## Homework 3

```
[1] import tensorflow as tf
   import matplotlib.pyplot as plt
   import numpy as np

[2] cifar = tf.keras.datasets.cifar10
      (x_train, y_train), (x_test, y_test) = cifar.load_data()

      Downloading data from https://www.cs.toronto.edu/~kriz/cifar-10-python.tar.gz
      170498071/170498071 [==========] - 14s Ous/step

[3] # Convert 2D to 1D array
      y_train = y_train.reshape(-1,)
      y_test = y_test.reshape(-1,)
[4] # Normalization
      x_train, x_test = x_train / 255.0, x_test / 255.0
```

- [1] I imported necessary packages.
- [2] Download CIFAR10 dataset and assign it to cifar variable. It already has train and test data separated, so assign those to the x and y variables.
- [3] Initially, y is 2D array, I do reshape(-1,) to convert it to a 1D array.
- [4] Divide the x by 255.0 for a normalization.

```
model = tf.keras.models.Sequential([
        tf.keras.layers.Conv2D(filters=32, kernel_size=(3,3), padding='same', activation='relu', input_shape=(32, 32, 3)),
        tf.keras.layers.BatchNormalization(),
        tf.keras.layers.Conv2D(filters=32, kernel_size=(3,3), padding='same', activation='relu'),
        tf.keras.layers.BatchNormalization(),
        tf.keras.layers.MaxPool2D((2, 2)),
        tf.keras.layers.Dropout(0.2),
        tf.keras.layers.Conv2D(filters=64, kernel_size=(3,3), padding='same', activation='relu'),
        tf.keras.layers.BatchNormalization(),
        tf.keras.layers.Conv2D(filters=64, kernel_size=(3,3), padding='same', activation='relu'),
        tf.keras.layers.BatchNormalization(),
        tf.keras.layers.MaxPool2D((2, 2)),
        tf.keras.layers.Dropout(0.3),
        tf.keras.layers.Conv2D(filters=128, kernel_size=(3,3), padding='same', activation='relu'),
        tf.keras.layers.BatchNormalization(),
        tf.keras.layers.Conv2D(filters=128, kernel_size=(3,3), padding='same', activation='relu'),
        tf.keras.layers.BatchNormalization(),
        tf.keras.layers.MaxPool2D((2, 2)),
        tf.keras.layers.Dropout(0.4),
        tf.keras.layers.Flatten(),
        tf.keras.layers.BatchNormalization(),
        tf.keras.layers.Softmax()
    loss = tf.keras.losses.SparseCategoricalCrossentropy()
    model.compile(loss=loss, optimizer='adam', metrics=['accuracy'])
    tensorboard_callback = tf.keras.callbacks.TensorBoard(log_dir='log')
```

This is the Keras CNN model. The input shape is (32, 32, 3). Since I will train in batch, so I have to add batch normalizations. Batch normalization has to be after Conv2D but before MaxPool2D. I train  $Conv2D \rightarrow BatchNormalization \rightarrow Conv2D \rightarrow Batch Normalization \rightarrow MaxPool2D \rightarrow Dropout, and increase the filters size from time to time. I have to deal with the overfitting on training data problem, so I add Dropout layer to my neural network. Then, flatten the layer, add one normal hidden layer, do the batch normalization again, then add the Softmax layer lastly. The loss function is Sparse categorical crossentropy. Optimizer will be AdamOptimizer. Use accuracy metrics for measuring training accuracy.$ 

```
model.summary()
₽
    batch_normalization_65 (Bat (None, 32, 32, 32)
                                                          128
     chNormalization)
    conv2d_75 (Conv2D)
                                (None, 32, 32, 32)
                                                          9248
    batch_normalization_66 (Bat (None, 32, 32, 32)
                                                          128
    chNormalization)
    max_pooling2d_39 (MaxPoolin (None, 16, 16, 32)
    g2D)
    dropout_31 (Dropout)
    conv2d_76 (Conv2D)
                                (None, 16, 16, 64)
                                                          18496
    batch_normalization_67 (Bat (None, 16, 16, 64)
    chNormalization)
    conv2d_77 (Conv2D)
                                (None, 16, 16, 64)
    batch_normalization_68 (Bat (None, 16, 16, 64)
    chNormalization)
    max_pooling2d_40 (MaxPoolin (None, 8, 8, 64)
    dropout_32 (Dropout)
                                (None, 8, 8, 64)
    conv2d_78 (Conv2D)
                                (None, 8, 8, 128)
    batch_normalization_69 (Bat (None, 8, 8, 128)
    chNormalization)
                                                          147584
    conv2d 79 (Conv2D)
                                (None, 8, 8, 128)
    batch_normalization_70 (Bat (None, 8, 8, 128)
    chNormalization)
```

These figures show the model summary.

