## **Instruction manual**

## **Thorlabs Instrumentation**

## **DCU USB 2.0 Cameras**

# **Development Kit (SDK)**



2007





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#### **Preface**

We have taken every possible care in preparing this manual. Nevertheless, we are unable to provide any guarantee with regard to content, entirety or quality of the details contained in this manual. The contents of this manual are revised regularly and brought up to latest standards. Furthermore, we are also unable to guarantee that the product will operate fault-free even if the specifications and recommended computer configuration are observed.

Under no circumstances whatsoever are we able to guarantee that a specific application objective can be achieved with the purchase of this product.

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## 1 Introduction

Thank you for your decision to purchase a camera of the *Thorlabs GmbH*. This manual describes the operation mode of the DCU camera family.

The DCU cameras are made for industrial, medical and multimedia applications in monochrome and colour. The cameras support USB standard 2.0 or higher. The images are available in 8 bit monochrome resp. 24 bit true colour quality.

To integrate a DCU camera into own programs under Windows 2000, Windows XP and Linux a SDK (software development kit) is contained in the scope of delivery.

This manual describes the functions of the DCU Software Development Kit (SDK).

Please, read the file *WhatsNew.txt*, which is on the installation CD. Here you can find additional information, which are possibly not contained in the printed edition of the manual.

We would like to wish you every success with the product.

## 2 Programming

### 2.1 Programming with Visual C++ 6.0, 7.0, 7.1 and 8.0

### NOTE

Please note that Microsoft modified the format of the lib File starting from version 6.0. The DCU driver has been created with Visual C++ 7.1. Thus the file uc480.lib is to be used only with a compiler of the version 6.0 or higher.

### 2.2 Programming with Visual Basic

The functions of the software development kit are exported with the call convention "\_cdecl". Visual BASIC needs however functions with the convention "\_stdcall " (pascal convention). You can call up the DCU functions directly from Visual BASIC, if you replace the functions is\_<function name> by iss\_<function name>.

All in this manual described "is\_<Function name>" functions are \_cdecl functions. \_stdcall functions exist parallel to these functions as "iss\_<Function name>". Function parameters and return values are identical.

### 2.3 CAMINFO – data structure of the EEPROM

Using the *is\_GetCameraInfo()* function the data which has been written to the DCU camera can be read out. The data structure (64 Byte) is build up as follows:

Char SerNo[12] serial number of the camera
Char ID[20] e.g. "Thorlabs GmbH"
Char Version[10] "V1.00" or later versions

Char Date[12] "01.08.2004" date of quality check

unsigned char Select Camera ID unsigned char Type Camera type

64 = DCU USB2.0

Char Reserved[8] reserved

Table 1: CAMINFO data structure of the EEPROMS

### 2.4 Colour formats

Each of the colour formats supported by the DCU cameras has a different memory format. These are shown in the following table:

	Pixel Data			
Format	Byte 3 [Bit 31:24]	Byte 2 [Bit 23:16]	Byte 1 [Bit 15:8]	Byte 0 [Bit 7:0]
RGB32				
RGB24				
RGB16				
RGB15				
UYVY	Y1	V0	Y0	U0
Y8	Y3	Y2	Y1	Y0

Table 2: Colour formats

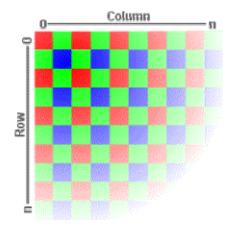


Fig. 1: Principle structure of the Bayer-Pattern

### **HINT**

In the case of the RGB16 and RGB15 data formats, from the internal 8 bits the upper ones are in use from R, G and B colours

### 2.5 Possible image output modes

### Bitmap Mode (BMP/DIB)

Once the *Camera viewer (uc480Viewer)* sample application has been started the bitmap mode is activated. The image from the DCU camera is stored in the main memory of the PC. The live video display has to be programmed by the user. This should be done by using the CPU to generate a bitmap and then copying it to the VGA board. The great advantage of this mode is that it is compatible with all VGA cards and it is possible to access the image data in the memory. Overlay functions have to be programmed by the user. As Windows takes over the control of the image display, the image can be completely or partly overlapped by many other windows and dialog boxes.

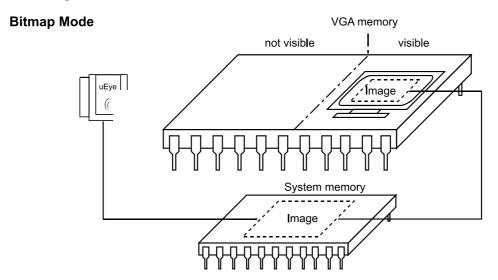


Fig. 2: Bitmap Mode

### DirectDraw BackBuffer mode (not available under LINUX)

In this mode, the image data is written to the non-visible area of the VGA card. The requirements for this are: installed DirectDraw driver, sufficient memory on the VGA card and back buffer support from the VGA cards' manufacturer. In overlay mode three non-visible image buffers are used:

- BackBuffer
- OverlayBuffer
- MixBuffer.

The size of the three buffers is: video\_x \* video\_y \* color depth (in bytes per pixel). The video image is written into the back buffer. The graphics data can be written in the overlay buffer (see also <u>4.28 is GetDC</u> and <u>4.65 is ReleaseDC</u>). The overlay is not always faded on. It has to be made visible with <u>is\_ShowDDOverlay()</u> (see <u>4.119 is\_ShowDDOverlay</u>). As its key color, the overlay uses black, thus an overlay cannot contain any black color.

BackBuffer and OverlayBuffer are written into the MixBuffer. The overlay data is overlaid on the video image. The mix buffer is then copied to the visible area of the VGA card. The result is an live image with overlaid text and graphic overlay. The frame rate and the load of the CPU depend on the adjusted colour depth and on the place (system memory of the PC or memory of the VG card) of the BackBuffer.

The driver tries to allocate the buffers directly in the VGA card in order to use the cards highspeed image transfer when mixing the three buffers. If this allocation fails the buffers are stored in the system memory, from which image transfers may be slower and, depending on the graphics card, sometimes not possible at all. A scaling of the video picture is not possible in the BackBuffer mode.

The BackBuffer mode is set as follows:

Mode = IS\_SET\_DM\_DIRECTDRAW | IS\_SET\_DM\_BACKBUFFER

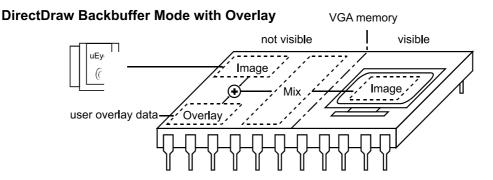


Fig. 3: DirectDraw Back-Buffer Mode

### DirectDraw overlay surface mode (not available under LINUX)

In this mode, a live image and at the same time display of the overlay can be achieved. The video image is digitized to a non-visible area of the VGA board. This area always has to be on the VGA board. By defining a key colour and drawing with that colour to the output window, the video image will be displayed only in those parts where the key colour is used. When the window is filled with the key colour, the video image is displayed completely. Graphics and text elements which use a different colour will not be destroyed (non-destructive overlay).

The fading is done by the VGA chip and requires hardly any CPU cycles. This mode is not supported by all VGA chips and only in 8, 15, and 16 bit mode available.

The best text and graphics overlay is achieved with the following video mode: Mode = IS\_SET\_DM\_DIRECTDRAW | IS\_SET\_DM\_ALLOW\_OVERLAY

If the video image should be scaled to the size of a window, the following can be used:

Mode = IS\_SET\_DM\_DIRECTDRAW | IS\_SET\_DM\_ALLOW\_OVERLAY | IS\_SET\_DM\_ALLOW\_SCALING

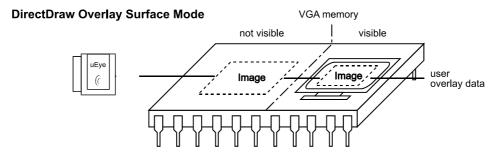


Fig. 4: DirectDraw Overlay-Surface-Mode

### **HINT**

The Back Buffer mode of the FALCON frame grabber is activated by setting the parameter IS\_SET\_DM\_DIRECTDRAW. The BackBuffer mode of the DCU

cameras is activated as follows: IS\_SET\_DM\_DIRECTDRAW | IS\_SET\_DM\_BACKBUFFER.

## 3 Function lists

### 3.1 Initialization und termination

#### **Function list**

cated with the SDK

is\_InitCamera Hardware initialization

is\_LoadParameters Load and use the camera parameters is\_SaveParameters Save the current camera parameters

is\_SetCameraID Sets a new camera ID

Table 3: Function list Initialization und termination

### 3.2 Image acquisition and memory management

### **Function list**

is\_AllocImageMem Allocates image memory is\_CaptureVideo Acquires live video

is\_ConvertImage Converts the Raw Bayer input picture to the desired format is\_CopyImageMem Copies image to memory as defined by programmer is\_CopyImageMemLines Copies single lines to memory as defined by programmer

is\_FreeImageMem Frees allocated image memory

is\_FreezeVideo Acquires image and writes to destined frame buffer is\_GetActiveImageMem Returns number and address of active image memory is\_GetBusSpeed Returns whether the camera is connected to a USB 2.0 host

controller.

is\_GetImageHistogram Calculates the histogram of the given picture is\_GetImageMem Returns start pointer to image memory

is\_GetImageMemPitch
is\_HasVideoStarted
is\_InquireImageMem
is\_IsVideoFinish
is\_SaveImageMem
Returns line offset (n) to (n+1)
Has the image acquisition started?
Returns image memory's properties
Has the image acquisition finished?
Save image memory as bitmap

cording

is\_SetBayerConversion Selects Bayer algorithm is\_SetImageMem Activates an image memory is\_SetTestImage Activates test images

is\_StopLiveVideo Terminates the recording (continuous or single frame)

Table 4: Function list Image acquisition and memory management

### 3.3 Selection of operating modes and return of properties

#### **Function list**

is\_CameraStatus Gets event counter and counter value

is\_GetAutoInfo Returns status informationen of the auto functionality is GetCameraList Gets information about the connected cameras

is\_GetCameraType Gets type of camera (e.g. DCU USB)
is\_GetColorDepth Gets current colour mode from VGA card

is\_GetDLLVersion Returns the version of uc480.dll

is\_GetError Calls error message

is\_GetExposureRange Determines the exposure range is\_GetFramesPerSecond Return current frame rate in live mode is\_GetFrameTimeRange Determines the range of the frame rate is\_GetNumberOfCameras Detects the number of attached cameras

is\_GetOsVersion Calls operating system type

is\_GetPixelClockRange returns the adjustable range for the pixel clock

is\_GetUsedBandwidth Sum of the current pixel clocks is\_GetVsyncCount Output of VSYNC counter

is\_GetWhiteBalanceMultipliers Readout the current white balance parameters is\_LoadBadPixelCorrectionTable Load a user defined hot pixel list from a file

is\_PrepareStealVideo Sets the steal mode

is\_ResetToDefault Reset the camera parameters to default values is\_SaveBadPixelCorrectionTable Stores the current, user-defined hot pixel list

is\_SetAOI Set size and position of an AOI

is\_SetAutoParameter Aktivates/deactivates Gain/Shutter/Whitebalance auto func-

tionality

is\_SetBadPixelCorrection Activate, deactivate and parameterise hot pixel correction

is\_SetBinning Controls the binning mode

is\_SetBlCompensation Activates/deactivates the black level compensation

is\_SetBrightness Sets brightness (digital reworking)

is\_SetColorCorrection Sets colour correction is\_SetColorMode Selects colour mode

is\_SetContrast Sets contrast (digital reworking)

is\_SetConvertParam Sets the conversion parameters for the Raw Bayer image

is\_SetDisplayMode Selects image display mode

is\_SetEdgeEnhancement Sets edge filter

is\_SetErrorReport Activates or deactivates error output

is\_SetExposureTime Set the exposure time is\_SetFrameRate Set the frame rate

is\_SetGainBoost Acitvates/deactivates the additional hardware gain

is\_SetGamma Set the gamma value (digital reworking) **Fehler! Verweisquelle konnte nicht** Activates or deactivates the *global start shutter* 

Fehler! Verweisquelle konnte nicht gefunden werden.

is\_SetHardwareGain Adjusting the hardware gain

is\_SetHardwareGamma Activates/deactivates the gamma control of the camera

is\_SetHWGainFactor Controlling of the camera amplifiers
is\_SetHwnd Controlling of the camera gain
is\_SetImageAOI Sets image position and image size
is\_SetImagePos Sets image position within image window

is\_SetImageSize Sets the size of the image is\_SetLED Switch LED on/off

OWNOR LLD ON/OR

is\_SetPixelClock Set pixel clock

is\_SetRopEffectSets real time ROP effectsis\_SetSaturationSets the software image saturationis\_SetSubSamplingControls the subsampling mode

is\_SetWhiteBalance Activate white balance

is\_SetWhiteBalanceMultipliers Set the white balance parameters

Table 5: Function list Selection of operating modes and return of properties

### 3.4 Double and multi buffering

#### **Function list**

is\_AddToSequence Records image memory in sequence list

is\_ClearSequence Delete complete sequence list

is\_GetActSeqBuf Determines the image memory which is currently being used

for the sequence.

is\_LockSeqBuf Protects image memory of the sequence from being overwrit-

ten.

is\_UnlockSeqBuf Allows image memory of the sequence to be overwritten.

Table 6: Function list Double and multi buffering

### 3.5 Reading from and writing to EEPROM

### **Function list**

is\_GetCameraInfo Reads pre-programmed manufacturer's information is\_GetRevisionInfo Revision information of the individual DCU components

is\_GetSensorInfo Readout the sensor information is\_ReadEEPROM Reads own data from EEPROM Writes own data to EEPROM

Table 7: Function list Reading from and writing to EEPROM

## 3.6 Saving and loading images

### **Function list**

is\_LoadImage Load bitmap file in the current image memory

is\_LoadImageMem Loads an image from a file

is\_SaveImage Saves video image as a bitmap (BMP) is\_SaveImageEX Saves an video image to a file

is\_SaveImageMem Saves image memory as a bitmap (BMP)

is\_SaveImageMemEx Saves an image to a file

Table 8: Function list Saving and loading images

### 3.7 Image output

#### **Function list**

is\_RenderBitmap Displays images in a window

is\_SetDisplayPos Enables the offset for the image output is\_UpdateDisplay Displays refresh with DirectDraw

Table 9: Function list Image output

### 3.8 Supplementary DirectDraw functions

### **Function list**

is\_DisableDDOverlay Deactivates the overlay mode is\_EnableDDOverlay Activates the live overlay mode

is GetDC Retrieves the device context handle's overlay memory

is\_GetDDOvlSurface Returns pointer to the DirectDraw surface

is\_HideDDOverlay Fades out the overlay

is\_LockDDMem Enables VGA card to access the back buffer

is\_LockDDOverlayMem Enables access to overlay memory

is\_ReleaseDC Releases the device context handle's overlay memory

is\_SetDDUpdateTime Timer interval for update cycle

is\_SetKeyColor Sets the keying colour for the overlay display

is\_ShowDDOverlay Fades on the overlay

is\_StealVideo Steals an image from a DirectDraw live mode and puts this

down into the image memory in the RAM

is\_UnlockDDMem Disables VGA card to access the back buffer

is\_UnlockDDOverlayMem Disables access to overlay memory

Table 10: Function list Supplementary DirectDraw functions

## 3.9 Event Handling

#### **Function list**

is\_DisableEvent Lock the event objects is\_EnableEvent Release the event objects

is\_EnableMessage Activating/deactivating the windows messages

is\_ExitEvent Quit the event handle is\_InitEvent Setup the event handle

is\_EnableAutoExit Camera resources are released automatically when tak-

ing the USB cable off

Table 11: Function list Event Handling

### **Events with single trigger recording**

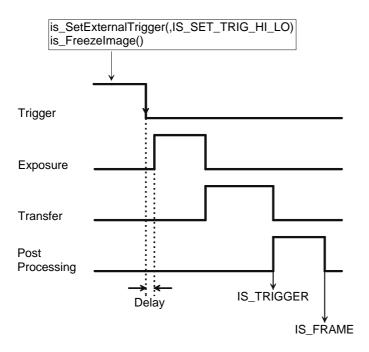


Fig. 5: Events with single trigger recording

### Events in live mode (sequence of 3 images)

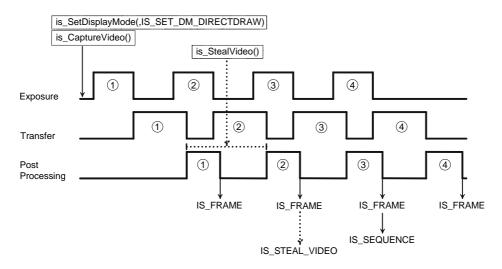


Fig. 6: Events in live mode

### **Events in memory mode**

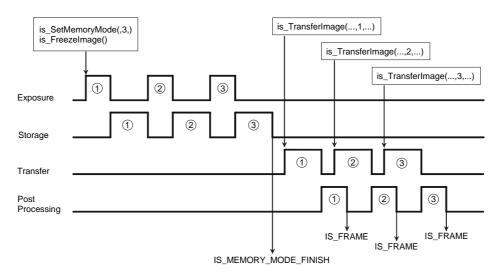


Fig. 7: Events in memory mode

### 3.10 Control of inputs / outputs

### **Function list**

is\_ForceTrigger Release a hardware trigger.

is\_GetGlobalFlashDelays Determine delay and duration of the flash output for cameras

with rolling shutter.

is\_SetExternalTrigger Activate external trigger input or the static input is\_SetFlashDelay Set delay and duration of the flash output is\_SetFlashStrobe Set the flash / strobe output or the static output

is\_SetIO (only UI-1543-M)
Set the additional digital outputs
is\_SetTriggerDelay
Specify a delay time of a trigger signal

Table 12: Function list Control of sync generator and input / outputs

## 3.11 Validity of functions

Some of the functions are responsible for all display modes, whereas others are only for Direct-Draw display modes. In the following tables the validity of each function is listed.

Funktion	Ditmon	DD-BackBuffer	DD Overley
runkuon	Bitmap	Surface	DD-Overlay Surface
is_AddToSequence	$\boxtimes$		
is_AllocImageMem	$\boxtimes$	*	*
is_CaptureVideo	X	X	X
is_ClearSequence	$\boxtimes$		
is_ConvertImage	X		
is_CopyImageMem	$\boxtimes$	*	*
is_CopyImageMemLines	X	*	*
is_DisableDDOverlay	_	$\boxtimes$	
is_EnableDDOverlay		$\boxtimes$	
is_FreeImageMem	$\boxtimes$	*	*
is_FreezeVideo	$\boxtimes$	$\mathbf{x}$	×
is_GetActiveImageMem	$\boxtimes$		Δ.
-	X		
is_GetActSeqBuf	凸		[ <del>\texts</del> ]
is_GetDC		X	X
is_GetDDOvlSurface		X	
is_GetImageHistogram	<b>X</b>	*	*
is_GetImageMem	$\boxtimes$	X	X
is_GetImageMemPitch	X	*	*
is_GetVsyncCount	X	X	$\boxtimes$
is_HasVideoStarted	X	X	$\boxtimes$
is_HideDDOverlay		X	
is_InquireImageMem	$\boxtimes$	*	*
is_IsVideoFinish	$\boxtimes$	$\boxtimes$	X
is_LoadImage	X		
is_LoadImageMem	X		
is_LockDDMem		$\boxtimes$	X
is_LockDDOverlayMem		X	
is_LockSeqBuf	×		
is_PrepareStealVideo	X	X	X
is_ReleaseDC		X	X
is_RenderBitmap	$\boxtimes$		
is_SaveImage	$\boxtimes$	$\boxtimes$	X
is_SaveImageEX	$\boxtimes$	$\boxtimes$	×
is_SaveImageMem	<u> </u>	*	*
is_SaveImageMemEx	$\boxtimes$	*	*
is_SetAllocatedImageMem	$\boxtimes$	*	*
is_SetBayerConversion	$\boxtimes$	<b>→</b> ⊠	×
is_SetBinning	×	X	X
is_SetColorMode	X	× ×	X
is_SetConvertParam	X	×	×
is_SetDisplayMode	×	<u>N</u>	<u> </u>
is_SetDisplayPos	$\boxtimes$		F-7
is_SetHwnd	-	<b>X</b>	<b>X</b>
is_SetImageMem	$\boxtimes$	*	*
is_SetImagePos	$\boxtimes$	$\boxtimes$	$\boxtimes$
is_SetImageSize	×	$\boxtimes$	<b>X</b>
is_SetKeyColor			X

is_SetRopEffect	X	X	X
is_SetSaturation			X
is_SetSubSampling	X	X	X
is_ShowDDOverlay		X	
is_StealVideo		X	X
is_StopLiveVideo	X	X	X
is_UnlockDDMem		X	X
is_UnlockDDOverlayMem		X	
is_UnlockSeqBuf	X		
is_UpdateDisplay		X	$\boxtimes$

<sup>\*</sup> only in steal mode; memory in DD modes not neccessary

Table 13: Validity of functions

### **HINT**

DirectDraw is not supported under LINUX

## 4 Description of the functions

To aid the integration of the DCU cameras into your own programs, the functions from the driver library, which are shipped with the camera, are described in this section. The functions are sorted alphabetically and structured as follows:

### <Name of function>

### Syntax:

Function prototype from the header file uc480.h

### **Description:**

Function description with cross reference to affected functions

#### Parameters:

Description of the function parameters with range of values

#### Return value:

Description and range of return value. If function returns IS\_NO\_SUCCESS (-1), the error can be called with the function *is\_GetError()*.

