

$x' = Ax$, A 2×2 complex eigenvalues

Ex1 $x' = \underbrace{\begin{bmatrix} -1 & -2 \\ 8 & -1 \end{bmatrix}}_A x$

Eigenval: $D = \det \begin{bmatrix} -1-\lambda & -2 \\ 8 & -1-\lambda \end{bmatrix} = (-1-\lambda)^2 + 16 = \lambda^2 + 2\lambda + 17$

$$\lambda = \frac{-2 \pm \sqrt{4-68}}{2} = -1 \pm 4i$$

Fact: If A is real, v an eigenvect. w/ eigenval λ

$\Leftrightarrow \bar{v}$ is an eigenvector w/ eigenvalue $\bar{\lambda}$.

reason: $Av = \lambda v$

$$\Leftrightarrow A\bar{v} = \overline{Av} = \overline{\lambda v} = \bar{\lambda} \bar{v}$$

Eigenvector for $\boxed{\lambda = -1 + 4i}$ (pick one)

solve $(A - \lambda I)v = 0$

$$\begin{bmatrix} -4i & -2 \\ 8 & -4i \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \quad \begin{aligned} \Rightarrow -4iv_1 - 2v_2 &= 0 \\ \Rightarrow v_2 &= -2iv_1 \end{aligned}$$

$$v = \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} v_1 \\ -2iv_1 \end{bmatrix} = \begin{bmatrix} 1 \\ -2i \end{bmatrix} v_1, v_1 \neq 0$$

Pick one: $\boxed{v = \begin{bmatrix} 1 \\ -2i \end{bmatrix}}$

Gen soln: $X = C_1 e^{(1+4i)t} \begin{bmatrix} 1 \\ -2i \end{bmatrix} + C_2 e^{(-1-4i)t} \begin{bmatrix} 1 \\ 2i \end{bmatrix}$

$$Y = u + iv$$

$$\bar{Y} = u - iv$$

complex basis of soln's

But we want to write the soln's in terms of real valued functions instead (physically more meaningful)

Note, Soln to $x' = Ax$ is $x = e^{At}x(0)$, so if A is real and $x(0)$ is real, then x should be real.

$$Y = e^{(1+4i)t} \begin{bmatrix} 1 \\ -2i \end{bmatrix}$$

$$= e^{-t+i(4t)} \begin{bmatrix} 1 \\ -2i \end{bmatrix}$$

$$= \left(e^{-t} \cos(4t) + ie^{-t} \sin(4t) \right) \left(\begin{bmatrix} 1 \\ 0 \end{bmatrix} + i \begin{bmatrix} 0 \\ -2 \end{bmatrix} \right)$$

$$= \left(e^{-t} \cos 4t \begin{bmatrix} 1 \\ 0 \end{bmatrix} - e^{-t} \sin 4t \begin{bmatrix} 0 \\ -2 \end{bmatrix} \right) + i \left(e^{-t} \sin 4t \begin{bmatrix} 1 \\ 0 \end{bmatrix} + e^{-t} \cos 4t \begin{bmatrix} 0 \\ -2 \end{bmatrix} \right)$$

$$\operatorname{Re} Y = u$$

$$\operatorname{Im} Y = v$$

Both u and v are soln's to $x' = Ax$

Euler's formula

$$e^{i\theta} = \cos \theta + i \sin \theta$$

$$e^{a+i\theta} = e^a \cos \theta + i e^a \sin \theta$$

$$\text{Reason 1: } y = u + iv, \quad y' = Ay$$

$$(u + iv)' = A(u + iv)$$

$$u' + iv' = Au + iAv$$

$$\Rightarrow \begin{cases} u' = Au \\ v' = Av \end{cases}$$

Reason 2

$$\begin{array}{l} y = u + iv \\ \bar{y} = u - iv \end{array} \xleftrightarrow[\text{basis}]{\text{Change of}} \begin{cases} u = \frac{y + \bar{y}}{2} = \operatorname{Re} y \\ v = \frac{y - \bar{y}}{2i} = \operatorname{Im} y \end{cases}$$

