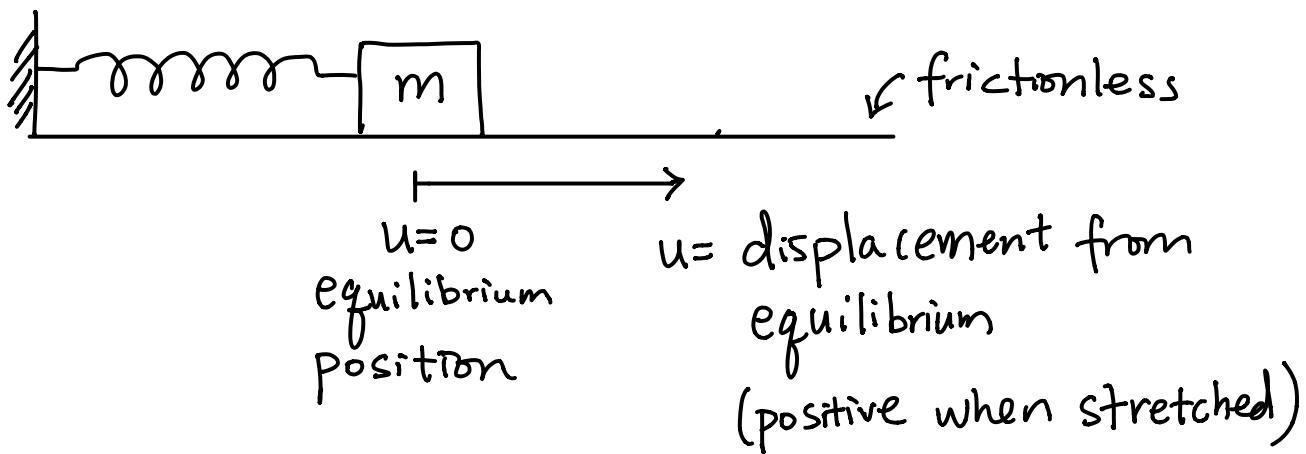


Harmonic Oscillator §3.7



$$m u'' = F_{\text{spring}} = -ku \quad (\text{Hooke's law})$$

$$[k] = \text{kg/s}^2$$

$$\boxed{mu'' + ku = 0}$$

$$u'' + \frac{k}{m}u = 0$$

$$u'' + \omega_0^2 u = 0, \quad \omega_0 = \sqrt{\frac{k}{m}}$$

$$\text{char eq: } r^2 + \omega_0^2 = 0$$

$$r^2 = -\omega_0^2$$

$$r = \pm i\omega_0$$

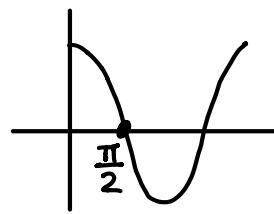
$$\boxed{u = C_1 \cos(\omega_0 t) + C_2 \sin(\omega_0 t)}$$

Experiment 1 to find k

Take $m = 1 \text{ kg}$, pull 1 unit to the right,
release from rest:

$$u(0) = 1, \quad u'(0) = 0$$

Solve IVP
 $\Rightarrow u = \cos(\sqrt{k}t)$



Then record how long it takes to arrive at equilibrium for the first time. Say it took $t_1 = 0.5$ sec.