The source code of the example program *Camera Viewer.EXE*, which uses the DCU library, is delivered with the camera on the installations-CD. In the source code the initialization of and access to the camera is shown as well as the various operating modes.

### 4.1 is\_AddToSequence

### Syntax:

INT is\_AddToSequence (HIDS hf, char\* pclmgMem, INT nID)

### **Description:**

*is\_AddToSequence()* inserts image memory into the image memory list, which is to be used for ring buffering. The image memory has to be allocated with *is\_AllocImageMem()*. All image memory which is used for ring buffering must have been allocated the same colour depth (i.e. bits per pixel). The number of image memories for a sequence (nID) is limited to the integer value range.

### Parameters:

hf Camera handle

pcMemPointer to image memorynIDID of image memory

### Return value:

IS\_SUCCESS, IS\_NO\_SUCCESS

### 4.2 is\_AllocImageMem

### **Syntax**

INT is\_AllocImageMem (HIDS hf, INT width, INT height, INT bitspixel, char\*\* ppcImgMem, INT\* pid)

### **Description:**

is\_AllocImageMem() allocates image memory for an image with width, width and height, height and colour depth bitspixel. Memory size is at least:

```
size = [width * ((bitspixel + 1) / 8) + adjust] * height adjust see below
```

Line increments are calculated with:

line = width \* [(bitspixel + 1) / 8]

lineinc = line + adjust.

adjust = 0 when *line* without rest is divisible by 4

adjust = 4 - rest(line / 4) when line without rest is not divisible by 4

The line increment can be read with the *is\_GetImgMemPitch()* function.

The start address in the image memory is returned with *ppclmgMem*.

pid contains an identification number of the allocated memory. A newly activated memory location is not directly activated. In other words, images are not directly digitized to this new memory location. Before this can happen, the new memory location has to be activated with <code>is\_SetImageMem()</code>. After <code>is\_SetImageMem()</code> an <code>is\_SetImageSize()</code> must follow so that the image conditions can be transferred to the newly activated memory location. The returned pointer has to be saved and may be reused, as it is required for all further ImageMem functions! The freeing of the memory is achieved with <code>is\_FreeImageMem()</code>.

In the DirectDraw modes, the allocation of an image memory is not required!

### **HINT**

Most operating Systems begin to swap older parts of the main memory to the hard disk, if there is a lack of free physical main memory. Because of this, image acquisition could become slower, if there was more Image memory allocated than can be kept in the physical main memory at the same time.

#### Parameters:

hfCamera handlewidthWidth of imageheightHeight of image

bitspixelColour depth of image (bits per pixel)ppcImgMemContains pointer to start of memory locationpidContains the ID for this memory location

### Return value:

IS\_SUCCESS, IS\_NO\_SUCCESS

### 4.3 is\_CameraStatus

### Syntax:

ULONG is\_CameraStatus (HIDS hf, INT nInfo, ULONG ulValue)

### **Description:**

*is\_CameraStatus()* returns various status information and settings. Some of the settings can be changed with *is\_CameraStatus()*.

### Parameters:

hf nInfo	Camera handle
IS_FIFO_OVR_CNT	Number of FIFO Overruns. Will be increased each time image data is lost due to USB bus overload.
IS_SEQUENCE_CNT	Is set to zero with <i>is_CaptureVideo()</i> . With each change of the sequence Buffers (image counter) the increase takes place by 1.
IS_SEQUENCE_SIZE	Number of sequence buffer (read only)
IS_EXT_TRIGGER_EVENT_CNT	Trigger interrupt counter
IS_CAMERA_REVISION	Returns the hardware revision of the camera (read only).
IS_WAIT_TIMEOUT	Timeout for hardware trigger (on use with IS_WAIT or IS_DONT_WAIT), 1ms steps.
IS_TRIGGER_MISSED	Number of not processed trigger signals. It is set to 0 after each call.
IS_LAST_CAPTURE_ERROR	Error during capturing (read only):
ulValue	

### Return value:

IS\_GET\_STATUS

IS\_SUCCESS, IS\_NO\_SUCCESS or current value of ulValue = IS\_GET\_STATUS

After the event *IS\_SET\_TRANSFER\_FAILED* or the message *IS\_TRANSFER\_FAILED* the occured error can be read out with *IS\_LAST\_CAPTURE\_ERROR*. The following return values are possible:

Read the parameter value for nInfo.

- IS\_SUCCESS
- IS\_TRANSFER\_ERROR Capturing was cancelled.
- IS\_TIMED\_OUT

The maximally permissible capturing time was exceeded.

- IS\_NO\_ACTIVE\_IMAGE\_MEM
   It exists no memory for the image.
- IS\_SEQUENCE\_BUF\_ALREADY\_LOCKED The memory image is not describable.
- IS\_COULD\_NOT\_CONVERT

The current picture could not be converted.

### 4.4 is\_CaptureVideo

### Syntax:

INT is\_CaptureVideo (HIDS hf, INT Wait)

### **Description:**

is\_CaptureVideo() digitizes video images in real time and transfers the images to the previously allocated image memory. Alternatively if you are using DirectDraw the images can be transferred to the graphics board. The image acquisition (DIB Mode) takes place in the memory which has been set by is\_SetImageMem() and is\_AllocImageMem(). Is\_GetImageMem() determines exactly where the start address in memory is. In case of ring buffering, then image acquisition loops endlessly through all image memeories added to the sequence.

#### Parameters:

hf Camera handle

Wait

IS\_DONT\_WAIT This function synchronizes the image acquisition of

the V-SYNC, but returns immediately.

IS\_WAIT This function synchronizes the image acquisition of the

V-SYNC and only then does return (i.e. waits until im-

age acquisition begins)

10 < Wait < 32768 Wait time in 10 ms steps. A maximum of 327.68 seconds (this

is approx. 5 minutes and 20 seconds) can be waited. For 1 <

Wait < 10 Wait becomes equal to 10.

(Exp.: Wait =  $100 \Rightarrow$  wait 1 sec.)

### Return value:

IS\_SUCCESS, IS\_NO\_SUCCESS

### 4.5 is\_ClearSequence

### Syntax:

INT is\_ClearSequence (HIDS hf)

### **Description:**

is\_ClearSequence() deletes all image memory from the sequence list that was inserted with is\_AddToSequence(). After is\_ClearSequence() no more image memory is active. To make a certain part of the image memory active, is\_SetImageMem() and is\_SetImageSize() have to be executed.

Parameters:

hf Camera handle

Return value:

IS\_SUCCESS, IS\_NO\_SUCCESS

### 4.6 is\_ConvertImage

### Syntax:

INT is\_ConvertImage(HIDS hf, char\* pcSource, INT nIDSource, char\*\* ppcDest, INT \*nIDDest, INT \* reserved)

### **Description:**

Converts the Raw Bayer input picture to the desired format. If the pointer of the destination image data is NULL a new memory is allocated.

### Parameters:

Hf Camera handle

pcSourcepointer of memory of the input picturenIDSourceid of memory of the input pictureppcDestpointer of memory of the output picturenIDDestid of memory of the output picture

### Return value:

IS\_SUCCESS or IS\_NO\_SUCCESS

### Example:

```
Convert a Raw Bayer picture in RGB24. The memory will be allocated automatically:
```

```
// Create a Raw Bayer test picture
char * pcSource;
INT nIDSource;
is_AllocImageMem (hf, 256, 256, 8, &pcSource, &nIDSource);
Int nX,nY,nBits,nPitch;
is_InquireImageMem (hf, pcSource, nIDSource, &nX, &nY, &nBits,
&nPitch);
for (int j = 0; j < nY; j++)
  for (int i = 0; i < nX; i++)
        pcSource[i + j*nPitch] = i;
INT Gamma = 120;
double rgbGains[3];
rgbGains[0] = 1.0 ; // Red gain
rgbGains[1] = 3.0 ; // Green gain
rgbGains[2] = 1.0 ; // Blue gain
char* pcDest; // Pointer to the data of the new allocated picture
INT nIDDest; // id of the new allocated picture
INT nRet;
// Set the conversion parameters
nRet = is_SetConvertParam(hf, TRUE, IS_SET_BAYER_CV_BETTER,
IS_SET_CM_RGB24, Gamma, rgbGains);
// Convert the picture
```

```
if (nRet == IS_SUCCESS)
{
   pcDest = NULL;
   is_ConvertImage(hf, pcSource, nIDSource, &pcDest, &nIDDest, 0);
}

// Free the allocated memory
is_FreeImageMem (m_hCam, pcSource, nIDSource);
is_FreeImageMem (m_hCam, pcDest, nIDDest);
```

### 4.7 is\_CopyImageMem

### Syntax:

INT is\_CopyImageMem (HIDS hf, char\* pcSource, INT nID, char\* pcDest)

### **Description:**

*is\_CopyImageMem()* copies the contents of the image memory, as described is *pcSource* and *nID* to the area in memory, which *pcDest* points to.

Camera handle

Pointer to image memory

### HINT

The user must make sure that the allocated memory *pcDest* is large enough to store the whole image (not just the area of interest) in the current format (bits per pixel)

### Parameters:

hf
pcSource
nID
pcDest

ID of this image memory Pointer to destination memory to which the image should be copied.

### Return value:

IS\_SUCCESS, IS\_NO\_SUCCESS

### 4.8 is\_CopyImageMemLines

### Syntax:

INT is\_CopyImageMemLines (HIDS hf, char\* pcSource, INT nID, INT nLines, char\* pcDest)

### **Description:**

is\_CopyImageMemLines() copies the contents of the image memory, as described is pcSource and nID to the area in memory, which pcDest points to. nLines lines are copied.

### HINT

The user must make sure that the allocated memory pcDest is large enough to store the whole image (not just the area of interest) in the current format (bits per pixel).

**Parameters:** 

hf Camera handle

pcSourcePointer to image memorynIDID of this image memory

**nLines** Number of lines which are copied

pcDest Pointer to destination memory to which the image should be

copied

Return value:

IS\_SUCCESS, IS\_NO\_SUCCESS

## 4.9 is\_DisableDDOverlay

### Syntax:

INT is\_DisableDDOverlay (HIDS hf)

### **Description:**

When in DirectDraw BackBuffer mode, *is\_DisableDDOverlay()* deactivates the overlay mode and releases the memory which is currently occupied by the overlay, which causes the overlay data to be deleted.

Parameters:

hf Camera handle

### Return value:

IS\_SUCCESS, IS\_NO\_SUCCESS

### 4.10 is\_DisableEvent

### Syntax:

INT is DisableEvent (HIDS hf, INT which)

### **Description:**

is\_DisableEvent() blocks the event given here. The event (e.g. a frame) will generally still occur, but not trigger an event signal any more. After this function is called, the application does not notice the blocked events any more. A desired event can be reactivated with is\_EnableEvent() if required. See also 4.53 is\_InitEvent.

#### Parameters:

hf Camera handle which ID of the event

See 4.53 is\_InitEvent

### Return value:

IS\_SUCCESS, IS\_NO\_SUCCESS

### **Example:**

See 4.53 is\_InitEvent

### 4.11 is\_EnableAutoExit

### Syntax:

INT is\_EnableAutoExit (HIDS hf, INT nMode)

### **Description:**

is\_EnableAutoExit() activates the automatic closing of the camera-handle after a camera was removed during operation. With closing, all reserved memory by the SDK will be released.

#### Parameters:

hf Camera handle

nMode

IS\_ENABLE\_AUTO\_EXIT Activates automatic closing IS\_DISABLE\_AUTO\_EXIT Deactivates automatic closing

IS\_GET\_AUTO\_EXIT\_ENABLED Read the status

#### Return value:

Actual settings when called with IS\_GET\_AUTO\_EXIT\_ENABLED(), else IS\_SUCCESS or IS\_NO\_SUCCESS

### 4.12 is\_EnableDDOverlay

### Syntax:

INT is\_EnableDDOverlay (HIDS hf)

### **Description:**

When in DirectDraw BackBuffer mode *is\_EnableDDOverlay()* activates the live overlay mode. In BackBuffer mode three non-visible image buffers are used: Back buffer, overlay buffer and mix buffer. The video image is digitized in the back buffer. The graphics data can be written in the overlay buffer and thus the overlay data is overlaid on the video image. The mix buffer is then copied to the visible area of the VGA card. The size of the three buffers is: video\_x \* video\_y \* color depth (in bytes per pixel). The driver tries to allocate the buffer directly on the VGA card, (making best use of the high speed image transfer that the VGA card can offer) when mixing the three buffers. If the buffers cannot be allocated in the VGA card, they will be stored in system memory. The image transfer from the system memory is slower and, depending on the graphics card, sometimes not at all possible. The overlay is not always faded on. It has to be made visible with *is\_ShowDDOverlay()* (see <u>4.119 is ShowDDOverlay</u>). As its key color, the overlay uses black, an thus an overlay cannot contain any black color.

#### Parameters:

hf Camera handle

#### Return value:

IS\_SUCCESS, IS\_NO\_SUCCESS

### 4.13 is\_EnableEvent

### Syntax:

INT is\_EnableEvent (HIDS hf, INT which)

### **Description:**

Release of the equipped event object. After the release, the event signalling of the current event object is allowed. See also <u>4.53 is\_InitEvent</u>.

#### Parameters:

hf Camera handle

whichID of the event to releaseSee 4.53 is\_InitEventA new image is available.

### Return value:

IS\_SUCCESS, IS\_NO\_SUCCESS

### **Example:**

See See 4.53 is\_InitEvent.

### 4.14 is\_EnableMessage

### Syntax:

INT is\_EnableMessage (HIDS hf, INT which, HWND hWnd)

### **Description:**

With *is\_EnableMessage()* messages can be activated or deactivated (hWnd = NULL), which are sent when occurring a certain event to the user program. The message is build up as follows:

Msg: IS\_DCU\_MESSAGE wParam: Arrived event (see Table)

IParam: Camera handle that belongs to the message

### Parameters:

hf Camera handle

which ID of the message to be activated/deactivated

IS\_FRAME A new image is available.

IS\_SEQUENCE The sequence was gone through.

IS\_SET\_STEAL\_VIDEO An image detracted from the overlay is available.

IS\_TRANSFER\_FAILED An Error occurred during data transfer (Frame rate, Pixelclock

too high)

IS\_TRIGGER An image, ist recording was released by a trigger, was com-

pletely received. This is the earliest time for a new recording. The picture must pass the post processing of the driver and is

after IS\_FRAME available for the processing.

IS\_MEMORY\_MODE\_FINISH Recording images to the optional memory module has been

terminated.

IS\_DEVICE\_REMOVED A camera, opened with *is\_InitCamera()* has been removed.

IS\_DEVICE\_RECONNECTED A camera opened with is\_InitCamera() and thereafter re-

moved was reconnected.

IS\_NEW\_DEVICE A new camera was attached. Independent of the device han-

dle (hf will be ignored).

IS\_DEVICE\_REMOVAL A camera was removed. Independent of the device handle

(hf will be ignored).

IS\_WB\_FINISHED The automatic white balance control is finished.

IS\_AUTOBRIGHTNESS\_FINISHED The automatic brightness control is finished (if

IS\_SET\_AUTO\_BRIGHTNESS\_ONCE has been specified).

Application window, which gets the message. (NULL deacti-

vates the message, defined with which).

#### Return value:

hWnd

IS\_SUCCESS or IS\_NO\_SUCCESS

### 4.15 is\_ExitCamera

### Syntax:

INT is\_ExitCamera (HIDS hf)

### **Description:**

is\_ExitCamera() cancels the active device handle hf and deallocates the data structures and memory areas currently associated with the DCU camera. The image memory which has been allocated by the user and which has not been released yet, is released with is\_ExitCamera.

### HINT

The DCU SDK is *thread safe* in general. The API function calls are all done in *critical sections*. Due to internal structures of *DirectDraw* we strongly recommend to call the following functions from only one thread to avoid unpredictable behaviour of your application.

is\_InitCamera()
is\_SetDisplayMode()
is\_ExitCamera()

Parameters:

hf Camera handle

Return value:

IS\_SUCCESS, IS\_NO\_SUCCESS

### 4.16 is ExitEvent

### Syntax:

INT is\_ExitEvent (HIDS hf, INT which)

### **Description:**

Deletes set event object. After deleting it can not be activated with is\_EnableEvent().

### Parameters:

hf Camera handle

which ID of event that should be deleted

See 4.53 is\_InitEvent

### Return value:

IS\_SUCCESS, IS\_NO\_SUCCESS

### Example:

See 4.53 is\_InitEvent.

### 4.17 is\_ForceTrigger

### Syntax:

INT is ForceTrigger (HIDS hf)

### **Description:**

The function *is\_ForceTrigger()* enables to force a trigger during a hardware trigger recording to take up a picture independently of a real trigger signal. This function can only be used, if the trigger recording was started with the parameter *IS\_DONT\_WAIT*.

See also 4.19 is\_FreezeVideo and 4.94 is\_SetExternalTrigger.

#### Parameters:

hf

Camera handle

### Return value:

IS\_SUCCESS, IS\_NO\_SUCCESS

### Example:

Activate the trigger and wait 1 second for an external trigger. Force a recording with *is\_ForceTrigger()* if no trigger was released.

```
HANDLE hevent = CreateEvent(NULL, TRUE, FALSE, "");
if (hEvent != NULL)
{
   is_InitEvent(hf, m_hEvent, IS_SET_EVENT_FRAME);
   is_EnableEvent(hf, IS_SET_EVENT_FRAME);

   is_SetExternalTrigger(hf, IS_SET_TRIG_HI_LO);
   is_FreezeVideo(hf, IS_DONT_WAIT);
   if (WaitForSingleObject(m_hEvent, 1000) != WAIT_OBJECT_0)
   {
      // no trigger signal, force to take picture
      is_ForceTrigger(hf);
   }
   is_DisableEvent(hf, IS_SET_EVENT_FRAME);
   is_ExitEvent(hf, IS_SET_EVENT_FRAME);
}
```

# 4.18 is\_FreeImageMem

# Syntax:

INT is\_FreeImageMem (HIDS hf, char\* pcImgMem, INT id)

# **Description:**

*is\_FreeImageMem()* deallocates previously allocated image memory. For *pcImgMem* one of the pointers from *is\_AllocImgMem()* has to be used. All other pointers lead to an error message! The repeated handing over of the same pointers also leads to an error message!

### Parameters:

hf Camera handle

pcImgMemPointer to image memoryidID of this image memory

# Return value:

# 4.19 is\_FreezeVideo

## Syntax:

INT is FreezeVideo (HIDS hf, INT Wait)

#### **Description:**

is\_FreezeVideo() digitizes an image and transfers it to the active image memory. In DirectDraw mode the image is digitized in the DirectDraw buffer (either on the VGA card or in a back buffer). When working with ring buffering, image acquisition only takes place in the first image memory of the sequence.

If there is a change in camera settings (exposure, Pclk, AOI, ...) after selecting the function with the parameter IS\_DONT\_WAIT, the recording is aborted and the new camera settings are installed.

The picture recording takes place triggered, if the trigger mode were activated before with *is\_SetExternalTrigger()*.

#### **HINT**

After Activation of the memory mode with is\_SetMemoryMode() or is\_MemoryFreezeVideo() the images taken with is\_FreezeVideo() are stored in the camera memory. In order to get image acquisition without memory mode, the memory mode must be switched off again with the function is\_SetMemoryMode(IS\_MEMORY\_MODE\_DISABLE, 0)

#### Parameters:

hf Camera handle

Wait

IS\_WAIT The function waits until an image is grabbed. If the fourfold frame time is exceeded, this is acknowledged with a timout.

IS\_DONT\_WAIT The function returns straight away

10 <= Wait < 21474836 Wait time in 10 ms steps. A maximum of 214748.36 seconds (this is approx. 59 hours) can be waited.

