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# Optimization and Optimal Control

## Duality

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# Content

- ❖ Lagrangian function
- ❖ Lagrange dual problem
- ❖ Weak and strong duality
- ❖ KKT optimality conditions

# Standard optimization problem

**Standard form problem:** (not necessarily convex)

$$\begin{array}{ll}\text{minimize} & f_0(x) \\ \text{subject to} & f_i(x) \leq 0, \quad i = 1, \dots, m \\ & h_i(x) = 0, \quad i = 1, \dots, p\end{array}$$

variable  $x \in \mathbf{R}^n$ , domain  $\mathcal{D}$ , optimal value  $p^\star$

# Motivation

## ❖ Reformulation

$$\text{minimize } f_0(x) + \sum_{i=1}^m I_-(f_i(x)) + \sum_{k=1}^p I_0(h_k(x))$$

where  $I_-(u) = 0$  if  $u \leq 0$ ,  $I_-(u) = \infty$  otherwise (indicator function of  $R_-$ )  
 $I_0(u) = 0$  if  $u=0$ ,  $I_0(u) = \infty$  otherwise

$$L(x, \lambda, \nu) = f_0(x) + \sum_{i=1}^m \lambda_i f_i(x) + \sum_{i=1}^p \nu_i h_i(x)$$

$$M(x) = \max_{\lambda, \nu, \lambda \geq 0} f_0(x) + \sum_{i=1}^m \lambda_i f_i(x) + \sum_{j=1}^p \nu_j h_j(x) = \begin{cases} f_0(x) & x \text{ in feasible domain} \\ +\infty & \text{otherwise} \end{cases}$$

$$\begin{aligned} \min_x M(x) &= \min_x \max_{\lambda, \nu, \lambda \geq 0} L(x, \lambda, \nu) \stackrel{\text{???????}}{=} \max_{\lambda, \nu, \lambda \geq 0} \min_x L(x, \lambda, \nu) \\ &\geq \end{aligned}$$

# Lagrangian

**Lagrangian:**  $L : \mathbf{R}^n \times \mathbf{R}^m \times \mathbf{R}^p \rightarrow \mathbf{R}$ , with  $\text{dom } L = \mathcal{D} \times \mathbf{R}^m \times \mathbf{R}^p$ ,

$$L(x, \lambda, \nu) = f_0(x) + \sum_{i=1}^m \lambda_i f_i(x) + \sum_{i=1}^p \nu_i h_i(x)$$

- weighted sum of objective and constraint functions
- $\lambda_i$  is Lagrange multiplier associated with  $f_i(x) \leq 0$
- $\nu_i$  is Lagrange multiplier associated with  $h_i(x) = 0$

# Lagrange dual function

**Lagrange dual function:**  $g : \mathbf{R}^m \times \mathbf{R}^p \rightarrow \mathbf{R}$ ,

$$\begin{aligned} g(\lambda, \nu) &= \inf_{x \in \mathcal{D}} L(x, \lambda, \nu) \\ &= \inf_{x \in \mathcal{D}} \left( f_0(x) + \sum_{i=1}^m \lambda_i f_i(x) + \sum_{i=1}^p \nu_i h_i(x) \right) \end{aligned}$$