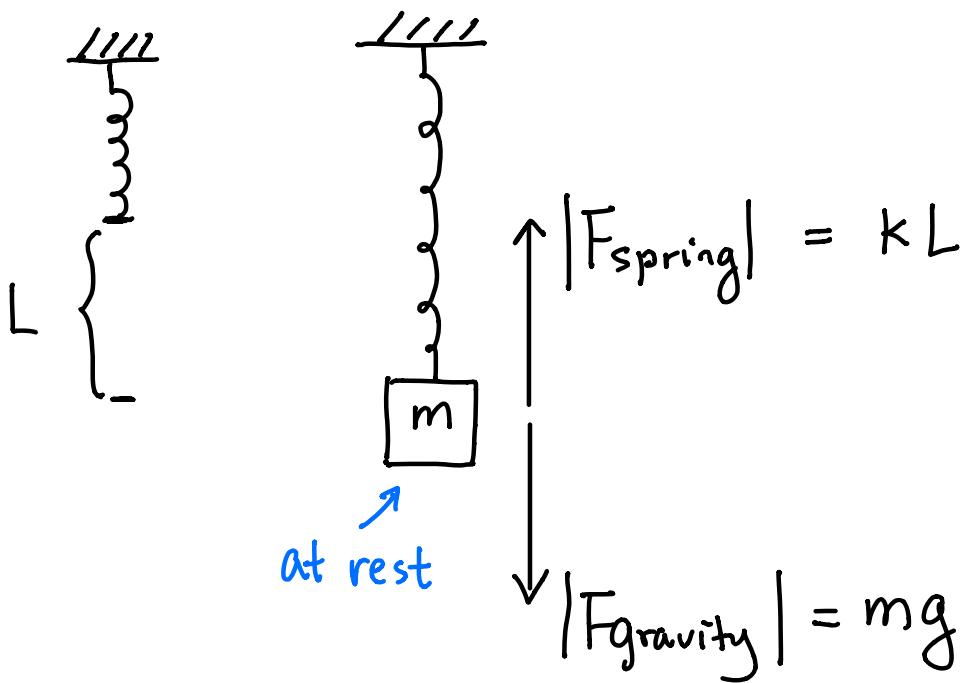
$$0 = u(0.5) = \cos(\sqrt{k} \cdot 0.5)$$