For 1 < Wait < 10 Wait becomes equal to 10.

(Exp.: Wait =  $100 \Rightarrow$  wait 1 sec.)

### Return value:

IS\_SUCCESS, IS\_NO\_SUCCESS

#### **Example:**

Activate trigger mode, set *High-Active* flash mode and record image. is\_SetExternalTrigger(hf, IS\_SET\_TRIG\_SOFTWARE); is\_SetFlashStrobe(hf, IS\_SET\_FLASH\_HI\_ACTIVE); is\_FreezeVideo(hf, IS\_WAIT);

# 4.20 is\_GetActiveImageMem

# Syntax:

INT is\_GetActiveImageMem (HIDS hf, char\*\* ppcMem, INT\* pnID)

# **Description:**

*is\_GetActiveImageMem()* returns the pointer to the beginning and the ID number of the active memory. If DirectDraw mode is active and image memory has been allocated, this function returns the pointer and the ID of the image memory, which was activated with *is\_SetImageMem()*. However, it should be noted that in DirectDraw mode, this memory is not used for digitizing. Also see *is\_GetImgMem()*.

#### Parameters:

hf Camera handle

**ppcMem**Contains the pointer to the beginning of the image memory.

**pnID** Contains the ID of the image memory.

#### Return value:

# 4.21 is\_GetActSeqBuf

#### Syntax:

INT is\_GetActSeqBuf (HIDS hf, INT\* pnNum, char\*\* ppcMem, char\*\* ppcMemLast);

## **Description:**

With *is\_GetActSeqBuf()* the image memory in which image acquisition (*ppcMem*) is currently taking place and the image memory which was last used for image acquisition (*ppcMemLast*) can be determined. This function is only available when the ring buffer is active. If image acquisition is started for a ring buffer, *is\_GetActSeqBuf* returns 0 in *pnNum* as long as data is acquired to the first image memory of the sequence. And thus *pnNum* receives the number of the sequence image memory, in which image acquisition is currently taking place. The number is **not** the ID of the image memory which is provided from *is\_AllocImageMem()*, but the running number in the sequence as defined in *is\_AddToSequence()*.

#### Parameters:

hf Camera handle

**pnNum** Contains the number of the image memory in which image

acquisition is currently taking place.

0: image acquisition has not started in the first image

memory

1 to max: image acquisition in the sequence image memory N

has started.

**ppcMem**Contains the start address of the image memory in which the

current image acquisition is taking place.

**ppcMemLast** Contains the start address of the image memory, which was

last used for image acquisition.

#### Return value:

# 4.22 is\_GetAutoInfo

## Syntax:

INT is\_GetAutoInfo (HIDS hf, PDCU\_AUTO\_INFO info)

## **Description:**

With the function *is\_GetAutoInfo()* status information of autofunctionality can be readout. The information is available in the structure *DCU\_AUTO\_INFO*.

#### HINT

The status information in the structure DCU\_AUTO\_INFO is only valid if at least one autofunctionality is activated.

### DCU\_AUTO\_INFO

INT AutoAbility 0x01: AutoShutter possible

(AC\_SHUTTER)

0x02: AutoGain possible (AC\_GAIN)0x03: AutoGain und AutoShutter possible

0x04: AutoWhiteBalance possible

(AC\_WHITEBAL)

0x07: All auto functions are possible

AUTO\_BRIGHT\_STATUSsBrightCtrlStatusSee AUTO\_BRIGHT\_STATUSAUTO\_WB\_STATUSsWBCtrlStatusSee AUTO\_WB\_STATUSDWORDreservedReserved for extensions

In the structure DCU\_AUTO\_INFO the structures AUTO\_BRIGHT\_STATUS and AUTO\_WB\_STATUS are used.

## **AUTO\_BRIGHT\_STATUS**

 INT
 curValue
 Current average grey value (Ist)

 INT
 curError
 Current control deviation (Error)

 INT
 curController
 Current brightness control

0x01: AC\_SHUTTER 0x02: AC\_GAIN

INT curCtrlStatus Current control status

0x01: ACS\_ADJUSTING
0x02: ACS\_FINISHED
0x04: ACS\_DISABLED

### **AUTO\_WB\_STATUS**

INT curController Current white balance controller

0x08: AC\_WB\_RED\_CHANNEL
0x10: AC\_WB\_GREEN\_CHANNEL
0x20: AC\_WB\_BLUE\_CHANNEL
See AUTO\_WB\_CHANNEL\_STATUS

AUTO\_WB\_CHANNEL\_STATUSRedChannelSee AUTO\_WB\_CHANNEL\_STATUSAUTO\_WB\_CHANNEL\_STATUSGreenChannelSee AUTO\_WB\_CHANNEL\_STATUSAUTO\_WB\_CHANNEL\_STATUSBlueChannelSee AUTO\_WB\_CHANNEL\_STATUS

In the following the structure *AUTO\_WB\_CHANNEL\_STATUS* is described which is used in the structure *AUTO\_WB\_STATUS*.

# AUTO\_WB\_CHANNEL\_STATUS

 INT
 curValue
 Current average grey value

 INT
 curError
 Current control error

 INT
 curCtrlStatus
 Current control status

0x01: ACS\_ADJUSTING
0x02: ACS\_FINISHED
0x04: ACS\_DISABLED

Parameters:

hf Camera handle

info Structure DCU\_AUTO\_INFO (see above)

Return value:

IS\_SUCCESS, IS\_NO\_SUCCESS

Example:

Readout AutoInfo:

DCU\_AUTO\_INFO autoinfo;

Int ret = is\_GetAutoInfo(m\_hCam, &autoinfo);

# 4.23 is\_GetBusSpeed

# Syntax:

INT is\_GetBusSpeed (HIDS hf)

# **Description:**

The function *is\_GetBusSpeed()* can be used to check whether a camera is connected to a USB 2.0 host controller.

If the value zero (0) is sent for the camera handle, a check is made whether a USB 2.0 controller is present in the system.

Parameters:

hf Camera handle

Return value:

IS\_SUCCESS

USB 2.0 Controller available (hf=0)

IS\_NO\_SUCCESS

no USB 2.0 Controller available (hf=0)

IS\_USB\_10 Controller port to which the camera is connected supports no

**USB 2.0** 

IS\_USB\_20 Camera is connected to a USB 2.0 controller

# 4.24 is\_GetCameraInfo

# Syntax:

INT is\_GetCameraInfo (HIDS hf, PCAMINFO pInfo)

# **Description:**

The function *is\_GetCameraInfo()* reads the data from the EEPROM and writes it to the data structure *plnfo*. The data structure is described in chapter <u>2.3 CAMINFO – data structure of the EEPROM</u>.

Reading and writing own data in and from the EEPROM are accomplished over the functions is\_ReadEEPROM() and is\_WriteEEPROM().

#### Parameters:

hf Camera handle

**plnfo** Pointer to data structure with the information from the

**CAMINFO** 

### Return value:

# 4.25 is\_GetCameraList

## Syntax:

INT is GetCameraList (PDCU CAMERA LIST pucl)

#### **Description:**

With the function *is\_GetCameraList()* information about the attached cameras can be queried. In the following tables the used structures are described.

#### DCU\_CAMERA\_LIST

ULONG dwCount Number of cameras attached at the system.

DCU\_CAMERA\_INFO uci[1] Placeholder for 1 .. n structures DCU\_CAMERA\_INFO

#### DCU\_CAMERA\_INFO

DWORD dwCameraID User defined camera ID

DWORD dwDeviceID System internal devices ID

DWORD dwSensorID Sensor ID

DWORD dwInUse 1 = camer in use

0 = camera not in use

Char SerNo[16] serial number of the camera

Char Model[16] camera model DWORD dwReserved[16] Reserved

#### Parameters:

pucl Structure DCU\_CAMERA\_LIST

#### Return value:

IS\_SUCCESS, IS\_ACCESS\_VIOLATION (not enough memory allocated) or IS\_CANT\_OPEN\_DEVICE bzw. IS\_IO\_REQUEST\_FAILED (Communication with driver failed)

## Example:

```
PDCU_CAMERA_LIST pucl = new DCU_CAMERA_LIST;
pucl->dwCount = 0;
if (is_GetCameraList (pucl) == IS_SUCCESS){
  DWORD dwCameraCount = pucl->dwCount;
  delete pucl;
                    //reallocate the required list size
  pucl = (PDCU_CAMERA_LIST) new char [sizeof (DWORD) + dwCameraCount *
  sizeof (DCU_CAMERA_INFO)];
  pucl->dwCount = dwCameraCount;
  //let the DLL fill in the camera info
  if (is_GetCameraList(pucl) == IS_SUCCESS){
    for (int iCamera = 0; iCamera < (int) pucl->dwCount; iCamera++){
       //process camera info
       printf("Camera %i Id: %d", iCamera,
       pucl->uci[iCamera].dwCameraID);
    }
  }
}
```

# 4.26 is\_GetCameraType

### Syntax:

INT is\_GetCameraType (HIDS hf)

## **Description:**

is\_GetCameraType() returns the result of which type of camera family is installed. With the DCU camera family is always returned IS\_CAMERA\_TYPE\_DCU\_USB.

#### Parameters:

hf Camera handle

#### Return value:

IS\_CAMERA\_TYPE\_DCU\_USB

# 4.27 is\_GetColorDepth

### Syntax:

INT is\_GetColorDepth(HIDS hf, INT\* pnCol, INT\* pnColMode)

### **Description:**

is\_GetColorDepth() gets the current VGA card colour setting and returns the bit depth (pnCol) and the related colour mode (pnColMode). The colour mode can be directly passed to the is\_SetColorMode() function.

#### Parameters:

hf Camera handle

PnCol Returns bit depth of colour setting

8 at 256 colours

15 at 32768 colours (5:5:5 mode)
16 at 65536 colours (5:6:5 mode)
24 at 16777216 colours (8:8:8 mode)
32 at 16777216 colours (0:8:8:8 mode)

pnColMode Returns colour mode for is\_SetColorMode()

IS\_SET\_CM\_Y8 at pnCol = 8
IS\_SET\_CM\_RGB15 at pnCol = 15
IS\_SET\_CM\_RGB16 at pnCol = 16
IS\_SET\_CM\_RGB24 at pnCol = 24
IS\_SET\_CM\_RGB32 at pnCol = 32

#### Return value:

# 4.28 is\_GetDC

#### Syntax:

INT is\_GetDC (HIDS hf, HDC\* phDC)

## **Description:**

In DirectDraw BackBuffer mode *is\_GetDC()* returns the overlay buffer's device context handle. Using this handle Windows GDI functions can access the overlay. All graphics commands such as line, circle, rectangle and text out from Windows are available. The device context handle must be released as soon as possible with the *is\_ReleaseDC()* function. Within the *GetDC - ReleaseDC* blocks there are **no** updates of the overlay buffer on the display.

#### Parameters:

hf Camera handle

**phDC** Pointer to the variable, which the device handle takes over.

#### Return value:

IS\_SUCCESS, IS\_NO\_SUCCESS

# 4.29 is\_GetDDOvlSurface

## Syntax:

INT is\_GetDDOvlSurface (HIDS hf, LPDIRECTDRAWSURFACE\* ppDDSurf)

#### **Description:**

In DirectDraw back buffer mode *is\_GetDDOvlSurface()* returns the pointer to the internal DirectDraw surface. And thus functions from the DirectDraw surface interface can be used.

#### Parameters:

hf Camera handle

ppDDSurf Contains pointer to the DirectDraw surface interface

#### Return value:

# 4.30 is\_GetDLLVersion

# Syntax:

INT is\_GetDLLVersion()

# **Description:**

Returns the version number of the DCU\_api.DLL.

The return value contains the version number in the following coding:

Bits 31-24: major version number Bits 16-23: minor version number Bits 15-0: build version number

#### Parameters:

< none >

### Return value:

Number of the version

# 4.31 is\_GetError

# Syntax:

INT is\_GetError (HIDS hf, INT\* pErr, char\*\* ppcErr)

## **Description:**

*is\_GetError()* finds out what the last error was and returns the error code and error message. The last error message is not deleted, but overwritten with a new one.

# Parameters:

hf Camera handle

**PErr** Pointer to variable, which will contain the error code.

**PpcErr** Pointer to the string, which then contains the error message

#### Return value:

# 4.32 is\_GetExposureRange

#### Syntax:

INT is\_GetExposureRange (HIDS hf, double \*min, double \*max, double \*intervall)

## **Description:**

The function *is\_GetExposureRange()* can be used to check the possible exposure values in milliseconds for the currently set timing (pixel clock, frame rate). The possible times lie between min and max and can be set in large stages in interval.

#### Parameters:

hf Camera handle

minContains the minimum possible exposure timemaxContains the maximum possible exposure time

intervall Contains the step sizes with which the image duration can be

changed

#### Return value:

IS\_SUCCESS, IS\_NO\_SUCCESS

# 4.33 is\_GetFramesPerSecond

# Syntax:

INT is\_GetFramesPerSecond (HIDS hf, double \*dbIFPS)

## **Description:**

*is\_GetFramesPerSecond()* returns the number of the actual frame rate in live mode (see <u>4.4</u> <u>is\_CaptureVideo</u>).

#### Parameters:

hf Camera handle dbIFPS Frame rate

#### Return value:

# 4.34 is\_GetFrameTimeRange

# Syntax:

INT is\_GetFrameTimeRange (HIDS hf, double \*min, double \*max, double \*intervall)

## **Description:**

*is\_GetFrameTimeRange()* can be used to read out the frame rate settings that are possible for the current settings of the pixel clock. The returned values state the minimum and maximum possible duration of an image in seconds. The possible frame duration can be set in steps in interval between *min* and *max*.

$$fps(\min) = \frac{1}{\max}$$

$$fps(\max) = \frac{1}{\min}$$

$$fps(n) = \frac{1}{\min + m}$$
 $m = n*intervall$ 

#### Parameters:

hf Camera handle

minContains the minimum possible duration of an imagemaxContains the maximum possible duration of an image

intervall Contains the step sizes with which the image duration can be

changed

### Return value:

# 4.35 is\_GetGlobalFlashDelays

### Syntax:

INT is\_GetGlobalFlashDelays (HIDS hf, ULONG \*pulDelay, ULONG \*pulDuration)

## **Description:**

### Rolling shutter cameras:

The function *is\_GetGlobalFlashDelays()* allows the required times to be determined in order to implement a global flash function for *rolling shutter cameras*. Thus a *rolling shutter camera* can be operated as *global shutter camera*, if the scene to be taken is dark in the lightning break between two images.

If the exposure time is set too short, so that a global lightning is no longer possible, *IS\_NO\_SUCCESS* is returned.

#### Global shutter cameras:

The exposure is delayed with global shutter cameras in freerun mode, if the exposure time is not set to the maiximum value. The function *is\_GetGlobalFlashDelays()* acquires the necessary delay, in order to synchronize exposure and flash. In triggered mode the return values for the delay and duration of the flash are 0, because there is no delay needed up to the beginning of the exposure.

#### Parameters:

hf Camera handle

ulDelayDelay time of the flash (in  $\mu$ s)ulDurationFlash duration time (in  $\mu$ s)

#### Return value:

# 4.36 is\_GetImageHistogram

### Syntax:

INT is GetImageHistogram (HIDS hf, int nID, INT ColorMode, DWORD\* pHistoMem)

#### **Description:**

*is\_GetImageHistogram()* calculates the histogram of the given picture, only the following color formats are supported RGB32, RGB24, RGB16, RGB15, Raw Bayer and Y8.

#### Parameters:

```
Hf
                         Camera handle
nID
                         memory id
ColorMode
                         Colour mode of the image with the memory id nID
 IS_SET_CM_RGB32
                         DWORD array [256*3]
 IS_SET_CM_RGB24
                         DWORD array [256*3]
 IS_SET_CM_RGB16
                         DWORD array [256*3]
 IS_SET_CM_RGB15
IS_SET_CM_BAYER
                         DWORD array [256*3]
                         DWORD array [256*3]
 IS_SET_CM_Y8
                         DWORD array [256])
                         pointer to a DWORD array
pHistoMem
```

#### Return value:

```
IS_SUCCESS
IS_NO_SUCCESS
IS_NULL_POINTER invalid array
IS_INVALID_COLOR_FORMAT unsupported color format
IS_INVALID_PARAMETER unknown parameter ColorMode
```

## Example:

```
Create a RGB test picture
char * pcSource;
INT nIDSource;
is_AllocImageMem (hf, 256, 256, 24, &pcSource, &nIDSource);
Int nX,nY,nBits,nPitch;
is_InquireImageMem (hf, pcSource, nIDSource, &nX, &nY, &nBits,
&nPitch);
for (int j = 0; j < nY; j++) {
  for (int i = 0; i < nX*3; i+=3) {
        pcSource[i + j*nPitch] = 0; // Blue pixels
        pcSource[i + j*nPitch + 1] = i/3; // Green pixels
        pcSource[i + j*nPitch + 2] = 255; // Red pixels
  }
// memory for the rgb histogram
DWORD bgrBuffer [256*3];
//Assign a pointer to each color histogram
DWORD * pBlueHisto = bgrBuffer;
DWORD *pGreenHisto = bgrBuffer + 256;
DWORD * pRedHisto = bgrBuffer + 512;
is_GetImageHistogram (hf, nIDSource, IS_SET_CM_RGB24, bgrBuffer);
```

is\_FreeImageMem (hf, pcSource, nIDSource);

# 4.37 is\_GetImageMem

# Syntax:

INT is\_GetImageMem (HIDS hf, VOID\*\* pMem)

# **Description:**

*is\_GetImageMem()* returns the pointer to the start of the active image memory. In DirectDraw mode the pointer is returned to the back buffer (or the visible area - DirectDraw Primary Surface mode).

## **HINT**

In DirectDraw mode the address pointer changes when the output window is moved (see also 4.60 is\_LockDDMem). When ring buffering is being used (4.1 is\_AddToSequence), is\_GetImageMem() returns the previously active image memory.

Parameters:

hf Camera handle

**pMem** Pointer to beginning of image memory

Return value:

# 4.38 is\_GetImageMemPitch

## Syntax:

INT is GetImageMemPitch (HIDS hf, INT\* pPitch)

## **Description:**

is\_GetImageMemPitch() returns the line increment in bytes. The line increment is the number of bytes from the beginning of a line to the beginning of the next line. If required, the line increment can be larger than the returned parameters from is\_AllocImageMem(). The line increment is always a multiple of 4 (also see 4.2 is\_AllocImageMem).

The line increment is calculated as follows:

line = width \* [(bitspixel + 1) /8]

lineinc = line + adjust.

adjust = 0 - when line without remainder is divisible by 4

adjust = 4 - rest(line / 4) when line with remainder is divisible by 4

#### Parameters:

hf Camera handle

**pPitch** Pointer to variable, which contains line increment

#### Return value:

IS\_SUCCESS, IS\_NO\_SUCCESS

# 4.39 is\_GetLastMemorySequence

# Syntax:

INT is\_GetLastMemorySequence (HIDS hf, INT \*pID)

# **Description:**

The function *is\_GetLastMemorySequence()* returns the ID of the last recorded sequence in the memory board. This parameter can then be used in combination with the function *is\_TransferImage()* to read images out of the camera memory.

### Parameters:

hf Camera handle

**pID** Returns the ID of the last recorded sequence to the memory.

## Return value:

# 4.40 is\_GetMemorySequenceWindow

## Syntax:

INT is\_GetMemorySequenceWindow (HIDS hf, INT nID, INT \*left, INT \*top, INT \*right, INT \*bottom)

# **Description:**

The function *is\_GetMemorySequenceWindow()* can be used to check the window size of a specified memory board sequence. The assigned sequence ID is required as a parameter.

### Parameters:

hf Camera handle

**nID** Sequence ID for which window coordinates can be checked.

leftReturns the start column.topReturns the start row.rightReturns the end column.bottomReturns the end row

#### Return value:

IS\_SUCCESS, IS\_NO\_SUCCESS

# 4.41 is\_GetNumberOfCameras

# Syntax:

INT is\_GetNumberOfCameras (INT\* pnNumCams)

### **Description:**

Function is\_GetNumberOfCameras() delivers the number of DCU cameras attached to the PC.

#### Parameters:

pnNumCams Number of cameras found

#### Return value:

IS\_SUCCESS

# 4.42 is\_GetNumberOfMemoryImages

#### Syntax:

INT is\_GetNumberOfMemoryImages (HIDS hf, INT nID, INT \*pnCount)

## **Description:**

The function *is\_GetNumberOfMemoryImages()* returns the number of valid images that are currently located in the camera memory within the specified sequence ID. This number can differ from the originally recorded number of images because of overwriting.