$g(\lambda, \nu)$  is concave

if  $f(x, y)$  is convex in  $(x, y)$  and  $C$  is a convex set, then

$$g(x) = \inf_{y \in C} f(x, y)$$

is convex



if  $f(x, y)$  is convex in  $x$  for each  $y \in \mathcal{A}$ , then

$$g(x) = \sup_{y \in \mathcal{A}} f(x, y)$$

is convex



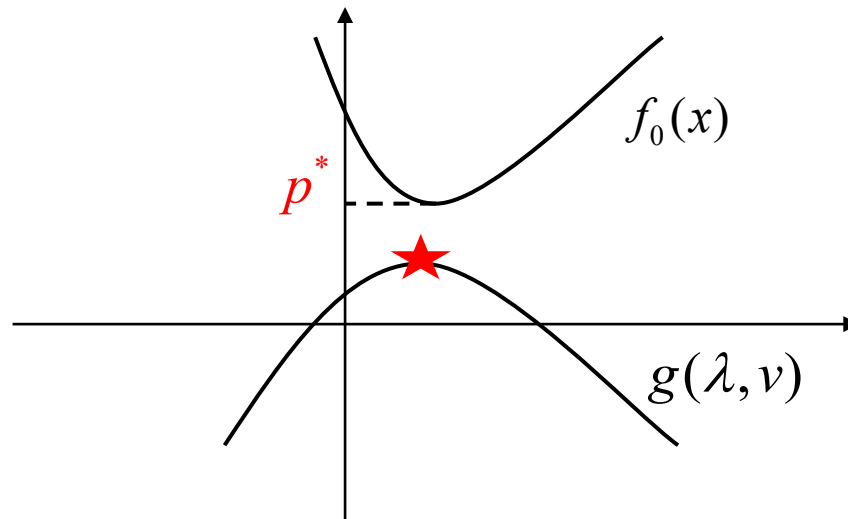
# Lower bound property

**Lower bound property:** if  $\lambda \succeq 0$ , then  $g(\lambda, \nu) \leq p^*$

proof: if  $\tilde{x}$  is feasible and  $\lambda \succeq 0$ , then

$$f_0(\tilde{x}) \geq L(\tilde{x}, \lambda, \nu) \geq \inf_{x \in \mathcal{D}} L(x, \lambda, \nu) = g(\lambda, \nu)$$

minimizing over all feasible  $\tilde{x}$  gives  $p^* \geq g(\lambda, \nu)$



## Least-norm solution of linear equations

$$\begin{array}{ll}\text{minimize} & x^T x \\ \text{subject to} & Ax = b\end{array}$$

### dual function

- Lagrangian is  $L(x, \nu) = x^T x + \nu^T (Ax - b)$
- to minimize  $L$  over  $x$ , set gradient equal to zero:

$$\nabla_x L(x, \nu) = 2x + A^T \nu = 0 \quad \implies \quad x = -(1/2)A^T \nu$$

- plug in in  $L$  to obtain  $g$ :

$$g(\nu) = L((-1/2)A^T \nu, \nu) = -\frac{1}{4}\nu^T A A^T \nu - b^T \nu$$

a concave function of  $\nu$

**lower bound property:**  $p^* \geq -(1/4)\nu^T A A^T \nu - b^T \nu$  for all  $\nu$



# Standard form LP

$$\begin{array}{ll}\text{minimize} & c^T x \\ \text{subject to} & Ax = b, \quad x \succeq 0\end{array}$$

## dual function

- Lagrangian is

$$\begin{aligned}L(x, \lambda, \nu) &= c^T x + \nu^T (Ax - b) - \lambda^T x \\ &= -b^T \nu + (c + A^T \nu - \lambda)^T x\end{aligned}$$

- $L$  is linear in  $x$ , hence

$$g(\lambda, \nu) = \inf_x L(x, \lambda, \nu) = \begin{cases} -b^T \nu & A^T \nu - \lambda + c = 0 \\ -\infty & \text{otherwise} \end{cases}$$

$g$  is linear on affine domain  $\{(\lambda, \nu) \mid A^T \nu - \lambda + c = 0\}$ , hence concave

**lower bound property:**  $p^* \geq -b^T \nu$  if  $A^T \nu + c \succeq 0$

# Equality constrained norm minimization

$$\begin{array}{ll}\text{minimize} & \|x\| \\ \text{subject to} & Ax = b\end{array}$$

## dual function

$$g(\nu) = \inf_x (\|x\| - \nu^T Ax + b^T \nu) = \begin{cases} b^T \nu & \|A^T \nu\|_* \leq 1 \\ -\infty & \text{otherwise} \end{cases}$$

where  $\|v\|_* = \sup_{\|u\| \leq 1} u^T v$  is dual norm of  $\|\cdot\|$

proof: follows from  $\inf_x (\|x\| - y^T x) = 0$  if  $\|y\|_* \leq 1$ ,  $-\infty$  otherwise

