

Evaluation of an Appearance-Preserving Mesh Simplification Scheme

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Outline

Introduction

First Subsection Name

Second Subsection

Implementation

Evaluation

Results

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Make Titles Informative. Use Uppercase Letters.

Subtitles are optional.

- ▶ Item 1
- ▶ Item 2

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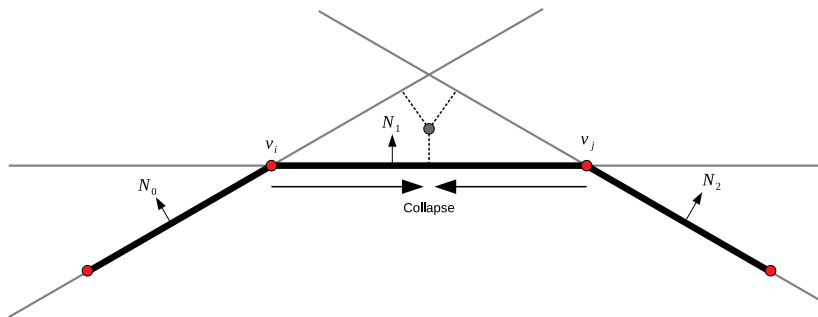
Results

Make Titles Informative.

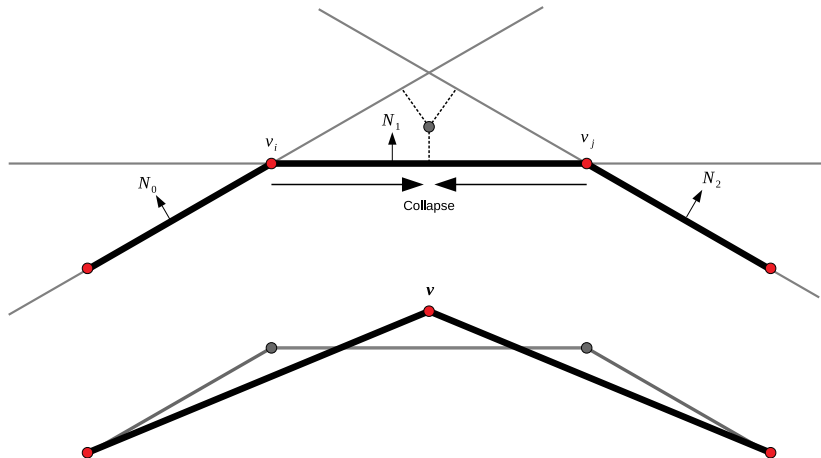
Make Titles Informative.

Quadric Error Metric

- ▶ Iteratively perform edge collapses
- ▶ Cost based on distance to neighboring faces' planes



Quadric Error Metric



Quadric Error Metric

Squared distance from point \mathbf{v} to plane f

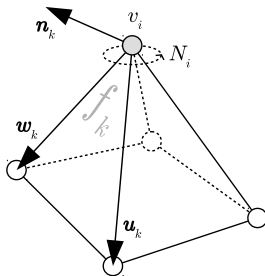
$$\mathbf{v} = [x, y, z, 1]^T, \mathbf{f} = [a, b, c, d]^T$$

$$\begin{aligned} D^2 &= (\mathbf{f}^T \mathbf{v})^2 \\ &= \mathbf{v}^T (\mathbf{f} \mathbf{f}^T) \mathbf{v} \\ &= \mathbf{v}^T \mathbf{Q} \mathbf{v} \end{aligned}$$

$$Q_f = \begin{bmatrix} a^2 & ab & ac & ad \\ ab & b^2 & bc & bd \\ ac & bc & c^2 & cd \\ ad & bd & cd & d^2 \end{bmatrix}$$

Sum of distances to planes f_k of triangles in v_j 's neighborhood

$$\begin{aligned} D^2 &= \sum_k \mathbf{v}_i^T \mathbf{Q}_k \mathbf{v}_i \\ &= \mathbf{v}_i^T \left(\sum_k \mathbf{Q}_k \right) \mathbf{v}_i \\ &= \mathbf{v}_i^T \mathbf{Q}_j \mathbf{v}_i \end{aligned}$$