### Parameters:

hf Camera handle

nID Specifies the ID at which the number of existing images is to

be indicated.

**pnCount** This parameter indicates the number of images in the se-

quence.

#### Return value:

IS\_SUCCESS, IS\_NO\_SUCCESS

# 4.43 is GetOsVersion

# Syntax:

INT is\_GetOsVersion ()

# **Description:**

is\_GetOsVersion() returns the type of operating system, which is currently running on the machine at which the camera is attached.

## Parameters:

no parameter

#### Return value:

IS\_OS\_WIN2000, IS\_OS\_WINXP, IS\_OS\_WINSERVER2003

# 4.44 is\_GetPixelClockRange

Syntax:

INT is\_GetPixelClockRange (HIDS hf, INT \*pnMin, INT \*pnMax)

**Description:** 

is\_GetPixelClockRange() returns the adjustable range for the pixel clock.

Parameters:

hf Camera handle

pnMinReturns the lower limit.pnMaxReturns the upper limit.

Return value:

# 4.45 is\_GetRevisionInfo

# Syntax:

INT is\_GetRevisionInfo(HCAM hf, PREVISIONINFO prevInfo)

# **Description:**

The function *is\_GetRevisionInfo()* readout the revision information of the individual DCU components. The revision structure is built-on as follows:

SizeSize of the structureSensorHardware sensor revision

**Cypress** 

Lowbyte:

**Blackfin** 

Highbyte: 1 = Type FX2

2 = Type FX2LP Cypress revision DSP revision

DSPFirmware Blackfin firmware version
USB\_Board USB Board revision
Sensor\_Board Sensor Board revision
Processing\_Board Processing Board revision

HousingHousing modelFilterEmbedded filtertypeTiming\_BoardTiming Board revisionProductProduct revisionReservedreserved

iveserved reserv

**Parameters:** 

hf Camera handle

**prevInfo** Pointer to Revision Information Structure

Return value:

# 4.46 is\_GetSensorInfo

# Syntax:

INT is\_GetSensorInfo (HIDS hf, PSENSORINFO pInfo)

# **Description:**

With *is\_GetSensorInfo()* information about the used camera sensor can be queried. The information contained in the structure SENSORINFO is listed in the following table:

WORD	SensorID	VOORTINI O 13 listed iii tile lollowi	9	
		Sensor type	hex	dec
		CCD		
		IS_SENSOR_UI223X_M	80	128
		IS_SENSOR_UI223X_C	81	129
		IS_SENSOR_UI241X_C	82	130
		IS_SENSOR_UI241X_C	83	131
		IS_SENSOR_UI221X_M	88	136
		IS_SENSOR_UI221X_C	89	137
		IS_SENSOR_UI231X_M	90	144
		IS_SENSOR_UI231X_C	91	145
		IS_SENSOR_UI222x_M	92	146
		IS_SENSOR_UI222x_C	93	147
		IS_SENSOR_UI233x_M	94	148
		IS_SENSOR_UI233x_C	95	149
		IS_SENSOR_UI224x_M	96	150
		IS_SENSOR_UI224x_C	97	151
		IS_SENSOR_UI225x_M	98	152
		IS_SENSOR_UI225x_C	99	153
Char	strSensorName[32]	Sensor name e.g. " DCU224C "		
Char	nColorMode	Sensor colour mode:		
		IS_COLORMODE_BAYER		
		IS_COLORMODE_MONOCHR	OME	
DWORD	nMaxWidth	Maximum windows width e.g. 1280	)	
DWORD	nMaxHeight	Maximum window height e.g. 1024		
BOOL	bMasterGain	Is a common amplifier present?		
		e.g. FALSE		
BOOL	bRGain	Red amplifier present?		
		e.g. TRUE		
BOOL	bGGain	Green amplifier present?		
		e.g. TRUE		
BOOL	bBGain	Blue amplifier present?		
		e.g. TRUE		
BOOL	bGlobShutter	Global or Rolling Shutter?		
		e.g. TRUE (=global shutter present	t)	
Char	Reserved[16]	Reserved		
	-			
Parameters:				
hf		Camera handle		
plnfo		Sensor Info structure		
Pillio		Gensor into structure		

# Return value:

IS\_SUCCESS, IS\_NO\_SUCCESS

# 4.47 is\_GetUsedBandwidth

# Syntax:

INT is\_GetUsedbandwidth (HIDS hf)

# **Description:**

is\_GetUsedBandwidth() indicates the bandwidth currently being used with the pixel clock of all active cameras.

Parameters:

hf Camera handle

# Return value:

Sum of the pixelclock

# 4.48 is\_GetVsyncCount

## Syntax:

INT is\_GetVsyncCount (HIDS hf, long\* pIntr, long\* pFrame)

### **Description:**

is\_GetVsyncCount() reads the VSYNC counter. This is increased by 1 for each VSYNC.

#### Parameters:

hf Camera handle

pIntrCurrent VSYNC counterpFrameCurrent Frame-SYNC counter

#### Return value:

IS\_SUCCESS, IS\_NO\_SUCCESS

# 4.49 is\_GetWhiteBalanceMultipliers

### Syntax:

INT is\_GetWhiteBalanceMultipliers (HIDS hf, double \*pdblRed, double \*pdblGreen, double \*pdblBlue)

## **Description:**

is\_GetWhiteBalanceMultipliers() returns the present multipliers of the white balance. These have been set previously with is\_SetWhiteBalanceMultipliers() or have been calculated with the automatic white balance.

#### Parameters:

hf Camera handle

pdblRedMultiplier for the red channelpdblGreenMultiplier for the green channelpdblBlueMultiplier for the blue channel

# Return value:

# 4.50 is\_HasVideoStarted

## Syntax:

INT is\_HasVideoStarted (HIDS hf, BOOL\* pbo)

## **Description:**

*is\_HasVideoStarted()* can check whether the digitizing of an image has started or not. This function is useful when used together with *is\_FreezeVideo()* and the parameter IS\_DONT\_WAIT.

#### Parameters:

hf Camera handle

**pbo** Contains the digitization status:

0 = not started

1 = image acquisition started

#### Return value:

IS\_SUCCESS, IS\_NO\_SUCCESS

# 4.51 is\_HideDDOverlay

### Syntax:

INT is\_HideDDOverlay (HIDS hf)

### **Description:**

is\_HideDDOverlay() fades out the overlay in DirectDraw back buffer mode. Then only the image buffer is displayed, so that the image refresh frequency is higher than then the overlay, which is being superimposed. When the overlay is faded out the overlay data is not lost.

#### Parameters:

hf Camera handle

#### Return value:

# 4.52 is\_InitCamera

## Syntax:

INT is InitCamera (HIDS\* phf, HWND hWnd)

## **Description:**

is\_InitCamera() opens the driver and establishes contact to the hardware. If the hardware is successfully initialized, this function allocates a handle to the camera. All of the following functions require this as their first parameter. If DirectDraw is not used for image output, hWnd can be set to Null.

To install several DCU cameras at one computer (multi camera operation), you have to decide during initialisation of the handle which camera is to be initialized. The Camera-ID is fixed in the EEPROM (see also <u>4.24 is GetCameraInfo</u>). If a special board is to be addressed, you have to initialize the handle *hf* with the relevant Camera-ID.

If you don't want multi camera operation, handle *hf* must be initialized with the value zero before calling function *is\_InitCamera()*. Here the value zero means, that the first not used camera will be used.

#### HINT

The DCU SDK is thread safe in general. The API function calls are all done in critical sections. Due to internal structures of DirectDraw we strongly recommend to call the following functions from only one thread to avoid unpredictable behaviour of your application.

is\_InitCamera()
is\_SetDisplayMode()

is\_ExitCamera()

Parameters:

phf Pointer to the camera handle. The values have the following

meaning:

0: use first unused camera

1-254: use camera with this Camera-ID

**hWnd** Handle to the window in which the image is to be displayed

#### Return value:

IS\_SUCCESS, error code (see header file)

# 4.53 is\_InitEvent

## Syntax:

INT is InitEvent (HIDS hf, HANDLE hEv, INT which)

#### **Description:**

Initializes the event handler by registering the event object in the central driver.

#### Parameters:

hf Camera handle hEv Event-Handle of the C/C++-Function CreateEvent() which event ID to be initialized: IS\_SET\_EVENT\_FRAME A new image is available. IS\_SET\_EVENT\_SEQ The sequence was gone through. IS\_EVENT\_STEAL An image detracted from the overlay is available. IS\_SET\_EVENT\_TRANSFER\_FAILED Data loss during transmission An image, its recording was released by a trigger, was IS\_SET\_EVENT\_EXTTRIG completely received. This is the earliest time for a new recording. The picture must pass the post processing of the driver and is after IS\_FRAME available for the processing. IS\_SET\_EVENT\_MEMORY\_MODE\_FINISH Recording images to the optional memory module has been terminated. IS\_SET\_EVENT\_REMOVE A camera, opened with is\_InitCamera() has been removed. IS\_SET\_EVENT\_DEVICE\_RECONNECTED A camera opened with is\_InitCamera() and thereafter removed was reconnected. IS\_SET\_EVENT\_NEW\_DEVICE A new camera was attached. Independent of the device handle (hf will be ignored). A camera was removed. Independent of the device IS\_SET\_EVENT\_REMOVAL

handle (hf will be ignored).

The automatic white balance control is finished.

#### Return value:

IS\_SUCCESS, IS\_NO\_SUCCESS

IS\_SET\_EVENT\_WB\_FINISHED

#### **Example:**

Activate frame events, start image recording and wait for an event:

```
HANDLE hEvent = CreateEvent(NULL, TRUE, FALSE, "");
if (hEvent != NULL) {
   is_InitEvent(hf, hEvent, IS_SET_EVENT_FRAME);
   is_EnableEvent(hf, IS_SET_EVENT_FRAME);
   is_FreezeVideo(hf, IS_DONT_WAIT);
   if (WaitForSingleObject(hEvent, 1000) == WAIT_OBJECT_0) {
      // Picture successful taken up
   }
   is_DisableEvent(hf, IS_SET_EVENT_FRAME);
   is_ExitEvent(hf, IS_SET_EVENT_FRAME);
}
```

# 4.54 is\_InquireImageMem

# Syntax:

INT is\_InquireImageMem (HIDS hf, char\* pcMem, int nID, int\* pnX, int\* pnY, int\* pnBits, int\* pnPitch);

# **Description:**

is\_InquireImageMem() reads the properties of the allocated image memory.

Parameters:

hf Camera handle

**pMem** Pointer to beginning of image memory from

is\_AllocImageMem()

NID ID of image memory from von is\_AllocImageMem()

pnX contains the width, with which the image memory was cre-

ated.

pnY contains the height, with which the image memory was cre-

ated.

**pnBits** contains the bit width, with which the image memory was cre-

ated.

**pnPitch** contains the line increment of the image memory.

#### Return value:

# 4.55 is\_IsVideoFinish

### Syntax:

INT is IsVideoFinish (HIDS hf, BOOL\* pbo)

### **Description:**

is\_IsVideoFinish() can check to see whether an image has been completely and fully acquired in the image memory. This function is useful when used together with is\_FreezeVideo() with the IS\_DONT\_WAIT parameter.

If \*pbo is preset with IS\_TRANSFER\_FAILED before the call of is\_IsVideoFinish(), the return value contains additional information whether a transfer error or an error in the pixel path occurred.

#### Parameters:

hf Camera handle

\*pbo != IS\_TRANSFER\_FAILED before the function call

pbo contains the digitizer status:

IS\_VIDEO\_NOT\_FINISH = digitizing not finished IS\_VIDEO\_FINISH = digitizing of image finished

\*pbo == IS\_TRANSFER\_FAILED before the function call

pbo contains the digitizer status:

IS\_VIDEO\_NOT\_FINISH = Digitization of the picture not yet

finished

IS\_VIDEO\_FINISH = Digitization of the picture finished IS\_TRANSFER\_FAILED = Transfer error or problem when

converting (e.g. goal memory in-

validly)

#### Return value:

# 4.56 is\_LoadBadPixelCorrectionTable

## Syntax:

INT is\_LoadBadPixelCorrectionTable (HIDS hf, char \*File)

#### **Description:**

is\_LoadBadPixelCorrectionTable() loads a table saved previously with the function SaveBad-PixelCorrectionTable(). File specifies the file in which the coordinates were saved; if a ZERO pointer is sent, a dialogue is displayed for selection of the file.

#### Parameters:

hf Camera handle

File Pointer to file with saved coordinates. Both the absolute and

the relative path can be passed.

#### Return value:

IS\_SUCCESS, IS\_NO\_SUCCESS

# 4.57 is\_LoadImage

#### Syntax:

INT is\_LoadImage (HIDS hf, char\* File)

#### **Description:**

is\_LoadImage() loads an image from a file. The image must be available in BMP format. The image is loaded into the active image memory (see also <u>4.37 is\_GetImageMem</u> and <u>4.105</u> is\_SetImageMem).

#### Parameters:

hf Camera handle

File Pointer on filename. Both the absolute and the relative path

can be passed.

#### Return value:

IS\_SUCCESS Image is loaded error free.

IS\_FILE\_READ\_INVALID\_BMP\_SIZE The image to be load is larger than the active image memory. IS\_FILE\_READ\_INVALID\_BMP\_ID The file to be load does not have a valid bitmap format.

IS\_FILE\_READ\_OPEN\_ERROR The file cannot be opened.

# 4.58 is\_LoadImageMem

#### Syntax:

INT is\_LoadImageMem (HIDS hf, char\* File, char\*\* ppcImgMem, int\* pid)

## **Description:**

is\_LoadImage() loads an image from a file. The image must be available in BMP format. The image is loaded into a new allocated image memory with the properties color format and depth. With the function is\_FreeImageMem () (see <u>4.18 is\_FreeImageMem</u>) the image memory is released.

#### Parameters:

Hf Camera handle

File Name of the image file, NULL -> "Open" dialog box is opened.

Both the absolute and the relative path can be passed.

**Pointer** to variable receiving the start address **Pid**Pointer to variable receiving a memory ID

#### Return value:

IS\_SUCCESS (image is loaded error free)

IS\_FILE\_READ\_INVALID\_BMP\_ID (the file to be loaded does not have a valid bitmap format)

IS\_FILE\_READ\_OPEN\_ERROR (the file cannot be opened)

# 4.59 is\_LoadParameters

### Syntax:

INT is\_LoadParameters (HIDS hf, char\* pFilename)

### **Description:**

is\_LoadParameters() loads the parameters of a camera that were previously saved as an ini file with is\_SaveParameters(). If NULL is passed as the value of pFilename, the Windows Open file dialog is displayed.

### **HINT**

ini files can only be loaded for the sensor type they were saved for. While loading an ini-file it is to consider that already allocated memory matches to the parameters of the ini-file concerning size (AOI) and colour depth. Otherwise this leads to incorrect displaying

Parameters:

hf Camera handle

**pFilename** Pointer on filename. Both the absolute and the relative path

can be passed.

## Return value:

IS\_SUCCESS, IS\_NO\_SUCCESS

## **Example ini-File:**

[Sensor]

Sensor=UI122x-M

[Image size]

Start X=0

Start Y=0

Start X absolute=0

Start Y absolute=0

Width=752

Height=480

Binning=0

Subsampling=0

[Timing]

Pixelclock=20

Framerate=30.003810

Exposure=33.329100

[Parameters]

Colormode=6

Brightness=100

Contrast=215

Gamma=1.000000

Blacklevel Mode=1

Blacklevel Offset=0

[Gain]

Master=0

Red=0

Green=0

Blue=0

[Processing]

EdgeEnhancement=0

RopEffect=0

Whitebalance=0

Whitebalance Red=1.000000

Whitebalance Green=1.000000

Whitebalance Blue=1.000000

Color correction=0

[Auto features]

Auto Framerate control=0

Brightness exposure control=0

Brightness gain control=0

Brightness reference=128

Brightness speed=50

Brightness max gain=-1.000000

Brightness max exposure=1.000000

Brightness Aoi Left=0

Brightness Aoi Top=0

Brightness Aoi Width=1280

Brightness Aoi Height=1024

Auto WB control=0

Auto WB offsetR=0

Auto WB offsetB=0

Auto WB gainMin=0

Auto WB gainMax=100

Auto WB speed=50

Auto WB Aoi Left=0

Auto WB Aoi Top=0

Auto WB Aoi Width=1280

Auto WB Aoi Height=1024

Auto WB Once=0

# 4.60 is\_LockDDMem

## Syntax:

INT is LockDDMem (HIDS hf, void\*\* ppMem, INT\* pPitch)

#### **Description:**

In DirectDraw mode *is\_LockDDMem()* gives access to the image memory and returns the address pointer to the beginning of the image memory. In most cases the image memory is on the VGA card. Using the pointer the image memory can be accessed directly. Access is disabled with *is\_UnlockDDMem()* – this must be done as soon as possible.

Digitizing to memory cannot be terminated with is\_LockDDMem()!

When in DirectDraw BackBuffer mode, within a LockDDMem –UnlockDDMem block there are no updates of the BackBuffer on the display!

#### Parameters:

hf Camera handle

**ppMem**Pointer to variable, which will contain address pointer. **pPitch**Pointer to variable, which will contain the pitch value.

#### Return value:

IS\_SUCCESS, IS\_NO\_SUCCESS

# 4.61 is\_LockDDOverlayMem

#### Syntax:

INT is\_LockDDOverlayMem(HIDS hf, void\*\* ppMem, INT\* pPitch)

### **Description:**

In DirectDraw mode *is\_LockDDOverlayMem()* gives access to the image memory and returns the address pointer to the beginning of the image memory. And thus the overlay buffer can be directly written to, without having to use the Windows GDI functions. pPitch returns the line offset in bytes from the beginning of one line to the beginning of the following line. Access must be disabled as soon as possible with the *UnlockDDOverlayMem()* function. Within a *LockDDMem – UnlockDDMem* block there are no updates of the BackBuffer on the display.

### Parameters:

hf Camera handle

**ppMem** Pointer to variable, which will contain address pointer. **pPitch** Pointer to variable, which will contain the pitch value.

### Return value:

# 4.62 is\_LockSeqBuf

# Syntax:

INT is\_LockSeqBuf (HIDS hf, INT nNum, char\* pcMem)

# **Description:**

is\_LockSeqBuf() can be used to disable the overwriting of the image memory with new image data. And thus it is possible to prevent images which are required for further processing from being overwritten. Full access to the image memory is still available.

Only one image memory can be disabled at the same time. To access the image memory use function *is\_UnlockSeqBuf()*.

# Parameters:

hf Camera handle

**nNum** Number of the disabled image memory (1...max).

pcMem Start address of the image memory, which should be pro-

tected.

### **HINT**

nNum indicates the position in the sequence list and not the memory ID assigned with *is\_AllocImageMem()*.

# Return value:

# 4.63 is\_PrepareStealVideo

## Syntax:

INT is\_PrepareStealVideo (HIDS hf, int Mode, ULONG StealColorMode)

# **Description:**

Sets the steal mode. There are two different steal modes

normal steal

This option initiates the stealing of a single image out of a DirectDraw live stream. This option redirect a single image out of a DirectDraw live stream into the current active user memory.

copy steal

This option shows the picture with DirectDraw and copies it into the current active image memory.

#### Parameters:

Hf Camera handle

Mode

IS\_SET\_STEAL\_NORMAL Normal modus IS\_SET\_STEAL\_COPY Copy modus StealColorMode Not used

# Return value:

# 4.64 is\_ReadEEPROM

#### Syntax:

INT is ReadEEPROM (HIDS hf, INT Adr, char\* pcString, INT Count)

## **Description:**

There is a rewritable EEPROM in the camera which serves as a small memory. Additionally to the information which is stored in the EEPROM, 64 extra bytes can be written. With the *is\_ReadEEPROM()* command the contents of these 64 bytes can be read. Also see <u>4.126</u> *is\_WriteEEPROM*.

#### Parameters:

hf Camera handle

Adr Begin address from where data is to be read: Value range 0

to 63

**pcString** Buffer for data to be read (min. size = Count)

**Count** Number of characters to be read

#### Return value:

IS\_SUCCESS, IS\_NO\_SUCCESS

## Example:

char buffer[64];
is\_ReadEEPROM(m\_hCam, 0x00, buffer, 64);

# 4.65 is\_ReleaseDC

## Syntax:

INT is\_ReleaseDC (HIDS hf, HDC hDC)

# **Description:**

In DirectDraw BackBuffer mode *is\_ReleaseDC()* releases the overlay buffer's device context handle. Once the handle has been released, an update of the overlay buffer on the display follows (if the overlay has been blended on with *is\_ShowDDOverlay()*).