- if  $\|y\|_* \leq 1$ , then  $\|x\| - y^T x \geq 0$  for all  $x$ , with equality if  $x = 0$
- if  $\|y\|_* > 1$ , choose  $x = tu$  where  $\|u\| \leq 1$ ,  $u^T y = \|y\|_* > 1$ :

$$\|x\| - y^T x = t(\|u\| - \|y\|_*) \rightarrow -\infty \quad \text{as } t \rightarrow \infty$$

**lower bound property:**  $p^* \geq b^T \nu$  if  $\|A^T \nu\|_* \leq 1$

## Two-way partitioning

$$\begin{array}{ll}\text{minimize} & x^T W x \\ \text{subject to} & x_i^2 = 1, \quad i = 1, \dots, n\end{array}$$

- a nonconvex problem; feasible set contains  $2^n$  discrete points
- interpretation: partition  $\{1, \dots, n\}$  in two sets;  $W_{ij}$  is cost of assigning  $i, j$  to the same set;  $-W_{ij}$  is cost of assigning to different sets

### dual function

$$\begin{aligned}g(\nu) &= \inf_x (x^T W x + \sum_i \nu_i (x_i^2 - 1)) = \inf_x x^T (W + \mathbf{diag}(\nu)) x - \mathbf{1}^T \nu \\ &= \begin{cases} -\mathbf{1}^T \nu & W + \mathbf{diag}(\nu) \succeq 0 \\ -\infty & \text{otherwise} \end{cases}\end{aligned}$$

**lower bound property:**  $p^* \geq -\mathbf{1}^T \nu$  if  $W + \mathbf{diag}(\nu) \succeq 0$

example:  $\nu = -\lambda_{\min}(W)\mathbf{1}$  gives bound  $p^* \geq n\lambda_{\min}(W)$

# Lagrange dual and conjugate function

$$\begin{array}{ll}\text{minimize} & f_0(x) \\ \text{subject to} & Ax \preceq b, \quad Cx = d\end{array}$$

## dual function

$$\begin{aligned}g(\lambda, \nu) &= \inf_{x \in \text{dom } f_0} (f_0(x) + (A^T \lambda + C^T \nu)^T x - b^T \lambda - d^T \nu) \\ &= -f_0^*(-A^T \lambda - C^T \nu) - b^T \lambda - d^T \nu\end{aligned}$$

- recall definition of conjugate  $f^*(y) = \sup_{x \in \text{dom } f} (y^T x - f(x))$
- simplifies derivation of dual if conjugate of  $f_0$  is known

## example: entropy maximization

$$f_0(x) = \sum_{i=1}^n x_i \log x_i, \quad f_0^*(y) = \sum_{i=1}^n e^{y_i - 1}$$

# Lagrange dual problem

## Lagrange dual problem

$$\begin{array}{ll}\text{maximize} & g(\lambda, \nu) \\ \text{subject to} & \lambda \succeq 0\end{array}$$

- finds **best** lower bound on  $p^*$ , obtained from Lagrange dual function
- a convex optimization problem; optimal value denoted  $d^*$

### Exercise:

#### Primal problem

$$\begin{array}{ll}\text{minimize} & c^T x \\ \text{subject to} & Ax = b \\ & x \succeq 0\end{array}$$

#### Dual problem

$$\begin{array}{ll}\text{maximize} & -b^T \nu \\ \text{subject to} & A^T \nu + c \succeq 0\end{array}$$

# Weak and strong duality

**Weak duality:**  $d^* \leq p^*$

- always holds (for convex and nonconvex problems)

**Strong duality:**  $d^* = p^*$

- does not hold in general
- (usually) holds for convex problems

**constraint qualifications**

# Slater's constraint qualification

strong duality holds for a convex problem

$$\begin{array}{ll}\text{minimize} & f_0(x) \\ \text{subject to} & f_i(x) \leq 0, \quad i = 1, \dots, m \\ & Ax = b\end{array}$$

if it is strictly feasible, *i.e.*,

$$\exists x \in \mathbf{int} \mathcal{D} : \quad f_i(x) < 0, \quad i = 1, \dots, m, \quad Ax = b$$