Gen soln to $x' = Ax$ in terms of real basis is

$$x = C_1 \operatorname{Re} y + C_2 \operatorname{Im} y$$

$$x = C_1 \left(e^{-t} \cos 4t \begin{bmatrix} 1 \\ 0 \end{bmatrix} - e^{-t} \sin 4t \begin{bmatrix} 0 \\ -2 \end{bmatrix} \right) + C_2 \left(e^{-t} \sin 4t \begin{bmatrix} 1 \\ 0 \end{bmatrix} + e^{-t} \cos 4t \begin{bmatrix} 0 \\ -2 \end{bmatrix} \right)$$

$$= C_1 \begin{bmatrix} e^{-t} \cos 4t \\ 2e^{-t} \sin 4t \end{bmatrix} + C_2 \begin{bmatrix} e^{-t} \sin 4t \\ -2e^{-t} \cos 4t \end{bmatrix} \quad \begin{aligned} &\text{As } t \rightarrow \infty, \\ &x(t) \rightarrow 0 \end{aligned}$$

$$x(t) = e^{-t} \begin{bmatrix} \cos 4t & \sin 4t \\ 2 \sin 4t & -2 \cos 4t \end{bmatrix} \begin{bmatrix} C_1 \\ C_2 \end{bmatrix}$$

$$= e^{-t} \begin{bmatrix} \cos 4t & -\frac{\sin 4t}{2} \\ 2\sin 4t & \cos 4t \end{bmatrix} \begin{bmatrix} C_1 \\ -2C_2 \end{bmatrix}$$

$\nearrow e^{At}$

$$X(0) = \begin{bmatrix} 1 & 0 \\ 0 & -2 \end{bmatrix} \begin{bmatrix} C_1 \\ C_2 \end{bmatrix} = \begin{bmatrix} C_1 \\ -2C_2 \end{bmatrix}$$

$$= e^{At} X(0)$$

Ex 2 : $A = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}, \quad x' = Ax$

Eigenval : $\pm i$, pick $\lambda = i$

Corresp. eigenvec : $V = \begin{bmatrix} 1 \\ i \end{bmatrix}$

$$y = e^{it} \begin{bmatrix} 1 \\ i \end{bmatrix} = (\cos t + i \sin t) \left(\begin{bmatrix} 1 \\ 0 \end{bmatrix} + i \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right)$$

$$x(t) = C_1 \operatorname{Re}(y) + C_2 \operatorname{Im}(y)$$

$$= C_1 \left(\cos t \begin{bmatrix} 1 \\ 0 \end{bmatrix} - \sin t \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right) + C_2 \left(\sin t \begin{bmatrix} 1 \\ 0 \end{bmatrix} + \cos t \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right)$$

$$= C_1 \begin{bmatrix} \cos t \\ -\sin t \end{bmatrix} + C_2 \begin{bmatrix} \sin t \\ \cos t \end{bmatrix}$$

$$x(t) = \begin{bmatrix} \cos t & \sin t \\ -\sin t & \cos t \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \end{bmatrix}$$

$e^{At} \rightarrow$

$$= e^{At} x(0)$$

$$x(0) = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} = \begin{bmatrix} c_1 \\ c_2 \end{bmatrix}$$

Rmk: $e^{At} = P e^{Dt} P^{-1} = P \begin{bmatrix} e^{it} & 0 \\ 0 & e^{-it} \end{bmatrix} P^{-1} = \begin{bmatrix} \cos t & \sin t \\ -\sin t & \cos t \end{bmatrix}$

$$A = P D P^{-1}$$

$$P = \begin{bmatrix} 1 & i \\ i & -1 \end{bmatrix}, \quad D = \begin{bmatrix} i & 0 \\ 0 & -i \end{bmatrix}$$

