



#### Basic Kernel Methods

Statistical Methods for Machine Learning

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Mernel Perceptron

Kernel Nearest Neighbor

Representer Theorem



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### Perceptron learning algorithm

#### **Algorithm 1:** Kernel perceptron

```
Input: data \{(x_1,y_1),\dots\}\subseteq (\mathcal{X}\times\{-1,1\})^\ell, kernel k
Output: hypothesis h(x)=\mathrm{sgn}\left(\sum_{i=1}^\ell\alpha_iy_ik(x_i,x)\right)

1 \alpha\leftarrow 0
2 repeat
3 | for i=1,\dots,\ell do
4 | if y_i\sum_{j=1}^\ell\alpha_jy_jk(x_j,x_i)\leq 0 then
5 | \alpha_i\leftarrow\alpha_i+1
```

6 until no mistake made within for loop



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## $\kappa$ -nearest neighbor ( $\kappa$ -NN)

#### **Algorithm 2:** $\kappa$ -nearest neighbor

**Input**: kernel k,  $\kappa \in \mathbb{N}^+$ , data  $\{(x_1,y_1),\dots\}\subseteq (\mathcal{X}\times\{-1,1\})^\ell$ , new input x to be classified

**Output**: predicted label y of x

1 
$$S = \{(x_1, y_1), \dots\}$$

2 
$$S_{\kappa}=\emptyset$$

3 while 
$$|S_{\kappa}| < \kappa$$
 do

4 
$$S' \leftarrow \left\{ \operatorname{argmin}_{(x_i, y_i) \in S} \sqrt{k(x, x) - 2k(x, x_j) + k(x_j, x_j)} \right\}$$

$$S_{\kappa} \leftarrow S_{\kappa} \cup S'$$

$$\mathbf{6} \quad \mid \quad S \leftarrow S \setminus S'$$

**Result**: 
$$y = \operatorname{sgn}\left(\frac{1}{|S_{\kappa}|} \sum_{(x_i, y_i) \in S_{\kappa}} y_i\right)$$



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### Representer theorem

Let  $\Omega:[0,\infty[\to\mathbb{R}]$  be a strictly monotonic increasing function,  $\mathcal{H}$  a RKHS with kernel k on  $\mathcal{X}$  and L a loss function. Given  $S=\{(x_1,y_1),\ldots,(x_\ell,y_\ell)\}\subset (\mathcal{X}\times\mathbb{R})^\ell$ , each minimizer  $f\in\mathcal{H}^b$  of the regularized empirical risk

$$\sum_{i=1}^{\ell} L(y_i, f(x_i)) + \Omega(\|f\|_k^2)$$

admits a representation of the form

$$f(x) = \sum_{i=1}^{\ell} \beta_i k(x_i, x) + b$$

with  $\alpha_1, \ldots, \alpha_\ell, b \in \mathbb{R}$ .



### Proof of representer theorem

Projecting candidate solution onto span of training patterns

$$f(x) = f_{\parallel}(x) + f_{\perp}(x) + b = \sum_{i=1}^{\ell} \alpha_i k(x_i, x) + f_{\perp}(x) + b$$

$$\forall j \in \{1, \dots, \ell\} : f(x_j) = \langle f(\cdot), k(x_j, \cdot) \rangle + b$$

$$= \sum_{i=1}^{\ell} \alpha_i k(x_i, x_j) + \langle f_{\perp}(\cdot), k(x_j, \cdot) \rangle + b = \sum_{i=1}^{\ell} \alpha_i k(x_i, x_j) + b$$

$$\Omega\left(\left\|\sum_{i=1}^{\ell} \alpha_i k(x_i,.)\right\|_k^2 + \|f_{\perp}\|_k^2\right) \ge \Omega\left(\left\|\sum_{i=1}^{\ell} \alpha_i k(x_i,.)\right\|_k^2\right)$$



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### Regularization networks I

The squared loss function gives an empirical risk

$$\frac{1}{\ell} \sum_{i=1}^{\ell} (y_i - f(x_i))^2 .$$

Applying Tikhonov regularization leads to regularized riks

$$\frac{1}{\ell} \sum_{i=1}^{\ell} (y_i - f(x_i))^2 + \gamma ||f||^2$$

for  $f \in \mathcal{H}$ ; we know there is a solution of the form

$$f(x) = \sum_{i=1}^{\ell} \alpha_i k(x_i, x) .$$



### Regularization networks II

We have  $\partial f(x)/\partial \alpha_i = k(x_i,x)$ . Setting functional derivative of regularized loss to zero yields for all  $i=1,\ldots,\ell$ :

$$\frac{2}{\ell} \sum_{j=1}^{\ell} (y_j - f(x_j)) k(x_i, x_j) - 2\gamma \langle f, k(x_i, \cdot) \rangle = 0$$

$$\sum_{j=1}^{\ell} (y_j - f(x_j)) k(x_i, x_j) - \ell \gamma f(x_i) = 0$$

$$\sum_{j=1}^{\ell} \left[ y_j - \sum_{m=1}^{\ell} \alpha_m k(x_m, x_j) \right] k(x_i, x_j) - \ell \gamma \sum_{l=1}^{\ell} \alpha_l k(x_l, x_i) = 0$$

$$\sum_{j=1}^{\ell} \left[ y_j - \sum_{m=1}^{\ell} \alpha_m k(x_m, x_j) - \ell \gamma \alpha_j \right] k(x_i, x_j) = 0$$



### Regularization networks III

$$\sum_{j=1}^{\ell} \left[ y_j - \sum_{m=1}^{\ell} \alpha_m k(x_m, x_j) - \ell \gamma \alpha_j \right] k(x_i, x_j) = 0$$

for all i is fulfilled if for all j

$$y_j - \sum_{m=1}^{\ell} \alpha_m k(x_m, x_j) - \ell \gamma \alpha_j = 0$$

(which is necessary if k is strictly positive definite) In matrix form we have

$$\boldsymbol{y} - (\ell \gamma \boldsymbol{I} + \boldsymbol{K}) \boldsymbol{\alpha} = \boldsymbol{0}$$

Algorithm "almost magical for its simplicity and effectiveness" (Poggio & Smale, 2003)



### Regularization networks IV

#### **Algorithm 3:** Regularization network

**Input**: kernel k, regularization parameter  $\gamma \in \mathbb{R}^+$ , data

$$\{(x_1,y_1),\ldots\}\subseteq (\mathcal{X}\times\mathbb{R})^\ell$$

**Output**: hypothesis  $h(x) = \sum_{i=1}^{\ell} \alpha_i k(x_i, x)$ 

- 1  $y = (y_1, \dots, y_{\ell})^{\mathsf{T}}$
- 2  $I = \operatorname{diag}(1, \dots, 1) \in \mathbb{R}^{\ell \times \ell}$
- з  $oldsymbol{K} \in \mathbb{R}^{\ell imes \ell}, [oldsymbol{K}]_{ij} = k(x_i, x_j)$
- 4  $\boldsymbol{\alpha} \leftarrow (\ell \gamma \boldsymbol{I} + \boldsymbol{K})^{-1} \boldsymbol{y}$



### Summary

- Kernel trick leads to many simple, but effective algorithms
- Regularization networks algorithm is key learning method
- Minimizer of the regularized loss lies in the span of the kernels centered on the training points

#### References:

- B. Schölkopf and A. J. Smola, Learning with Kernels, MIT Press, 2002.
- T. Poggio and S. Smale, The mathematics of learning: Dealing with data. Notices of the American Mathematical Society, 50(5):537–544, 2003

