Segmentação do DeepLabV3+

Discente: Hector José Rodrigues Salgueiros

Instalação das dependências

Importação do dataset

```
from roboflow import Roboflow

rf = Roboflow(api_key="API_KEY")
project = rf.workspace("questao2").project("spine_det-alvah")

version = project.version(1)
dataset = version.download("coco")
```

Importação das bibliotecas

```
import os
import torch
import torchvision
from torchvision.models.segmentation import deeplabv3_resnet50
from torchvision.transforms import functional as F
from torchvision.utils import draw_segmentation_masks
from torchvision.datasets import CocoDetection
from torch.utils.data import DataLoader
import matplotlib.pyplot as plt
import numpy as np
from PIL import Image
from tqdm import tqdm
import json
from pycocotools.coco import COCO
from torchvision import transforms
from sklearn.metrics import f1_score
import torch.nn as nn
import torch.optim as optim
import segmentation_models_pytorch as smp
```

Dataset customizado com formato COCO

```
class CocoSegmentationDataset(CocoDetection):
   def __init__(self, img_folder, ann_file, transforms=None):
       super(). init (img folder, ann file)
       self. transforms = transforms
   def getitem (self, idx):
       img, target = super(). getitem (idx)
       ann ids = self.coco.getAnnIds(imgIds=self.ids[idx])
       anns = self.coco.loadAnns(ann ids)
       mask = np.zeros((img.size[1], img.size[0]), dtype=np.uint8)
       for ann in anns:
           # Verifica se a anotação tem um polígono/RLE válido
           if not ann["segmentation"]: # Filtra segmentações vazias
               continue
           try:
               cat id = ann['category id']
               rle = self.coco.annToMask(ann) # Gera a máscara binária
               mask[rle > 0] = cat_id # Atribui o category_id às regiões segmentadas
           except Exception as e:
               print(f"Ignorando anotação inválida (ID {ann['id']}): {e}")
               continue
       mask = Image.fromarray(mask)
       if self. transforms:
           img, mask = self._transforms(img, mask)
       img = transforms.functional.to_tensor(img)
       mask = torch.from_numpy(np.array(mask)).long()
       return img, mask
```

Transformação das imagens e carregamento em lotes

```
class CustomTransform():
    def call (self, img, mask):
        img = transforms.functional.resize(img, (512, 512))
        mask = transforms.functional.resize(mask, (512, 512), interpolation=transforms.InterpolationMode.NEAREST)
        return img, mask
def get loader(folder, batch size=4):
    img dir = os.path.join(folder)
    ann_path = os.path.join(folder, "_annotations.coco.json")
    dataset = CocoSegmentationDataset(img_dir, ann_path, transforms=CustomTransform())
    return DataLoader(dataset, batch_size=batch_size, shuffle=True, num_workers=2, pin memory=True)
# Cria os DataLoaders
train loader = get loader(dataset.location + "/train")
val loader = get loader(dataset.location + "/valid")
test_loader = get_loader(dataset.location + "/test")
```

Treinamento e avaliação do modelo

```
def train_one_epoch(model, loader, optimizer, criterion):
   model.train()
    total loss = 0
    for imgs, masks in tqdm(loader, desc="Treinando"):
        imgs, masks = imgs.to(device), masks.to(device)
        optimizer.zero_grad()
        output = model(imgs)
       loss = criterion(output, masks.long())
        loss.backward()
        optimizer.step()
        total_loss += loss.item()
   return total_loss / len(loader)
def evaluate(model, loader):
   model.eval()
   y_true, y_pred = [], []
   with torch.no_grad():
        for imgs, masks in tqdm(loader):
            imgs, masks = imgs.to(device), masks.to(device)
            outputs = model(imgs)
            preds = torch.argmax(outputs, dim=1).cpu().numpy()
            y_pred.extend(preds.flatten())
            y_true.extend(masks.cpu().numpy().flatten())
   f1 = f1_score(y_true, y_pred, average='macro')
   return f1
```

DeepLabV3+ com ResNet50 e treinamento

```
# Configuração do dispositivo
device = torch.device("cuda" if torch.cuda.is_available() else "cpu")
# Modelo DeepLabV3+ com encoder ResNet-50
model = smp.DeepLabV3Plus(
   encoder_weights="imagenet", # pesos pré-treinados
   in_channels=3,
                    # RGB
   classes=2
                                # fundo e escoliose
).to(device)
# CrossEntropy para segmentação com 2 classes
criterion = nn.CrossEntropyLoss()
optimizer = optim.Adam(model.parameters(), lr=1e-4)
n_{epochs} = 25
for epoch in range(n_epochs):
   print(f"\nÉpoca {epoch+1}/{n_epochs}")
   train_loss = train_one_epoch(model, train_loader, optimizer, criterion)
   val_f1 = evaluate(model, val_loader)
    print(f"Loss de treino: {train_loss:.4f} | F1 Val: {val_f1:.4f}")
```

Resultado da última época

Plotagem

```
def show_predictions(model, loader, n=3):
    model.eval()
    imgs, masks = next(iter(loader))
    imgs, masks = imgs.to(device), masks.to(device)
    with torch.no_grad():
        outputs = model(imgs)
        preds = torch.argmax(outputs, dim=1)
    for i in range(n):
        img = imgs[i].cpu()
       mask = preds[i].cpu().numpy()
        plt.figure(figsize=(10,3))
        plt.subplot(1,2,1)
        plt.title("Imagem")
        plt.imshow(img.permute(1,2,0))
        plt.axis('off')
        plt.subplot(1,2,2)
        plt.title("Máscara Predita")
        plt.imshow(mask, cmap='jet', alpha=0.6)
        plt.axis('off')
        plt.show()
print("\nVisualizando previsões...")
show_predictions(model, test_loader)
```

Resultado da Segmentação



lmagem



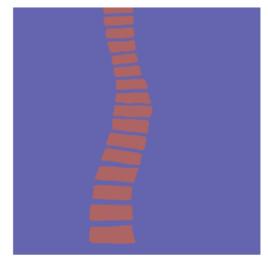
lmagem



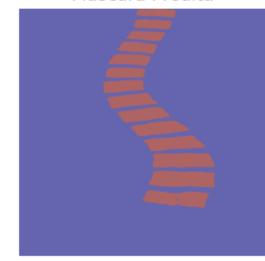
Máscara Predita



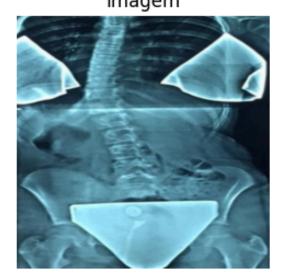
Máscara Predita



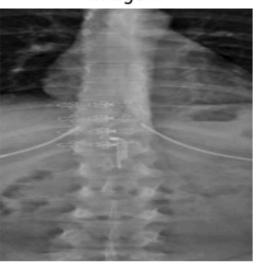
Máscara Predita



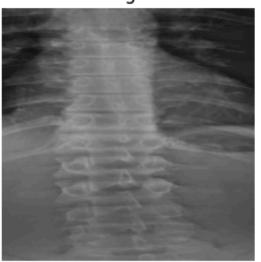
Resultado da Segmentação



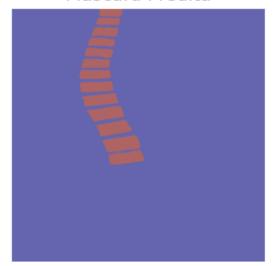
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Máscara Predita



Máscara Predita