Finding optimal position for v_i

$$\begin{bmatrix} q_{11} & q_{12} & q_{13} & q_{14} \\ q_{21} & q_{22} & q_{23} & q_{24} \\ q_{31} & q_{32} & q_{33} & q_{34} \\ 0 & 0 & 0 & 1 \end{bmatrix} \bar{\mathbf{v}}_i = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix}$$

Quadric Error Metric

Initialization

1. Compute 4×4 matrix Q for each vertex
2. Compute optimal vertex position for each edge collapse
3. Compute cost of each edge collapse
4. Store edge collapses in min-heap with cost as key

Simplification

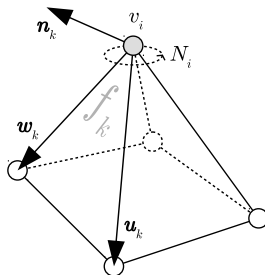
1. Collapse edge on top of min-heap
2. Recompute optimal positions and costs
3. Repeat

Quadric Error Metric

$$\mathbf{f}_k : \mathbf{n}_k^T \mathbf{v}_i + d = 0 \quad (1)$$

$$\mathbf{Q}_i = \sum_{f_k \in N_i} \mathbf{f}_k \mathbf{f}_k^T \quad (2)$$

$$\Delta(\mathbf{v}) = \mathbf{v}^T \mathbf{Q} \mathbf{v} \quad (3)$$



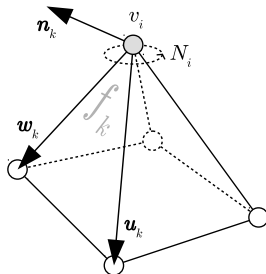
Quadric Error Metric

$$\begin{aligned} D^2 &= (\mathbf{n}^T \mathbf{v} + d)^2 \\ &= \mathbf{v}^T (\mathbf{n} \mathbf{n}^T) \mathbf{v} + 2d \mathbf{n}^T \mathbf{v} + d^2 \end{aligned} \quad (4)$$

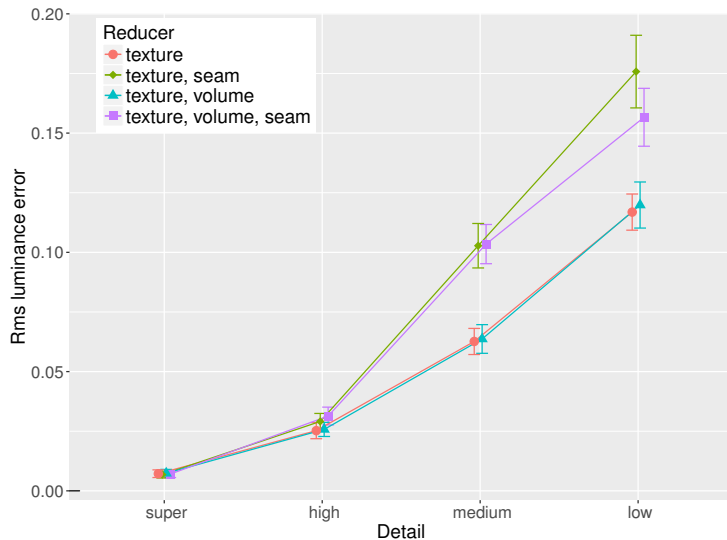
$$\begin{aligned} Q &= (\mathbf{n} \mathbf{n}^T, d \mathbf{n}, d^2) \\ &= (\mathbf{A}, \mathbf{b}, c) \end{aligned} \quad (5)$$

$$\mathbf{A} \mathbf{v} + \mathbf{b} = 0 \quad (6)$$

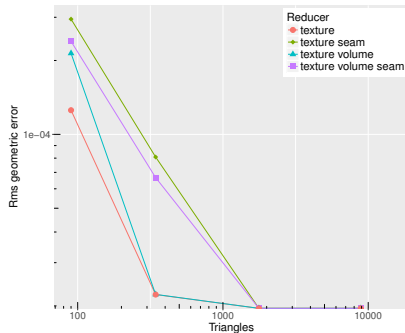
$$Q(\mathbf{v}) = \mathbf{v}^T \mathbf{A} \mathbf{v} + 2\mathbf{b}^T \mathbf{v} + c \quad (7)$$