$$\sqrt{k} \cdot 0.5 = \frac{\pi}{2}$$

$$\sqrt{k} = \pi$$

$$k = \pi^2 \text{ kg/s}^2$$

Experiment 2 for finding k

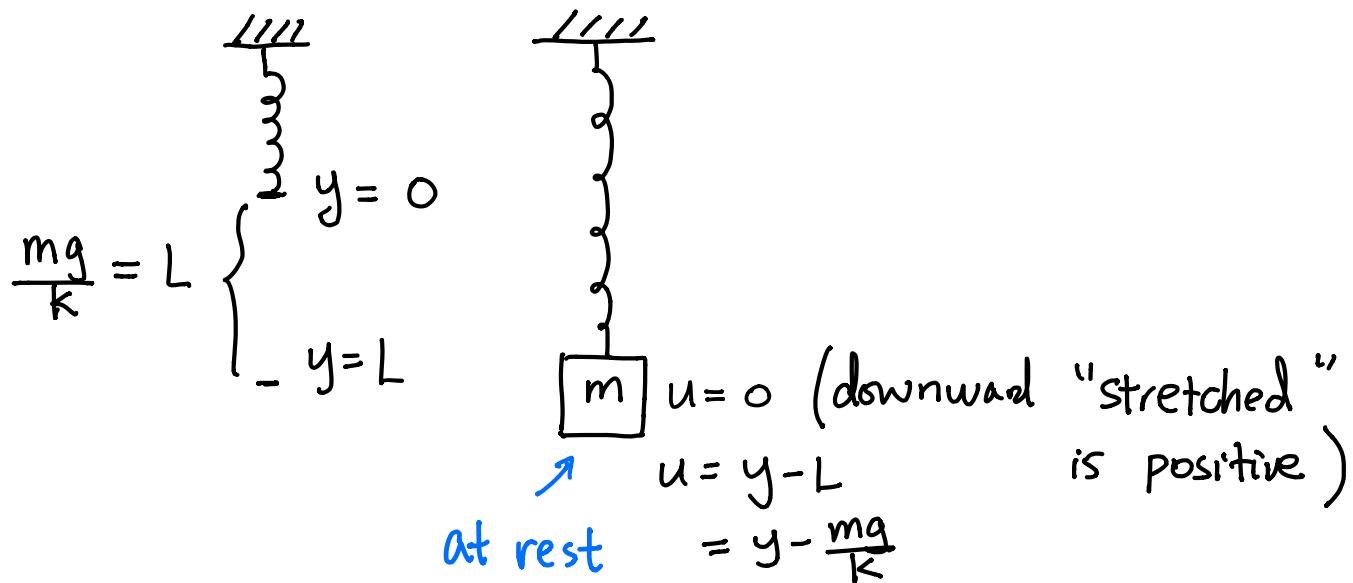


$$kL = mg$$

$$k = \frac{mg}{L}$$

End of lecture 1

Hanging Harmonic Oscillator



$u(t) = 0$ is a constant / equilibrium soln
u = displacement from equilibrium
 $mu'' =$ Force that causes motion / displacement
(i.e. F_{spring} in excess of gravity)
 $= -ku$
 $mu'' + ku = 0$
 $u = C_1 u_1 + C_2 u_2$

$$\left\{ \begin{array}{l} m \frac{d^2y}{dt^2} = F_{\text{gravity}} + F_{\text{spring}} = mg - ky \\ my'' + ky = mg \\ y = \underbrace{c_1 y_1 + c_2 y_2}_{\text{gen soln to } my'' + ky = 0} + \frac{mg}{k} \end{array} \right.$$

Compare y and u :

