto x ) {
    return x * 2; } , 10 );

std::vector< int > values;
boost::copy( iota_range , std::back_inserter( values ) );
for( auto i : values ) { cout << i << endl; }</pre>
```

Examples – generalized iota

Problem: We can not easily generate a square iota: 1, 4, 9, 16, 25, 36, ...

Examples – generalized iota

Problem: We can not easily generate a square iota:

1, 4, 9, 16, 25, 36, ...

Introduce a projected map range.

Map range - applications

- Generalized iota
- Ordinary differential equations
- Maps (dynamical maps)
- Functional random number generators
- Opmization methods
 - Genetic algorithms, Simulated annealing, ...

Map range - applications

- Generalized iota
- Ordinary differential equations
- Maps (dynamical maps)
- Converging algorithms
- Functional random number generators

Iterators for GPUs algorithms

High-level libraries for GPUs

- Thrust
- VexCL
- Boost.Compute
- ViennaCL
- Cuda-MTL

Thrust

Thrust is STL-like library for Cuda – Based on iterators.

```
thrust::host_vector<int> h_vec( 1024 );
std::generate(h_vec.begin(), h_vec.end(), rand);
thrust::device_vector<int> d_vec = h_vec;
thrust::sort(d_vec.begin(), d_vec.end());
thrust::copy(d_vec.begin(), d_vec.end(), h_vec.begin());
```

Iterators in Thrust

- device_vector< T >::iterator
- host_vector< T >::iterator
- Special (fancy) iterator
 - zip_iterator
 - transform_iterator
 - permutation_iterator
 - constant_iterator, counting_iterator, discard_iterator, reverse_iterator

Custom algorithms

Special iterators for Thrust

Calculate the norm of a vector

$$||x|| = \sum_{i=1}^{N} x_i^2$$

```
thrust::device_vector< double > x;
// fill x
double n = thrust::reduce(x.begin(), x.end(), 0.0); // ?
```

Special iterators for Thrust

Calculate the norm of a vector

$$||x||=\sum_{i=1}^N x_i^2$$

```
thrust::device_vector< double > x;
// fill x

auto op = []( auto x , auto y ) { return x + y*y; };
double n = thrust::reduce(x.begin() ,x.end() ,0.0 ,op); //
?
```

Special iterators for Thrust

Calculate the norm of a vector

$$||x|| = \sum_{i=1}^N x_i^2$$

```
thrust::device_vector< double > x;
// fill x

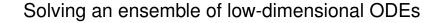
op = []( auto x ) { return x*x; };
double n = thrust::reduce(
    thrust::make_transform_iterator(x.begin(), op) ,
    thrust::make_transform_iterator(x.end(), op), 0.0);
// correct
```

SAXPY

$$s = ax + y$$

Special problems - and solutions

Bucket sort



Lorenz example and ODEs