

Héctor Barreiro Cabrera, Ph.D. in Computer Science

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GITHUB [hecbarcab](https://github.com/hecbarcab)

RESIDENCE Valencia, Spain

WORK EXPERIENCE

- 2022 – Now **Senior Scientist** [SEDDI Inc](#) [C++, OpenGL, Python, PyTorch](#)
- Implemented state-of-the-art methods to generate personalized avatars using statistical models.
 - Refactored the avatar generation pipeline for maintainability while honoring best design practices.
 - Optimized critical data structures to enable vectorization, resulting in up to 10x performance boost.
 - Improved robustness and realism of real-time cloth simulation engine.
- 2021 – 2022 **Research Engineer** [Meta Reality Labs Research](#) [C++, CUDA](#)
- Implemented robust interactive soft-body simulation leveraging SIMD for superior performance.
 - Added seamless support for CPU and GPU solvers through template metaprogramming.
- 2020 **Research Intern** [Meta Reality Labs Research](#) [C++, CUDA](#)
- Prototyped GPU-accelerated finite element analysis with significant boost over CPU baseline.
- 2015 – 2021 **Student Researcher** [Universidad Rey Juan Carlos](#) [C++, C#, CUDA, Direct Compute, Unity](#)
- Developed a novel constraint-based formulation for simulating viscous and viscoelastic fluids.
 - Devised novel strategies for driving ultrasonic haptic devices for interacting with virtual fluids.
 - Engaged in reading seminars to explore and discuss the advancements in computer graphics research.
 - Collaborated on the production of papers and demos, ensuring to meet project deadlines.
- 2020 **Research Intern** [Ultraleap Ltd](#) [C++, Python](#)
- Integrated a model to predict the effects of ultrasonic focal points in virtual skin phantom.
- 2017 – 2018 **Student Researcher** [AnyVerse](#) [Python](#)
- Explored machine learning methods to infer the time evolution of fluid dynamic states.
 - Funded by Spain's government under the *Doctorados Industriales* program (ref. DI-16-08640).
- 2013 – 2015 **Junior Programmer** [IRTIC](#) [C#, Unity](#)
- Ported training simulator for cargo handling in port operations to Unity.
 - Developed Augmented Reality interactive applications and demos using Unity and Vuforia.

EDUCATION

- 2016 – 2021 **Ph.D. in Computer Science** [Universidad Rey Juan Carlos](#)
- Obtained Best Doctoral Thesis Award by the Spanish Section of Eurographics.
- 2015 – 2016 **M.Sc. in CG, Videogames and VR** [Universidad Rey Juan Carlos](#)
- Rendering techniques, GPGPU, physics-based simulation, geometry processing, videogames, VR...
- 2010 – 2015 **B.Sc. in Multimedia Engineering** [Universitat de València](#)
- Computer engineering & multimedia systems (graphics, simulation, sound, ...).

PUBLICATIONS

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|------|--|--|
| 2021 | Soft-Tissue Simulation for Comp. Planning of Orthognathic Surgery | Journal of Personalized Medicine, 2021 |
| 2021 | Natural Tactile Interaction with Virtual Clay | IEEE World Haptics Conference, 2021 |
| 2020 | Robust Eulerian-on-Lagrangian Rods | ACM Trans. on Graphics, 2020 |
| 2020 | Path Routing Optimization for STM Ultrasound Rendering | IEEE Trans. on Haptics, 2020 |
| 2019 | Ultrasound Rendering of Tactile Interaction with Fluids | IEEE World Haptics Conference, 2019 |
| 2017 | Conformation Constraints for Efficient Viscoelastic Fluid Simulation | ACM Trans. on Graphics, 2017 |
| 2015 | Real-time Inextensible Hair with Volume and Shape | CEIG, 2015 |

CERTIFICATIONS

Machine Learning
[Stanford Online](#) @ Coursera

Neural Networks and Deep Learning
[Deeplearning.ai](#) @ Coursera

Improving Deep Neural Networks:
Hyperparameter tuning
[Deeplearning.ai](#) @ Coursera

PROFESSIONAL INTERESTS



OTHER SKILLS AND PERSONAL INTERESTS

Tools	Visual Studio, VS Code
Frameworks	Eigen, PyTorch, Numpy, Sympy
HPC	CUDA, OpenCL, OpenGL, GLSL, HLSL
Game Engines	Unity, Godot
Hobbies & Interests	Single player videogames, travelling, trying out new food, comedy shows, petting dogs, naps

For further information, please contact me or visit my online portfolio.

Thank you for your time