$$u = y - \frac{mg}{k}, \quad \text{so} \quad y = u + \frac{mg}{k}$$

$$m \left(u + \frac{mg}{k} \right)'' + k \left(u + \frac{mg}{k} \right) = mg$$

$$mu'' + ku + \cancel{mg} = \cancel{mg}$$

$$mu'' + ku = 0$$

Notice : $mg - ky = 0 \Rightarrow y(t) = \frac{mg}{k}$ is an equilibrium soln

Harmonic Oscillator

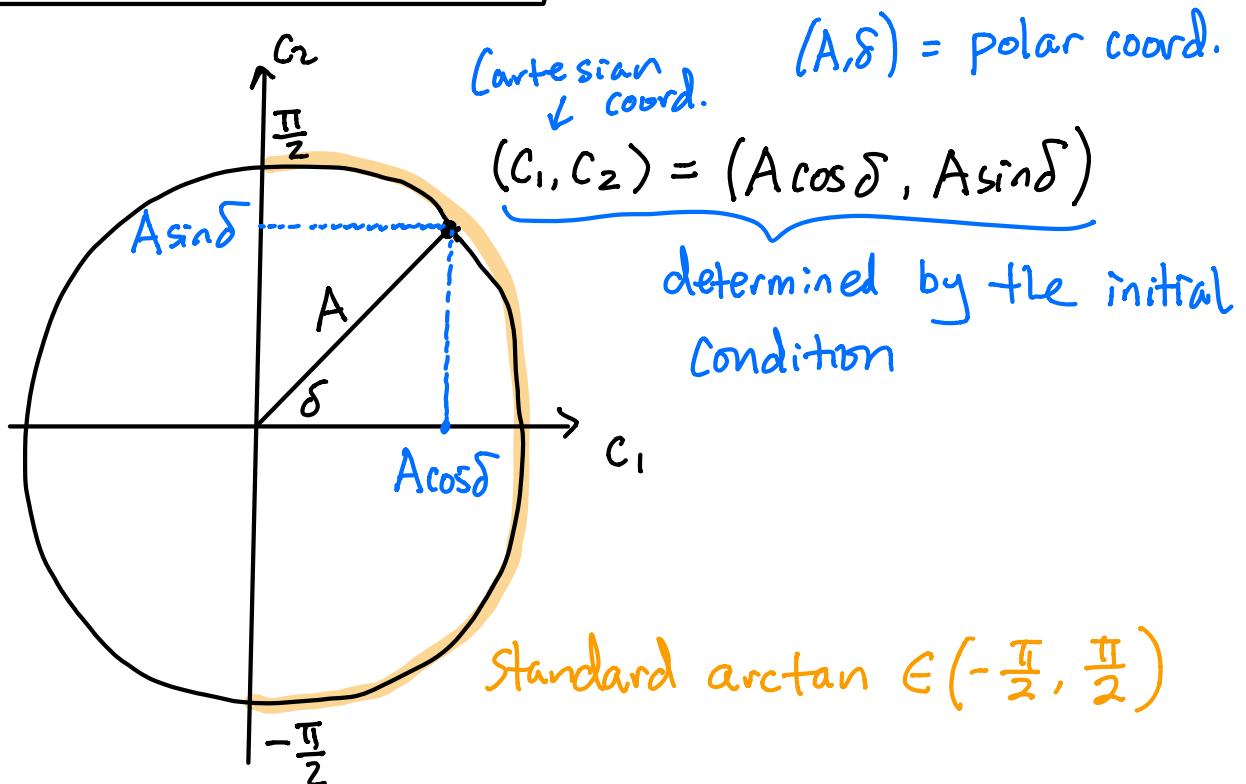
$$m u'' + k u = 0$$

$$u = C_1 \cos(\omega_0 t) + C_2 \sin(\omega_0 t)$$

$$\omega_0 = \sqrt{\frac{k}{m}}$$

$$= \underbrace{A \cos \delta \cos(\omega_0 t)}_{=C_1} + \underbrace{A \sin \delta \sin(\omega_0 t)}_{=C_2}$$

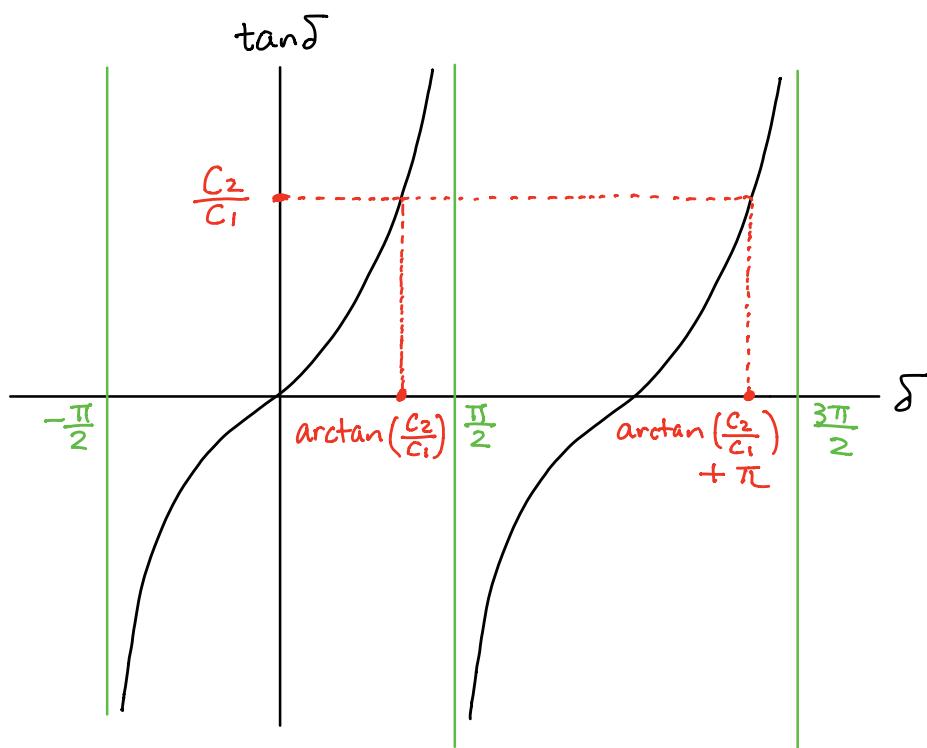
$$u(t) = A \cos(\omega_0 t - \delta)$$



determined by initial conditions

$$\left\{ \begin{array}{l} \text{Amplitude } A = \sqrt{C_1^2 + C_2^2} = \sqrt{A^2 \cos^2 \delta + A^2 \sin^2 \delta} \\ \text{Phase shift : } \cos \delta = \frac{C_1}{A} \\ \sin \delta = \frac{C_2}{A} \end{array} \right\} \Rightarrow \tan \delta = \frac{C_2}{C_1}$$