Hw4
#2

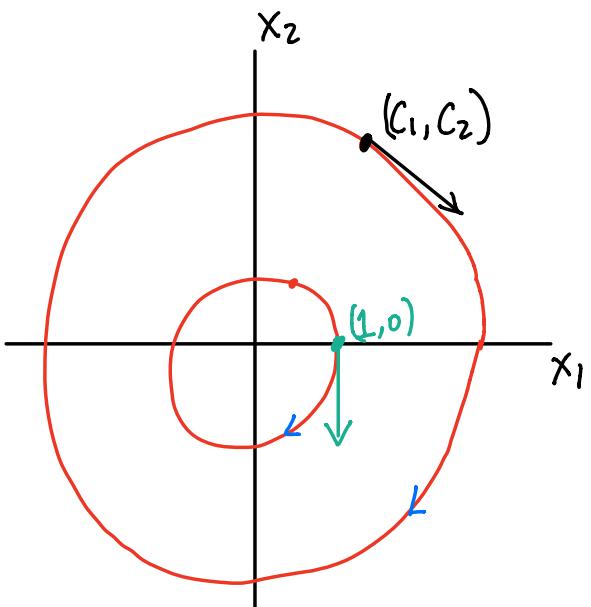
Ex 2 cont'd

$$x_1 = c_1 \cos t + c_2 \sin t$$

$$x_2 = -c_1 \sin t + c_2 \cos t$$

can Verify : $x_1^2 + x_2^2 = c_1^2 + c_2^2$

circle centered at the origin of radius $\sqrt{c_1^2 + c_2^2}$.



$$x(0) = \begin{pmatrix} c_1 \\ c_2 \end{pmatrix}$$

$$x'(0) = Ax(0) = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} = \begin{bmatrix} c_2 \\ -c_1 \end{bmatrix}$$

* all circles go in the same direction, so can use any "easy" initial condition to check the direction

Easy test case: when $x(0) = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$

$$x'(0) = Ax(0) = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ -1 \end{bmatrix}$$

Ex 3 Sketch $x = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} \cos 4t & \sin 4t \\ 2\sin 4t & -2\cos 4t \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \end{bmatrix}$

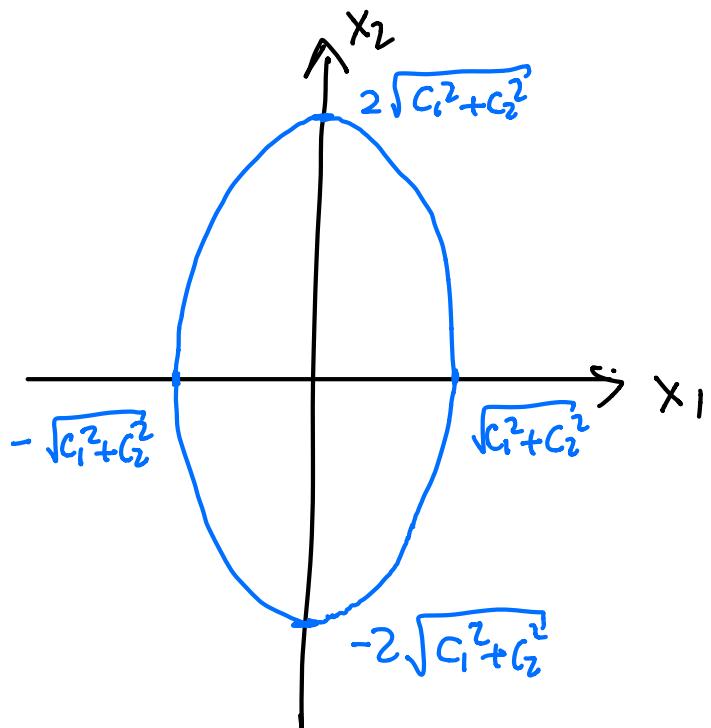
$$x_1 = c_1 \cos 4t + c_2 \sin 4t$$

$$x_2 = 2(c_1 \sin 4t - c_2 \cos 4t)$$

Can verify $x_1^2 + \left(\frac{x_2}{2}\right)^2 = c_1^2 + c_2^2$

\Rightarrow ellipse centered at the origin

\Rightarrow axes of the ellipse = x_1, x_2 axes



$$\left(\frac{x_1}{a}\right)^2 + \left(\frac{x_2}{b}\right)^2 = c \quad \text{has "straight" axis}$$

Rmk: HW 5 #1 find axes for ellipse with tilted axis.