**Sufficient condition**

## Inequality form LP

**primal problem**

$$\begin{array}{ll}\text{minimize} & c^T x \\ \text{subject to} & Ax \preceq b\end{array}$$

**dual function**

$$g(\lambda) = \inf_x ((c + A^T \lambda)^T x - b^T \lambda) = \begin{cases} -b^T \lambda & A^T \lambda + c = 0 \\ -\infty & \text{otherwise} \end{cases}$$

**dual problem**

$$\begin{array}{ll}\text{maximize} & -b^T \lambda \\ \text{subject to} & A^T \lambda + c = 0, \quad \lambda \succeq 0\end{array}$$

- from Slater's condition:  $p^* = d^*$  if  $A\tilde{x} \prec b$  for some  $\tilde{x}$
- in fact,  $p^* = d^*$  except when primal and dual are infeasible



## Quadratic program

**primal problem** (assume  $P \in \mathbf{S}_{++}^n$ )

$$\begin{array}{ll}\text{minimize} & x^T P x \\ \text{subject to} & Ax \preceq b\end{array}$$

**dual function**

$$g(\lambda) = \inf_x (x^T P x + \lambda^T (Ax - b)) = -\frac{1}{4} \lambda^T A P^{-1} A^T \lambda - b^T \lambda$$

**dual problem**

$$\begin{array}{ll}\text{maximize} & -(1/4) \lambda^T A P^{-1} A^T \lambda - b^T \lambda \\ \text{subject to} & \lambda \succeq 0\end{array}$$

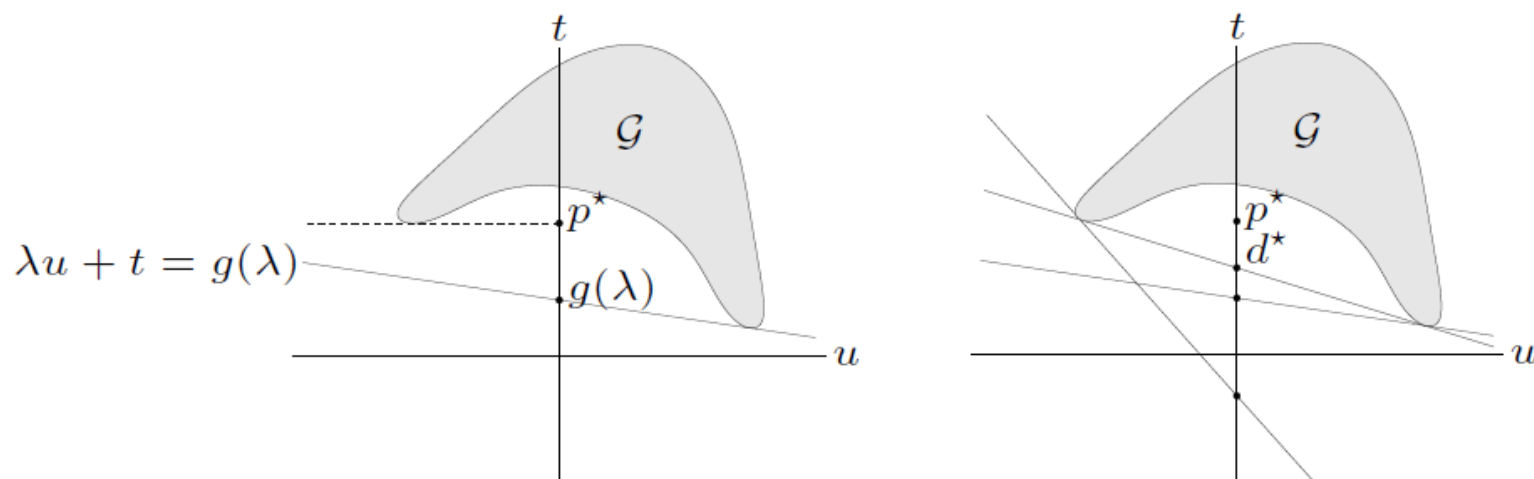
- from Slater's condition:  $p^* = d^*$  if  $A\tilde{x} \prec b$  for some  $\tilde{x}$
- in fact,  $p^* = d^*$  always

