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HOMEWORK 2 U1 ADAPTIVE THRESHOLD

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Abstract—In this report we documented our coding process of basic segmentation operations. From the selected images we chose the most suitable operation.

Index Terms—Thresholds, Color Segmentation, RGB, HSV, OpenCv2, Bitwise Operation, Adaptive Threshold, Adaptive Gaussian.

1 ADAPTIVE THRESHOLD

A Daptive thresholding is the method where the threshold value is calculated for smaller regions and therefore, there will be different threshold values for different regions. Basic threshold has problems with images that may have different illumination. Unlike fixed threshold, the threshold value at each pixel location depends on the neighboring pixel intensities. There are two types of adaptive thresholding:

- 1) Adaptive Mean.
- 2) Gaussian.

2 PROBLEM TO SOLVE

From the attached images perform the following:

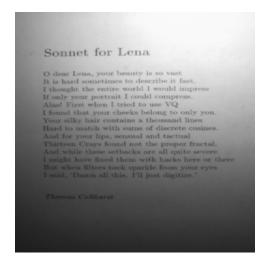
Apply the most suitable Threshold Operation to segment a new image showing up only the bone.



Apply the most suitable Threshold Operation to segment a new image showing up only the stick.



Apply the most suitable Threshold Operation to segment a new image showing up only the text.



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3 CODING PROCESS

3.1 FIRST IMAGE

In order to get the output image the most similar to the one requested, we decided to use the "Binary Threshold" for the first image.

First, we first imported the libraries needed to run our code. Then, we used the command **cv2.imread(")** to read our source image which will be considered as our main input image.

With the cv2.cvtColor(") command, we convert our input image from BGR to gray-scale in order to apply the threshold. Then, we used the command: cv2.threshold() to put the corresponding data to apply the five thresholds.

Finally, we use the command **cv2.imshow(")** to show the final results of the output image.

3.2 SECOND IMAGE

For the second image, we decided to use the same type of threshold as for the exercise number one. This is the "Binary Threshold". Besides being the same threshold used, we changed different value parameters that helped us to get an accurate, general result. Similar to the one requested. The difference between the use of both thresholds was the line:

ret, th2 = cv2.threshold(img2, 20, 255, cv2.THRESH_BINARY)

Within this line we changed the second parameter of the code, having a value of twenty. This value changed the white value to be considered by the program.

3.3 THIRD IMAGE

For this last image we decided to us two different type of unique adaptive thresholds "Adaptive Median" and "Adaptive Gaussian".

This types of thresholds is useful if an image has different lighting conditions in different areas. In that case, adaptive thresholding can help. Here, the algorithm determines the threshold for a pixel-based on a small region around it. So we get different thresholds for different regions of the same image which gives better results for images with varying illumination.

4 CONCLUSIONS

These exercises were the result of the first topics seen in unit one of Artificial Vision. This was helpful because we decided to make something practical with the knowledge learned. There were not many problems regarding the exercise, besides having some syntax coding mistakes.

5 RESULTS



Bone Result - Binary Threshold



Stick Result - Binary Threshold

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Thomas Cabiners

Stick Result - Mean Threshold

Soquet for Lone

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Thomas Calbinia

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Stick Result - Gaussian Threshold