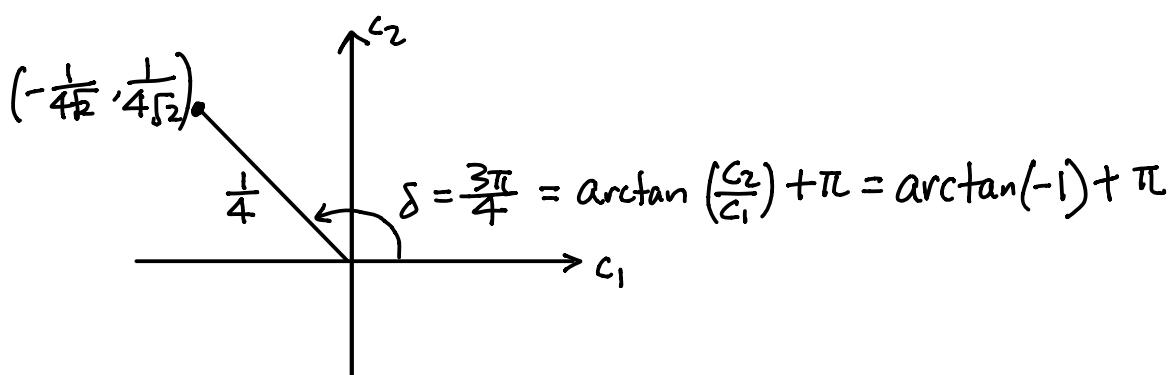
This carries less info than these. So need to also know the sign of C_1 .



$$\left\{ \begin{array}{l} \text{If } c_1 > 0, \quad \delta = \arctan \left(\frac{c_2}{c_1} \right) \\ \text{If } c_1 < 0, \quad \delta = \arctan \left(\frac{c_2}{c_1} \right) + \pi \\ \text{If } c_1 = 0, \quad \delta = \begin{cases} \frac{\pi}{2} & \text{if } c_2 > 0 \\ -\frac{\pi}{2} & \text{if } c_2 < 0 \end{cases} \end{array} \right.$$

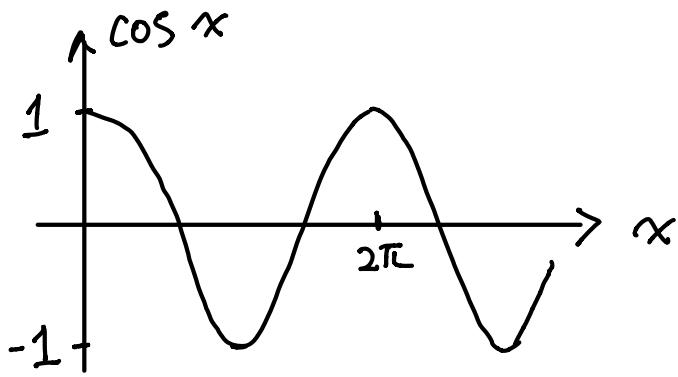
Ex1 : $u(t) = -\frac{1}{4\sqrt{2}} \cos(2\pi t) + \frac{1}{4\sqrt{2}} \sin(2\pi t)$

