

# Special Topics in Applied Mathematics I

## Solution 1

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### Question 1

#### Iterative eigenvalue methods: an intuitive story

Think of a matrix  $A$  as a machine that acts on vectors: it can rotate, shear, and stretch them. Most directions are changed in complicated ways, but some special directions come back pointing the same way after applying  $A$ . Those directions are *eigenvectors*  $v \neq 0$  satisfying

$$Av = \lambda v,$$

where  $\lambda$  is the corresponding *eigenvalue* (the factor by which  $A$  stretches  $v$ ). When matrices are large, computing all eigenvalues exactly (e.g., from a characteristic polynomial) is impractical and numerically fragile. Iterative methods instead exploit one operation we can often do efficiently: repeatedly multiply by  $A$  (or solve linear systems involving  $A$ ).

#### Power iteration: repeated multiplication reveals the dominant direction

The simplest method is *power iteration*. Choose any nonzero starting vector  $b_0$  and repeat:

$$\begin{aligned} c_{k+1} &= Ab_k, \\ b_{k+1} &= \frac{c_{k+1}}{\|c_{k+1}\|}. \end{aligned}$$

Normalization “resets the length” so we can watch the direction. The method tends to align  $b_k$  with the eigenvector associated with the eigenvalue of largest magnitude.

**Why it converges (qualitative).** Assume  $A$  is diagonalizable with eigenpairs  $(\lambda_i, v_i)$  and  $|\lambda_1| > |\lambda_2| \geq \dots$ . Write the starting vector as a combination of eigenvectors:

$$b_0 = \sum_{i=1}^n \alpha_i v_i \quad (\alpha_1 \neq 0).$$

Then

$$A^k b_0 = \sum_{i=1}^n \alpha_i \lambda_i^k v_i = \lambda_1^k \left( \alpha_1 v_1 + \sum_{i=2}^n \alpha_i \left( \frac{\lambda_i}{\lambda_1} \right)^k v_i \right).$$

As  $k$  grows, the ratios  $\left( \frac{\lambda_i}{\lambda_1} \right)^k$  shrink toward 0, so the direction of  $A^k b_0$  becomes dominated by  $v_1$ . The convergence speed is governed by the spectral gap; a common rule of thumb is that the directional error shrinks like

$$\left| \frac{\lambda_2}{\lambda_1} \right|^k.$$

## Estimating the eigenvalue: Rayleigh quotient

Once we have an approximate eigenvector  $x$ , a natural estimate of its eigenvalue is the *Rayleigh quotient*

$$R(x) = \frac{x^\top A x}{x^\top x}.$$

If  $x$  is exactly an eigenvector  $v$ , then  $R(v) = \lambda$  because  $v^\top A v = v^\top (\lambda v) = \lambda v^\top v$ . When  $x$  is close to an eigenvector,  $R(x)$  typically gives a good scalar approximation of the associated eigenvalue, so one can monitor the sequence  $R(b_k)$  during power iteration.

## Question 2

## Appendix

AI conversation for Q1: <https://www.perplexity.ai/search/i-am-going-to-introduce-how-it-YmfU>  
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