# Parameters:

hf Camera handle

hDC Device context handle from is\_GetDC()

#### Return value:

# 4.66 is\_RenderBitmap

## Syntax:

INT is\_RenderBitmap (HIDS hf, INT nMemID, HWND hwnd, INT nMode)

### **Description:**

is\_RenderBitmap() displays images from an image memory in the defined window. For displaying the images Win32 Bitmap functions are used. Displaying generally takes place in the format, which was specified during allocation of the image memory. In the function is\_AllocImageMem() the parameter bitspixel specifies the colour depth and the presentation format. RGB16 and RGB 15 uses the same amount of memory, however they can be differentiated with the parameter bitspixel.

### **HINT**

The color format UYVY can only displayed expediently in the overlay mode. However this is not realizable with the functions of the Windows API.

#### Parameters:

hf Camera handle

**nMemID**ID of the memory which should be displayed **hwnd**Window handle of the display window

nMode

IS\_RENDER\_NORMAL Image output 1:1 from the memory IS\_RENDER\_FIT\_TO\_WINDOW Fit the image into the size of the window

IS\_RENDER\_ DOWNSCALE\_1\_2 Display the image with a size of 50% of the original size.

Options which can be OR combined with

the modes above:

IS\_RENDER\_MIRROR\_UPDOWN horizontal mirroring of the image

#### Return value:

IS\_SUCCESS or IS\_NO\_SUCCESS.

### Example:

Fit the image into a window with horizontal mirroring:

```
is_RenderBitmap (hf, nMemID, hwnd, IS_RENDER_FIT_TO_WINDOW |
    IS_RENDER_MIRROR_UPDOWN);
```

# 4.67 is\_ResetToDefault

# Syntax:

INT is\_ResetToDefault (HIDS hf)

Des	cri	pti	on:

is\_ResetToDefault() resets all parameters of the camera to the standard values.

Parameters:

hf Camera handle

Return value:

# 4.68 is\_SaveBadPixelCorrectionTable

# Syntax:

INT is\_SaveBadPixelCorrectionTable (HIDS hf, char \*File)

# **Description:**

*is\_SaveBadPixelCorrectionTable()* stores the current, user-defined hot pixel list into the file, indicated with the *file* parameter.

With handing over the value NULL for the parameter *File* a dialogue for the selection of the file is shown.

#### Parameters:

hf Camera handle

File Pointer to the file in which the data are stored. Both the abso-

lute and the relative path can be passed.

## Return value:

# 4.69 is\_SaveImage

## Syntax:

INT is SaveImage (HIDS hf, char\* File)

## **Description:**

Saves an image from the computer's memory to a file. The file is saved in BMP format. The images are read from the currently valid image memory (also see <u>4.37 is GetImageMem</u>). The readout of the graphic card memory can last several 100msec, depending on the image size. In DirectDraw modes the image data are read from the corresponding DirectDraw buffer. Consider in DirectDraw primary surface mode that the image is saved as displayed on the screen. The maximum image size is the size of the output window, independent of which image size is set with *is\_SetImageSize()*. Overlapped parts of the output window will be saved with the content of the overlapping window.

The bitmap is saved with an 8, 15, 16, 24 or 32 bit colour depth, as was allocated in the image memory and/or the colour mode of the DirectDraw mode. Some image processing programs do not support all 15 bit, 16 bit and 32 bit bitmaps and therefore will be unable to load the images. The file name can contain an absolute as well as a relative file path. With *is\_LoadImage()* the BMP images can be loaded.

Overlay data are not saved!

#### Parameters:

hf Camera handle File BMP file name

NULL -> Save as - dialog is displayed (see is\_CameraStatus()

for maintaining the selected directory path).

Both the absolute and the relative path can be passed.

#### Return value:

# 4.70 is\_SaveImageEX

## Syntax:

INT is Savelmage (HIDS hf, char\* File, fileFormat, INT Param)

## **Description:**

Saves an image from the computer's memory as bitmap or JPEG to a file (see also <u>4.69</u> <u>is SaveImage</u>). The images are read from the currently valid image memory. The bitmap is saved with an 8, 15, 16, 24 or 32 bit colour depth, as it was allocated in the image memory and/or the colour mode of the DirectDraw mode. Some image processing programs do not support all 15 bit, 16 bit and 32 bit bitmaps and therefore will be unable to load the images. The file name can contain an absolute as well as a relative file path.

#### Parameters:

hf Camera handle File BMP file name

NULL -> Save as - dialog is displayed (see is\_CameraStatus()

for maintaining the selected directory path).

Both the absolute and the relative path can be passed.

**fileFormat** determines the output format of the file

IS\_IMG\_BMP Bitmap IS\_IMG\_JPG JPEG

Param if JPEG is selected as file format, the quality of the compres-

sion can be set with this parameter. The quality can be set between 1 and 100, if this parameter is 0 the default quality

(75) is used.

# Return value:

# 4.71 is\_SaveImageMem

## Syntax:

INT is\_SaveImageMem (HIDS hf, char\* File, char\* pcMem, int nID)

## **Description:**

Saves an image in bitmap format (BMP) to a file. The images are read from the image memory. The bitmap is saved with an 8, 15, 16, 24 or 32 bit colour depth, as was allocated in the image memory. Some image processing programs do not support all 15 bit, 16 bit and 32 bit bitmaps and therefore will be unable to load the images.

Overlay data are not saved!

#### Parameters:

hf Camera handle

File Name of the BMP image file

NULL -> "Save as" dialog box is opened (see

*is\_CameraStatus()* for maintaining the selected directory path. Both the absolute and the relative path can be passed.)

pcMem Pointer to image memory nID ID of image memory

USE\_ACTUAL\_IMAGE\_SIZE OR nID: Save the image with

the current setting of height

## Return value:

# 4.72 is\_SaveImageMemEx

### Syntax:

INT is\_SaveImageMemEx (HIDS hf, char\* File, char\* pcMem, int nID,INT fileFormat,INT Param).

### **Description:**

Saves an image in bitmap format (BMP) or JPEG format. The images are read from the image memory. The bitmap is saved with an 8, 15, 16, 24 or 32 bit color depth, as allocated in the image memory. Some image processing programs do not support all 15 bits, 16 bits and 32 bits bitmaps and therefore will be unable to load the images. The JPEG file is always saved with a 8 bits or 24 bits color depth.

#### Parameters:

Hf Camera handle

File Name of the image file, NULL -> "Save as" dialog box is

opened.

Both the absolute and the relative path can be passed.

pcMem Pointer to image memory nID ID of image memory

**fileFormat** determines the output format of the file.

IS\_IMG\_BMP Bitmap file format IS\_IMG\_JPG JPeg file format

Param if JPEG is selected as file format, the quality of the compres-

sion can be set with this parameter. The quality can be set between 1 and 100, if this parameter is 0 the default quality

(75) is used.

# Return value:

IS\_SUCCESS, IS\_NO\_SUCCESS

IS\_INVALID\_PARAMETER (invalid file format or JPEG Quality)

# 4.73 is\_SaveParameters

# Syntax:

INT is\_SaveParameters (HIDS hf, char\* pFilename)

# **Description:**

is\_SaveParameters() saves the parameters of a camera to an ini file, which can later be loaded with is\_LoadParameters(). If NULL is passed as the value of pFilename, the Windows Save file dialog is displayed.

## Parameters:

hf Camera handle

**pFilename** Pointer on filename. Both the absolute and the relative path

can be passed.

## Return value:

IS\_SUCCESS, IS\_NO\_SUCCESS

## **Example ini-File:**

See 4.59 is LoadParameters

# 4.74 is\_SetAllocatedImageMem

### Syntax:

INT is\_SetAllocatedImageMem (HIDS hf, INT width, INT height, INT bitspixel, char\* pcImgMem, int\* pid)

## **Description:**

is\_SetAllocatedImageMem() defines an allocated memory to the current memory, in which the image will be digitized. The size of memory must be large enough and must be locked global! A memory indicated with is\_SetAllocatedImageMem() can be built into a sequence. The memory must be taken out of the driver-internal administration with is\_FreeImageMem(), before it is actually released. The allocated memory must not be reallocated.

The following steps have to be done:

- Allocate memory: HANDLE hgMem = GlobalAlloc (size);
- Lock memory: char\* pcMem = (char\*) GlobalLock (hgMem);

With the function *is\_SetAllocatedImageMem()* the address of the memory is given to the DCU driver. Additionally as with function *is\_AllocImageMem()* the size of the image must be set and as a result an identification number (pid) returns. This number might be needed in other functions. *is\_SetAllocatedImageMem (hf, width, height, bitspixel, pcMem, &ID)*;

# **HINT**

size >= (width \* height \* bitspixel / 8)

Now the image memory can be used. Sequences are also possible.

The area of the memory must be taken from driver administration again with the function is\_FreeImageMem (hf, pcMem, ID). With this the memory is NOT released.

The user must take care, that the memory is released:

- GlobalUnlock (hgMem);
- GlobalFree (hgMem);

#### Parameters:

hfCamera handlewidthWidth of imageheightHeight of image

bitspixelColour depth of image (bits per pixel)pcImgMemContains pointer to start of memory location.pidContains the ID for this memory location.

#### Return value:

# 4.75 is\_SetAOI

## Syntax:

INT is\_SetAOI (HIDS hf, INT type, INT \*pXPos, INT \*pYPos, INT \*pWidth, INT \*pHeight)

## **Description:**

With *is\_SetAOI()* the size and position of an AOI can be set with one command call. Possible AOI are:

- Image AOI
- Auto Brightness AOI
- Auto Whitebalance AOI

The auto image areas are used for appropriate auto functionality. As default value the window is always maximally, thus always as large as the current image AOI.

### HINT

After changes of image geometry, e.g. by new setting of the image AOI the Auto Feature AOI are always restored to the default value. This means that after a change of the image AOI or activation of binning the Auto Feature AOI must be set again. Auto Whitebalance AOI is not available in DirectDraw mode and in UYVY mode.

With the functions *is\_SetImagePos()* (see <u>4.106 is\_SetImagePos</u>) and *is\_SetImageSize()* (see <u>4.107 is\_SetImageSize()</u> information about the size and position of the AOI can be read out.

#### Parameters:

hf	Camera handle
Туре	
IS_SET_IMAGE_AOI	Set Image AOI
IS_GET_IMAGE_AOI	Returns the current Image AOI
IS_SET_AUTO_BRIGHT_AOI	Set the Auto Feature AOI for Auto Gain and Auto Shutter
IS_GET_AUTO_BRIGHT_AOI	Returns current average value of the AOI
IS_SET_AUTO_WB_AOI	Set AOI for Auto Whitebalance
IS_GET_AUTO_WB_AOI	Returns the current Auto Whitebalance AOI
pXPos	Horizontal position of the AOI
pYPos	Vertical position the AOI
pWidth	Width of the AOI
pHeight	Height of the AOI

### Return value:

IS\_SUCCESS, IS\_NO\_SUCCESS

## **Examples:**

&width,
&height);

# 4.76 is\_SetAutoParameter

## Syntax:

INT is\_SetAutoParameter (HIDS hf, INT param, double\* pval1, double\* pval2)

## **Description:**

is\_SetAutoParameter() controls Auto Gain, Auto Shutter, Auto Framerate and Auto Whitebalance functionality. Purpose of the auto functions is it to control the camera image in its average brightness and color rendering to the given value and to hold the picture framerate to a maximum value. While controlling the average brightness the exposure control is preferred. That means that the maximally possible exposure time is set, before the gain is controlled. AutoGain controls the MasterGain of the camera in the range of 0-100%. AutoExposure uses the current exposure range which result from pixelclock and framerate. The control limits can be set separately for exposure and gain.

The framerate can be changed further manually or automatically with activated shutter control, in order to maintain the range of the exposure control dynamically. The automatic framerate control has the purpose of adjusting the framerate to an optimal value. Thus the necessary control range is available for shutter control in all situations with a framerate as high as possible. During the control of the white balance the RGB gain settings of the camera are changed within the range 0-100% until the red and the blue channel reaches the average brightness of the green channel. In order to get a desired color rendering the setpoint for the red and the blue channel can be adjusted by an offset relative to the green channel.

The speed of the auto functions can be adjusted in a range of 0 - 100%. Thus the absorbability and/or the inertia of the regulation are affected. High speed (100%) results in a small absorbability for a fast reacting regulation and in reverse. In this connection the control for the average brightness and the control for the color rendering use separated speeds.

By setting the parameter *IS\_SET\_AUTO\_WB\_ONCE* the white balance can be terminated automatically, as soon as the target value was reached. The end of the control is communicated to the system over an event/message (see also <u>4.53 is\_InitEvent</u>). Alternatively the control keeps active and reacts to deviations from the target value.

#### HINT

With activating AutoShutter the adjustment of the pixel clock using the function is\_SetPixelClock() is deactivated.

AutoFramerate is only possible with activated AutoShutter control because the Auto-Framerate adjusts the shutter range dynamically and AutoGain was never activated. Therefore these two features are mutually locked.

AutoGain is only possible for cameras with MasterGain adjustment.

Auto Whitebalance is possible only for cameras with hardware RGB Gain adjustment. With activated Auto Whitebalance the activation of the software Whitebalance over the function *is\_SetWhiteBalance()* is disabled. This is also deactivated, if it is active when activating the Auto Whitebalance.

#### Parameters:

hf	Camera handle
param	
IS_SET_ENABLE_AUTO_GAIN	Acvtivates/deactivates the AutoGain functionality
IS_GET_ENABLE_AUTO_GAIN	Returns the current AutoGain settings
IS_SET_ENABLE_AUTO_SHUTTER	Acvtivates/deactivates the AutoShutter functionality
IS_GET_ENABLE_AUTO_SHUTTER	Returns the current AutoShutter settings
IS_SET_ENABLE_AUTO_WHITEBALANCE	Acvtivates/deactivates the AutoWhitebalance functionality
IS_GET_ENABLE_AUTO_WHITEBALANCE	Returns the current AutoWhitebalance settings
IS_SET_ENABLE_AUTO_FRAMERATE	Acvtivates/deactivates the AutoFramerate functionality
IS_GET_ENABLE_AUTO_FRAMERATE	Returns the current AutoFramerate settings
IS_SET_AUTO_REFERENCE	Set setpoint for AutoGain/AutoShutter. Corresponds to a grey value of 0-255.
IS_GET_AUTO_REFERENCE	Returns the setpoint of AutoGain/AutoShutter
IS_SET_AUTO_GAIN_MAX	Set upper control level for AutoGain
IS_GET_AUTO_GAIN_MAX	Returns the upper control level of AutoGain
IS_SET_AUTO_SHUTTER_MAX	Set upper control level for AutoShutter
IS_GET_AUTO_SHUTTER_MAX	Returns upper control level of AutoShutter
IS_SET_AUTO_SPEED	Sets the speed value of the auto function.
IS_GET_AUTO_SPEED	Returns the speed value of the auto function.
IS_SET_AUTO_WB_OFFSET	Sets the offset for the red and the blue channel.
IS_GET_AUTO_WB_OFFSET	Returns the offset values of the red channel and the blue channel.
IS_SET_AUTO_WB_GAIN_RANGE	Sets the control range for Auto Whitebalance.
IS_GET_AUTO_WB_GAIN_RANGE	Returns the control range of Auto Whitebalance.
IS_SET_AUTO_WB_SPEED	Sets the speed for Auto Whitebalance.
IS_GET_AUTO_WB_SPEED	Returns the speed range of Auto Whitebalance.
IS_SET_AUTO_WB_ONCE	Sets the automatic termination of the Auto Whitebalance.
IS_GET_AUTO_WB_ONCE	Returns the current state of the Auto Whitebalance.
pval1	Parameter (value)
pval2	Parameter (value)

The parameters *pval1* und *pval2* can take different values depending upon the used type of the parameter *param*.

# **Auto Brightness function**

For the enable parameter variable *pval1* accepts the values 0 (inaktiv) and 1(active). In the case of the nominal value the value describes a grey tone of 0-255. For the control limits valid values for GAIN (0-100) and SHUTTER (exposure time) are adjusted.

If the value 0 is handed over for the parameter *IS\_SET\_AUTO\_SHUTTER\_MAX* the maximum shutter time is set. If this is changed by adjustment of the camera timing, the value is updated. However if a value within the current limits is handed over, this remains so long set, until a new value is handed over. With the readout of the shutter limit the user value or, if 0 was handed over, the maximum limit value is returned.

### **Auto Whitebalance function**

With the settings for offset and GainRange of the Auto Whitebalance function both variables are used. In order to adjust the offset for the red and the blue channel, the offset for red is handed over as variable *pval1* and the offset for blue is handed over as *pval2*. The offset can be adjusted in a range from -50 to +50. Within the specified limits *pval1* stand for the minimum and *pval2* stand for the maximum gain value. The limits can be specified in a range from 0 to 100. If

the maximum gain value should be smaller than the minimum, the maximum is set on the minimum gain value and reverse.

If only one of the parameters *pval1/pval2* is to be handed over, then a NULL-pinter is to be used for the other parameter.

If the settings are to be returned, then the values are written to the addresses indicated as *pval1* and *pval2*.

## Pre-defined values for the auto features: (values obviously out of uc480.h)

IS\_DEFAULT\_AUTO\_BRIGHT\_REFERENCE Default setpoint for AutoGain and AutoShutter IS\_MIN\_AUTO\_BRIGHT\_REFERENCE Minimum setpoint for AutoGain and AutoShutter IS\_MAX\_AUTO\_BRIGHT\_REFERENCE Maximum setpoint for AutoGain and AutoShutter IS DEFAULT AUTO SPEED Default value for AutoSpeed IS\_MIN\_AUTO\_SPEED Minimum setpoint for AutoSpeed IS\_MIN\_AUTO\_SPEED Maximum setpoint for AutoSpeed - currently not used IS\_DEFAULT\_WB\_OFFSET Default value for Auto Whitebalance Offset IS\_MIN\_WB\_OFFSET Minimum value for Auto Whitebalance Offset IS\_MAX\_WB\_OFFSET Maximum value for Auto Whitebalance Offset IS\_DEFAULT\_AUTO\_WB\_SPEED Default value for Auto Whitebalance speed IS\_MIN\_AUTO\_WB\_SPEED Minimum value for Auto Whitebalance speed IS\_MAX\_AUTO\_WB\_SPEED Maximum value for Auto Whitebalance speed

# Further possibilities of activate/deactivating the AutoBrightness functions:

AutoGain functionality can be activated with the function *is\_SetHardwareGain()*, if the parameter IS\_SET\_ENABLE\_AUTO\_GAIN will be used instead of the first value. The auto functionality is again deactivated by setting a value (see also <u>4.100</u> <u>is\_SetHardwareGain</u>).

AutoExposure funtionality can be activated with the function *is\_SetExposureTime()*, if the parameter *IS\_SET\_ENABLE\_AUTO\_SHUTTER* will be used. The auto functionality is again deactivated by setting a value (see also <u>4.93 is\_SetExposureTime</u>).

## Return value:

IS\_SUCCESS, IS\_NO\_SUCCESS

#### **Examples:**

```
Activate AutoGain:
```

```
Double dEnable = 1;
int ret = is_SetAutoParameter (m_hCam ,IS_SET_ENABLE_AUTO_GAIN,
&dEnable, 0);
```

#### Set brightness setpoint to 128:

```
double soll = 128;
int ret = is_SetAutoParameter (m_hCam, IS_SET_AUTO_REFERENCE, &soll,
0);
```

# Readout shutter control limit:

```
double maxShutter;
int ret = is_SetAutoParameter (m_hCam, IS_GET_AUTO_SHUTTER_MAX, & max-
Shutter, 0);
```

# 4.77 is\_SetBadPixelCorrection

## Syntax:

INT is\_SetBadPixelCorrection (HIDS hf, INT nEnable, INT threshold)

## **Description:**

*is\_SetBadPixelCorrection()* switches the hot pixel correction on or off. A selection among three different versions is possible.

## Parameters:

hf	Camera handle
nEnable	
IS_BPC_DISABLE	Switches the correction off
IS_BPC_ENABLE_HARDWARE	Activates hardware correction (only UI_141x sensors), threshold parameter is used
IS_BPC_ENABLE_SOFTWARE	Activates software correction on basis of the hot pixel list deposited in the EEPROM.
IS_BPC_ENABLE_USER	Activates software correction with user defined values. The function <i>is_SetBadPixelCorrectionTable()</i> must selected first
IS_GET_BPC_MODE	Indicates the current mode.
IS_GET_BPC_THRESHOLD	Indicates the current threshold value.
threshold	Only used with UI_141x sensors in connection with parameter <i>IS_BPC_ENABLE_HARDWARE</i> .
	Affects the degree of the correction.