$$A = \sqrt{c_1^2 + c_2^2} = \sqrt{\frac{1}{32} + \frac{1}{32}} = \frac{1}{4}$$



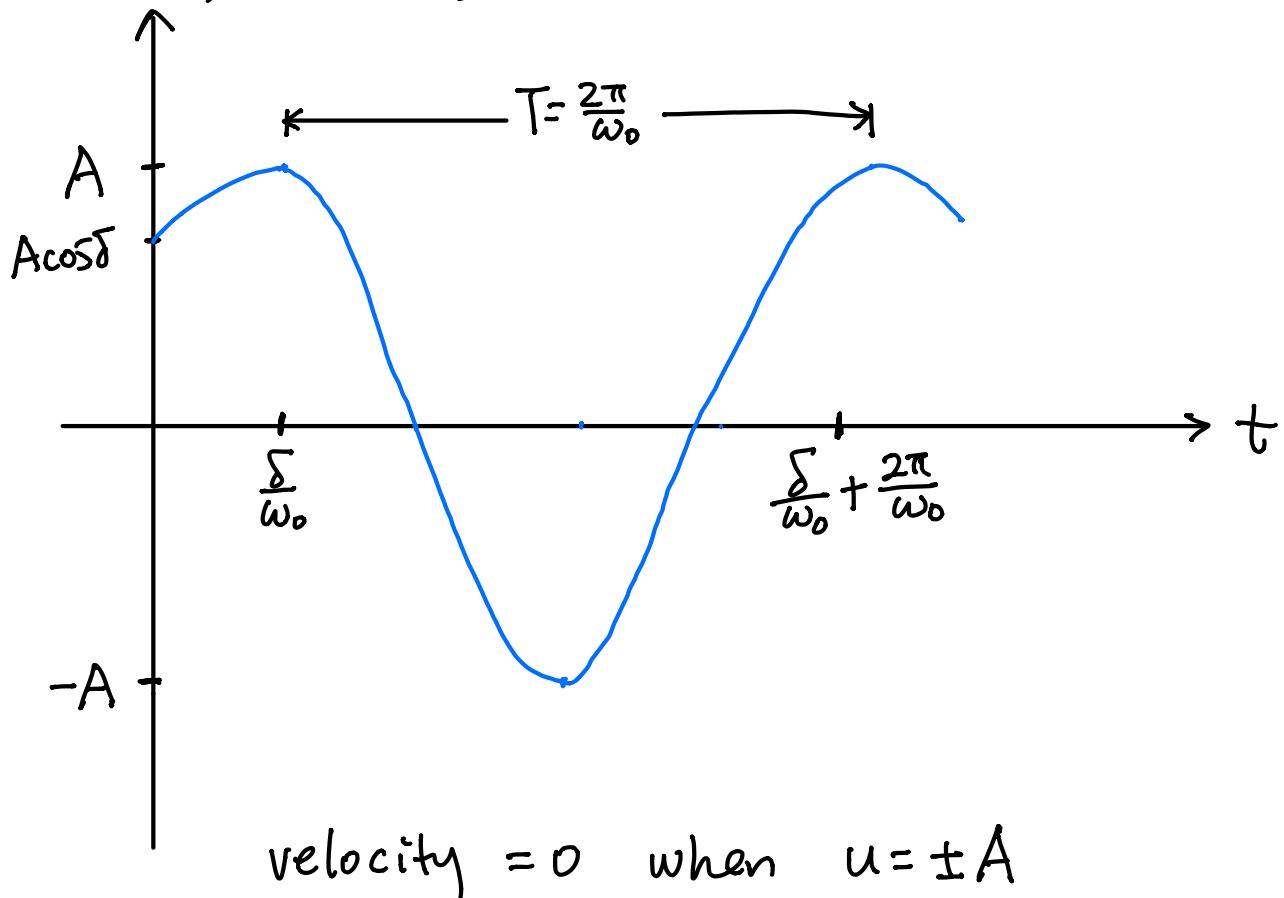
$$u(t) = \frac{1}{4} \cos \left(2\pi t - \frac{3\pi}{4} \right)$$

Graph $u(t) = A \cos(\omega_0 t - \delta)$



$$\cos(x) = \cos(x+2\pi)$$

$$u(t) = A \cos(\omega_0 t - \delta)$$



Comment added after the lecture:

First peak happens when $\omega_0 t - \delta = 0$ ↪ this is assuming we chose $-2\pi < \delta < 2\pi$, so the smallest
 i.e. $t = \frac{\delta}{\omega_0}$ $t > 0$ s.t. $\omega_0 t - \delta = 2\pi n$ happens when $\omega_0 t - \delta = 0$

