

```
In [ ]: import numpy as np
        from numpy.linalg import matrix_power
        from scipy.stats import norm, gaussian_kde, beta
        import scipy.linalg as la
        import matplotlib
        import matplotlib.pyplot as plt
        from numba import vectorize, jit, njit, float64, prange
```

Exercise 1.1. {-}

Let X be an $n \times n$ matrix with all positive entries. The spectral radius $r(X)$ of X is the maximum of $|\lambda|$ over all eigenvalues λ of X where $|\cdot|$ is the modulus of a complex number.

A version of the local spectral radius theorem states that if X has all positive entries and v is any strictly positive $n \times 1$ vector, then

$$\lim_{i \rightarrow \infty} \|X^i v\|^{1/i} \rightarrow r(X) \quad (\text{LSR})$$

where $\|\cdot\|$ is the usual Euclidean norm.

Intuitively, the norm of the iterates of a positive vector scale like $r(X)$ asymptotically.

The data file `matrix_data.txt` contains the data for a single matrix X .

1. Read it in and compute the spectral radius using the tools for working with eigenvalues in `scipy.linalg`.
2. Test the claim in (LSR) iteratively, computing $\|X^i v\|^{1/i}$ for successively larger values of i . See if the sequence so generated converges to $r(A)$.

```
In [49]: matrix = np.loadtxt("matrix_data.txt")
        λ = la.eigvals(mat)
        spectral_radius = np.absolute(λ).max()
```

```
In [50]: def problem1_1(v, X, i):
        r = la.norm(matrix_power(X, i) @ v) ** (1/i)
        distance = np.absolute(r - spectral_radius)
        return r, distance

        j, jj = matrix.shape
        v = np.ones(j)
```

```
In [51]: i = 1000
        r, distance = problem1_1(v, matrix, i)
        print(distance)
```

```
0.0012011304694321545
```

```
In [52]: i = 100000
         r, distance = problem1_1(v, matrix, i)
         print(distance)

1.200420037306138e-05
```

Exercise 1.2. {-}

Recall the the quadratic map generates time series of the form

$$x_{t+1} = 4x_t(1 - x_t)$$

for some given x_0 , and that these trajectories are chaotic.

This means that different initial conditions generate seemingly very different outcomes.

Nevertheless, the regions of the state space where these trajectories spend most of their time are in fact typically invariant to the initial condition.

Illustrate this by generating 100 histograms of the time series generated from the quadratic map, with x_0 drawn independently from the uniform distribution on $(0, 1)$.

Do they all look alike?

Try to make your code efficient.

```
In [53]: @njit
         def problem1_2(x_0, length):
             x = x_0
             for t in range(length-1):
                 x = 4*x*(1-x)
             return x
```

```
In [54]: print(problem1_2(0.4,10))

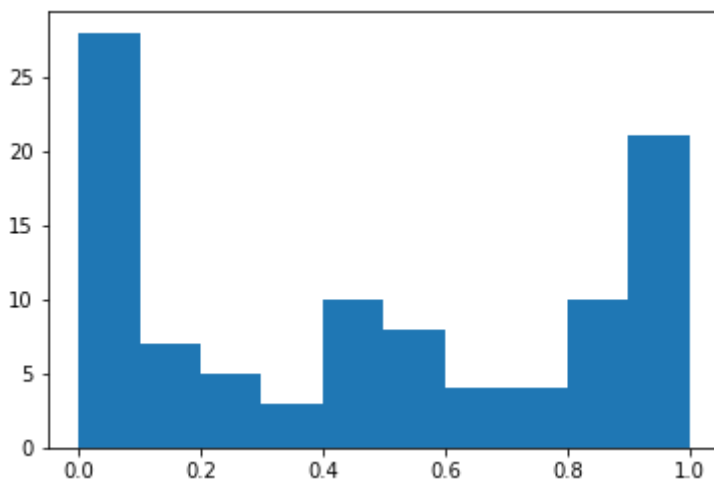
0.918969052370147
```

```
In [55]: %%time
length = 10000000
xknot = np.random.rand(100)
out = np.empty(xknot.size)

for i,x_0 in enumerate(xknot):
    out[i] = problem1_2(x_0, length = length)

plt.hist(out)
```

CPU times: user 2.04 s, sys: 13.7 ms, total: 2.06 s
Wall time: 2.07 s



Exercise 1.3. {-}

In the lecture it was claimed that, if (\mathbb{X}, g) is a dynamical system, g continuous at $\hat{x} \in \mathbb{X}$, and for some $x \in \mathbb{X}$, $g^t(x) \rightarrow \hat{x}$, then \hat{x} is a steady state of (\mathbb{X}, g) . Prove this.