There is the possibility of linking hardware correction with a software mode; both software corrections, however, cannot be used together. Possible combinations are:

- 1) IS\_BPC\_DISABLE
- 2) IS\_BPC\_ENABLE\_HARDWARE
- 3) IS\_BPC\_ENABLE\_SOFTWARE
- 4) IS\_BPC\_ENABLE\_USER
- 5) IS\_BPC\_ENABLE\_HARDWARE | IS\_BPC\_ENABLE\_SOFTWARE
- 6) IS\_BPC\_ENABLE\_HARDWARE | IS\_BPC\_ENABLE\_USER

## Return value:

IS\_SUCCESS, IS\_NO\_SUCCESS, the current mode in connection with IS\_GET\_BPC\_MODE or the current level in connection with IS\_GET\_BPC\_THRESHOLD

# 4.78 is\_SetBadPixelCorrectionTable

## Syntax:

INT is\_SetBadPixelCorrectionTable (HIDS hf, INT nMode, WORD \*pList)

## **Description:**

is\_SetBadPixelCorrectionTable() sets the table with hot pixels that is used for the user-defined hot pixel correction. The hotpixel correction is switched on. Each value in the table consists of one 2-byte WORD data type. The first value specifies the number of pixel coordinates within the table; this is followed by the coordinates (first X, then Y).

A table with 3 hot pixels must be structured as follows:

3	X1	Y1	X2	Y2	Х3	Y3

### Parameters:

hf	Camera handle
nMode	
IS_SET_BADPIXEL_LIST	Sets a new user-defined list.
	The parameter pList indicates a list in the previously written format.
IS_GET_LIST_SIZE	Indicates the number of pixel coordinates that there are in the user-defined list.
IS_GET_BADPIXEL_LIST	Copies the user-defined table in the parameter pList; the

memory must be reserved first.

# **Examples for reading out the table:**

```
WORD *pList = NULL;
// number of coordinates in the table
DWORD nCount = is_SetBadPixelCorrectionTable(hf, IS_GET_LIST_SIZE,
NULL);
// allocate memory for table
pList = new WORD[ 1 + 2*nCount ];
is_SetBadPixelCorrectionTable(hf, IS_GET_BADPIXEL_LIST, pList);
// clear table
delete [] pList;
```

### Return value:

 $IS\_SUCCESS$ ,  $IS\_NO\_SUCCESS$ , or the number or coordinates in the list with  $IS\_GET\_LIST\_SIZE$ 

# 4.79 is\_SetBayerConversion

# Syntax:

INT is\_SetBayerConversion (HIDS hf, INT nMode)

# **Description:**

*is\_SetBayerConversion()* makes *it* possible to select among three different color conversion algorithms, which differ in the quality and the necessary CPU load.

# **Boundary conditions**

Function only valid for 24-Bit, 32-Bit and Y8 colour format.

# Parameters:

nf 	_	Camera handle
1Mc	ode	
	IS_SET_BAYER_CV_NORMAL	Standard conversion is no longer supported. If this mode is selected the better algorithm is used.
	IS_SET_BAYER_CV_BETTER	Better quality – higher CPU load
	IS_SET_BAYER_CV_BEST	Highest quality - highest CPU load
	IS_GET_BAYER_CV_MODE	Current settings are returned.

#### **Return values:**

In connection with <code>IS\_GET\_BAYER\_CV\_MODE</code> the current settings are read, else <code>IS\_SUCCESS</code> or <code>IS\_NO\_SUCCESS</code>.

# 4.80 is\_SetBinning

## Syntax:

INT is SetBinning (HIDS hf, INT mode)

## **Description:**

With *is\_SetBinning()* the binning mode can be activated both in horizontal and in vertical direction. Thus the image size for each binnig direction can be halved or quartered. Depending on the sensor the sensitivity or the framerate can be increased with activated binning. For the simultaneous activation of horizontal and vertical binning the horizontal and vertical binning parameters can be combined by a logical OR.

#### Parameters:

hf camera handle

mode

IS\_BINNING\_DISABLE Deactivates binning.

IS\_BINNING\_2X\_VERTICAL Activates 2x vertical binning
IS\_BINNING\_4X\_VERTICAL Activates 4x vertical binning
IS\_BINNING\_2X\_HORIZONTAL Activates 2x horizontal binning
IS\_BINNING\_4X\_HORIZONTAL Activates 4x horizontal binning
IS\_GET\_BINNING Returns the current settings

IS\_GET\_SUPPORTED\_BINNING Returns the supported binning modes

IS\_GET\_BINNING\_TYPE The return value specifies whether the camera uses colour

conserving Binning (IS\_BINNING\_COLOR) or not

(IS\_BINNING\_MONO)

#### Return value:

IS SUCCESS, IS NO SUCCESS or the current settings with IS GET BINNING

# 4.81 is\_SetBICompensation

# Syntax:

INT is\_SetBlCompensation (HIDS hf, INT nEnable, INT offset, INT reserved)

# **Description:**

*is\_SetBlCompensation()* activates black level compensation which can be used to improve image quality if necessary. Depending on the time of the change of the compensation this affects only with the recording of the next image.

#### Parameters:

hf nEnable	Camera handle
IS_BL_COMPENSATION_DISABLE	Turns the compensation off
IS_BL_COMPENSATION_ENABLE IS_GET_BL_COMPENSATION IS_GET_BL_OFFSET	Activates black level compensation using the set offset value.  Returns the current mode.  Returns the current offset.
IS_GET_BL_DEFAULT_MODE IS_GET_BL_DEFAULT_OFFET IS_GET_BL_SUPPORTED_MODE	Returns the standard mode Returns the standard offset Returns the supported modes
.o_o_r_b_	Possible values:  IS_BL_COMPENSATION_ENABLE  The used sensor supports black level compensation  IS_BL_COMPENSATION_OFFSET  With the used sensor only the offset of the black level compensation can be set
IS_IGNORE_PARAMETER offset	The parameter <i>nEnable</i> is ignored.  Contains the offset which is used for the compensation. Valid values lie between 0 and 255.
IS_IGNORE_PARAMETER	The parameter <i>offset</i> is ignored.

## Return value:

IS\_SUCCESS, IS\_NO\_SUCCESS, current settings with IS\_GET\_BL\_COMPENSATION, or the preset offset with IS\_GET\_BL\_OFFSET

# 4.82 is\_SetBrightness

## Syntax:

INT is SetBrightness (HIDS hf, INT Bright)

## **Description:**

*is\_SetBrightness()* sets the brightness of the image digital. The parameter *Bright* can have a value of between 0 and 255. The adjustment of the brightness is carried out by changing the luminance value, with an offset of the *Bright* parameter. *Bright* is set at the default value of 128 (*IS\_DEFAULT\_BRIGHTNESS*).

#### Parameters:

hf Camera handle

**Bright** 

0...255 Brightness in the range of 0 and 255

IS\_GET\_BRIGHTNESS retrieves the current setting

#### Return value:

Current setting when called with *IS\_GET\_BRIGHTNESS* else *IS\_SUCCESS*, *IS\_NO\_SUCCESS*.

# 4.83 is\_SetCameralD

### Syntax:

INT is\_SetCameralD (HIDS hf, INT nID)

# **Description:**

*is\_SetCameralD()* makes it possible to assign the ID number, which can be used to open the Camera (see also is\_InitCamera).

## Parameters:

hf Camera handle

nID

1..254 New camera ID

IS\_GET\_CAMERA\_ID Returns the current ID

#### Return value:

In connection with <code>IS\_GET\_CAMERA\_ID</code> the current ID is returned, else <code>IS\_SUCCESS</code> or <code>IS\_NO\_SUCCESS</code>.

# 4.84 is\_SetColorCorrection

## Syntax:

INT is\_SetColorCorrection (HIDS hf, INT nEnable, double \*factors)

# **Description:**

In order to receive a better colour reproduction, with *is\_SetColorCorrection()* a colour matching can be activated.

# HINT

After changing these parameters, a white balance adjustment must be done (see 4.76 is\_SetAutoParameter)

#### Parameters:

hf Camera handle

IS\_CCOR\_DISABLE Deactivates colour correction
IS\_CCOR\_ENABLE Activates colour correction
IS\_GET\_CCOR\_MODE Returns current settings

factors reserved

#### Return value:

Current settings when called with  $IS\_GET\_CCOR\_MODE()$ , else  $IS\_SUCCESS$ ,  $IS\_NO\_SUCCESS$ 

# 4.85 is\_SetColorMode

## Syntax:

INT is SetColorMode (HIDS hf, INT Mode)

## **Description:**

is\_SetColorMode() sets the required colour mode with which the image data is to be saved or displayed by the VGA board. For the first case it is important that, depending upon the colour mode which is used, the allocated image memory is large enough. A 24 bit colour image requires three times as much memory as an 8 bit monochrome image. When accessing the image data, it is important to know how the memory is arranged in each of the memory modes (see <a href="2.4">2.4</a> Colour formats). Incorrect interpretation of the memory contents leads to incorrect results. With the direct transfer to the VGA card's image memory, it is important to ensure that the display settings correspond to those of the colour mode. Under certain circumstances the images can be displayed with either the incorrect colours or they can become so distorted that it is impossible to recognize what is actually being displayed.

### Parameters:

hf	Camera handle
Mode	
IS_SET_CM_RGB32	32 bit true colour mode; R-G-B-Dummy
IS_SET_CM_RGB24	24 bit true colour mode; R-G-B
IS_SET_CM_RGB16	Hi colour mode; 5 R - 6 G - 5 B
IS_SET_CM_RGB15	Hi colour mode; 5 R - 5 G - 5 B
IS_SET_CM_Y8	8 bit monochrome image
IS_SET_CM_BAYER	Raw-Bayer data at colour sensors
IS_SET_CM_UYVY	16 Bit UYVY Format
IS_GET_COLOR_MODE	Retrieval of current setting

#### Return value:

Current setting when called with *IS\_GET\_COLOR\_MODE*, else *IS\_SUCCESS*, *IS\_NO\_SUCCESS*.

# 4.86 is\_SetContrast

# Syntax:

INT is\_SetContrast (HIDS hf, INT Cont)

# **Description:**

is\_SetContrast() changes the images contrast (luminance amplification) digital in the range of 0% to 200%

## Parameters:

hf Camera handle

Cont

0...511 Sets contrast

IS\_GET\_CONTRAST Retrieval of current setting

# Return value:

Current settings when called with IS\_GET\_CONTRAST else IS\_SUCCESS, IS\_NO\_SUCCESS.

# 4.87 is\_SetConvertParam

## Syntax:

INT is\_SetConvertParam(HIDS hf, BOOL ColorCorrection, INT BayerConversionMode, INT ColorMode, INT Gamma, double \*WhiteBalanceMultipliers)

#### **Description:**

Sets the conversion parameters for the Raw Bayer image that will be converted to other format with the function is\_ConvertImage(). This function sets:

- · color correction
- bayer conversion mode
- · color mode
- gamma
- white balance multipliers.

#### Parameters:

Hf Camera handle

**ColorCorrection** activates/desactivates the color correction

**BayerConversionMode** sets the bayer conversion mode.

IS\_SET\_BAYER\_CV\_BETTER Better quality

IS\_SET\_BAYER\_CV\_BEST Highest quality – higher CPU load

ColorMode sets the color mode of the output image

IS\_SET\_CM\_RGB32 32 bit true colour mode; R-G-B-Dummy IS\_SET\_CM\_RGB24 24 bit true colour mode; R-G-B IS\_SET\_CM\_RGB16 Hi colour mode; 5 R - 6 G - 5 B

IS\_SET\_CM\_RGB15 Hi colour mode; 5 R - 5 G - 5 B IS\_SET\_CM\_Y8 8 bit monochrome image IS\_SET\_CM\_UYVY 16 Bit UYVY Format

**Gamma** Gamma value multiplied with 100. - Range: [1...1000] WhiteBalanceMultipliers pointer to a double array with the red, green and blue gains

#### Return value:

IS\_SUCCESS, IS\_NO\_SUCCESS, IS\_INVALID\_COLOR\_FORMAT or IS\_INVALID\_PARAMETER

### **Example:**

See 4.6 is ConvertImage

# 4.88 is\_SetDDUpdateTime

# Syntax:

INT is\_SetDDUpdateTime (HIDS hf, INT ms)

# **Description:**

*is\_SetDDUpdateTime()*sets the timer interval for the update cycle of the video image in Direct-Draw BackBuffer mode. Valid values are between 20ms and 2000ms.

## Parameters:

hf Camera handle
ms Time in milliseconds

# Return value:

#### 4.89 is\_SetDisplayMode

# Syntax:

INT is SetDisplayMode (HIDS hf, INT Mode)

### **Description:**

is\_SetDisplayMode() defines the way in which images are displayed on the screen. For real live video plus overlay, the DirectDraw overlay surface mode has been introduced. The availability of this mode depends upon the type of VGA card used.

To use any DirectDraw mode colormode has to be set to UYVY.

Using a VGA resolution of 640x480 the image size must be limited to the same size before starting a Direct-Draw mode. For this purpose function is\_SetImageSize() can be used. For example: VGA with 1024x768x16 = 1.5 MB -> OverlayBuffer with up to 1.5 MB

### HINT

The DCU SDK is thread safe in general. The API function calls are all done in critical sections. Due to internal structures of DirectDraw we strongly recommend to call the following functions from only one thread to avoid unpredictable behaviour of your application.

> is\_InitCamera() is\_SetDisplayMode() is\_ExitCamera()

## Parameters:

hf Camera handle

Mode

IS\_SET\_DM\_DIB Acquire image in image memory (RAM)

(no automatic display - display possible with

is\_RenderBitmap()!)

IS SET DM DIRECTDRAW | DirectDraw mode (back buffer mode)

IS\_SET\_DM\_BACKBUFFER

IS\_SET\_DM\_DIRECTDRAW | Overlay surface mode

IS\_SET\_DM\_ALLOW\_OVERLAY DirectDraw overlay surface exten-

sion

IS\_SET\_DM\_ALLOW\_SCALING

Real time scaling in overlay surface mode

Return mode

IS\_GET\_DISPLAY\_MODE Return the current settings

## Return value:

Current setting with IS\_GET\_DISPLAY\_MODE, else IS\_SUCCESS, IS\_NO\_SUCCESS

#### **Example:**

is\_SetDisplayMode (hf, Mode);

Bitmap-Modus (digitized in system memory):

Mode = IS\_SET\_DM\_DIB

```
DirectDraw back buffer mode (Overlay possible. See is_EnableDDOverlay)
```

```
Mode = IS_SET_DM_DIRECTDRAW
```

# Allows memory storage in system memory:

```
Mode = IS_SET_DM_DIRECTDRAW | IS_SET_DM_ALLOW_SYSMEM
```

DirectDraw overlay surface mode (best live overlay):

Mode = IS\_SET\_DM\_DIRECTDRAW | IS\_SET\_DM\_ALLOW\_OVERLAY

## Allows automatic scaling to the size of window:

```
Mode = IS_SET_DM_DIRECTDRAW | IS_SET_DM_ALLOW_OVERLAY
IS_SET_DM_ALLOW_SCALING
```

# 4.90 is\_SetDisplayPos

### Syntax:

INT is\_SetDisplayPos (HIDS hf, INT x, INT y)

## **Description:**

The function *is\_SetDisplayPos()* enables the offset for the image output, produced with is\_RenderBitmap. The offset takes place by the parameters *x* and *y*.

## Parameters:

hf Camera handle
x Offset in x direction
y Offset in y direction

#### Return value:

# 4.91 is\_SetEdgeEnhancement

## Syntax:

INT is SetEdgeEnhancement (HIDS hf, INT nEnable)

### **Description:**

Due to the colour conversion of the Bayer format the original edges can become out of focus. The activation of the digital edge enhancer, counteract this effect. Two settings (IS\_EDGE\_EN\_STRONG, IS\_EDGE\_EN\_WEAK) with different effects are available. Using this function increases CPU load.

#### Parameters:

hf Camera handle

nEnable

IS\_EDGE\_EN\_DISABLE
IS\_EDGE\_EN\_STRONG
IS\_EDGE\_EN\_WEAK
IS\_GET\_EDGE\_ENHANCEMENT
Deactivates the edge enhancer
Activates the strong edge enhancer
Activates the weak edge enhancer
Returns the current settings

#### Return value:

IS\_SUCCESS or IS\_NO\_SUCCESS

# 4.92 is\_SetErrorReport

### Syntax:

INT is SetErrorReport (HIDS hf, INT Mode)

## **Description:**

Toggles the error report mode. When the error report mode is active, errors are displayed in a dialog box. When you quit the dialog box with *Cancel*, the error reporting is automatically deactivated. If the error report mode is not active, errors may be called up with *is\_GetError()*. The camera handle is not analysed, *is\_SetErrorReport()* is working global, not device related. *is\_SetErrorReport()* can be called up before function *is\_InitCamera()*.

## Parameters:

hf Camera handle or NULL

Mode

IS\_DISABLE\_ERR\_REP Disable error report IS\_ENABLE\_ERR\_REP Enable error report

#### Return value:

Current setting when called with *IS\_GET\_ERR\_REP\_MODE* else *IS\_SUCCESS*, *IS\_NO\_SUCCESS*.

# 4.93 is\_SetExposureTime

## Syntax:

INT is SetExposureTime (HIDS hf, double EXP, double\* newEXP)

## **Description:**

The function *is\_SetExposureTime()* sets the with *EXP* indicated exposure time in ms. Since this is adjustable only in multiples of the time, a line needs, the actually used time can deviate from the desired value.

Exposure-time interacting functions:

- is\_SetImageSize
- is\_SetPixelClock
- is\_SetFrameRate (only if the new image time will be shorter than the exposure time)

Which minimum and maximum values are possible and the dependence of the individual sensors is explained in detail in the description to the DCU timing.

Depending on the time of the change of the exposure time this affects only with the recording of the next image.

#### Parameters:

hf Camera handle

**EXP** New desired exposure-time.

IS\_GET\_EXPOSURE\_TIME Returns the actual exposure-time through parameter

newEXP.

If EXP = 0.0 is passed, an exposure time of 1/framerate is

used.

IS\_GET\_DEFAULT\_EXPOSURE Returns the default exposure time.

**newEXP** Actual exposure time.

## **HINT**

In the case of use of the constant *IS\_SET\_ENABLE\_AUTO\_SHUTTER* for the parameter *EXP* the AutoExposure functionality is activated. Setting a value will deactivate the functionality. (see also *4.76 is\_SetAutoParameter*).

#### Return value:

# 4.94 is\_SetExternalTrigger

## Syntax:

INT is\_SetExternalTrigger (HIDS hf, INT nTriggerMode)

### **Description:**

is\_SetExternalTrigger() activates the trigger input. This function call sets the edge on which an action takes place. When the trigger input is active, is\_FreezeVideo() function waits for an input of the trigger signal.

- Action on high low edge (TTL) IS\_SET\_TRIG\_HI\_LO
- Action on low high edge (TTL) IS\_SET\_TRIG\_LO\_HI
- Deactivates trigger IS\_SET\_TRIG\_OFF

If wihtout trigger functionality (IS\_SET\_TRIG\_OFF) the level at the trigger input can be queried statically. Thus the trigger input is used as digital input.

#### HINT

Due to the time response of the UI-144x-xx with this model the exposure time must be set to the value 1/framerate in the trigger mode.

#### Parameters:

hf Camera handle

nTriggerMode

IS\_SET\_TRIG\_OFF Disable trigger processing.

IS\_SET\_TRIG\_HI\_LO Sets active trigger flank to the negative edge.

IS\_SET\_TRIG\_LO\_HI Sets active trigger flank to the positive edge.

IS\_SET\_TRIG\_SOFTWARE Activate the software trigger mode; With call of the

function is\_FreezeVideo() the camera is triggered and

supplies a picture.

IS\_GET\_EXTERNALTRIGGER Retrieval of trigger mode settings

IS\_GET\_TRIGGER\_STATUS Return the current level at the trigger input. IS\_GET\_SUPPORTED\_TRIGGER\_MODE Return the supported trigger modes.

### Return value:

IS\_SUCCESS, IS\_NO\_SUCCESS or current setting with IS\_GET\_EXTERNALTRIGGER IS\_SET\_TRIG\_SOFTWARE | IS\_SET\_TRIG\_HI\_LO | IS\_SET\_TRIG\_LO\_HI using IS\_GET\_SUPPORTED\_TRIGGER\_MODE

#### **Example:**

```
Activate trigger mode and set High-Active flash mode.
```

```
is_SetExternalTrigger(hf, IS_SET_TRIG_SOFTWARE);
is_SetFlashStrobe(hf, IS_SET_FLASH_HI_ACTIVE);
is_FreezeVideo(hf, IS_WAIT);
```

# 4.95 is\_SetFlashDelay

# Syntax:

INT is\_SetFlashDelay (HIDS hf, ULONG ulDelay, ULONG ulDuration)

## **Description:**

*is\_SetFlashDelay()* allows you to set the time by which flash activation is delayed. In addition, the duration of the flash can be set. This allows a global flash function to be implemented where all rows of a rolling shutter sensor are exposed. (See also <u>4.35 is\_GetGlobalFlashDelays</u>). If 0 is given for *ulDelay*, the normal flash function is used.