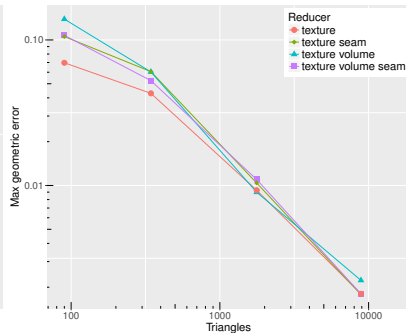
Rms Luminance Error



Geometric Error

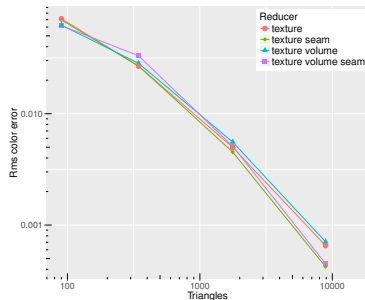


Rms geometric error

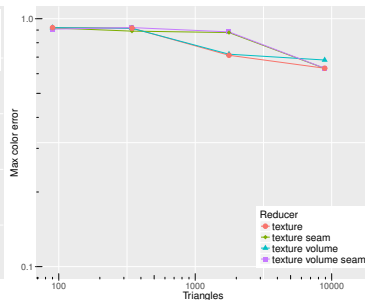


Max geometric error

Color error

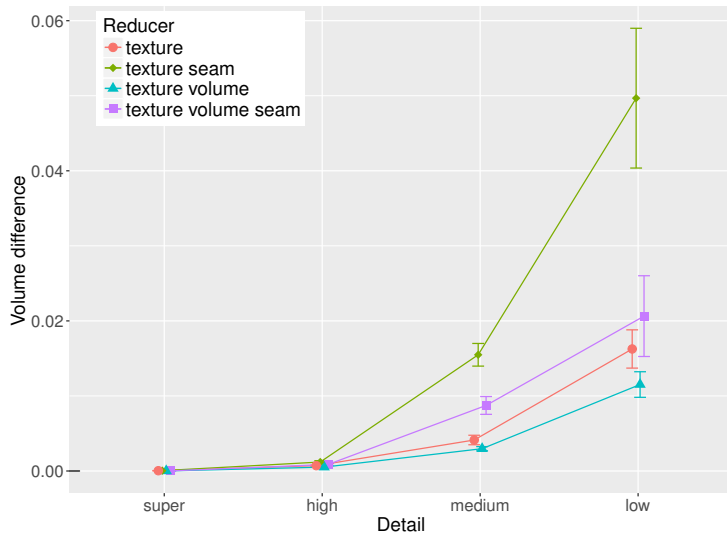


Rms color error

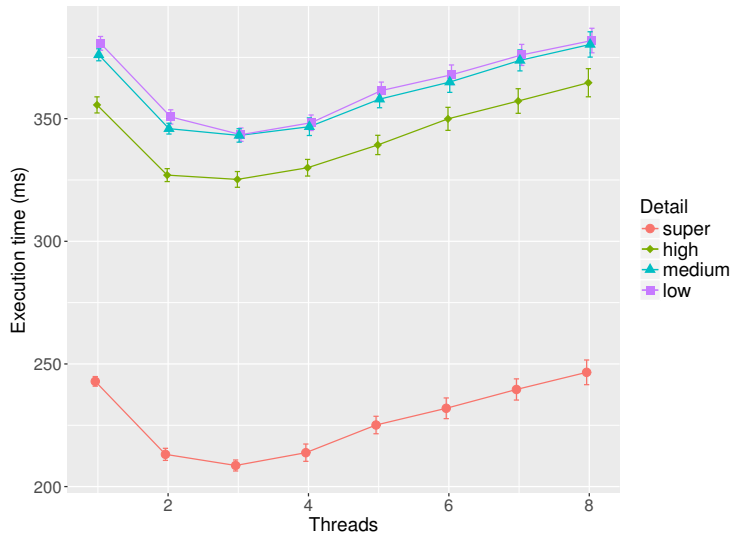


Max color error

Volume



Execution Time





Original



Bound



Improved





Super



High



Medium



Low



Super



High



Medium



Low

Summary

- ▶ The **first main message** of your talk in one or two lines.
 - ▶ The **second main message** of your talk in one or two lines.
 - ▶ Perhaps a **third message**, but not more than that.
-
- ▶ Outlook
 - ▶ Something you haven't solved.
 - ▶ Something else you haven't solved.