Solution. {-}

Let $y \in C = \{x \in \mathbb{X} \mid \lim_{t \rightarrow \infty} g^t(x) = \hat{x}\}$. Since g is continuous at \hat{x} , and $\lim_{t \rightarrow \infty} g^{t-1}(y) = \hat{x}$, we have that

$$\begin{aligned} \hat{x} &= \lim_{t \rightarrow \infty} g^t(x) \\ &= g \left(\lim_{t \rightarrow \infty} g^{t-1}(x) \right) \\ &= g(\hat{x}). \end{aligned}$$

■

Exercise 2.1. {-}

```
In [56]: class problem2_1:

    def __init__(self, X, h=None):

        self.X = X
        self.n = X.size

        if not h:
            self.h = self.silverman()
        else:
            self.h = h

    def silverman(self):
        return 1.06 * (self.n ** (-1/5)) * np.sqrt(np.var(self.X))

    def f(self, x):
        K = norm.pdf
        summand = K( (x - self.X) / self.h )
        return (1/(self.h*self.n)) * summand.sum()

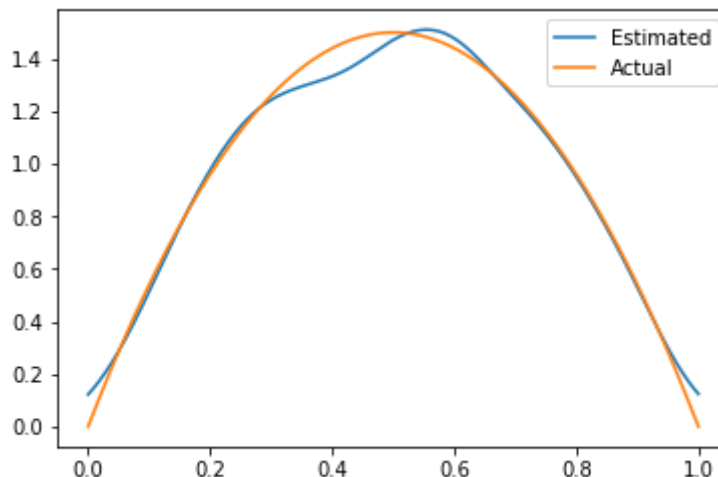
    def estimate(self, grid=np.linspace(0,1,1000)):
        estimation = np.empty_like(grid)

        for j,k in enumerate(grid):
            estimation[j] = self.f(k)

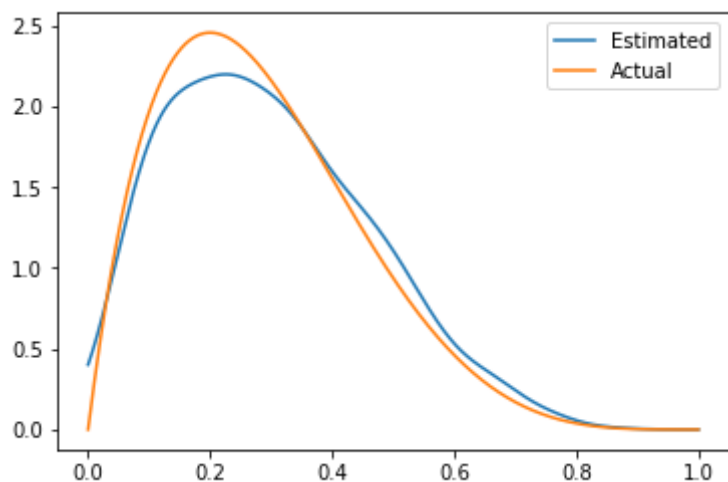
        return estimation
```

```
In [57]: n, grid = 1000, np.linspace(0,1,1000)
```