If only the flash is to be activated with a delay, but not deactivated before the end of the image, 0 can be passed for the flash duration *ulDuration*.

#### Parameters:

hf	Camera handle
ulDelay	Time the flash is delayed (in µs)
IS_GET_FLASH_DELAY	Returns the current delay time.
IS_GET_FLASH_DURATION	Returns the current flash duration time.
IS_GET_MIN_FLASH_DELAY	Returns the minimum adjustable value for the flash delay.
IS_GET_MIN_FLASH_DURATION	Returns the minimum adjustable value for the flash duration.
IS_GET_MAX_FLASH_DELAY	Returns the maximum adjustable value for the flash delay
IS_GET_MAX_FLASH_DURATION	Returns the maximum adjustable value for the flash duration.
IS_GET_FLASH_DELAY_GRANULARITY	The resolution of the adjustable flash delay.
IS_GET_FLASH_DURATION_GRANULARITY	The resolution of the adjustable flash dduration.
ulDuration	Time in that is switched on lightning (in µs)

# Return value:

*IS\_SUCCESS, IS\_NO\_SUCCESS*, current settings in connection with *IS\_GET\_FLASH\_DELAY* or *IS\_GET\_FLASH\_DURATION*.

#### 4.96 is\_SetFlashStrobe

## Syntax:

INT is SetFlashStrobe (HIDS hf, INT nMode, INT nLine)

### **Description:**

is\_SetFlashStrobe() activates the flash strobe. Using the nMode parameter the actuation can be activated or deactivated. You can also set the active level (high or low). By default, the strobe is set to high-active.

The constants IS\_SET\_FLASH\_HIGH and IS\_SET\_FLASH\_LOW allow the strobe output to be used as a digital output.

Flash duration and delay can be set with the is\_SetFlashDelay() function (see 4.95 is\_SetFlashDelay). For cameras with Rolling Shutter sensors it is recommended to use the values from the function is\_GetGlobalFlashDelays () (see also 4.35 is\_GetGlobalFlashDelays) as flash delay and flash duration, because otherwise unexpected results can occour. For flash output in capture mode this is especially to be attended.

For the modes high-active and low-active the respective parameter must be selected suitably for the camera mode.

IS\_SET\_FLASH\_LO\_ACTIVE and IS\_SET\_FLASH\_HI\_ACTIVE are used in trigger mode (see also <u>4.94 is SetExternalTrigger</u>).

IS\_SET\_FLASH\_LO\_ACTIVE\_FREERUN and IS\_SET\_FLASH\_HI\_ACTIVE\_FREERUN are working only in capture mode (see 4.4 is Capture Video).

### Parameters:

hf	Camera handle

#### nMode

IS SET FLASH OFF Switches the strobe output off. IS\_SET\_FLASH\_LO\_ACTIVE Switches the strobe output Low-Active. IS\_SET\_FLASH\_HI\_ACTIVE Switches the strobe output High-Active. IS\_SET\_FLASH\_LO\_ACTIVE\_FREERUN Switches the strobe output Low-Active in freerun mode. IS\_SET\_FLASH\_HI\_ACTIVE\_FREERUN Switches the strobe output High-Active in freerun mode. IS\_SET\_FLASH\_HIGH Switches the strobe output HIGH. IS\_SET\_FLASH\_LOW Switches the strobe output LOW. IS\_GET\_FLASHSTROBE\_MODE Return the current mode.

nLine reserved

# **HINT**

The parameters IS\_SET\_FLASH\_LO\_ACTIVE\_FREERUN and IS\_SET\_FLASH\_HI\_ACTIVE\_FREERUN are not supported with the cameras UI-1440 und UI-1210.

#### Return value:

IS SUCCESS. IS NO SUCCESS, the current mode when used with *IS\_GET\_FLASHSTROBE\_MODE* 

### **Example:**

Activate trigger mode and set *High-Active* flash mode. is\_SetExternalTrigger(hf, IS\_SET\_TRIG\_SOFTWARE); is\_SetFlashStrobe(hf, IS\_SET\_FLASH\_HI\_ACTIVE,0); is\_FreezeVideo(hf, IS\_WAIT);

# 4.97 is SetFrameRate

# Syntax:

INT is\_SetFrameRate (HIDS hf, double FPS, double\* newFPS)

# **Description:**

*is*\_SetFrameRate() sets the number of frames/s the sensor shall work with. If the Framerate is too highly adjusted, not every frame can be read in and the actual frame rate drops.

Like exposure-time, it is not possible to adjust any value. Therefore the new frame rate is returned after the function call with the parameter newFPS. You can find more exact details in the description to the DCU timing.

Similarly to the Exposure time changes at the window size or at the Pixelclock affect the Framerate.

Framerate affecting functions:

- is\_SetImageSize()
- is\_SetPixelClock()

## Parameters:

hf Camera handle

**FPS** Number of pictures per second.

IS\_GET\_FRAMERATE Returns the actual frame rate with the parameter newFPS.

IS\_GET\_DEFAULT\_FRAMERATE Returns the standard frame rate newFPS Returns the frame rate value.

#### Return value:

# 4.98 is\_SetGainBoost

## Syntax:

INT is SetGainBoost (HIDS hf, INT mode)

## **Description:**

*is\_* SetGainBoost () activates or deactivates an extra hardware camera gain. This feature is supported by the following cameras:1220-C/M, 1440-C/M, 1540-C/M, 1450-C, 1460-C, 1480-C and monochrome CCD-models.

## Parameters:

hf Camera handle

mode

IS\_GET\_GAINBOOST Returns the current mode of the gain boost, or

IS\_NOT\_SUPPORTED if the camera doesn't support

this features

IS\_SET\_GAINBOOST\_ON Activates the Gain boost IS\_SET\_GAINBOOST\_OFF Deactivates the Gain boost

IS\_GET\_SUPPORTED\_GAINBOOST Returns IS\_SET\_GAINBOOST\_ON if this features is

supported, otherwise returns IS\_SET\_GAINBOOST\_OFF

#### Return value:

Current setting when called with *IS\_GET\_GAINBOOST* else *IS\_NOT\_SUPPORTED*, *IS\_SUCCESS* or *IS\_NO\_SUCCESS* 

# 4.99 is\_SetGamma

## Syntax:

INT is\_SetGamma (HIDS hf, INT Gamma)

## **Description:**

*is\_SetGamma()* sets the value for the digital gamma correction. The valid range of values lies between 0.01 and 10. However the parameter gamma must be fixed as integer value with a range from 1 to 1000 (gamma value \* 100).

## Parameters:

hf Camera handle

Gamma value multiplied with 100. - Range: [1...1000]

IS\_GET\_GAMMA Returns the current settings

# Return value:

Current settings in connection with  $IS\_GET\_BRIGHTNESS$ , sonst  $IS\_SUCCESS$  or  $IS\_NO\_SUCCESS$ 

# Example:

Set Gamma value to 1.42:

ret = SetGamma(hf, 142);

# 4.100 is\_SetHardwareGain

### Syntax:

INT is SetHardwareGain (HIDS hf, INT nMaster, INT nRed, INT nGreen, INT nBlue)

### **Description:**

is\_SetHardwareGain() controls the camera integrated amplifier. They can be tuned between 0% - 100% independent of each other. is\_GetSensorInfo() returns the available amplifiers.
Depending on the time of the change of the hardware gain this affects only with the recording of the next image.

### Parameters:

hf Camera handle nMaster Entire amplification.

IS\_IGNORE\_PARAMETER

No changes to master-amplifier

IS\_GET\_MASTER\_GAIN

Returns master amplification

IS\_GET\_RED\_GAIN

Returns green amplification

IS\_GET\_BLUE\_GAIN

Returns blue amplification

IS\_GET\_DEFAULT\_MASTER
Returns standard master amplification
IS\_GET\_ DEFAULT\_RED
Returns standard red amplification
IS\_GET\_ DEFAULT\_GREEN
Returns standard green amplification
IS\_GET\_ DEFAULT\_BLUE
Returns standard blue amplification

nRed Red channel

IS\_IGNORE\_PARAMETER No changes to red-amplifier

nGreen Green channel

IS\_IGNORE\_PARAMETER No changes to green-amplifier

nBlue Blue channel

IS\_IGNORE\_PARAMETER No changes to blue-amplifier

### **HINT**

In the case of use of the constant *IS\_SET\_ENABLE\_AUTO\_GAIN* for the parameter *EXP* the AutoGain functionality is activated. Setting a value will deactivate the functionality. (see also <u>4.76 is SetAutoParameter</u>).

### Return value:

Current setting when called with IS\_GET\_MASTER\_GAIN, IS\_GET\_RED\_GAIN, IS\_GET\_ GREEN\_GAIN, IS\_GET\_BLUE\_GAIN else IS\_SUCCESS or IS\_NO\_SUCCESS

# 4.101 is\_SetHardwareGamma

### Syntax:

INT is\_SetHardwareGamma (HIDS hf, INT nMode)

# **Description:**

is\_SetHardwareGamma() activates/deactivates the gamma control of the camera.

### Parameters:

hf	Camera handle
nMode	
IS_GET_HW_SUPPORTED_GAMMA	IS_SET_HW_GAMMA_ON Gamma control is supported by the camera. IS_SET_HW_GAMMA_OFF Gamma control is not suported by the camera.
IS_SET_HW_GAMMA_OFF	Activates gamma control.
IS_SET_HW_GAMMA_ON	Deactivates gamma control.
IS_GET_HW_GAMMA	Returns the current settings.

### Return value:

IS\_SUCCESS, IS\_NO\_SUCCESS or IS\_NOT\_SUPPORTED

# 4.102 is\_SetHWGainFactor

### Syntax:

INT is SetHWGainFactor (HIDS hf, INT nMode, INT nFactor)

### **Description:**

The function *is\_SetHWGainFactor()* is used for the control of the amplifier in the camera. These can be adjusted independently, from minimum to maximum gain. *is\_GetSensorInfo()* returns the available amplifiers.

For the conversion of a gain value from the function *is\_SetHardwareGain()* the parameter *nMode* can be set to one of the *IS\_INQUIRE\_x\_FACTOR* values. In this case the range of values for *nFactor* is between 0 and 100.

For setting the gain the parameter *nFactor* must be defined with *IS\_GET\_x\_GAIN\_FACTOR* as an integer value with a range from 100 to maximum. The maximum can be acquired with *IS\_IN-QUIRE\_x\_FACTOR* and a value of 100 for *nFactor*. A gain factor with the value 100 correspond to no amplification, a value of 200 to an amplification factor of two and so on.

The return value corresponds to the adjusted gain. This can deviate from the desired value, because only certain values can be set. Always the gain value is set which is next to the desired value.

Depending on time of the change of the gain value this affects only with the recording of the next image.

### **Pparameters:**

hf	Camera handle
nMode	
IS_GET_MASTER_GAIN_FACTOR	Returns the master gain value
IS_GET_RED_GAIN_FACTOR	Returns the red gain value
IS_GET_GREEN_GAIN_FACTOR	Returns the green gain value
IS_GET_BLUE_GAIN_FACTOR	Returns the blue gain value
IS_SET_MASTER_GAIN_FACTOR	Sets the master gain value
IS_SET_RED_GAIN_FACTOR	Sets the red gain value
IS_SET_GREEN_GAIN_FACTOR	Sets the green gain value
IS_SET_BLUE_GAIN_FACTOR	Sets the blue gain value
IS_GET_DEFAULT_MASTER_GAIN_FACTOR	Returns the standard master gain value
IS_GET_DEFAULT_RED_GAIN_FACTOR	Returns the standard red gain value
IS_GET_DEFAULT_GREEN_GAIN_FACTOR	Returns the standard green gain value
IS_GET_DEFAULT_BLUE_GAIN_FACTOR	Returns the standard blue gain value
IS_INQUIRE_MASTER_GAIN_FACTOR	Conversion of the index value of the master gain
IS_INQUIRE_RED_GAIN_FACTOR	Conversion of the index value of the red gain
IS_INQUIRE_GREEN_GAIN_FACTOR	Conversion of the index value of the green gain
IS_INQUIRE_BLUE_GAIN_FACTOR	Conversion of the index value of the blue gain
nFactor	Gain value

### Return value:

Current settings in connection with IS\_GET\_MASTER\_GAIN\_FACTOR, IS\_GET\_RED\_GAIN\_FACTOR, IS\_GET\_BLUE\_GAIN\_FACTOR.

Adjusted settings after the use of IS\_SET\_MASTER\_GAIN\_FACTOR, IS\_SET\_RED\_GAIN\_FACTOR, IS\_SET\_BLUE\_GAIN\_FACTOR.

Standard settings after the use of IS\_GET\_DEFAULT\_MASTER\_GAIN\_FACTOR, IS\_GET\_DEFAULT\_RED\_GAIN\_FACTOR, IS\_GET\_DEFAULT\_BLUE\_GAIN\_FACTOR.

Converted gain index after the use of IS\_INQUIRE\_ MASTER\_GAIN\_FACTOR, IS\_INQUIRE\_ RED\_GAIN\_FACTOR, IS\_INQUIRE\_ GREEN\_GAIN\_FACTOR, IS\_INQUIRE \_\_BLUE\_GAIN\_FACTOR.

### Example:

### Set master gain value to 3.57:

```
ret = is_SetHWGainFactor(hf, IS_SET_MASTER_GAIN_FACTOR, 357);
//ret contains the value 363 for the UI-1460-C
```

### Read the maximal gain factor of the red channel:

```
ret = is_SetHWGainFactor(hf, IS_INQUIRE_RED_GAIN_FACTOR, 100);
//ret contains the value 725 for the UI-1460-C
```

# 4.103 is\_SetHwnd

### Syntax:

INT is\_SetHwnd (HIDS hf, HWND hwnd)

### **Description:**

*is\_SetHwnd()* sets a new window handle for the image output with DirectDraw. The new handle and the image output is only activated when *is\_SetDisplayMode()* is called.

### Parameters:

hf Camera handle hwnd Handle to a window

### Return value:

IS\_SUCCESS, IS\_NO\_SUCCESS

# 4.104 is\_SetImageAOI

### Syntax:

INT is\_SetImageAOI (HIDS hf, INT xPos, INT yPos, INT width, INT height)

### Parameters:

hf Camera handle

xPos x-position of the upper left corner yPos y-position of the upper left corner

widthimage widthheightimage height

### Return values:

# 4.105 is\_SetImageMem

### Syntax:

INT is\_SetImageMem (HIDS hf, char\* pcImgMem, INT id)

### **Description:**

is\_SetImageMem() sets the allocated image memory to active memory. Only an active image memory can receive image data. After calling is\_SetImageMem() function is\_SetImageSize() must follow to set the image size of the active memory. A pointer from function is\_AllocImgMem() has to be given to parameter pcImgMem.

### **HINT**

In DirectDraw mode it is not necessary to set the image memory!

All other pointer lead to an error report! A repeated hand-over of the same pointer is allowed.

Parameters:

hf Camera handle

**pcImgMem** Pointer to the beginning of the image memory

id ID for this memory

Return value:

# 4.106 is\_SetImagePos

### Syntax:

INT is\_SetImagePos (HIDS hf, INT x, INT y)

### **Description:**

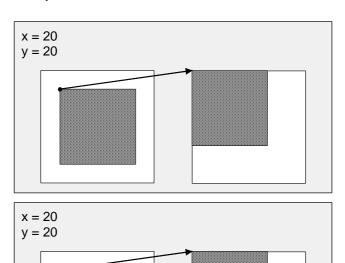
*is\_SetImagePos()* defines the starting point of the window. A section can be cut out of the full video image using the function *is\_SetImageSize()*. In this case, the following described order for selecting functions must be observed:

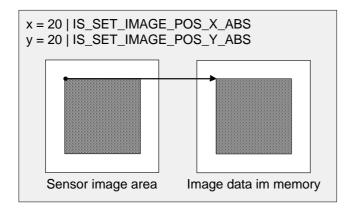
- 1. is\_SetImageSize()
- 2. is\_SetImagePos()

The function *is\_SetAOI()* (see <u>4.75 is\_SetAOI()</u> combines the two functions. With *is\_SetAOI()* the position and the size of an AOI can be set with one function call.

The parameters x and y represent an offset in relation to the left upper corner of the image. The cut-out window is copied to the start of the memory. If the image is to be copied to the same offset within the memory, the new position can be logical OR involved with the parameter  $IS\_SET\_IMAGE\_POS\_X\_ABS$  and  $IS\_SET\_IMAGE\_POS\_Y\_ABS$ .

### Example:





# **Boundary conditions**

See <u>4.75 is\_SetAOI</u>.

### Parameters:

hf	Camera handle
X	
0xMax	Horizontal position
IS_GET_IMAGE_POS_X	Retrieval of current X-position
IS_GET_IMAGE_POS_X_ABS	Retrieval whether the X-position for the current memory is assumed
IS_GET_IMAGE_POS_X_MIN	Smallest value for the horizontal AOI position
IS_GET_IMAGE_POS_X_MAX	Largest value for the horizontal AOI position
IS_GET_IMAGE_POS_X_INC	Increment for the horizontal AOI position
IS_GET_IMAGE_POS_Y	Retrieval of current Y-position
IS_GET_IMAGE_POS_X_ABS	Retrieval whether the X-position for the current memory is assumed
IS_GET_IMAGE_POS_Y_MIN	Smallest value for the vertical AOI position
IS_GET_IMAGE_POS_Y_MAX	Largest value for the vertical AOI position
IS_GET_IMAGE_POS_Y_INC	Increment for the vertical AOI position
у	
0yMax	Vertical position

### Return value:

Current settings when called with *IS\_GET\_IMAGE\_POS\_X* and *IS\_GET\_IMAGE\_POS\_Y* as a parameter for x, else *IS\_SUCCESS*, *IS\_NO\_SUCCESS* 

# 4.107 is\_SetImageSize

### Syntax:

INT is\_SetImageSize (HIDS hf, INT x, INT y)

### **Description:**

*is\_SetImageSize()* determines the image size when used with the setting from *is\_SetImagePos()*.

The following described order for selecting functions must be observed:

- 1. is\_SetImageSize()
- 2. is\_SetImagePos()

The function *is\_SetOI()* (see <u>4.75 is\_SetAOI()</u> combines the two functions. With *is\_SetAOI()* the position and the size of an AOI can be set with one function call.

### **Boundary conditions**

See 4.75 is\_SetAOI.

### Parameters:

hf	Camera handle
x	
1xMax	Width of the image
IS_GET_IMAGE_SIZE_X	Retrieval of current width
IS_GET_IMAGE_SIZE_X_MIN	Smallest value for the AOI width
IS_GET_IMAGE_SIZE_X_MAX	Largest value for the AOI width
IS_GET_IMAGE_SIZE_X_INC	Increment for the AOI width
IS_GET_IMAGE_SIZE_Y	Retrieval of current height
IS_GET_IMAGE_SIZE_Y_MIN	Smallest value for the AOI height
IS_GET_IMAGE_SIZE_Y_MAX	Largest value for the AOI height
IS_GET_IMAGE_SIZE_Y_INC	Increment for the AOI height
у	
1yMax	Height of the image

### Return value:

When used with IS\_GET\_IMAGE\_SIZE\_X and IS\_GET\_IMAGE\_SIZE\_Y the current settings are read, else IS\_SUCCESS or IS\_NO\_SUCCESS.

# 4.108 is\_SetIO (only UI-1543-M)

### Syntax:

INT is SetIO(HIDS hf, INT nIO)

### **Description:**

is\_SetIO() sets the two additional digital outputs or reads the currents settings.

### Parameters:

hf Camera handle
nIO Output bitmask
0x00 (00) Both outputs on 0
0x01 (01) First output on 1 second on 0
0x02 (10) First output on 0 second on 1

0x03 (11) Both outputs on 1
IS\_GET\_IO Returns the current bitmask

### Return value:

IS\_SUCCESS, IS\_NO\_SUCCESS, current settings in connection with IS\_GET\_IO.

# 4.109 is\_SetKeyColor

### Syntax:

INT is\_SetKeyColor (HIDS hf, INT r, INT g, INT b)

### **Description:**

With *is\_SetKeyColor()* the keying colour for the DirectDraw overlay surface mode is defined. The function is also used to read out the key colour. The colour value to be read out is transferred via the parameter r. Depending on selection, the function supplies as a result either the value of a colour component (0...255) or the RGB value (0 ... 16777215).