In general:

If $\lambda = ib$ (purely imaginary)

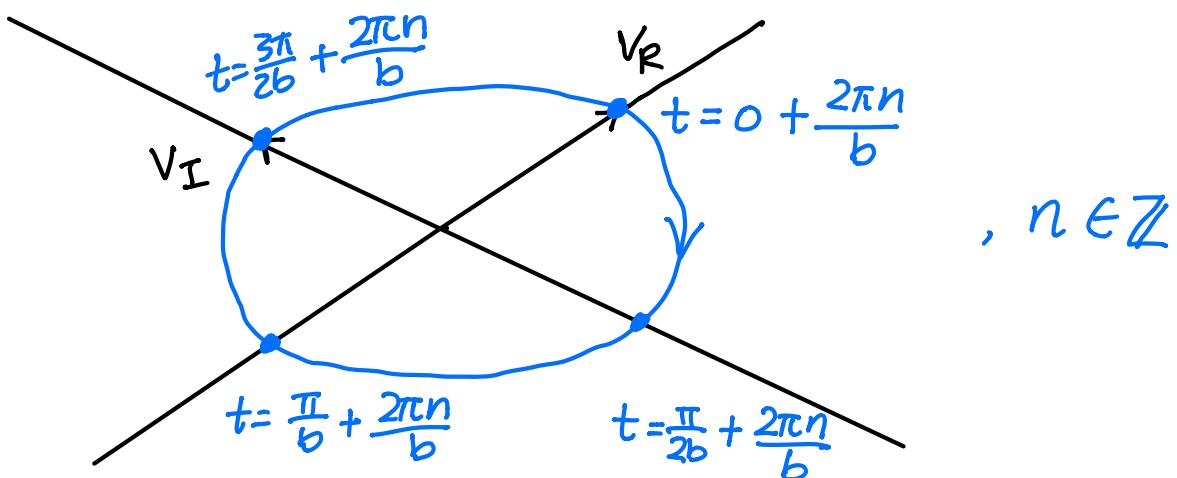
$$V = V_R + i V_I$$

One real soln is

$$\operatorname{Re}(e^{ibt} v)$$

$$= \operatorname{Re} \left((\cos bt + i \sin bt) (V_R + i V_I) \right)$$

$$= \cos(bt) V_R - (\sin bt) V_I$$



* But V_I and V_R may not be axes of the ellipse, not when V_I and V_R are not \perp .

* other trajectories are concentric ellipses

Ex 1 (cont'd) eigenvalue $\lambda = a \pm bi$, $a \neq 0$

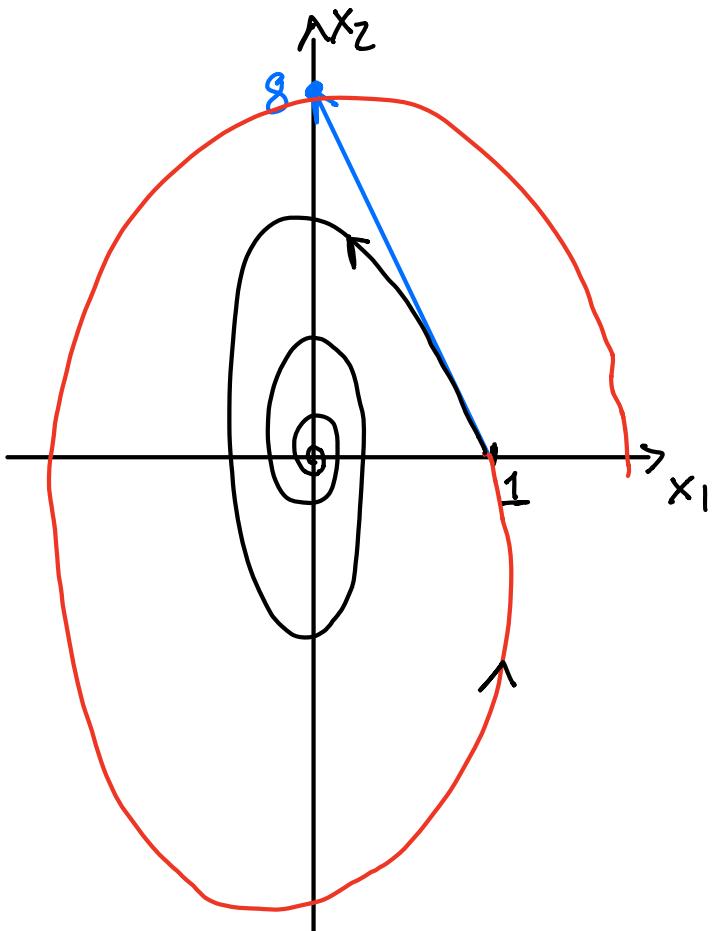
$$x(t) = e^{-t} \begin{bmatrix} \cos 4t & \sin 4t \\ 2 \sin 4t & -2 \cos 4t \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \end{bmatrix}$$