# Geometric interpretation

for simplicity, consider problem with one constraint  $f_1(x) \leq 0$

**interpretation of dual function:**

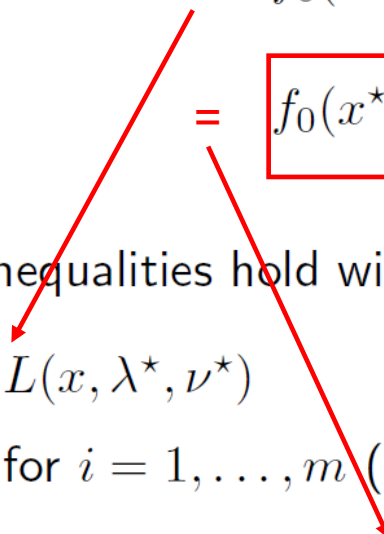
$$g(\lambda) = \inf_{(u,t) \in \mathcal{G}} (t + \lambda u), \quad \text{where } \mathcal{G} = \{(f_1(x), f_0(x)) \mid x \in \mathcal{D}\}$$



- $\lambda u + t = g(\lambda)$  is (non-vertical) supporting hyperplane to  $\mathcal{G}$
- hyperplane intersects  $t$ -axis at  $t = g(\lambda)$

# Complementary slackness

assume strong duality holds,  $x^*$  is primal optimal,  $(\lambda^*, \nu^*)$  is dual optimal

$$\begin{aligned} \boxed{f_0(x^*)} = g(\lambda^*, \nu^*) &= \inf_x \left( f_0(x) + \sum_{i=1}^m \lambda_i^* f_i(x) + \sum_{i=1}^p \nu_i^* h_i(x) \right) \\ &= f_0(x^*) + \sum_{i=1}^m \lambda_i^* f_i(x^*) + \sum_{i=1}^p \nu_i^* h_i(x^*) \\ &= \boxed{f_0(x^*)} \end{aligned}$$


hence, the two inequalities hold with equality

- $x^*$  minimizes  $L(x, \lambda^*, \nu^*)$
- $\lambda_i^* f_i(x^*) = 0$  for  $i = 1, \dots, m$  (known as complementary slackness):

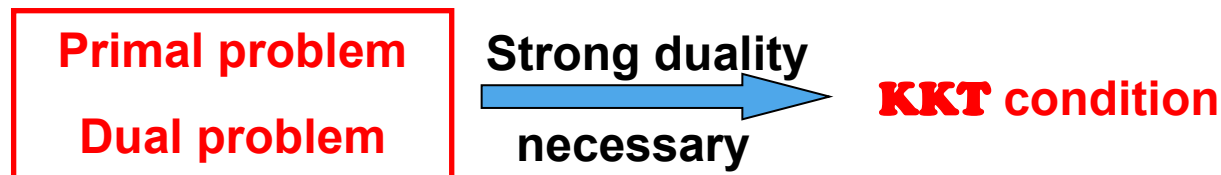
$$\lambda_i^* > 0 \implies f_i(x^*) = 0, \quad f_i(x^*) < 0 \implies \lambda_i^* = 0$$

# Karush-Kuhn-Tucker (**KKT**) conditions

1. primal constraints:  $f_i(x) \leq 0, i = 1, \dots, m, h_i(x) = 0, i = 1, \dots, p$
2. dual constraints:  $\lambda \succeq 0$
3. complementary slackness:  $\lambda_i f_i(x) = 0, i = 1, \dots, m$
4. gradient of Lagrangian with respect to  $x$  vanishes:

$$\nabla f_0(x) + \sum_{i=1}^m \lambda_i \nabla f_i(x) + \sum_{i=1}^p \nu_i \nabla h_i(x) = 0$$