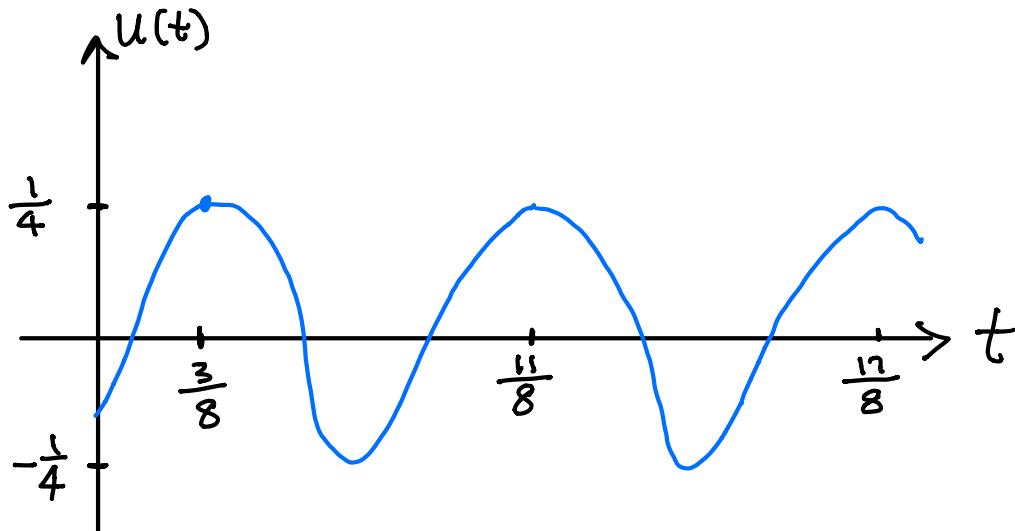
$$\begin{aligned}\text{Period : } \cos(\omega_0 t - \delta) &= \cos(\omega_0 t - \delta + 2\pi) \\ &= \cos\left(\omega_0\left(t + \frac{2\pi}{\omega_0}\right) - \delta\right)\end{aligned}$$

$$T = \frac{2\pi}{\omega_0} = 2\pi \sqrt{\frac{m}{k}}$$

$$\text{Natural Frequency } \omega_0 = \sqrt{\frac{k}{m}}$$

Frequency

Ex 1 cont'd Graph $u(t) = \frac{1}{4} \cos(2\pi t - \frac{3\pi}{4})$



First peak when $2\pi t - \frac{3\pi}{4} = 0$

$$2\pi t = \frac{3\pi}{4}$$

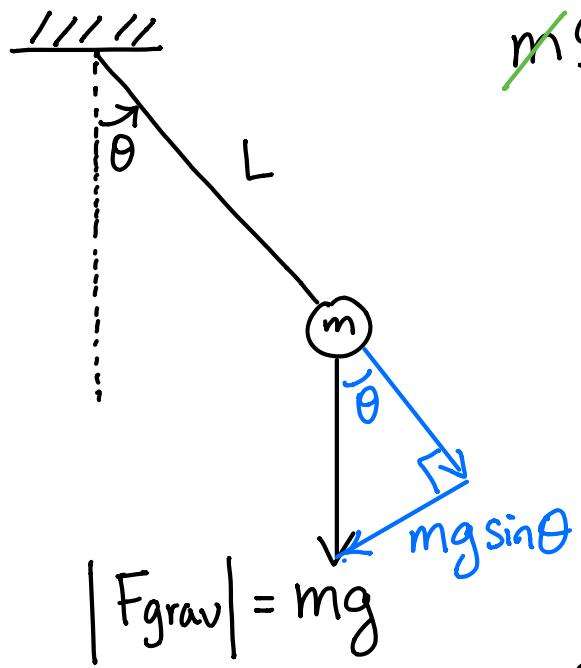
$$t = \frac{3}{8}$$

$$\text{Period : } T = \frac{2\pi}{\omega_0} = \frac{2\pi}{2\pi} = 1$$

There are many examples of vibration in nature.

End of lecture 2

Pendulum



$$|F_{\text{grav}}| = mg$$

$$m \frac{d^2(L\theta)}{dt^2} = -mg \sin \theta$$

$$L \frac{d^2\theta}{dt^2} = -g \sin \theta$$

$$\theta'' + \frac{g}{L} \sin \theta = 0 \quad (\text{nonlinear})$$

small oscillations $\Rightarrow \sin \theta \approx \theta$

$$\theta'' + \frac{g}{L} \theta = 0 \quad (\text{Linearization})$$