elliptical spiral

$$x' = Ax, \quad A = \begin{bmatrix} -1 & -2 \\ 8 & -1 \end{bmatrix}, \quad x(0) = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$x'(0) = A x(0)$$

$$= \begin{bmatrix} -1 & -2 \\ 8 & -1 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} -1 \\ 8 \end{bmatrix}$$



$t \in [0, \infty)$

$t \leq 0$

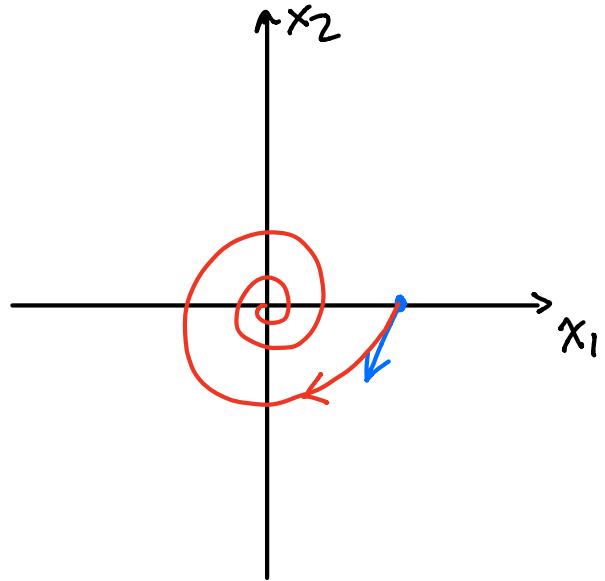
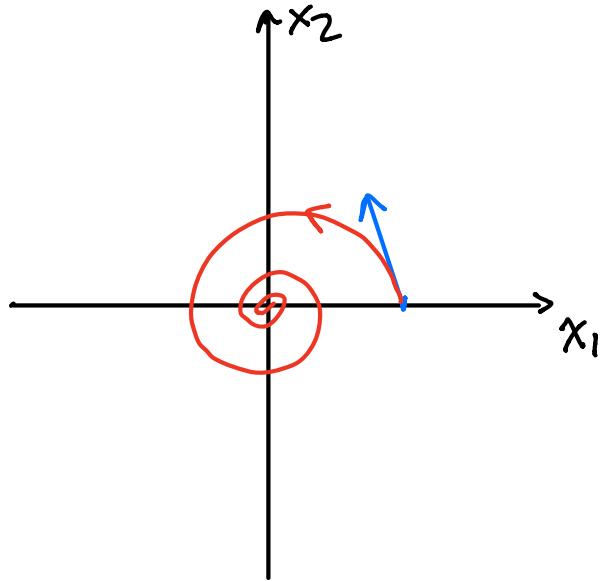
Stable spiral

counterclockwise

Different spiral

Stable
Spiral

trajectory for $t \geq 0$



Unstable
Spiral