### Parameters:

hf Camera handle

**r** Red channel of keying colour (0...255).

IS\_GET\_KC\_REDRetrieval of the R channelIS\_GET\_KC\_GREEENRetrieval of the G channelIS\_GET\_KC\_BLUERetrieval of the B channelIS\_GET\_KC\_RGBRetrieval of the RGB

g Green channel of keying colour (0...255).b Blue channel of keying colour (0...255).

### Return value:

Colour value in connection with IS\_GET\_KC\_RGB, IS\_GET\_KC\_RED, IS\_GET\_KC\_GREEN, IS\_GET\_KC\_BLUE else IS\_SUCCESS, IS\_NO\_SUCCESS

# 4.110 is\_SetLED

### Syntax:

INT is\_SetLED (HIDS hf, INT nValue)

### **Description:**

With is\_SetKeyColor() the LED on the rear side of the camera housing is switched on/off

### Parameters:

hf Handle auf Kamera

nValue

IS\_SET\_LED\_OFF Switches the LED off. IS\_SET\_LED\_ON Switches the LED on.

IS\_SET\_LED\_TOGGLE Toggles the LED between *ON* and *OFF*.

### Return value:

# 4.111 is\_SetPixelClock

### Syntax:

INT is\_SetPixelClock (HIDS hf, INT Clock)

### **Description:**

*is\_SetPixelClock()* sets the frequency, with that the sensor is read out. If the frequency is too high, it is possible, that images get lost during the transmission. Changing the Pixelclock has also influence on frame rate and the exposure time. The current recording of an image is cancelled.

### Parameters:

hf Camera handle
Clock Pixelclock in MHz

IS\_GET\_PIXEL\_CLOCK Returns current Pixelclock
IS\_GET\_DEFAULT\_PCLK Returns standard pixelclock

### Return value:

Current settings when called with IS\_GET\_PIXEL\_CLOCK, else IS\_SUCCESS or IS\_NO\_SUCCESS

# 4.112 is\_SetRopEffect

### Syntax:

INT is\_SetRopEffect (HIDS hf, INT effect, INT param, INT reserved)

### **Description:**

With function is\_SetRopEffect() raster operation effects can be set.

### Parameters:

hf Camera handle

effect

IS\_SET\_ROP\_MIRROR\_UPDOWN Reflects a frame around the horizontal axis in real time. IS\_SET\_ROP\_MIRROR\_LEFTRIGHT Reflects a frame in the camera around the vertical axis.

This function is a hardware or a software function, depending

on the camera.

IS\_GET\_ROP\_EFFECT Returns the current settings param Toggles the ROP effects

0 = turn off1 = turn on

reserved Not used

### Return value:

IS\_SUCCESS, IS\_NO\_SUCCESS or the current settings in connection with IS\_SET\_ROP\_EFFECT

# 4.113 is\_SetSaturation

### Syntax:

INT is\_SetSaturation (HIDS hf, INT ChromU, INT ChromV)

### **Description:**

Set the software colour saturation. This function will work only with the color format YUV.

### Parameters:

Hf Camera handle

**ChromU** Saturation-u value multiplied with 100.

Range: [IS\_MIN\_SATURATION ... IS\_MAX\_SATURATION]

IS\_GET\_SATURATION\_U Returns the value for the U-saturation

ChromV Saturation-v value multiplied with 100.

Range: [IS\_MIN\_SATURATION ... IS\_MAX\_SATURATION]

IS\_GET\_SATURATION\_V Returns the value for the V-saturation

### Return value:

IS\_SUCCESS, IS\_NO\_SUCCESS

IS\_INVALID\_PARAMETER (invalid ChromU or ChromV value)

Current settings in connection with IS\_GET\_SATURATION\_U or IS\_GET\_SATURATION\_V.

# 4.114 is\_SetSubSampling

### Syntax:

INT is\_SetSubSampling (HIDS hf, INT mode)

### **Description:**

The function *is\_SetSubSampling()* is used to activate horizontal and/or vertical *subsampling*. In the 2x mode every second pixel is read out from the sensor so the image size is reduced to the half for each subsampling direction and the frame rate may increased. This is equal to hardware scaling the image to 2:1. If a colour camera is used, 4:2 scaling is deployed in which two pixels are read and two left out.

Due to its design the UI-154x-M accomplishes only a colour subsampling. This can lead with fine picture structures to slight artifacts.

### Monochrom-Sensor

# Column/Horizontal a b c d e f g h i j k l m n o p q r 1 2 8 3 3 4 4 6 7 8 9

### Color-Sensor

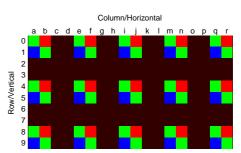


Fig. 8: twofold subsampling

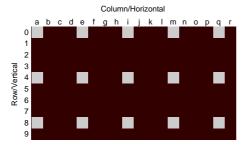


Fig. 10: fourfoldfold subsampling

Fig. 9: twofold subsampling

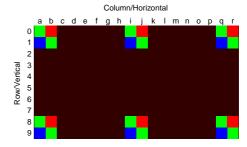


Fig. 11: fourfoldfold subsampling

### Parameters:

hf	Camera handle
mode	
IS_SUBSAMPLING_DISABLE	Disables subsampling.
IS_SUBSAMPLING_2X_VERTICAL	Enables 2x vertical subsampling.
IS_SUBSAMPLING_4X_VERTICAL	Enables 4x vertical subsampling.
IS_SUBSAMPLING_2X_HORIZONTAL	Enables 2x horizontal subsampling.
IS_SUBSAMPLING_4X_HORIZONTAL	Enables 4x horizontal subsampling.
IS_GET_SUBSAMPLING	Returns current settings.
IS_GET_SUBSAMPLING_TYPE	Returns weather the camera uses colour conserving binning ( <i>IS_SUBSAMPLING_COLOR</i> ) or not.
IS_GET_SUPPORTED_SUBSAMPLIN G	Returns supported subsampling modes.

### Return value:

Current setting when called with *IS\_GET\_SUBSAMPLING* else *IS\_SUCCESS*, *IS\_NO\_SUCCESS* 

# 4.115 is\_SetTestImage

### Syntax:

INT is\_SetTestImage (HIDS hf, INT nMode)

### **Description:**

The function *is\_SetTestImage()* switches on different pre-defined test imges in the memory mode. If a certain mode was activated, this test pattern is transferred with the next memory recording in place of the origin image data. Testimages vary per recording one line (greyvalue etc.)

### Parameters:

hf	Camera handle
nMode	
IS_SET_TEST_IMAGE_DISABLED	Test images are deactivated
IS_SET_TEST_IMAGE_MEMORY_1	1. Test image is activated (a monochrome grey ramp)
IS_SET_TEST_IMAGE_MEMORY_2	2. Test image is activated (a bayer rgb ramp)
IS_SET_TEST_IMAGE_MEMORY_3	3. Test image is activated (a white horizontal line over a black image)
IS GET TEST IMAGE	Current settings are returned

### Return value:

In connection with *IS\_GET\_TEST\_IMAGE* the current settings are read, else *IS\_SUCCESS* or *IS\_NO\_SUCCESS*.

# 4.116 is\_SetTriggerDelay

### Syntax:

INT is\_SetTriggerDelay (HIDS hf, INT nDelay)

### **Description:**

*is\_SetTriggerDelay ()* can be used to specify a delay time between occourance of an external trigger signal and start of the expression. The adjusted delay time affects itself additive to the default delay time. This is the delay time, which is always present, until the external trigger signal has been routed to the sensor. The following values apply to the default delay time (with TTL signal level and 50% trigger level):

CCD

HI\_LO: 61,5μsLO\_HI: 43,2μs

### Parameters:

 $\begin{array}{ll} \text{hf} & \text{Camera handle} \\ \text{nDelay} & \text{Delay time (in $\mu$s)} \\ \end{array}$ 

IS\_GET\_TRIGGER\_DELAY Return the current delay time

IS\_GET\_MIN\_TRIGGER\_DELAY Return the min. value IS\_GET\_MAX\_TRIGGER\_DELAY Return the max. value

IS\_GET\_TRIGGER\_DELAY\_GRANULARITY Returns the resolution of the adjustable delay time

### Return value:

IS\_SUCCESS, IS\_NO\_SUCCESS, current settings in connection with IS\_GET\_TRIGGER\_DELAY

# 4.117 is\_SetWhiteBalance

### Syntax:

INT is\_SetWhiteBalance (HIDS hf, INT nMode)

### **Description:**

is\_SetWhiteBalance() activates the white balance defined with nMode.

### HINT

The software white balance cannot be activated, if the automatic white balance has been switched on with the function *is\_SetAutoParameter()*.

is\_SetWhiteBalance() accomplishes a color scaling by software. In order to obtain optimal results the function is\_SetAutoParameter() is to be used.

### Parameters:

hf	Camera handle
nMode	
IS_SET_WB_DISABLE	Deactivates white balance
IS_SET_WB_USER	User defined values are used. (Factors must be set with <i>is_SetWhiteBalanceMultipliers()</i> .
IS_SET_WB_AUTO_ENABLE	Activates automatic white balance for every frame.
IS_SET_WB_AUTO_ENABLE_ONCE	Automatic white balance with the next recorded frame.
IS_SET_WB_DAYLIGHT_65	Industrial standard Daylight 65
IS_SET_WB_COOL_WHITE	Industrial standard CWF (Cool White Fluorescent)
IS_SET_WB_ILLUMINANT_A	Industrial standard Illuminant A
IS_SET_WB_U30	Industrial standard Ultralume 30
IS_SET_WB_HORIZON	Industrial standard Horizon
IS_GET_WB_MODE	Returns the actual mode

### Return value:

Current settings when called with  $IS\_GET\_WB\_MODE()$ , else  $IS\_SUCCESS$ ,  $IS\_NO\_SUCCESS$ 

# 4.118 is\_SetWhiteBalanceMultipliers

### Syntax:

INT is\_SetWhiteBalanceMultipliers (HIDS hf, double dblRed, double dblGreen, double dblBlue)

### **Description:**

is\_SetWhiteBalanceMultipliers() sets the user defined factors used for the white balance. Details can also be found at 4.117 is\_SetWhiteBalance.

### **HINT**

is\_SetWhiteBalanceMultipliers() set the parameters for the software color scaling which ist executed with the function is\_SetWhiteBalance(). A better controlling of the fundamental colours can be achieved with the function is\_SetAutoParameter().

Parameters:

hfCamera handledblRedNew factor for reddblGreenNew factor for greendblBlueNew factor for blue

### Return value:

IS\_SUCCESS, IS\_NO\_SUCCESS

# 4.119 is\_ShowDDOverlay

### Syntax:

INT is\_ShowDDOverlay (HIDS hf)

### **Description:**

is\_ShowDDOverlay() fades on the overlay in DirectDraw back buffer mode. The last data received in the overlay buffer will be displayed. The display is created with only three image buffers. Depending upon the VGA card, the image refresh can be smaller than the overlay display.

### Parameters:

hf Camera handle

### Return value:

# 4.120 is\_StealVideo

### Syntax:

INT is\_StealVideo (HIDS hf, int Wait)

### **Description:**

The function *is\_StealVideo()* initiates the stealing or copy of a single image out of a DirectDraw live stream. The stolen picture is written into the current active image memory in the RAM. Thereby the preset color format is used. With the function *is\_PrepareStealVideo()* can be selected if the picture muss be stolen or copied. If the copy option is selected the same picture will be shown with DirectDraw and copied into the current active image memory.

See also Fig. 6: Events in live mode in 3.9 Event Handling

### Parameters:

hf Camera handle

Wait

IS\_WAIT Function waits until the image is recorded

IS\_DON'T\_WAIT Function returns immediately

### Return value:

IS\_SUCCESS, IS\_NO\_SUCCESS

# 4.121 is\_StopLiveVideo

### Syntax:

INT is\_StopLiveVideo (HIDS hf, INT Wait)

### **Description:**

The *is\_StopLiveVideo()* function freezes the image in the VGA card or in the PC's system memory. The function is controlled with the parameter *Wait*.

The function has two modes: Using the first mode, the function immediately returns to the calling function and grabs the image in the background. In the second mode the function waits until the image has been completely acquired and only then does the function return.

By the use of *IS\_FORCE\_VIDEO\_STOP* a single frame recording which is started with *is\_FreezeVideo(hf, IS\_DONT\_WAIT)* can be terminated immediately.

### Parameters:

hf Camera handle

Wait

IS\_WAIT Function waits until the entire image is in memory

IS\_DONT\_WAIT Function returns straight away.
IS\_FORCE\_VIDEO\_STOP Terminated digitization immediately

### Return value:

# 4.122 is\_UnlockDDMem

### Syntax:

INT is\_UnlockDDMem (HIDS hf)

### **Description:**

is\_UnlockDDMem() disables access to the image memory in DirectDraw mode. Then the contents of the back buffer are updated on the display.

**Parameters:** 

hf Camera handle

Return value:

IS\_SUCCESS, IS\_NO\_SUCCESS

# 4.123 is\_UnlockDDOverlayMem

### Syntax:

INT is\_UnlockDDOverlayMem (HIDS hf)

### **Description:**

is\_UnlockDDOverlayMem() disables access to the overlay buffer in DirectDraw back buffer mode. The contents of the overlay buffer are updated on the display (if is\_ShowDDOverlay() has faded on the overlay)

Parameters:

hf Camera handle

Return value:

# 4.124 is\_UnlockSeqBuf

### Syntax:

INT is\_UnlockSeqBuf (HIDS hf, INT nNum, char\* pcMem)

### **Description:**

With *is\_UnlockSeqBuf()* image acquisition is allowed in a previously locked image memory. The image memory is put to the previous position in the sequence list.

### **Parameters:**

hf Camera handle

**nNum** Number of the image memory which is to be released (1...

max).

**pcMem** Start address of image memory

### **HINT**

nNum indicates the position in the sequence list and not the memory ID assigned with *is\_AllocImageMem()*.

### Return value:

# 4.125 is\_UpdateDisplay

### Syntax:

INT is\_UpdateDisplay (HIDS hf)

### **Description:**

is\_UpdateDisplay() updates the display when the display mode is set with IS\_SET\_DM\_DIRECTDRAW. Also see function 4.89 is\_SetDisplayMode.

### Parameters:

hf Camera handle

### Return value:

IS\_SUCCESS, IS\_NO\_SUCCESS

# 4.126 is\_WriteEEPROM

### Syntax:

INT is\_WriteEEPROM (HIDS hf, INT Adr, char\* pcString, INT Count)

### **Description:**

In the DCU camera there is a rewritable EEPROM, where 64 bytes of information can be written. With the *is\_ReadEEPROM()* function the contents of this 64 byte block can be read.

### Parameters:

hf Camera handle

Adr Start address to where data will be written. Value range 0 to

63

pcString Character chain, which contains certain data

**Count** Number of readable characters

### Return value:

# 5 Error messages

Nr	Fehler	Beschreibung
-1	IS NO SUCCESS	general error message
0	IS SUCCESS	general success message – no error
1	IS_INVALID_CAMERA_HANDLE	Camera handle is invalid. Most of the functions of the DCU SDk expect the amera handle as first parameter.
2	IS_IO_REQUEST_FAILED	An IO requirement of the DCU driver failed. Possibly Api DLL and driver file do not fit.
3	IS_CANT_OPEN_DEVICE	An attempt to open the camera failed (camera missing or error when initialising).
11	IS_CANT_OPEN_REGISTRY	Error while opening a Windows Registry key
12	IS_CANT_READ_REGISTRY	Error while reading settings from the windows registry
15	IS_NO_IMAGE_MEM_ALLOCATED	The driver could not allocate memory.
16	IS_CANT_CLEANUP_MEMORY	The driver could not release the used memory.
17	IS_CANT_COMMUNICATE_WITH_DRIVER	Communication with the driver failed, because no driver is loaded.
49	IS_INVALID_MEMORY_POINTER	Invalid pointer or invalid memory ID
50	IS_FILE_WRITE_OPEN_ERROR	File cannot be opened for writing.
51	IS_FILE_READ_OPEN_ERROR	File cannot be opened for reading.
52	IS_FILE_READ_INVALID_BMP_ID	The indicated file is not a valid bit-map
53	IS_FILE_READ_INVALID_BMP_SIZE	The size of the bit-map is wrong (too large).
108	IS_NO_ACTIVE_IMG_MEM	No activated bit map memory available. The memory must be activated with the function is_SetActiveImageMem, or a sequence must be created with the function is_AddTo_Sequence.
112	IS_SEQUENCE_LIST_EMPTY	The sequence list is empty and can not be deleted.
113	IS_CANT_ADD_TO_SEQUENCE	The bit map memory is already in the sequence and cannot be added twice.
117	IS_SEQUENCE_BUF_ALREADY_LOCKED	The memory could not be locked. The pointer on the buffer is invalid.
118	IS_INVALID_DEVICE_ID	The device ID is invalid. Valid IDs are between 0 and 255.
119	IS_INVALID_BOARD_ID	The board ID is invalid. Valid IDs are between 1 and 255.
120	IS_ALL_DEVICES_BUSY	All cameras are in use
122	IS_TIMED_OUT	A Timeout arose. A picture recording could not be finished in the prescribed time.
125	IS_INVALID_PARAMETER	One of the handed over parameters is outside of the valid range, or is not supported for this sensor and/or is not accessible in this mode.
127	IS_OUT_OF_MEMORY	No memory could be allcated.
139	IS_NO_USB20	The camera is connected at a port, which does not support the high speed standard USB 2,0. Cameras without memory wont be operate at USB 1.1 ports.
140	IS_CAPTURE_RUNNING	An aquisition is running. This must be terminated, before a new one can be begun.
141	IS_MEMORY_BOARD_ACTIVATED	The memory mode is active. Therefore no changes of the dimension of the picture can be made.
143	IS_NO_MEMORY_BOARD_CONNECTED	No memory board was detected. The function requires a camera with memory board.
144	IS_TOO_LESS_MEMORY	The adjusted number of pictures exceeds in the current size the capacity of the memory board (4MB)

Nr	Fehler	Beschreibung
145	IS_IMAGE_NOT_PRESENT	The requested picture is missing or no longer valid in the camera memory.
147	IS_MEMORYBOARD_DISABLED	The memory board was deactivated due to an error. The function is not available any longer.
148	IS_TRIGGER_ACTIVATED	The function is not possible, because the camera waits for a Triggersignal.
151	IS_CRC_ERROR	Reading the settings a CRC error arose.
152	IS_NOT_YET_RELEASED	This function is not yet activated in this driver version.
153	IS_NOT_CALIBRATED	The camera does not contain calibration data.
154	IS_WAITING_FOR_KERNEL	Still waiting for a feedback of the kernel driver.
155	IS_NOT_SUPPORTED	The used camera model does not support this function or attitude.
157	IS_OPERATION_ABORTED	No file could be stored, because the dialogue was terminated without selection.
158	IS_BAD_STRUCTURE_SIZE	An internal structure has the wrong size.
159	IS_INVALID_BUFFER_SIZE	The bit image memory has the wrong size to take the picture in the desired format.
160	IS_INVALID_PIXEL_CLOCK	This attitude is not possible with the current adjusted pixel clock.
161	IS_INVALID_EXPOSURE_TIME	This attitude is not possible with the current exposure time.
162	IS_AUTO_EXPOSURE_RUNNING	The attitude cannot be changed, as long as the automatic exposure control is activated.
163	IS_CANNOT_CREATE_BB_SURF	Error creating backbuffer surface.
164	IS_CANNOT_CREATE_BB_MIX	BackBuffer mixer surfaces can not be created
165	IS_BB_OVLMEM_NULL	BackBuffer overlay mem could not be locked
166	IS_CANNOT_CREATE_BB_OVL	BackBuffer overlay mem could not be created .
167	IS_NOT_SUPP_IN_OVL_SURF_MODE	Function not supported in overlay surface mode.
168	IS_INVALID_SURFACE	Surface invalid.
169	IS_SURFACE_LOST	Surface has been lost.
170	IS_RELEASE_BB_OVL_DC	Error releasing backbuffer overlay DC.
171 172	IS_BB_TIMER_NOT_CREATED IS_BB_OVL_NOT_EN	BackBuffer timer could not be created.  BackBuffer overlay has not been enabled.
172	IS ONLY IN BB MODE	Only possible in backbuffer mode.
173	IS_INVALID_COLOR_FORMAT	Invalid color format.
174	IO_IIAAVEID_OOFOI/_I OLIMIYI	myana color format.

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