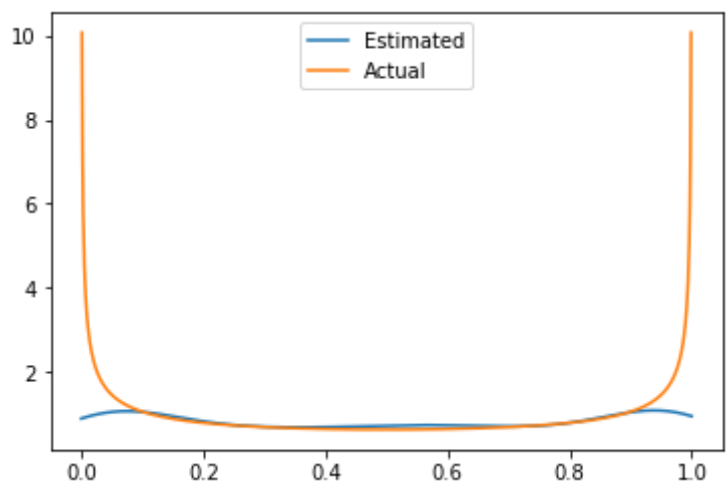
```
In [58]:  $\alpha 2 \beta 2$  = np.random.beta(2,2,size=(n,1))
estimator_ $\alpha 2 \beta 2$  = problem2_1(X =  $\alpha 2 \beta 2$ )
estimate_ $\alpha 2 \beta 2$  = estimator_ $\alpha 2 \beta 2$ .estimate(grid=grid)
plt.plot(grid, estimate_ $\alpha 2 \beta 2$ , label = "Estimated")
plt.plot(grid, beta.pdf(grid,2,2),label = "Actual")
plt.legend()
plt.show()
```



```
In [59]:  $\alpha 2 \beta 5$  = np.random.beta(2,5,size=(n,1))
estimator_ $\alpha 2 \beta 5$  = problem2_1(x= $\alpha 2 \beta 5$ )
estimate_ $\alpha 2 \beta 5$  = estimator_ $\alpha 2 \beta 5$ .estimate(grid=grid)
plt.plot(grid, estimate_ $\alpha 2 \beta 5$ , label="Estimated")
plt.plot(grid, beta.pdf(grid,2,5), label= "Actual")
plt.legend()
plt.show()
```



```
In [60]:  $\alpha 05 \beta 05$  = np.random.beta(0.5,0.5,size=(n,1))
estimator_ $\alpha 05 \beta 05$  = problem2_1(x= $\alpha 05 \beta 05$ )
estimate_ $\alpha 05 \beta 05$  = estimator_ $\alpha 05 \beta 05$ .estimate(grid=grid)
plt.plot(grid, estimate_ $\alpha 05 \beta 05$ , label="Estimated")
plt.plot(grid, beta.pdf(grid,0.5,0.5), label="Actual")
plt.legend()
plt.show()
```



Exercise 2.2. {-}

```
In [61]:  $\varrho$ , b,  $\sigma$ ,  $\mu$ , s = 0.9, 0.0, 0.1, -3, 0.2
```

```
In [62]: def problem2_2(x, q=q, b=b, σ=σ):
        ξ = np.random.standard_normal()
        return (q * x) + b + (σ * ξ)
```

```
In [66]: grid = np.linspace(0,1,1000)
        ψ = norm.pdf(grid, loc=μ, scale=s**2)
        plt.plot(np.linspace(μ- 3*s, μ+3*s), matplotlib.mlab.normpdf(np.linspace(
        μ- 3*s, μ+3*s), μ, s))
        plt.plot(np.linspace(q*μ + b - 3*s, q*μ + b + 3*s), matplotlib.mlab.normp
        df(np.linspace(q*μ + b - 3*s, q*μ + b + 3*s), q*μ + b, np.sqrt((q**2)*(s*
        *2) + (σ**2))))
```