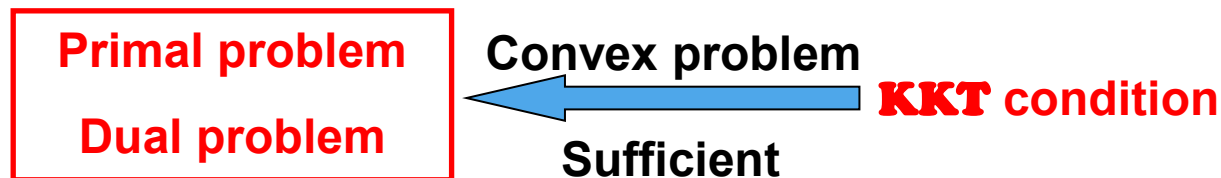
**Previous page:** if strong duality holds and  $x, \lambda, \nu$  are optimal, then they must satisfy the KKT conditions



# Sufficient condition

if  $\tilde{x}$ ,  $\tilde{\lambda}$ ,  $\tilde{\nu}$  satisfy KKT for a convex problem, then they are optimal

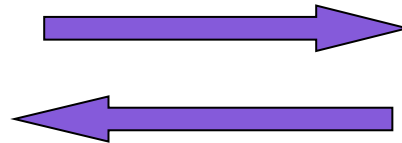
$$\begin{array}{ccc}
 f_0(\tilde{x}) & \xlongequal{\quad p^* = d^* \quad} & g(\tilde{\lambda}, \tilde{\nu}) \\
 \swarrow \text{Complementary slackness} & & \searrow \text{Convex property } \nabla_x L = 0 \\
 L(\tilde{x}, \tilde{\lambda}, \tilde{\nu}) = f_0(\tilde{x}) + \sum_{i=1}^m \tilde{\lambda}_i f_i(\tilde{x}) + \sum_{i=1}^p \tilde{\nu}_i h_i(\tilde{x}) & & 
 \end{array}$$



# Summary

Differentiable

$$\min f(x)$$

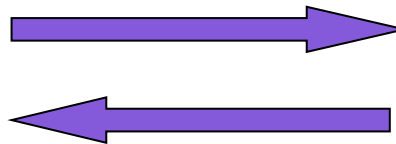


$$\nabla f(x) = 0$$

$$\text{Hessian matrix } H = [\nabla^2 f(x)] \succ 0$$

$\min f_0(x)$
$s.t. f_i(x) \leq 0, \quad i = 1, 2, \dots, m$
$h_i(x) = 0, \quad i = 1, 2, \dots, p$
$\text{maximize } g(\lambda, \nu)$
$\text{subject to } \lambda \succeq 0$

Strong duality



**KKT** conditions

Convex problem

# An Example

**example: water-filling** (assume  $\alpha_i > 0$ )

$$\begin{array}{ll}\text{minimize} & -\sum_{i=1}^n \log(x_i + \alpha_i) \\ \text{subject to} & x \succeq 0, \quad \mathbf{1}^T x = 1\end{array}$$

$x$  is optimal iff  $x \succeq 0$ ,  $\mathbf{1}^T x = 1$ , and there exist  $\lambda \in \mathbf{R}^n$ ,  $\nu \in \mathbf{R}$  such that

$$\lambda \succeq 0, \quad \lambda_i x_i = 0, \quad \frac{1}{x_i + \alpha_i} + \lambda_i = \nu$$

- if  $\nu < 1/\alpha_i$ :  $\lambda_i = 0$  and  $x_i = 1/\nu - \alpha_i$
- if  $\nu \geq 1/\alpha_i$ :  $\lambda_i = \nu - 1/\alpha_i$  and  $x_i = 0$
- determine  $\nu$  from  $\mathbf{1}^T x = \sum_{i=1}^n \max\{0, 1/\nu - \alpha_i\} = 1$

## interpretation

- $n$  patches; level of patch  $i$  is at height  $\alpha_i$
- flood area with unit amount of water
- resulting level is  $1/\nu^*$

