```
def kMeansIterate(partitionedPoints: Seq[SiloRef[Array[Point]]],
                centroids: Array[Point],
                iteration: Int): Array[Point] = {
                                                                             type: SiloRef[Array[Point]]
                                                   apply returns
val clusterParts =
                                                                             parameter of fn
                                                   a SiloRef
                                                                             passed to map on
  partitionedPoints.map(silo => silo.apply(
                                                                             Seq[SiloRef[Array[Point]]]
    spore {
      val lCentroids = centroids // spore header
                                                                             Spore passed to
                                                                             apply method on
      (points: Array[Point]) =>
                                                                             SiloRef
        SiloRef.populate(currentHost, kmeansLocal(points, lCentroids))
   ).send())
                send returns
                a Future
                              Await.result is a barrier which blocks
                                                                             type: Seq[Array[Point]]]
val newCentroids =
                             until the argument future is resolved
                                                                             parameter of fn
                                                                             passed to map on
  Await.result(Future.sequence(clusterParts).map(seq => {
                                                                             Future[Seq[Array[Point]]]
    seq.reduce((x, y) \Rightarrow x ++ y)
        .groupBy(x \Rightarrow x. 1)
        .toSeq
                                                                            Chained higher-
        .sortBy(x \Rightarrow x. 1)
                                                                             order functions
                                                                             on standard Scala
        .map(x \Rightarrow x. 2)
                                                                             collections
        .map(clp => clp.map(x => x. 2).toArray.unzip)
        .map({ case (ns, points) => (ns.sum, sumPoints(points)) })
        .map({ case (n, sum) => divPoint(sum, n) })
  }), Duration.Inf).toArray
val diff =
                                                                             Pattern match
  newCentroids.zip(centroids).map({ case (p1, p2) => dist(p1, p2) }).max deconstructing a
                                                                             pair and
  if (diff < epsilon) // check if converged else iterate again</pre>
                                                                             assigning names
                                                                             to each
    newCentroids
                                                                             component.
  else
    kMeansIterate(partitionedPoints, newCentroids, iteration + 1)
 }
```