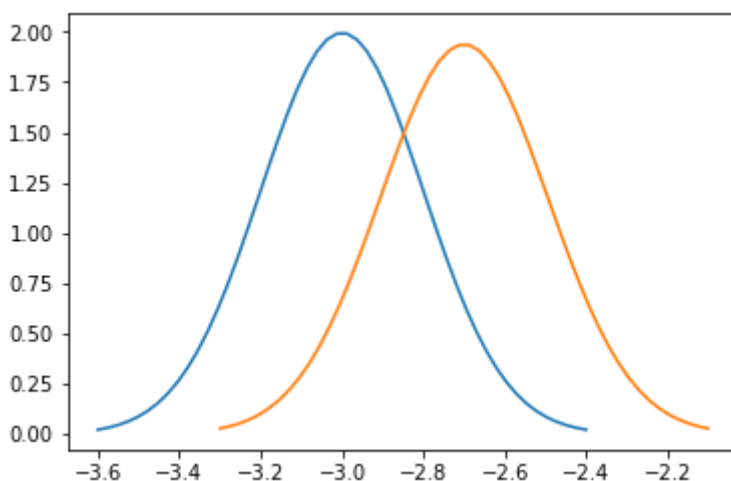
/anaconda3/lib/python3.6/site-packages/ipykernel_launcher.py:3: MatplotlibDeprecationWarning: scipy.stats.norm.pdf

This is separate from the ipykernel package so we can avoid doing imports until

/anaconda3/lib/python3.6/site-packages/ipykernel_launcher.py:4: MatplotlibDeprecationWarning: scipy.stats.norm.pdf

after removing the cwd from sys.path.

Out[66]: [<matplotlib.lines.Line2D at 0x1a16114278>]



```

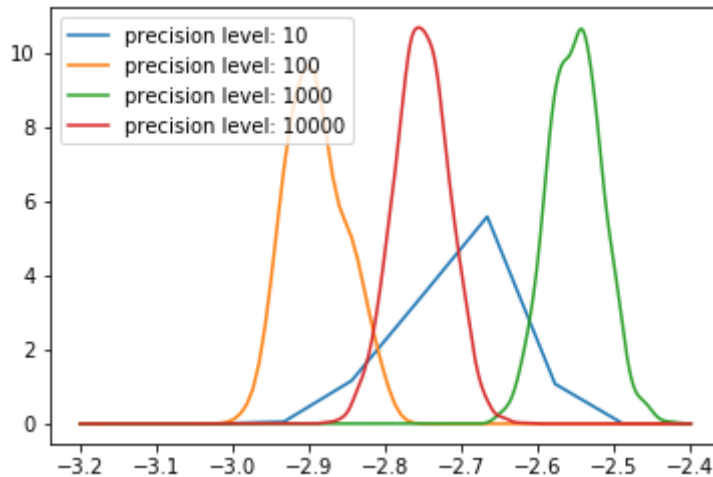
In [67]: ngrid = [10,100,1000,10000]
         for n in ngrid:
             dist = problem2_2(np.random.normal(μ, s**2, n))
             estimator = problem2_1(dist)

             grid = np.linspace(-3.2,-2.4,n)
             density = estimator.estimate(grid=grid)
             plt.plot(grid,density,label="precision level: {}".format(n))

         plt.legend()

```

Out[67]: <matplotlib.legend.Legend at 0x1a238b6748>



Exercise 2.3. {-}

In the lecture it was claimed that, for $n \times n$ matrix A , we have

$$r(A) < 1 \implies A^k \rightarrow 0$$

where convergence is in terms of the spectral norm.

Prove this using Gelfand's formula.

Solution. {-}

Let $A \in M_{n \times n}$, and let A have spectral radius $r(A) < 1$. Consider arbitrary ε such that $0 < \varepsilon < 1 - r(A)$.

By Gelfand's formula, $\exists K(\varepsilon) \in \mathbb{N}$ such that $\forall k \geq K(\varepsilon)$, we have that

$$\begin{aligned} (r(A) - \varepsilon)^k &< \|A^k\| \\ &< (r(A) + \varepsilon)^k. \end{aligned}$$

But $\|A^k\| \geq 0$, so

$$\begin{aligned} 0 &< \|A^k\| \\ &< (r(A) + \varepsilon)^k. \end{aligned}$$

Since ε arbitrary, it follows that $\lim_{k \rightarrow \infty} (r(A) + \varepsilon)^k = 0$. Thus, $\lim_{k \rightarrow \infty} \|A^k\| = 0$.

■