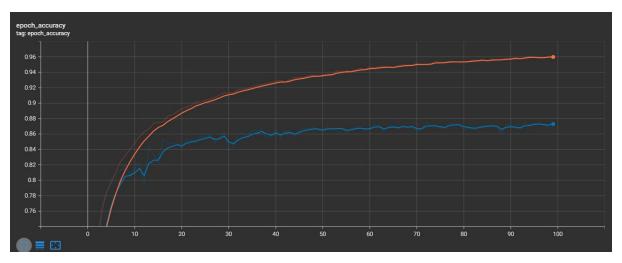
```
[59] model.fit(x_train, y_train, batch_size=64, epochs=100, callbacks=[tensorboard_callback], validation_data=(x_test, y_test))
     782/782 [====
                          ===========] - 8s 10ms/step - loss: 0.1445 - accuracy: 0.9501 - val_loss: 0.4680 - val_accuracy: 0.8662
     Epoch 73/100
782/782 [===
                                              ==] - 8s 10ms/step - loss: 0.1453 - accuracy: 0.9503 - val_loss: 0.4391 - val_accuracy: 0.8755
     Epoch 74/100
782/782 [====
     Epoch 75/100
782/782 [====
                                            ===] - 8s 10ms/step - loss: 0.1408 - accuracy: 0.9523 - val_loss: 0.4698 - val_accuracy: 0.8676
     782/782 [=
     Epoch 77/100
782/782 [====
                                              =] - 8s 10ms/step - loss: 0.1349 - accuracy: 0.9530 - val_loss: 0.4755 - val_accuracy: 0.8672
                                            ===] - 8s 10ms/step - loss: 0.1351 - accuracy: 0.9545 - val_loss: 0.4468 - val_accuracy: 0.8750
     782/782 [=
     Epoch 79/100
782/782 [====
                                             ==] - 8s 10ms/step - loss: 0.1322 - accuracy: 0.9537 - val_loss: 0.4672 - val_accuracy: 0.8729
     Epoch 80/100
782/782 [====
                                             ==] - 8s 10ms/step - loss: 0.1361 - accuracy: 0.9533 - val_loss: 0.4710 - val_accuracy: 0.8725
     Epoch 81/100
                                             ==] - 8s 10ms/step - loss: 0.1341 - accuracy: 0.9534 - val_loss: 0.4841 - val_accuracy: 0.8656
     782/782 [=
     Epoch 82/100
                                      =======] - 8s 10ms/step - loss: 0.1342 - accuracy: 0.9542 - val_loss: 0.4821 - val_accuracy: 0.8674
     782/782 [=:
     Epoch 83/100
782/782 [====
     Epoch 84/100
                                            ===] - 8s 10ms/step - loss: 0.1305 - accuracy: 0.9554 - val loss: 0.4726 - val accuracy: 0.8683
     782/782 [=
     Epoch 85/100
782/782 [====
                                             ==] - 8s 10ms/step - loss: 0.1270 - accuracy: 0.9566 - val_loss: 0.4663 - val_accuracy: 0.8714
     Epoch 86/100
                                      ======] - 8s 10ms/step - loss: 0.1301 - accuracy: 0.9542 - val_loss: 0.4691 - val_accuracy: 0.8709
     782/782 [===
                                      ======= | - 8s 10ms/step - loss: 0.1275 - accuracy: 0.9570 - val loss: 0.4646 - val accuracy: 0.8714
     782/782 [=
                                     =======] - 8s 10ms/step - loss: 0.1257 - accuracy: 0.9563 - val loss: 0.4762 - val accuracy: 0.8698
      782/782 [===:
Epoch 89/100
```

Then, fit the model. My batch size is 64, with 100 epochs. The validation data parameter here uses the variable x\_test and y\_test that we assigned it beforehand. Also use Google Colab's GPU because if not, its going to take too long time. After the training is completed, we will check the results.

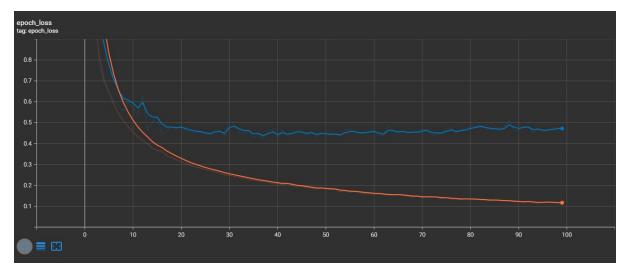
Here you can see that the training loss is 0.0066, the training accuracy is 0.9995, the testing loss is 0.4731, and the testing accuracy is 0.8749. I tried changing parameters for a several times, and this one was my best result. Now, let's see the Tensorboard graph results.



Orange line means training, blue line means validation (testing)



Here is the accuracy in each epoch of training (orange) and testing (blue) data.



Here is the loss in each epoch of training (orange) and testing (blue) data.

Here is the visualization of CNN architecture.

