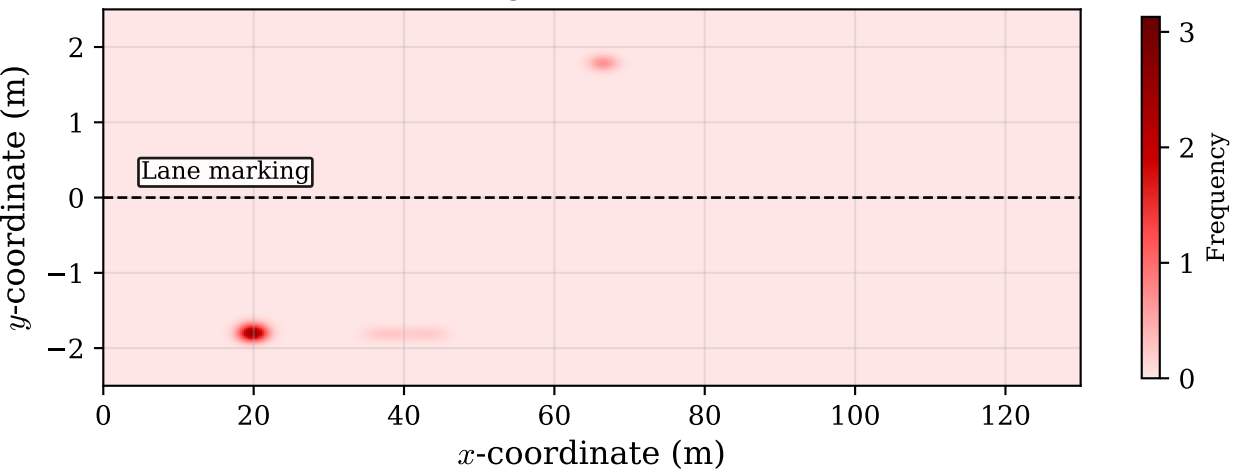


Self-driving car initial positions



Obstacle vehicles initial positions

